CSE 6740 Homework 2

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Deadline: Feb 27 Thursday, 9:30 am

- There are 2 sections in gradescope: Homework 2 and Homework 2 Programming. Submit your answers as a PDF file to Homework 2 (including report for programming) and also submit your code in a zip file to Homework 2 Programming.
- All Homeworks are due by the beginning of class. Homework is penalized by 20% for each day that it is late (this applies additively, meaning that no credit is gained after 5 late days).
- We strongly encourage the use of LaTeX for your submission. Unreadable handwriting is subject to zero credit.
- Explicitly mention your collaborators if any.
- Recommended reading: PRML¹ Section 1.5, 1.6, 2.5, 9.2, 9.3, 9.4

1 EM for Mixture of Gaussians

Mixture of K Gaussians is represented as

$$p(x) = \sum_{k=1}^{K} \pi_k \mathcal{N}(x|\mu_k, \Sigma_k), \tag{1}$$

where π_k represents the probability that a data point belongs to the kth component. As it is probability, it satisfies $0 \le \pi_k \le 1$ and $\sum_k \pi_k = 1$. In this problem, we are going to represent this in a slightly different manner with explicit latent variables. Specifically, we introduce 1-of-K coding representation for latent variables $z^{(k)} \in \mathbb{R}^K$ for k = 1, ..., K. Each $z^{(k)}$ is a binary vector of size K, with 1 only in kth element and 0 in all others. That is,

$$z^{(1)} = [1; 0; ...; 0]$$

$$z^{(2)} = [0; 1; ...; 0]$$

$$\vdots$$

$$z^{(K)} = [0; 0; ...; 1].$$

For example, if the second component generated data point x^i , its latent variable z^i is given by $[0; 1; ...; 0] = z^{(2)}$. With this representation, we can express p(z) as

$$p(z) = \prod_{k=1}^K \pi_k^{z_k},$$

¹Christopher M. Bishop, Pattern Recognition and Machine Learning, 2006, Springer.

where z_k indicates kth element of vector z.

Also, p(x|z) can be represented similarly as

$$p(x|z) = \prod_{k=1}^{K} \mathcal{N}(x|\mu_k, \Sigma_k)^{z_k}.$$

By the sum rule of probability, (1) can be represented by

$$p(x) = \sum_{z \in Z} p(z)p(x|z). \tag{2}$$

where $Z = \{z^{(1)}, z^{(2)}, ..., z^{(K)}\}.$

- (a) Show that (2) is equivalent to (1). [5 pts]
- (b) In reality, we do not know which component each data point is from. Thus, we estimate the responsibility (expectation of z_k^i) in the E-step of EM. Since z_k^i is either 1 or 0, its expectation is the probability for the point x_i to belong to the component z_k . In other words, we estimate $p(z_k^i = 1|x_i)$. [5 pts]

Note that, in the E-step, we assume all other parameters, i.e. π_k , μ_k , and Σ_k , are fixed, and we want to express $p(z_k^i|x_i)$ as a function of these fixed parameters.

Hint: Derive the formula for this estimation by using Bayes rule.

(c) In the M-Step, we re-estimate parameters π_k , μ_k , and Σ_k by maximizing the log-likelihood. Given N i.i.d (Independent Identically Distributed) data samples $x_1, ..., x_N$, write down the log likelihood function, and derive the update formula for each parameter. [8 pts]

Note that in order to obtain an update rule for the M-step, we fix the responsibilities, i.e. $p(z_k^i|x_i)$, which we have already calculated in the E-step.

Hint: Use Lagrange multiplier for π_k to apply constraints on it.

(d) Establish the convergence of the EM algorithm by showing that the log likelihood function will be nondecreasing in each iteration of this algorithm. [8 pts]

Hint: Use Jensen's inequality: for concave function f(x), we have $f(\sum_i \alpha_i x_i) \ge \sum_i \alpha_i f(x_i)$, where $\sum_i \alpha_i = 1$, $\alpha_i \ge 0$.

(e) EM and K-Means [5 pts]

K-means can be viewed as a particular limit of EM for Gaussian mixture. Briefly describe the expectation and maximization steps in K-Means Algorithm.

2 Density Estimation

(a) Given a sequence of m independently and identically distributed (iid) data points $D = \{x^1, x^2, x^3, \dots, x^m\}$, where each x^i is a nonnegative integer (i.e., $x^i \in \{0, 1, 2, \dots\}$) following a Poisson distribution. The Poisson distribution is given by:

$$P(x \mid \lambda) = e^{-\lambda} \frac{\lambda^x}{x!},\tag{3}$$

where $\lambda > 0$ is both the mean and the variance of the distribution (rate parameter). Find the Maximum Likelihood Estimation (MLE) for λ . [8 pts]

- (b) Given $D = \{x^1, x^2, x^3, \dots, x^m\}$ as above (i.e., $x^i \in \{0, 1, 2, \dots\}$ from a Poisson distribution), use results from (a), show the estimated mean and variance. [4 pts]
- (c) Given $D = \{x^1, x^2, x^3, \dots, x^m\}$, where each $x^i \in \{0, 1, 2, \dots\}$, consider a simple frequency-based (non-parametric) estimator for the discrete pmf. Let C_k denote the number of samples in D that equal k (i.e., $C_k = \sum_{i=1}^m I\{x^i = k\}$). For $k = 0, 1, 2, \dots$, define the estimator

$$p(k) = \frac{C_k}{m}. (4)$$

Discuss the conditions for a valid pmf and prove that this frequency-based estimator satisfies these conditions. [6 pts]

3 Information Theory

In the lecture you became familiar with the concept of entropy for one random variable and mutual information. One property of mutual information is $I(X,Z) \geq 0$, where the larger the value, the greater the relationship between the two variables.

Let X and Y take on values $x_1, x_2, ..., x_r$ and $y_1, y_2, ..., y_s$ respectively. Let Z also be a discrete random variable and Z = X + Y.

- (a) Show that H(Z|X) = H(Y|X). Argue that if X, Y are independent, then $H(Y) \leq H(Z)$ and $H(X) \leq H(Z)$. Thus the addition of independent random variables adds uncertainty. [8 pts]
- (b) Give an example of (necessarily dependent) random variables X, Y in which H(X) > H(Z) and H(Y) > H(Z). [2 pts]
- (c) Let Z be a discrete random variable defined as Z = X + Y. Is the independence between X and Y a necessary condition, a sufficient condition, or both for the equality H(Z) = H(X) + H(Y) to hold true? Justify your answer. [6 pts]

4 Programming: Gaussian Mixture Models

During lecture, we introduced Gaussian Mixture Models (GMMs). Here we ask you to implement your own GMM with numpy. Please follow the instruction in the submission.py to implement the required function. Specifically, you are asked to implement

- 1. initialize_parameters [5pt]: initialize parameters uniformly.
- 2. compute_sigma [5pt]: compute the covariance matrix.
- 3. prob [5pt]: compute probability of a n dimensional Gaussian.

- 4. E_step [5pt]: perform the expectation step.
- 5. M_step [5pt]: perform the maximization step.
- 6. likelihood [5pt]: compute the loglikelihood.
- 7. train_model [10pt]: train the GMM model until convergence (convergence criterion provided).

For submission, you are required to submit the ${\tt submission.py}$ file to Gradescope.