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In [2]: import numpy as np
       from matplotlib import pyplot as plt
        from matplotlib import cm as cmap
        from mpl_toolkits.mplot3d import Axes3D
        #working in weak lensing domain, 3d, with mass distributed across distance
        class location:
            def __init__(self, x=0, y=0, z=0):
                self.x = x
                self.y = y
                self.z = z
            def dl2(self,dx,dy,dz):
                self.x += dx
                self.y += dy
                self.z += dz
                return dx**2+dy**2+dz**2
       class mass:
            def __init__(self,mass,x,y,z):
                self.mass = mass
                self.loc = location(x,y,z)
       def bend(dist, mass):
            angle = mass/dist #units chosen such that 4G/c^2 = 1
            if(angle>0.2): #so weak lensing dist >> 2GM/c^2 = mass/2
                print(str(mass)+" mass is within strong lensing domain")
            return angle
        #redshift is distance light has traversed (pathlength)
        #massdistr sorted by proximity to observer (z)
        #make sure massdistr doesn't extend past z of source
       def beam(plot, magnifications, redshift, massdistr, xangle, yangle):
            magnification =1
            loc = location()
            totaldz = redshift/np.sqrt(1 + np.sin(xangle)**2 + np.sin(yangle)**2)
                apparentloc = location(totaldz*np.sin(xangle), totaldz*np.sin(yangle), totaldz)
                fig = plt.figure(1, figsize=(8,8))
                az = fig.add_subplot(111, projection='3d')
                az.plot([loc.x], [loc.y], 'ro',zs=loc.z, label="mass distribution")
az.plot([loc.x],[loc.y], 'o',zs=loc.z,label="observer")
                az.plot([apparentloc.x],[apparentloc.y],'o',zs=apparentloc.z,label="apparent source")
                az.plot([loc.x,apparentloc.x],[loc.y,apparentloc.y],'orange',zs=[loc.z,apparentloc.z],label="apparent pat
                az.set_xlabel("x distance from observer")
                az.set_ylabel("y distance from observer")
                az.set_zlabel("z distance from observer")
                fig2 = plt.figure(2, figsize=(8,8))
                ay = plt.subplot(111)
                plt.plot(loc.x,loc.z,'ro', label="mass distribution")
                plt.plot(loc.x,loc.z,'o',label="observer")
                plt.plot(apparentloc.x,apparentloc.z,'o',label="apparent source")
                plt.plot([loc.x,apparentloc.x],[loc.z,apparentloc.z],'orange',label="apparent path")
                plt.xlabel("x distance from observer")
                plt.ylabel("y distance from observer")
                fig3 = plt.figure(3, figsize=(8,8))
                ax = plt.subplot(111)
                plt.plot(loc.y,loc.z,'ro', label="mass distribution")
                plt.plot(loc.y,loc.z,'o',label="observer")
                plt.plot(apparentloc.y,apparentloc.z,'o',label="apparent source")
                plt.plot([loc.y,apparentloc.y],[loc.z,apparentloc.z],'orange',label="apparent path")
                plt.xlabel("x distance from observer")
                plt.ylabel("y distance from observer")
                locrecord = [(loc.x,loc.y,loc.z)]
            for m in massdistr:
                dz = m.loc.z - loc.z
                dx = dz*np.sin(xangle)
                dy = dz*np.sin(yangle)
                redshift -= np.sqrt(loc.dl2(dx,dy,dz)) #update ray location and pathlength
                    locrecord.append((loc.x,loc.y,loc.z))
                    plt.figure(1)
                    az.plot([m.loc.x], [m.loc.y], 'ro',zs=m.loc.z, markersize = 10*m.mass)
                    az.plot([m.loc.x, loc.x], [m.loc.y, loc.y], 'r--', zs=[m.loc.z, loc.z])
                    plt.figure(2)
                    plt.plot(m.loc.x, m.loc.z, 'ro', markersize = 10*m.mass)
                    plt.plot([m.loc.x, loc.x], [m.loc.z, loc.z], 'r--')
                    plt.figure(3)
                    plt.plot(m.loc.y, m.loc.z, 'ro', markersize = 10*m.mass)
                    plt.plot([m.loc.y, loc.y], [m.loc.z, loc.z], 'r--')
                xdist = loc.x-m.loc.x #calculate bend angle
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ydist = loc.y-m.loc.y
    mdist = np.sqrt(xdist**2 + ydist**2)
    angle = bend(mdist, m.mass)
    dz_LS = totaldz-loc.z #calculate magnification
    dz_S = dz+dz_LS
    thetaE2 = m.mass*dz_LS/(dz*dz_S)
    theta = np.arcsin(np.sqrt(np.sin(xangle)**2 + np.sin(yangle)**2))
    beta = theta-angle*dz_LS/dz_S
    u2 = thetaE2 / beta**2
    stepmag = (u2 +2)/(2*np.sqrt(u2)*np.sqrt(u2 +4)) + 1/2
    if(theta**2 < thetaE2):</pre>
        stepmag -= 1
    magnification *= stepmag
    if(plot):
        print(str(m.mass)+" mass magnifies by "+str(stepmag))
    xangle -= angle*xdist/mdist #adjust angles
    yangle -= angle*ydist/mdist #do these two lines require small angle approximation?
