



## Appendix I. Baum-Welch

### (1) Setup

Consider a discrete HMM of length  $T$ . The space of observation  $X = \{1, 2, \dots, N\}$ , and the space of underlying states  $Z = \{1, 2, \dots, M\}$ . An HMM  $\theta = (\pi, A, B)$  is parametrized by initial state matrix  $\pi$ , the state transition matrix  $A$ , and the emission matrix  $B$ .

The HMM training process includes learning the parametrization of  $\theta$  from a dataset of  $D$  observations. Let  $X = (X^{(1)}, \dots, X^{(D)})$ , where each  $X^{(i)} = (x_1^{(i)}, x_2^{(i)}, \dots, x_T^{(i)})$ . Each observation is drawn iid.

Baum-Welch repeats the following two steps until convergence:

$$\textcircled{1} \text{ Compute } Q(\theta, \theta^*) = \sum_{i=1}^D \log [P(X, z; \theta)] P(z | X; \theta^*);$$

$$\textcircled{2} \text{ Set } \theta^{s+1} = \underset{\theta}{\operatorname{argmax}} Q(\theta, \theta^*).$$

### (2) Derivation.

Noting that  $P(z, X) = P(X)P(z | X)$ , and  $P(X)$  is not affected by  $\theta$ , we have

$$\underset{\theta}{\operatorname{argmax}} \sum_{i=1}^D \log [P(X, z; \theta)] P(z | X; \theta^*) = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^D \log [P(X, z; \theta)] P(z | X; \theta^*) = \underset{\theta}{\operatorname{argmax}} \hat{Q}(\theta, \theta^*)$$

Now,

$$P(z, X; \theta) = \prod_{i=1}^T (\pi_{z_i^{(1)}} B_{z_i^{(1)}}(x_1^{(1)})) \prod_{t=2}^T A_{z_{t-1}^{(1)} z_t^{(1)}} B_{z_t^{(1)}}(x_t^{(1)})$$

Taking the log gives.

$$\log P(z, X; \theta) = \sum_{i=1}^D [\log \pi_{z_i^{(1)}} + \sum_{t=2}^T \log A_{z_{t-1}^{(1)} z_t^{(1)}} + \sum_{t=1}^T \log B_{z_t^{(1)}}(x_t^{(1)})]$$

Plugging this to  $\hat{Q}(\theta, \theta^*)$ .

$$\hat{Q}(\theta, \theta^*) = \sum_{i=1}^D \sum_{z=1}^M \log \pi_{z_i^{(1)}} P(z, X; \theta^*) + \sum_{i=1}^D \sum_{z=1}^M \sum_{t=2}^T \log A_{z_{t-1}^{(1)} z_t^{(1)}} P(z, X; \theta^*) + \sum_{i=1}^D \sum_{z=1}^M \sum_{t=1}^T \log B_{z_t^{(1)}}(x_t^{(1)}) P(z, X; \theta^*)$$

Constrained by the validity of probability distribution  $\pi, A, B$ , we introduce Lagrange multipliers. Let  $\hat{L}(\theta, \theta^*)$  be the Lagrangian.

$$\hat{L}(\theta, \theta^*) = \hat{Q}(\theta, \theta^*) - \lambda_{\pi} \left( \sum_{i=1}^M \pi_i - 1 \right) - \sum_{i,j=1}^M \lambda_{A_{ij}} \left( \sum_{j=1}^M A_{ij} - 1 \right) - \sum_{i=1}^M \lambda_{B_i} \left( \sum_{j=1}^N B_i(j) - 1 \right)$$

Take the partial derivative of  $\hat{L}$ 's,

$$\frac{\partial \hat{L}(\theta, \theta^*)}{\partial \pi_i} = \frac{\partial}{\partial \pi_i} \left( \sum_{i=1}^D \sum_{z=1}^M \log \pi_{z_i^{(1)}} P(z, X; \theta^*) \right) - \lambda_{\pi} = 0$$

$$\frac{\partial \hat{L}(\theta, \theta^*)}{\partial \lambda_{\pi}} = - \left( \sum_{i=1}^M \pi_i - 1 \right) = 0$$

Then it yields.

$$\pi_i = \frac{1}{D} \sum_{i=1}^D P(z_i^{(1)} = i | X^{(i)}, \theta^*) \quad (1)$$

Similarly for  $A_{ij}$ 's.

$$\partial \hat{L}(\theta, \theta^*) / \partial A_{ij} = \frac{\partial}{\partial A_{ij}} \left( \sum_{t \in \mathcal{T}} \sum_{d=1}^D \sum_{t=1}^T \log A_{z_t^{(d)}, z_t^{(d)}} \log A_{z_t^{(d)}, z_t^{(d)}} P(z, x; \theta^*) \right) - \lambda_{A_i} = 0$$

$$\partial \hat{L}(\theta, \theta^*) / \partial \lambda_{A_i} = - \left( \sum_{j=1}^I A_{ij} - 1 \right) = 0$$

$$\text{It yields } A_{ij} = \frac{\sum_{d=1}^D \sum_{t=1}^T P(z_t^{(d)} = i, z_t^{(d)} = j | x; \theta^*)}{\sum_{d=1}^D \sum_{t=1}^T P(z_t^{(d)} = i | x^{(d)}, \theta^*)} \quad (2)$$

The last thing is  $B_{ij}$ . Let  $I(x)$  denote an indicator function, which is 1 if  $x$  is true, 0 otherwise.

$$\partial \hat{L}(\theta, \theta^*) / \partial B_{ij} = \frac{\partial}{\partial B_{ij}} \left( \sum_{t \in \mathcal{T}} \sum_{d=1}^D \sum_{t=1}^T \log B_{z_t^{(d)}}(x_t^{(d)}) P(z, x; \theta^*) \right) - \lambda_{B_i} = 0$$

$$\partial \hat{L}(\theta, \theta^*) / \partial \lambda_{B_i} = - \left( \sum_{j=1}^I B_{ij} - 1 \right) = 0$$

It leads to,

$$B_{ij} = \frac{\sum_{d=1}^D \sum_{t=1}^T P(z_t^{(d)} = i | x^{(d)}, \theta^*) I(x_t^{(d)} = j)}{\sum_{d=1}^D \sum_{t=1}^T P(z_t^{(d)} = i | x^{(d)}, \theta^*)} \quad (3)$$

(1) ~ (3) give us an updated parameters of HMM.