

# Notes on Algebraic Topology

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I plan to learn algebraic topology with [Prof. Löh's notes](#), some other references:

- *A Basic Course in Algebraic Topology* (GTM 127), William S. Massey, Springer.
- *A Concise Course in Algebraic Topology*, Peter May, available at <https://www.math.uchicago.edu/~may/CONCISE/ConciseRevised.pdf>.

We denote the concatenation of two path  $g_{12} : x_1 \rightsquigarrow x_2$  and  $g_{23} : x_2 \rightsquigarrow x_3$  by  $g_{12} \cdot g_{23} : x_1 \rightsquigarrow x_3$ , i.e., we apply  $g_{12}$  **first**, then  $g_{23}$ .

## 1. Basic Definitions

### 1.1. Relative Homotopy

Two morphisms  $f$  and  $g$  from topology space  $X$  to  $Y$  is called *homotopic relative to  $A$*  for  $A \subset X$ , denoted as  $f \simeq g \text{ rel } A$ , if there exists a morphism  $h : X \times I \rightarrow Y$  such that

- $h(x, 0) = f(x)$  for all  $x \in X$ ;
- $h(x, 1) = g(x)$  for all  $x \in X$ ;
- $h(a, t) = f(a) = g(a)$  for all  $a \in A, t \in I$ .

*Remark.* So the classical homotopic relation between two paths with same end points is exactly the relative homotopy when  $A = \{\text{initial point}, \text{final point}\}$ .

### 1.2. Retract and Deformation Retract

- A subspace  $i : A \hookrightarrow X$  is called a *retract* of  $X$  if  $i$  admits a left inverse  $r : X \twoheadrightarrow A$ , i.e.  $r \circ i = \text{id}_A$ ;
- It is called a *deformation retract* of  $X$  if  $i \circ r \simeq \text{id}_X \text{ rel } A$ .

*Remark.* Note that  $r \circ i = \text{id}_A$  is equivalent to  $r \circ i \simeq \text{id}_A \text{ rel } A$  – so the condition of deformation retract is rather natural – indeed:

- If  $r \circ i = \text{id}_A$ , then define the homotopy  $h(x, t) = r \circ i(x) = \text{id}_A(x) = x$ , which is of course continuous in both  $x$  and  $t$ ;
- If  $r \circ i \simeq \text{id}_A \text{ rel } A$ , then by definition there exists a homotopy  $h : A \times I \rightarrow A$  such that  $h(a, t) = r \circ i(a) = \text{id}_A(a)$ , implies that  $r \circ i = \text{id}_A$ .

The main importance of deformation retract is embodied in the following theorem:

### Theorem 1.2.1 (A deformation retract shares the same fundamental group of the ambient sapce)

For a deformation retract  $i : A \hookrightarrow X$ , we have  $\pi_1(A, a) = \pi_1(X, a)$  for all  $a \in A$ .

*Proof.* Suppose the relative homotopy is witness by  $h$ .

Then by the proposition in Section 4, Chapter 1 of [May], we need only to prove that  $\gamma[h(a, -)] = \text{id}$ , but by the definition of relative homotopy,  $h(a, -) \equiv a$  so the equation is tautology.  $\square$

#### Remark

We can prove it directly, first we need a lemma: if  $f, g : X \rightarrow Y$  is relative homotopic respect to  $x_0 \in X$ , i.e. there exists a homotopy  $h : f \simeq g \text{ rel } \{x_0\}$ , we claim that  $f_* = g_* : \pi_1(X, x_0) \rightarrow \pi_1(Y, y_0)$  where  $y_0 := f(x_0) = g(x_0)$ .

By this lemma, and note that  $i \circ r \simeq \text{id}_A \text{ rel } \{a\}$ , we have  $(i \circ r)_* = i_* \circ r_* = (\text{id}_A)_*$ . Furthur since  $A$  is a retract,  $r \circ i = \text{id}$  and thus  $r_* \circ i_* = \text{id}$ . So we finish the proof of the theorem.