dz = redshift/np.sqrt(1 + np.sin(xangle)**2 + np.sin(yangle)**2)
loc.x += dz*np.sin(xangle)
loc.y += dz*np.sin(yangle)
loc.z += dz
if(plot):
    print("for a total magnification of "+str(magnification))
    locrecord.append((loc.x,loc.y,loc.z))
    xs = [1[0] for 1 in locrecord]
    ys = [1[1] for 1 in locrecord]
    zs = [1[2] for 1 in locrecord]
    plt.figure(1)
    plt.title("3-dimensional view")
    az.plot(xs ,[1[1] for l in locrecord],'g',zs=zs,label="light ray path")
    az.plot([loc.x],[loc.y], 'go', zs=loc.z, label="true source")
    az.legend()
    plt.figure(2)
    plt.title("projection on y=0 plane")
    plt.plot(xs, zs,'g',label="light ray path")
    plt.plot(loc.x,loc.z,'go',label="true source")
    plt.legend()
    plt.figure(3)
    plt.title("projection on x=0 plane")
    plt.plot(ys, zs,'g',label="light ray path")
    plt.plot(loc.y,loc.z,'go',label="true source")
    plt.legend()
    plt.show()
magnifications.append(magnification)
return loc #final x,y,z
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In [3]: >f imagesource(mags, massdistr, imagedistr, redshift, sourcezs):
          sourcedistr = []
          for xy in imagedistr:
              loc = beam(False, mags, redshift, sorted(massdistr, key=lambda m: m.loc.z), xy[0], xy[1])
              truexangle = np.arcsin(loc.x/loc.z)
              trueyangle = np.arcsin(loc.y/loc.z)
              sourcezs.append(loc.z)
              trueangle = (truexangle,trueyangle)
              sourcedistr.append(trueangle)
          return sourcedistr
       edshift =250
       assdistr = [mass(0.3,3,-2,60), mass(0.5,-3,-4,90), mass(0.8,-4,5,150)]
       ef center(massdistr):
          centerx = 0
          centery = 0
          totalmassdist = 0
          for m in massdistr:
              centerx += m.mass*m.loc.x/m.loc.z
              centery += m.mass*m.loc.y/m.loc.z
              totalmassdist += m.mass/m.loc.z
          centerx /= totalmassdist
          centery /= totalmassdist
          for m in massdistr:
              m.loc.x -= centerx
              m.loc.y -= centery
          return
       enter(massdistr)
       pparentxangle = -np.pi/30
       pparentyangle = np.pi/24
       pc = beam(True, [], redshift,sorted(massdistr, key=lambda m: m.loc.z),apparentxangle,apparentyangle)
       ruexangle = np.arcsin(loc.x/loc.z)
       rueyangle = np.arcsin(loc.y/loc.z)
       B = []
       ags = []
       hetas = np.linspace(0,2*np.pi,32)
       nage = [(apparentxangle + 0.02*np.cos(theta), apparentyangle + 0.02*np.sin(theta)) for theta in thetas]
       hage += [(apparentxangle + 0.005*np.cos(theta), apparentyangle + 0.005*np.sin(theta)) for theta in thetas]
       purce = imagesource(mags, massdistr, image, redshift, zs)
       nagefig = plt.figure(4,figsize=(9,8))
        = plt.subplot(111)
       pmags =np.array(mags)
       image = [pt[0] for pt in image]
       image = [pt[1] for pt in image]
       lt.scatter(ximage, yimage, c = mags, cmap="viridis")
       lt.plot(ximage, yimage, "orange")
       lt.axis('equal')
       lt.title("angular image distribution")
       lt.clim(npmags.min(),npmags.max())
       par = plt.colorbar()
       bar.set_label("magnification")
       lt.xlabel("radians from center of mass distribution")
       lt.ylabel("radians from center of mass distribution")
       burcefig = plt.figure(5,figsize=(9,8))
        = plt.subplot(111)
       source = [pt[0] for pt in source]
       source = [pt[1] for pt in source]
       burcedists = np.array([zs[n]*np.sqrt(1+np.sin(source[n][0])**2+np.sin(source[n][1])**2) for n in range(0,len(zs))
       lt.scatter(xsource, ysource, c= sourcedists, cmap="winter")
       lt.plot(xsource, ysource)
       lt.axis('equal')
       lt.clim(sourcedists.min(),sourcedists.max())
       bar = plt.colorbar()
       bar.set_label("true distance from observer")
       lt.title("angular source distribution")
       lt.xlabel("radians from center of mass distribution")
       lt.ylabel("radians from center of mass distribution")
       pmbfig = plt.figure(6, figsize=(9,7))
       bmb = plt.subplot(111)
       lt.plot(xsource, ysource, label="source distribution")
       lt.plot(ximage, yimage, label="image distribution")
       asszs = np.array([m.loc.z for m in massdistr])
       lt.scatter([np.arctan(m.loc.x/m.loc.z) for m in massdistr],[np.arctan(m.loc.y/m.loc.z) for m in massdistr],c=mass
       lt.clim(0,redshift)
       par = plt.colorbar()
       par.set_label("distance to mass")
       lt.title("view of true source, lensed image, and lensing masses")
       lt.legend()
       lt.xlabel("radians from center of mass distribution")
       lt.ylabel("radians from center of mass distribution")
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```
lt.axis('equal')
distfig = plt.figure(7, figsize=(7,8))
dist = plt.subplot(111)
def cn(array):
    return (array - array.min())/(array.max()-array.min())
cnxsource = cn(xsource)
cnysource = cn(ysource)
cnximage = cn(ximage)
cnyimage = cn(yimage)
plt.scatter(cnxsource,cnysource,label="source distribution")
plt.scatter(cnximage,cnyimage, "orange",label="image distribution")
plt.plot([cnxsource])
plt.title("distortion")
plt.legend()
plt.axis('equal')
lt.show()
   0.11 -
       -0.13
                -0.12
                         -0.11
                                   -0.10
                                            -0.09
                                                     -0.08
                   radians from center of mass distribution
```

In [ ]: