# Brownian motion near a boundary

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A discrete-time dynamical system is purely noise driven if

$$x_{n+1} = x_n + \sigma(x_n)r_n$$

where  $\{r_n\}$  are mean 0, i.i.d. random variables.

### DEFINITION (MULTIPLICATIVE NOISE)

 $\sigma(x)$  is not constant

Note if  $\mathbb{E}r_n^2 = \Delta t$  then  $\sigma(x) = \sqrt{2D(x)}$ , where

### DEFINITION (DIFFUSION CONSTANT)

$$D(x) := \frac{1}{2\Delta t} \mathbb{E}\left[ (x_{n+1} - x_n)^2 | x_n = x \right]$$

### **Proof:**

$$2D(x) = \frac{1}{\Delta t} \mathbb{E} \left[ (x_{n+1} - x_n)^2 | x_n = x \right]$$

$$= \frac{1}{\Delta t} \mathbb{E} \left[ (\sigma(x_n) r_n)^2 | x_n = x \right]$$

$$= \frac{1}{\Delta t} \mathbb{E} \left[ (\sigma(x) r_n)^2 | x_n = x \right]$$

$$= \frac{(\sigma(x))^2}{\Delta t} \mathbb{E} \left[ r_n^2 | x_n = x \right]$$

$$= \frac{(\sigma(x))^2}{\Delta t} \mathbb{E} \left[ r_n^2 \right]$$

$$= \frac{(\sigma(x))^2}{\Delta t} \Delta t$$

$$= (\sigma(x))^2$$

In homogeneous, isotropic fluid bulk, D(x) is constant.

$$D = \frac{1}{2\Delta t} \mathbb{E}\left[\Delta x^2\right] = \frac{\Delta t}{2} \mathbb{E}v^2$$

Assuming 1D equipartition,

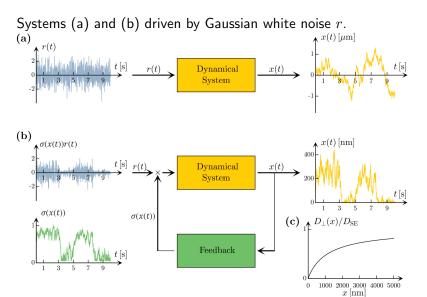
$$\frac{\Delta t}{m} \mathbb{E} \left[ \frac{1}{2} m v^2 \right] = \frac{\Delta t}{2m} k_B T$$

### DEFINITION (EINSTEIN RELATION)

$$D_E = \mu k_B T$$

Mobility  $\mu = v_{\text{ter}}(F)/F$  ratio of terminal velocity to applied force:

$$m\mu \approx \frac{m\Delta v}{F} = \frac{1}{F} \int_0^{\Delta t} F_{\mathsf{net}}(s) \mathrm{d}s \approx \frac{1}{F} \int_0^{\Delta t} \left(1 - \frac{s}{\Delta t}\right) F \mathrm{d}s = \frac{\Delta t}{2}.$$



Source: Giovanni Volpe and Jan Wehr 2016 Rep. Prog. Phys. **79** 053901. (c) Hydrodynamic effects reduce Brownian motion near a wall.

Let independent  $r_i(\Delta t):=\pm\sqrt{\Delta t}$  each with probability 1/2, and partial sum  $S_t:=\sum_{\{i:i\Delta t< t\}}r_i.$ 

#### LEMMA

For any  $t \geq 0$ ,  $S_t$  converges weakly to  $\mathcal{N}(0,t)$  as  $\Delta t \to 0$ .

**Sketch of proof:** Fix  $\Delta t$ . The  $r_i$  i.i.d. so by CLT, as  $n \to \infty$ :

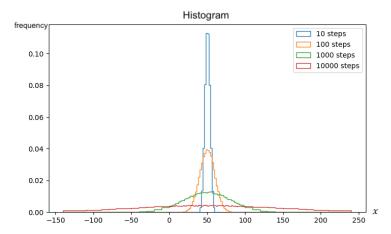
$$\mathcal{N}(0,1) \longleftarrow \frac{\frac{1}{n} \sum_{i=1}^{n} r_i - \mathbb{E}r_i}{\sqrt{\frac{1}{n} \mathbb{E}[r_i^2]}} = \frac{S_{n\Delta t}/n}{\sqrt{\Delta t}/\sqrt{n}} = \frac{S_{n\Delta t}}{\sqrt{n\Delta t}}$$

Choose  $\Delta t:=t/n$  for each n, giving a sequence  $\frac{S_t^{(n)}}{\sqrt{t}}\to \mathcal{N}(0,1).$ 

t=n for  $\Delta t=1$ , so for constant  $\sigma$  the distribution of

$$x_n = x_{n-1} \pm \sigma = x_0 + \sigma S_n$$

approaches  $\mathcal{N}(x_0, n\sigma^2)$  as  $n \to \infty$ .

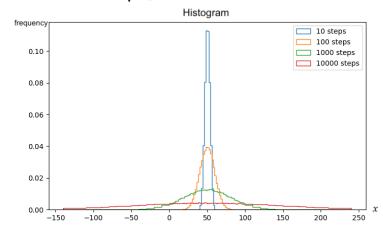


Source: Own simulations of the model for  $x_0 = 50, \ \sigma = 1.$ 

$$x_n = x_{n-1} \pm \sigma = x_{n-1} + \frac{\sigma}{\sqrt{\Delta t}} r_{n-1} = x_0 + \frac{\sigma}{\sqrt{\Delta t}} S_{n\Delta t}$$

As  $n \to 0$ , distribution approaches:

$$x_0 + \frac{\sigma}{\sqrt{\Delta t}} \mathcal{N}(0, n\Delta t) = \mathcal{N}(x_0, n\sigma^2)$$



Source: Own simulations of the model for  $x_0 = 50, \ \sigma = 1.$ 

Set  $\Delta t := 1/k$ , and interpolate S over  $t \in [0, 1]$ .

$$\xi_t^k := S_{n\Delta t} + \frac{t - n\Delta t}{\Delta t} r_n, \ t \in [n\Delta t, (n+1)\Delta t]$$
$$= \frac{1}{\sqrt{k}} \left( \sum_{i=1}^{[kt]} \eta_i + (kt - [kt]) \eta_{[kt]+1} \right), \ [kt] = n$$

where  $\eta_i$  i.i.d. with  $\mathbb{E}\eta_i=0$  and  $\mathbb{E}\eta_i^2=1$ .

### THEOREM (DONSKER'S INVARIANCE)

The sequence of distributions of  $\xi^k$  converges weakly to  $\mu$ , the Wiener measure on C[0,1].

Source: Krylov, N. V. Introduction to the Theory of Random Processes. American Mathematical Society; Graduate Studies in Mathematics, Volume 43; 2002; pp 28-32

For constant  $\sigma$ .

$$x_{n+1} = x_n + \sigma r_n = x_0 + \sigma S_{(n+1)\Delta t}$$

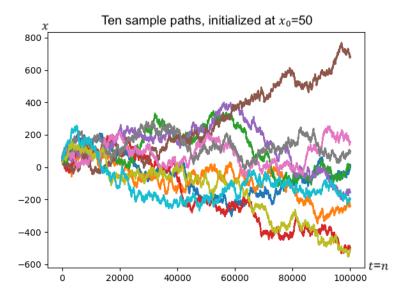
Interpolating model for  $r_n = \pm \sqrt{\Delta t}$  yields continuous paths with distributions weakly convergent to the Wiener measure.

$$x^{(k)}(t) := x_n + \frac{t - n\Delta t}{\Delta t} \sigma r_n$$

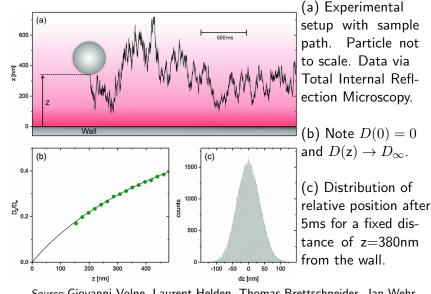
$$= x_0 + \sigma S_{n\Delta t} + \frac{t - n\Delta t}{\Delta t} \sigma r_n$$

$$= x^{(k)}(0) + \sigma \xi_t^k$$

$$(x(t) - x(s))^{(k)} = \sigma \xi_t^k - \sigma \xi_s^k = \sigma (\xi_t - \xi_s)^k$$
$$dx_{\cdot}^{(k)} = d(\sigma \xi_{\cdot}^k) = \sigma d\xi_{\cdot}^k \longrightarrow \sigma dW_{\cdot} := \sigma \mu (dx_{\cdot})$$



Source: Own simulations,  $\Delta t=1,~\sigma=1.$ 



Source: Giovanni Volpe, Laurent Helden, Thomas Brettschneider, Jan Wehr, and Clemens Bechinger 2010 Phys. Rev. Lett. 104, 170602