For the lemma, suppose  $[p] \in \pi_1(X, x_0)$  is a path, we prove that  $f \circ p \simeq g \circ p$ : the homotopy  $\hat{h} : I \times I \rightarrow Y$  is given by

$$\begin{array}{ccc} I \times I & & \\ \downarrow p \times \text{id} & \searrow \hat{h} & \\ X \times I & \xrightarrow{h} & Y \end{array}$$

Note that  $\hat{h}(s, t) = h(p(s), t)$  is indeed a homotopy between  $f$  and  $g$ . We are finished.

This can be used to compute the fundamental group  $\pi_1(\mathbb{R}^n, x_0)$  for all  $x_0 \in \mathbb{R}^n$ : we claim that  $\{x_0\}$  is a deformation retract of  $\mathbb{R}^n$ , and one of the required homotopies is given by  $h : \mathbb{R}^n \times I \rightarrow \mathbb{R}^n$  which sends  $(x, t)$  to  $tx + (1 - t)x_0$ .

$$\text{So } \pi_1(\mathbb{R}^n, x_0) = \pi_1(\{x_0\}, x_0) = \{*\}.$$

## 2. Covering Space

There are (at least) two definitions of covering spaces over a given base topological space  $X$ :

- **The “new” fashion:** A covering space over  $X$  is a morphism  $p : E \rightarrow X$  such that: for all  $x \in X$ , there exists an open neighbourhood  $x \in U_x$  such that  $p^{-1}(U_x) \cong U_x \times p^{-1}(x)$ , where  $p^{-1}(x)$  equipped with discrete topology.
- **The “old” fashion:** A covering space over  $X$  is a morphism  $p : E \rightarrow X$  such that: for all  $x \in X$ , there exists an *path-connected* open neighbourhood  $U_x$  such that each path-connected component of  $p^{-1}(U_x)$  is homeomorphic to  $U_x$  via  $p$ .

The new fashion can be found in [Wedhorn], [Löh], and [covering space on nLab](#) while the old one can be found in [Massey] and [May].

#### Remark

The old fashion definition is in fact not consistent:

- [Massey] requires that both covering spaces and base spaces are *path-connected* and *locally path-connected*.
- [May] requires nothing.

In short: Covering space is a locally trivial bundle with discrete fiber.

## 2.1. Examples and non-examples

Examples:

1. **The trivial bundle:** Identity  $\text{id}_X : X \rightarrow X$  is a covering space, with fiber  $\{*\}$ .
2. **Global trivial bundle with discrete fiber:** For a discrete space  $D$ , the projection  $X \times D \rightarrow X$  is of course a covering space, and  $D$  is the fiber.
3. **Exponential:** The exponential function  $\exp : \mathbb{R} \rightarrow S^1$  sends  $\theta$  to  $(\cos \theta, \sin \theta)$  is a local trivial bundle with fiber  $\mathbb{Z}$ .

Note that to be a covering map, the fiber must be *discrete*. Here is one of non-examples:

1. The projection  $S^1 \times [0, 1] \rightarrow S^1$  is not a covering map, since the fiber  $[0, 1]$  is not discrete.

## 2.2. Basic Topological Properties

### Theorem 2.2.1 (fiber-wise diagonal of covering space is open and closed)

For  $p : E \rightarrow X$  a covering, the diagonal  $\Delta(E) := \{(e, e) : e \in E\}$  is both closed and open in  $E \times_X E$ , the pullback of  $p : E \rightarrow X$ .

*Proof.* See [nLab - Covering spaces, Lemma 3.2](#). □

This will be used to prove the result: two lifts in a covering space of a path are either same, or different everywhere.

## 2.3. Produce covering spaces from group actions

In this section,  $G$  is a group endowed with discrete topology and  $X$  is an arbitrary space. We fix a  $G$ -action on space  $X$ :  $\alpha : G \rightarrow \text{Aut}_{\text{Top}}(X)$ , then it induces a covering space if this action is good enough. We always write  $gx$  for  $\alpha_g x$ .

