

# Yves Mojica

San Diego, CA | 818-318-4085 | sebastianYSM12@gmail.com

## Objective

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Computer Engineering major with coursework focus on Embedded Systems and Digital/Analog Circuits, looking to gain more hands-on experience through internships.

## Education

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**University of California, San Diego | San Diego, CA**

*September 2022 – (Expected) June 2026*

Bachelor of Science in Computer Engineering, GPA 3.16/4.0

## Projects

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**Rocket Propulsion Lab | San Diego, CA**

*October 2022 - Present*

### ***NMP Member***

- Participated in a new member project to lead a team of 5 to design a small-scale rocket using, 3D printed parts, and an avionics system on an Arduino nano to produce a functional small-scale rocket
- Designed an avionics bay in solidworks to house an Arduino nano, altimeter, and a battery that could slide inside our rocket.

### ***Hermes Avionics Engineer***

- Assisted in developing the avionics bay to create a system that could transmit/collect data and release recovery parachutes for a larger-scale solid propellant rocket.
- Developed code for various sensors on Arduino in C++ for flight data collection of altitude, temperature, location, and acceleration to be transmitted via radio/stored in an SD card
- 3D printed avionics system parts, hand-soldered pins for sensors and components for the PCB of our ejection system
- Conducted hands-on testing/troubleshooting for sensors and ejection system to ensure wiring and Arduino code worked properly.

**Radio Telemetry Tracking/E4E | San Diego, CA**

*November 2024 - Present*

### ***Hardware Member***

- Worked in a research project team called Engineers For Exploration to help develop technologies for local organizations like the San Diego Zoo.
- Sketched and designed an updated CAD for our drone payload to house different electrical components and manage wiring.

**Line Following Robot | San Diego, CA**

*December 2022*

### ***Team Member***

- Developed a small robot with a team of four in 2 weeks to navigate through tracks of black tape using photoresistors, with our design excelling at speed/accuracy in looping tracks
- Designed a chassis for the robot using onshape to be able to hold more components together and a shield portion to prevent external light from interfering with the photoresistors
- Wired and soldered the circuit boards with the Arduino to help create the electronics for the robot
- Built a final website for the project/course that acted as a detailed report that highlighted the functional specifications of our project through video and text

## Skills

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**Programming:** C, C++, Java, MATLAB, HTML/CSS, React

**Technical:** LTspice, 3D printing, Arduino, CAD Onshape, Solidworks, Git, Microsoft Office

**Equipment:** Function generators, Oscilloscopes, Multimeters, Soldering irons, Power Supplies