Let  $D(x) = D_{\infty} \left(\frac{x}{x+a}\right)^2$  for a > 0 (h asymptote, crosses origin)

$$\sigma(x) = \sqrt{2D(x)} = \sqrt{2D_{\infty}} \frac{x}{x+a}$$

Recall: 
$$x_{n+1} = x_n + \sigma(x_n)r_n$$

To ensure  $x_{n+1} \ge 0$  we need  $x_n \ge \sigma(x_n)||r_n||_{\infty} \ \forall n$ :

$$x \ge \sqrt{2D} \frac{x}{x+a} ||r||_{\infty} \Longrightarrow x^2 + ax \ge \sqrt{2D_{\infty}} ||r||_{\infty} x$$

$$\Longrightarrow x(x+a-\sqrt{2D_{\infty}} ||r||_{\infty}) \ge 0$$

$$(x \ge 0) \Longrightarrow a \ge \sqrt{2D_{\infty}} ||r||_{\infty} - x$$

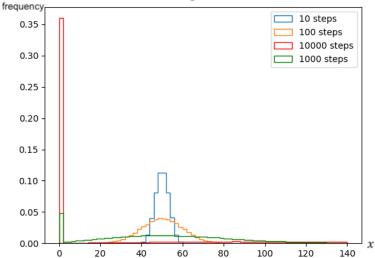
 $x \geq 0$  so we need  $a \geq \sqrt{2D_{\infty}}||r||_{\infty} = \sqrt{2D_{\infty}\Delta t}$  for our model.

We wouldn't be able to make this guarantee with Gaussian noise.

a>0 can be arbitrarily small if we shrink the time step  $\Delta t \to 0$ .

$$a = \sqrt{2D_{\infty}\Delta t} = 1$$

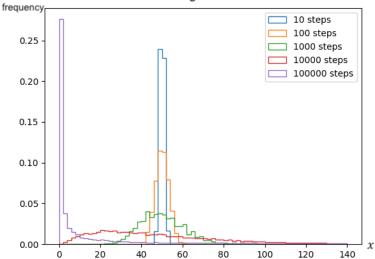
## Histogram



Source: Own simulations,  $\Delta t=1, \ \sigma=1.$ 

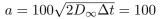
$$a = 100\sqrt{2D_{\infty}\Delta t} = 100$$

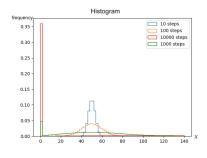


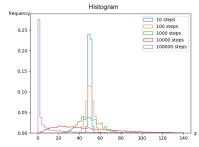


Source: Own simulations,  $\Delta t=1, \ \sigma=1.$ 

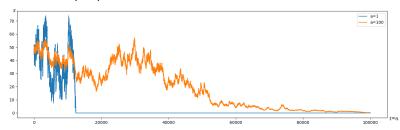
$$a = \sqrt{2D_{\infty}\Delta t} = 1$$







## Here's a sample path for each a:



Source: Own simulations,  $\Delta t=1, \ \sigma=1.$ 

Looks unrealistic. Why does this happen?

Let  $\Delta t = 1$ , and consider x > 0.

 $\sigma$  increasing and  $x_{n+1}^+ > x_n$  so  $\sigma(x_{n+1}^+) > \sigma(x_n)$ .

$$x_{n+2}^{+-} = x_{n+1}^{+} - \sigma(x_{n+1}^{+}) = \underbrace{x_n + \sigma(x_n)}_{x_n + \sigma(x_n)} - \sigma(x_{n+1}^{+})$$

$$< x_n + \sigma(x_n) - \sigma(x_n)$$

$$= x_n$$

 $x_{n+1}^- < x_n$  so by similar argument  $x_{n+2}^{-+} < x_n$ .

In either case, new position is behind.

$$p = 3/4 \text{ of } x_{n+2} < x_n$$

$$\sigma(x_n)$$
 is bad. Is  $\sigma\left(\frac{x_n+x_{n+1}}{2}\right)$  or  $\sigma(x_{n+1})$  better?

A convex combination of endpoints  $x_n, x_{n+1}$  gives  $\sigma(x_n + \alpha \Delta x_n)$  where  $\alpha \in [0,1]$  for  $\Delta x_n = x_{n+1} - x_n$ . Above,  $\alpha = 0, \frac{1}{2}, 1$ .

 $\Delta t \to 0$ , these choices lead to the Itô, Stratonovich, and "anti-Itô" interpretations of  $\mathrm{d}x_t = \sigma(x_t)\mathrm{d}W_t$ .