Denote the orbit of  $x \in X$  as  $Gx := \{gx : g \in G\}$ .

Firstly we need some definitions:

### Definition 2.3.1 (Orbit space)

The orbit space  $GX$  of  $X$  related to the action  $\alpha$  is defined as:

$$GX := \{Gx : x \in X\}.$$

We endow this set with quotient topology induced from the projection  $X \rightarrow GX$ .

## 2.4. Lebesgue number

Yes, Lebesgue and algebraic topology. We should say “thank you” to him for the following useful lemma:

### Theorem 2.4.1 (Lebesgue number)

For an open covering  $\{U_i\}$  of a compact metric space  $X$ , there exists  $\delta > 0$ , which is called a Lebesgue number, such that for all  $x \in X$  the open ball centered  $x$  with radius  $\delta$  is fully contained in one of those open sets, formally:  $B(x, \delta) \subset U_i$  for some  $U_i$ .

*Proof.* Suppose not, that is, for all  $n$ , there exists  $x_n$  such that  $B(x_n, \frac{1}{n})$  does not fully contained any  $U_i$ .

Since  $X$  is compact,  $\{x_n\}$  has a convergence subsequence  $\{y_n\}$  tends to  $y_0$ . Let  $\varepsilon_n$  the associated radius of  $y_n$ . Since  $\{U_i\}$  is an open cover of  $X$ , there exists  $\varepsilon_0 > 0$  and  $N$  such that  $B(y_0, \varepsilon) \subset U_i$  for some  $i$ , and for all  $m > N$  we have  $y_m \in B(y_0, \frac{\varepsilon_0}{2})$ .

Now make  $m$  so large that  $\varepsilon_m < \frac{\varepsilon_0}{2}$  and  $m > N$ , so  $B(y_m, \varepsilon_m) \subset B(y_0, \varepsilon_0) \subset U_i$ , contradiction to our assumption!  $\square$

#### Remark

We need  $X$  to be compact, otherwise there may be no such  $\delta$ , for example:  $\{B(r, \frac{r}{2})\}_{r \in (0,1)}$  covers  $(0, 1)$ .

Compactness ensures the existence of convergence subsequence of a infinite sequence: suppose  $\{x_n\}$  does not admit a convergence subsequence, then for all  $x \in X$ , there exists a open neighbourhood  $U_x$  of  $x$  that only contains finitely many  $x_n$ . Now note that  $\{U_x\}$  is an open cover of a compact space so it admits a finite subcover  $\{V_x\}$ , and their union only contains finitely many  $x_n$ .

Since  $\{V_x\}$  covers  $X$ , we know that there are only finitely many distinct points in  $\{x_n\}$ , which implies this sequence itself must coverage, contradiction!

This theorem is especially useful and when we want to prove something about covering spaces, it serves as a bridge from the trivial covering to general situations. We will see such examples in the next section, where we concern lifting properties.

## 2.5. Lifting Properties

### Theorem 2.5.1 (Lifting of paths)

For a given covering space  $p : \hat{X} \rightarrow X$  and a path  $f : I \rightarrow X$  with the initial point  $x_0 := f(0)$ , then for any  $\hat{x}_0 \in \hat{X}$  such that  $p(\hat{x}_0) = x_0$ , there exists an unique path  $\hat{f} : I \rightarrow \hat{X}$  with initial point  $\hat{x}_0$  such that  $p \circ \hat{f} = f$ .

In diagram:

$$\begin{array}{ccc} \{0\} & \xrightarrow{\hat{x}_0} & \hat{X} \\ \downarrow & & \downarrow p \\ [0, 1] & \xrightarrow{f} & X \end{array}$$

induces an unique  $\hat{f}$  such that

$$\begin{array}{ccc}
\{0\} & \xrightarrow{\hat{x}_0} & \hat{X} \\
\downarrow & \nearrow \exists! \tilde{f} & \downarrow p \\
[0, 1] & \xrightarrow{f} & X
\end{array}$$

commutes.

*Proof.* The main idea is that we first prove the case  $\hat{X}$  is *global trivial*, and then proceed to the general case.

