

**A GRADUATE COURSE  
IN  
OPTIMIZATION**



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**IN**  
**OPTIMIZATION**  
**CIE6010 Notebook**

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# Acknowledgments

This book is from the CIE6010 in fall semester, 2018.

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# Notations and Conventions

$X$	Set
$\inf X \subseteq \mathbb{R}$	Infimum over the set $X$
$\mathbb{R}^{m \times n}$	set of all $m \times n$ real-valued matrices
$\mathbb{C}^{m \times n}$	set of all $m \times n$ complex-valued matrices
$x_i$	$i$ th entry of column vector $\mathbf{x}$
$a_{ij}$	$(i, j)$ th entry of matrix $\mathbf{A}$
$\mathbf{a}_i$	$i$ th column of matrix $\mathbf{A}$
$\mathbf{a}_i^T$	$i$ th row of matrix $\mathbf{A}$
$\mathbb{S}^n$	set of all $n \times n$ real symmetric matrices, i.e., $\mathbf{A} \in \mathbb{R}^{n \times n}$ and $a_{ij} = a_{ji}$ for all $i, j$
$\mathbb{H}^n$	set of all $n \times n$ complex Hermitian matrices, i.e., $\mathbf{A} \in \mathbb{C}^{n \times n}$ and $\bar{a}_{ij} = a_{ji}$ for all $i, j$
$\mathbf{A}^T$	transpose of $\mathbf{A}$ , i.e, $\mathbf{B} = \mathbf{A}^T$ means $b_{ji} = a_{ij}$ for all $i, j$
$\mathbf{A}^H$	Hermitian transpose of $\mathbf{A}$ , i.e, $\mathbf{B} = \mathbf{A}^H$ means $b_{ji} = \bar{a}_{ij}$ for all $i, j$
$\text{trace}(\mathbf{A})$	sum of diagonal entries of square matrix $\mathbf{A}$
$\mathbf{1}$	A vector with all 1 entries
$\mathbf{0}$	either a vector of all zeros, or a matrix of all zeros
$\mathbf{e}_i$	a unit vector with the nonzero element at the $i$ th entry
$\mathcal{C}(\mathbf{A})$	the column space of $\mathbf{A}$
$\mathcal{R}(\mathbf{A})$	the row space of $\mathbf{A}$
$\mathcal{N}(\mathbf{A})$	the null space of $\mathbf{A}$
$\text{Proj}_{\mathcal{M}}(\mathbf{A})$	the projection of $\mathbf{A}$ onto the set $\mathcal{M}$



# Chapter 1

## Week1

### 1.1. Monday

#### 1.1.1. Introduction to Optimizaiton

The usual optimization formulation is given by:

$$\begin{aligned} \min f(\mathbf{x}), \quad & \text{where } f : \mathbb{R}^n \mapsto \mathbb{R} \\ \text{such that } \quad & \mathbf{x} \in X \subseteq \mathbb{R}^n \end{aligned}$$

One example of the set  $X$  is given by:

$$X = \left\{ \mathbf{x} \in \mathbb{R}^n \left| \begin{array}{l} C_i(\mathbf{x}) = \mathbf{0}, i = 1, 2, \dots, m \leq n \\ h_i(\mathbf{x}) \geq \mathbf{0}, i = 1, 2, \dots, p \end{array} \right. \right\}$$

Linear programming can be easily solved, but Integer linear programming is much harder. The equivalent LP formulation is given by:

$$\begin{aligned} \min \quad & \mathbf{c}^T \mathbf{x} \\ \text{s.t.} \quad & \mathbf{Ax} = \mathbf{b} \\ & \mathbf{c} \leq \mathbf{Bx} \leq \mathbf{c}' \end{aligned}$$