These interpretations evaluate the integrand  $\sigma$  at different points:

$$\mathbb{E}\left[\sum \sigma(x_{t_i} + \alpha \Delta x_{t_i})(\underbrace{W_{t_{i+1}} - W_{t_i}}_{\sim \mathcal{N}(0, \sqrt{\Delta t})})\right] \xrightarrow{L_2} \int \sigma(x_t) \circ_{\alpha} dW_t$$

Itô denoted by  $\sigma(x_t)dW_t := \sigma(x_t) \circ_{\alpha=0} dW_t$ .

Let  $\sigma_n$  denote  $\sigma(x_n)$ , and Taylor expand  $\sigma$  to "half order" in  $\Delta t$ :

$$\sigma(x_n + \alpha \Delta x_n) \approx \sigma_n + \alpha \sigma'_n \Delta x_n$$

$$= \sigma_n + \alpha \sigma'_n \sigma(x_n + \alpha \Delta x_n) (\pm \sqrt{\Delta t})$$

$$\approx \sigma_n \pm \alpha \sigma'_n (\sigma_n + \alpha \sigma'_n \underbrace{\Delta x_n}_{\pm \sigma \sqrt{\Delta t}}) \sqrt{\Delta t}$$

$$\approx \sigma_n \pm \alpha \sigma'_n \sigma_n \sqrt{\Delta t}$$

To first order in  $\Delta t$ ,  $x_{n+1} = x_n \pm \sigma(x_n + \alpha \Delta x_n) \sqrt{\Delta t}$   $\approx x_n \pm \left(\sigma_n \pm \alpha \sigma_n' \sigma_n \sqrt{\Delta t}\right) \sqrt{\Delta t}$   $= x_n \pm \sigma(x_n) \sqrt{\Delta t} + \underbrace{\alpha \sigma(x_n) \sigma'(x_n) \Delta t}_{\text{noise-induced drift}}$ 

Accordingly,  $dx_t = \sigma(x_t) \circ_{\alpha} dW = \sigma(x_t) dW_t + \alpha \sigma(x_t) \frac{d\sigma(x_t)}{dx} dt$ 

$$\sigma(x_t) \circ_{\alpha} dW = \sigma(x_t) dW_t + \alpha \sigma(x_t) \frac{d\sigma(x_t)}{dx} dt$$

Result remains valid with addition of deterministic drift, i.e. still holds for

$$dX_t = \mu(X_t)dt + \sigma(X_t) \circ_{\alpha} dW_t$$

E.g. Stratonovich ( $\alpha=1/2$ ) and Itô ( $\alpha=0$ ) integrals differ by

$$\int \sigma(X_t) \circ_{\alpha = \frac{1}{2}} dW_t - \int \sigma(X_t) dW_t = \frac{1}{2} \int \sigma(X_t) \frac{d\sigma}{dx} (X_t) dt$$

Dynamics of a colloid at thermal equilibrium with fluid are anti-Itô.

Equilibrium with heat bath at temp T yields Boltzmann distribution:

$$\rho(x,v) = Z^{-1} \exp\left(-\frac{U(x)}{k_B T} - \frac{mv^2}{2k_B T}\right) = \rho(x)\rho(v)$$

for colloidal particle of mass m at position x and velocity v.

$$\rho(v) \sim \mathcal{N}\left(0, \frac{k_B T}{m}\right)$$
 implies energy equipartition:

$$\mathbb{E}\left[\frac{1}{2}mv^2\right] = \frac{m}{2}\mathbb{E}[v^2] = \frac{m}{2}\frac{k_BT}{m} = \frac{1}{2}k_BT$$

Let F denote net external force (i.e.  $F(x) = -\frac{\mathrm{d}U(x)}{\mathrm{d}x}$ ) and  $\gamma(x)$  viscous friction coefficient. Modified Langevin equation:

$$\begin{split} ma &= F(x) - \gamma(x)(v + v_{\text{noise}}) \\ m\Delta v &= F(x)\Delta t - \gamma(x)v\Delta t - \gamma(x)v_{\text{noise}}\Delta t \\ v_{\text{noise}}\Delta t &= \Delta x_{\text{noise}} \approx \pm \sqrt{\mathbb{E}[(\Delta x)^2]} = \pm \sqrt{2D(x)\Delta t} \\ m\mathrm{d}v_t &= F(x_t)\mathrm{d}t - \gamma(x_t)v_t\mathrm{d}t + \gamma(x_t)\sqrt{2D(x_t)}\mathrm{d}W_t \\ v_t\mathrm{d}t &= \frac{1}{\gamma(x_t)}\Big(-m\mathrm{d}v_t + F(x_t)\mathrm{d}t\Big) + \sqrt{2D(x_t)}\mathrm{d}W_t \end{split}$$