- **Trivial Case:** Suppose  $\hat{X} \cong X \times D$  for a discrete space  $D$ .
  - Existence: We define  $\hat{f}(t) := (f(t), d_0)$ , where  $d_0 = \text{pr}_2(\hat{x}_0)$ . It is continuous and indeed a lifting.
  - Uniqueness: For another lift  $\tilde{f} : [0, 1] \rightarrow \hat{X}$ , since the diagram commutes, we have  $\tilde{f}(t) = (f(t), d(t))$  and  $d(0) = d_0$ .

A continuous image of a path-connected space is again path-connected, so  $\tilde{f}(I)$  is path-connected and we claim that  $d(t) \equiv d_0$ . Otherwise, because all discrete spaces are not path-connected,  $(\tilde{f}(t_1), d(t_1))$  can not be connected to  $(\tilde{f}(t_2), d(t_2))$  by path since  $D$  is discrete.

- **General Case:** Thanks to the local triviality of a covering space, for each  $x \in X$  there exists a open neighbourhood  $U_x$  such that  $p^{-1}(U_x) \cong U_x \times D$  a trivial covering of  $U_x$ , where  $D := p^{-1}(x)$  is equipped with discrete topology.

Now we need only to divide  $f$  into pieces of sub-paths  $\{f_i\}$  that each of them is fully contained in some trivial open neighbourhoods. Then use the result from the trivial case we obtain sub-liftings  $\{\hat{f}_i\}$ , and finally glueing them!

Since  $[0, 1]$  is compact and  $\{f^{-1}(U_x)\}_{x \in X}$  is an open cover of it, we obtain a finite subcover  $\{f^{-1}(V_x)\}$ , now we let  $\frac{1}{n}$  be a Lebesgue number of this cover where  $n$  is a integer, and divide  $[0, 1]$  into  $\{[0, \frac{1}{n}], [\frac{1}{n}, \frac{2}{n}], \dots, [1 - \frac{1}{n}, 1]\}$ . Let  $f_k : [\frac{k-1}{n}, \frac{k}{n}] \rightarrow X$  be the restriction of  $f$ . By the definition of  $n$ , image of each  $f_k$  is contained in a trivial open neighbourhood  $U_k$ , and thus the problem for each  $f_k$  reduces into the global trivial case, finally we obtain the sub-liftings  $\{\hat{f}_i\}$  with the given initial point of  $\widehat{f_{k+1}}$  defined to be the final point of  $\hat{f}_k$ .

Now glued them, we obtain the lifting  $\hat{f}$ .

For the uniqueness, if there are two such liftings, restrict them to  $[\frac{k-1}{n}, \frac{k}{n}]$  and by the uniqueness of trivial case, these two restriction are same. Thus the two liftings are same.

□

**Theorem 2.5.2 (lifts out of connected space into covering spaces are unique relative to any point)**

For a commutative diagram

$$\begin{array}{ccc}
 & & E \\
 & \nearrow \tilde{f}_2 & \uparrow \\
 Y & \nearrow \tilde{f}_1 & \downarrow p \\
 & \xrightarrow{f} & X
 \end{array}$$

where  $Y$  is connected and  $p : E \rightarrow X$  a covering, either  $\tilde{f}_1$  and  $\tilde{f}_2$  are same, or different everywhere.

*Proof.* These two lifts  $\tilde{f}_1$  and  $\tilde{f}_2$  induces a map  $\langle \tilde{f}_1, \tilde{f}_2 \rangle : Y \rightarrow E \times_X E$ .

