Testing of the Car.java class

Equivalence Partitionings

Negative

1 Initialize crashed during setup

Positive

- 2 Initialize car
- 3 Crash the car
- 4 Change velocity
- 5 Change position

Test log

default testcases	Expected	Eqivalence Partititoning	Result
requirementCarSetUpSuccessful()	True	2	Passed
requirementSetUpPositionSuccessful()	True	2	Passed
requirementCrashedIsFalseAfterSetUp()	False	1	Passed
requirement Marked As Crashed Successfull ()	True	3	Passed
requirementCalculateAcceleratedPositionWithoutChangingThePosition()	True	4	Passed
requirementMoveCalculatedRight()	True	5	Passed
requirementAccelerateWithEveryPossibleParameterChangeVelocityOneTim e()	True	4	Passed
requirementCalculateAccelerationCorrectInPositivePossibleXAndYDirections OnBoard()	True	4	Passed
requirementCalculateAccelerationCorrectInNegativePossibleXAndYDirectionsOnBoard()	True	4	Passed
requirementCalculateAccelerationCorrectInUpDiagonalUpRightDirection()	True	4	Passed
	True	4	Passed
requirementCalculateAccelerationCorrectInUpDiagonalUpLeftDirection()	True	4	Passed
requirementCalculateAccelerationCorrectInUpDiagonalDownRightDirection ()	True	4	Passed
requirementCalculateAccelerationCorrectInUpDiagonalDownLeftDirection()	True	4	Passed
requirementCalculateAccelerationCorrectFromPositiveXMaximumToNegativXMaximumPosition()	True	4	Passed
requirement Calculate Acceleration Correct From Positive YMaximum ToNegative YMaximum Position ()	True	4	Passed
requirementCalculateAccelerationCorrectFromDiagonalUpRightToDownLeft Position()	True	4	Passed
requirementCalculateAccelerationCorrectFromDiagonalUpLeftToDownRight Position()	True	4	Passed

Screenshots

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据 requirementCalculateAccelerationCorrectInUpDiagonalDownRightDirection (0.000 s)
    ⊱ requirementCalculateAccelerationCorrectFromPositiveXMaximumToNegativXMaximumPosition (0.000 s)
    requirementMarkedAsCrashedSuccessfull (0.000 s)
    据 requirementCalculateAccelerationCorrectInUpDiagonalDownLeftDirection (0.000 s)
    🗲 requirementCalculateAccelerationCorrectInUpDiagonalUpRightDirection (0.000 s)
    requirementCarSetUpSuccessful (0.000 s)
    \overline requirementCalculateAccelerationCorrectFromPositiveYMaximumToNegativYMaximumPosition (0.000 s)
    🚪 requirementCalculateAccelerationCorrectFromDiagonalUpRightToDownLeftPosition (0.000 s)
    🗲 requirementCalculateAccelerationCorrectInUpDiagonalUpLeftDirection (0.000 s)
    requirementMoveCalculatedRight (0.000 s)
    🟣 requirementCalculateAccelerationCorrectFromDiagonalUpLeftToDownRightPosition (0.000 s)
    🗲 requirementCalculateAccelerationCorrectInNegativePossibleXAndYDirectionsOnBoard (0.000 s)
    \overline requirementAccelerateWithEveryPossibleParameterChangeVelocityOneTime (0.000 s)
    Æ requirementCalculateAccelerationCorrectInPositivePossibleXAndYDirectionsOnBoard (0.000 s)
    🚈 requirementSetUpPositionSuccessful (0.000 s)
    \overline requirementCalculateAcceleratedPositionWithoutChangingThePosition (0.000 s)
    据 requirementCrashedIsFalseAfterSetUp (0.000 s)
```