Testing of the Car.java class

Equivalence Partitionings

Negative

1 Initialize crashed during setup

Positive

- 2 Initialize car
- 3 Crash the car
- 4 Change velocity
- 5 Change position

Test log

default testcases	Expected	Eqivalence Partititoning	Result
requirementCarSetUpSuccessful()	True	2	Passed
requirementSetUpPositionSuccessful()	True	2	Passed
requirement Crashed Is False After Set Up ()	False	1	Passed
requirement Marked As Crashed Successfull ()	True	3	Passed
requirementCalculateAcceleratedPositionWithoutChangingThePosition()	True	4	Passed
requirementMoveCalculatedRight()	True	5	Passed
requirementAccelerateWithEveryPossibleParameterChangeVelocityOneTim e()	True	4	Passed
requirementCalculateAccelerationCorrectInPositivePossibleXAndYDirections OnBoard()	True	4	Passed
requirementCalculateAccelerationCorrectInNegativePossibleXAndYDirectionsOnBoard()	True	4	Passed
requirement Calculate Acceleration Correct In Up Diagonal Up Right Direction ()	True	4	Passed
	True	4	Passed
requirementCalculateAccelerationCorrectInUpDiagonalUpLeftDirection()	True	4	Passed
requirementCalculateAccelerationCorrectInUpDiagonalDownRightDirection ()	True	4	Passed
requirementCalculateAccelerationCorrectInUpDiagonalDownLeftDirection()	True	4	
requirement Calculate Acceleration Correct From Positive XMaximum To Negative XMaximum Position ()	True	4	Passed
requirementCalculateAccelerationCorrectFromPositiveYMaximumToNegativYMaximumPosition()	True	4	Passed
$requirement Calculate Acceleration Correct From Diagonal Up Right To Down Left \\ Position ()$	True	4	Passed
requirement Calculate Acceleration Correct From Diagonal Up Left To Down Right Position ()	True	4	Passed

Screenshots

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据 requirementCalculateAccelerationCorrectInUpDiagonalDownRightDirection (0.000 s)
🚛 requirementCalculateAccelerationCorrectFromPositiveXMaximumToNegativXMaximumPosition (0.000 s)
requirementMarkedAsCrashedSuccessfull (0.000 s)
据 requirementCalculateAccelerationCorrectInUpDiagonalDownLeftDirection (0.000 s)
🗲 requirementCalculateAccelerationCorrectInUpDiagonalUpRightDirection (0.000 s)
requirementCarSetUpSuccessful (0.000 s)
\overline requirementCalculateAccelerationCorrectFromPositiveYMaximumToNegativYMaximumPosition (0.000 s)
🚪 requirementCalculateAccelerationCorrectFromDiagonalUpRightToDownLeftPosition (0.000 s)
🗲 requirementCalculateAccelerationCorrectInUpDiagonalUpLeftDirection (0.000 s)
requirementMoveCalculatedRight (0.000 s)
🟣 requirementCalculateAccelerationCorrectFromDiagonalUpLeftToDownRightPosition (0.000 s)
🗲 requirementCalculateAccelerationCorrectInNegativePossibleXAndYDirectionsOnBoard (0.000 s)
\overline requirementAccelerateWithEveryPossibleParameterChangeVelocityOneTime (0.000 s)
据 requirementCalculateAccelerationCorrectInPositivePossibleXAndYDirectionsOnBoard (0.000 s)
🚈 requirementSetUpPositionSuccessful (0.000 s)
\overline requirementCalculateAcceleratedPositionWithoutChangingThePosition (0.000 s)
据 requirementCrashedIsFalseAfterSetUp (0.000 s)
```