Since  $\Delta(E)$  is clopen in  $E \times_X E$  (recall [Theorem 2.2.1](#)), the pre-image of it under  $\langle \tilde{f}_1, \tilde{f}_2 \rangle$  is also clopen. But  $Y$  is connected, so the pre-image is either  $Y$  or empty.  $\square$

### Theorem 2.5.3 (Lifting of homotopies)

**TODO.**

*Proof.* **TODO.**  $\square$

### Theorem 2.5.4 (Lifting of arbitrary maps)

Let  $(\tilde{X}, p)$  be a covering of  $X$  and  $\tilde{x}_0 \in \tilde{X}$  be a pre-image of  $x_0$ . Suppose  $Y$  is **connected and locally path-connected**. For a continuous map  $\varphi : (Y, y_0) \rightarrow (X, x_0)$ , there exists a lifting  $\tilde{\varphi} : (Y, y_0) \rightarrow (\tilde{X}, \tilde{x}_0)$  if and only if  $\varphi_* \pi_1(Y, y_0) \subset p_* \pi_1(\tilde{X}, \tilde{x}_0)$ .

$$\begin{array}{ccc}
 & & (\tilde{X}, \tilde{x}_0) \\
 & \nearrow \exists \tilde{\varphi} & \downarrow p \\
 (Y, y_0) & \xrightarrow{\varphi} & (X, x_0)
 \end{array}$$

*Proof.* For simplicity we denote the fundamental group of a space  $W$  at point  $w$  as  $\pi(W, w)$ , i.e. omit the subscript 1.

- If such  $\tilde{\varphi}$  exists, then since the fundamental group  $\pi : \text{Top}_* \rightarrow \text{Grp}$  is a functor, the following diagram also commutes:

$$\begin{array}{ccc}
 & & \pi(\tilde{X}, \tilde{x}_0) \\
 & \nearrow \tilde{\varphi}_* & \downarrow p_* \\
 \pi(Y, y_0) & \xrightarrow{\varphi_*} & \pi(X, x_0)
 \end{array}$$

So the desired property is immediate.

- If  $\varphi_* \pi_1(Y, y_0) \subset p_* \pi_1(\tilde{X}, \tilde{x}_0)$ , we need to construct a  $\tilde{\varphi}$  such that the diagram in theorem commutes.

Note that  $Y$  is global path-connected since it is connected and locally path-connected, so there exists at least one path  $g : y_0 \rightsquigarrow y$  for all point  $y \in Y$ . Then by compose  $\varphi$  we obtain a path  $\varphi g : x_0 \rightsquigarrow x := \varphi g(y)$ . By the lifting property of paths in  $X$ , we then obtain a path  $\tilde{\varphi} g$  in  $\tilde{X}$  with the chosen initial point  $\tilde{x}_0$ , let  $\tilde{x}$  be the final point of this lifting path.

So we start with an arbitrary point  $y$  in  $Y$  and end with a point  $\tilde{x}$  in  $\tilde{X}$ , and we, bravely, define  $\tilde{\varphi}(y) = \tilde{x}$ .

Of course we need to verify this procedure is well-defined:

- **$\tilde{x}$  is independent with the connecting path:** Suppose we have two different paths  $g_1, g_2 : y_0 \rightsquigarrow y$ , and the resulting final points by using these paths in  $\tilde{X}$  are  $\tilde{x}_1$  and  $\tilde{x}_2$ , resp. We need to verify  $\tilde{x}_1 = \tilde{x}_2$ .

Let  $g_2^{-1} : y \rightsquigarrow y_0$  be the inverse path of  $g_2$ , then  $g_1 \cdot g_2^{-1} : y_0 \rightsquigarrow y_0$  is an (representative) element in  $\pi(Y, y_0)$ . And thus  $\varphi_*(g_1 \cdot g_2^{-1}) = (\varphi g_1) \cdot (\varphi g_2)^{-1} \in \pi(X, x_0)$ . By assumption, there exists a path  $\alpha \in \pi(\tilde{X}, \tilde{x}_0)$  such that  $p_*\alpha = (\varphi g_1) \cdot (\varphi g_2)^{-1}$ .

So tired, for a complete proof see [nLab - Coverign space, Proposition 3.9](#).

- **$\tilde{\varphi}$  makes the diagram commutative:** Because of the lifting property of  $\tilde{\varphi}g$ .
- **$\tilde{\varphi}$  is continuous: TODO.**

□

### 3. Basic notions in Singular Homology

For motivations, see []