Near equilibrium, system satisfies the fluctuation-dissipation relation  $D(x)\gamma(x)=k_BT$ . By definition  $\mathrm{d}x_t=v_t\mathrm{d}t$ , so

$$dx_t = -\frac{m}{k_B T} D(x_t) dv_t + \frac{1}{k_B T} D(x_t) F(x_t) dt + \sqrt{2D(x_t)} dW_t$$

Only first term depends on  $m \to 0$  for microscopic particles.

$$-\int_0^t \frac{m}{k_B T} D(x_s) dv_s = -\int_0^t \frac{m}{k_B T} D(x_s) \frac{dv_s}{ds} ds = (IBP)$$
$$= \frac{1}{k_B T} \left( m v_0 D(x_0) - m v_t D(x_t) \right) + \int_0^t \frac{m}{k_B T} \frac{dD(x_s)}{ds} v_s ds$$

Boundary term vanishes by equipartition. Integral term is the "spurious" drift:

$$\int_0^t \frac{m}{k_B T} \frac{\mathrm{d}D(x_s)}{\mathrm{d}s} v_s \mathrm{d}s = \int_0^t \frac{m}{k_B T} \frac{\mathrm{d}D(x_s)}{\mathrm{d}x} v_s^2 \mathrm{d}s$$

$$\approx \int_0^t \frac{2}{k_B T} \frac{\mathrm{d}D(x_s)}{\mathrm{d}x} \mathbb{E}\left[\frac{1}{2} m v_s^2\right] \mathrm{d}s$$

$$= \int_0^t \frac{\mathrm{d}D(x_s)}{\mathrm{d}x} \mathrm{d}s$$

$$dx_t = \underbrace{\frac{dD(x_s)}{dx}}_{\text{spurious drift}} + \frac{1}{k_B T} D(x_t) F(x_t) dt + \sqrt{2D(x_t)} dW_t$$

Spurious drift is just anti-Itô noise-induced drift since  $\sigma=\sqrt{2D}$  :

$$D = \frac{1}{2}\sigma^2 \Longrightarrow \frac{\mathrm{d}D}{\mathrm{d}\sigma} = \sigma \Longrightarrow \frac{\mathrm{d}D}{\mathrm{d}x} = \frac{\mathrm{d}D}{\mathrm{d}\sigma}\frac{\mathrm{d}\sigma}{\mathrm{d}x} = \sigma\frac{\mathrm{d}\sigma}{\mathrm{d}x}$$

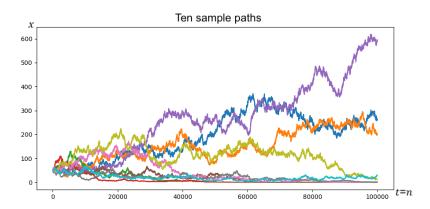
Thus,  $dx_t = \beta D(x_t)F(x_t)dt + \sqrt{2D(x_t)} \circ_{\alpha=1} dW_t$ .

Source: Giovanni Volpe and Jan Wehr 2016 Rep. Prog. Phys. 79 053901.

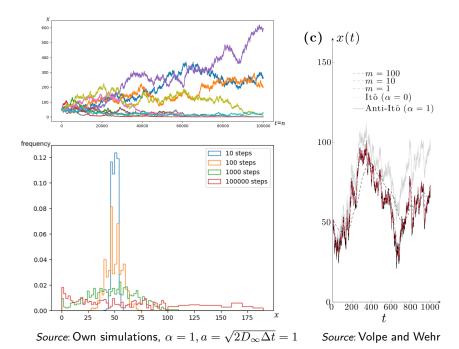
Back to  $x_{n+1} = x_n \pm \sigma(x_{n+1}) \sqrt{\Delta t}$ . How to actually find  $\sigma(x_{n+1})$ ?

$$\sigma(x) = \sqrt{2D_{\infty}} \frac{x}{x+a} \Longrightarrow$$

$$x_{n+1} = \frac{x_n - a \pm \sqrt{2D_{\infty}\Delta t} + \sqrt{(x_n + a)^2 \pm \sqrt{2D_{\infty}\Delta t}(x_n - a)}}{2}$$



Source: Own simulations,  $\alpha = 1, a = \sqrt{2D_{\infty}\Delta t} = 1$ 



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