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# Neural Network and Deep Learning Workshop

## Spring 2020

# Neural Networks

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Can you recognize these digits?

504192

# Neural Networks

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Can you recognize these digits?

504192



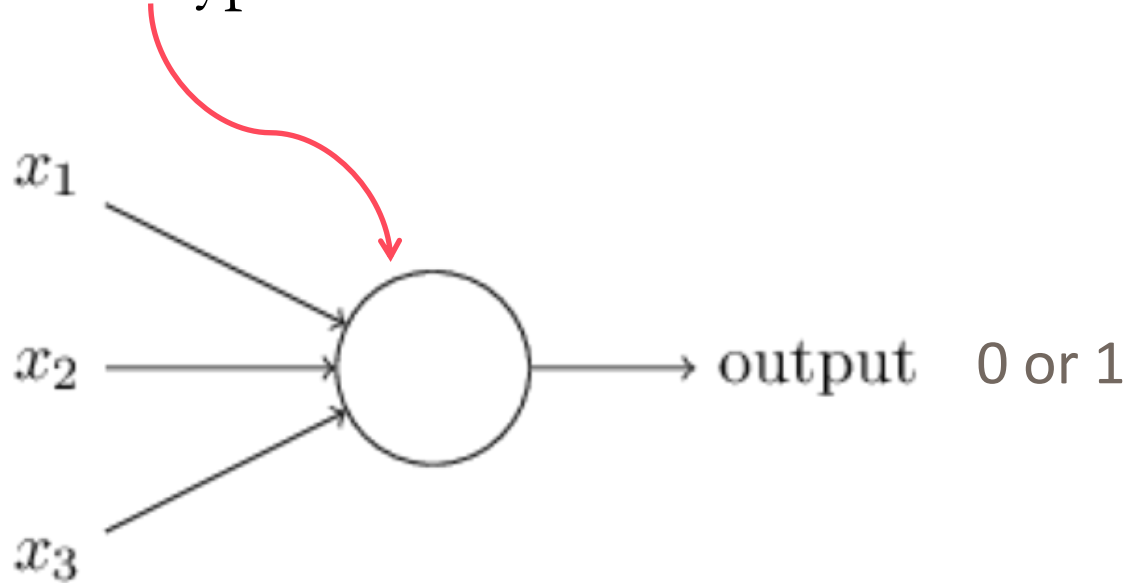
Training Examples

Neural Networks: Develops a system to learn from these training examples: to automatically infer rules for recognizing these digits

# What is a Neural Network?

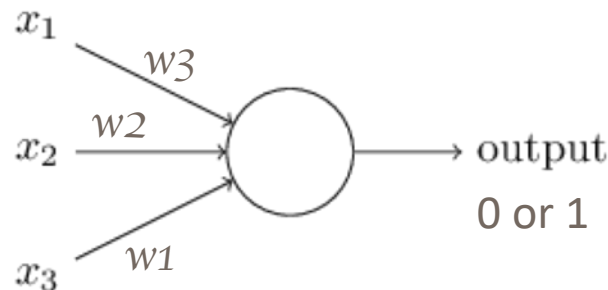
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- Perceptron: Type of artificial neuron



# What is a Neural Network?

- To compute output of a perceptron:



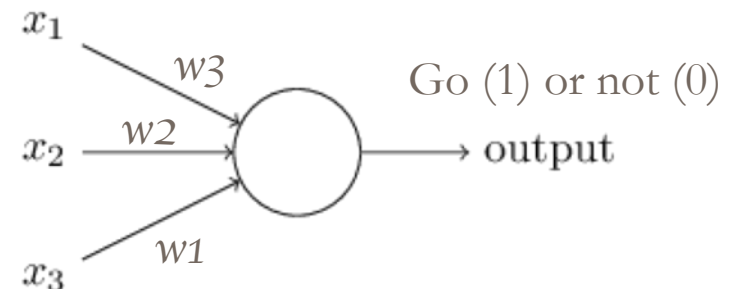
$w_1$ ,  $w_2$  and  $w_3$  are weights (real numbers) that express importance of the respective inputs to the output

$$\text{output} = \begin{cases} 0 & \text{if } \sum_j w_j x_j \leq \text{threshold} \\ 1 & \text{if } \sum_j w_j x_j > \text{threshold} \end{cases}$$

# Neural Network: Example

You would like to go to the Durham beer festival

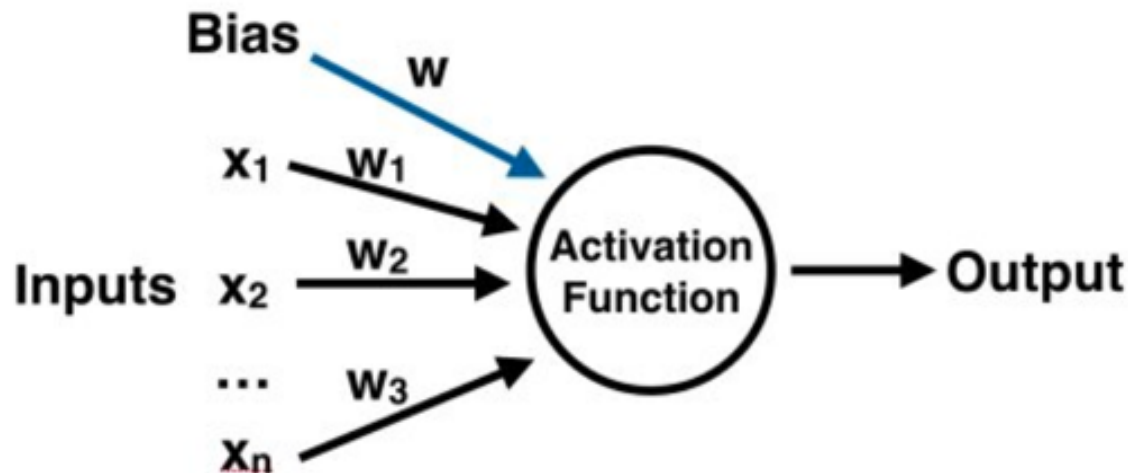
- You like beer and you want to decide whether or not to go to the festival. You might make your decision by weighting three factors:
  - Weather is good? ( $x_1=1$  if weather is good, otherwise=0)
  - Friend will go with you? ( $x_2= 1$  if your friend wants to go with you)
  - Festival near public transit? (you don't own a car) ( $x_3=1$  if festival near public transit)



Use weights  $w_1$ ,  $w_2$ ,  $w_3$  to indicate your preference for each of the inputs. If  $w_1$  = larger then weather matter a lot to you much more than others. Choose a threshold for perceptron (e.g., 4 or 5) and then implement the desired decision model.

# Neural Network: Perceptron

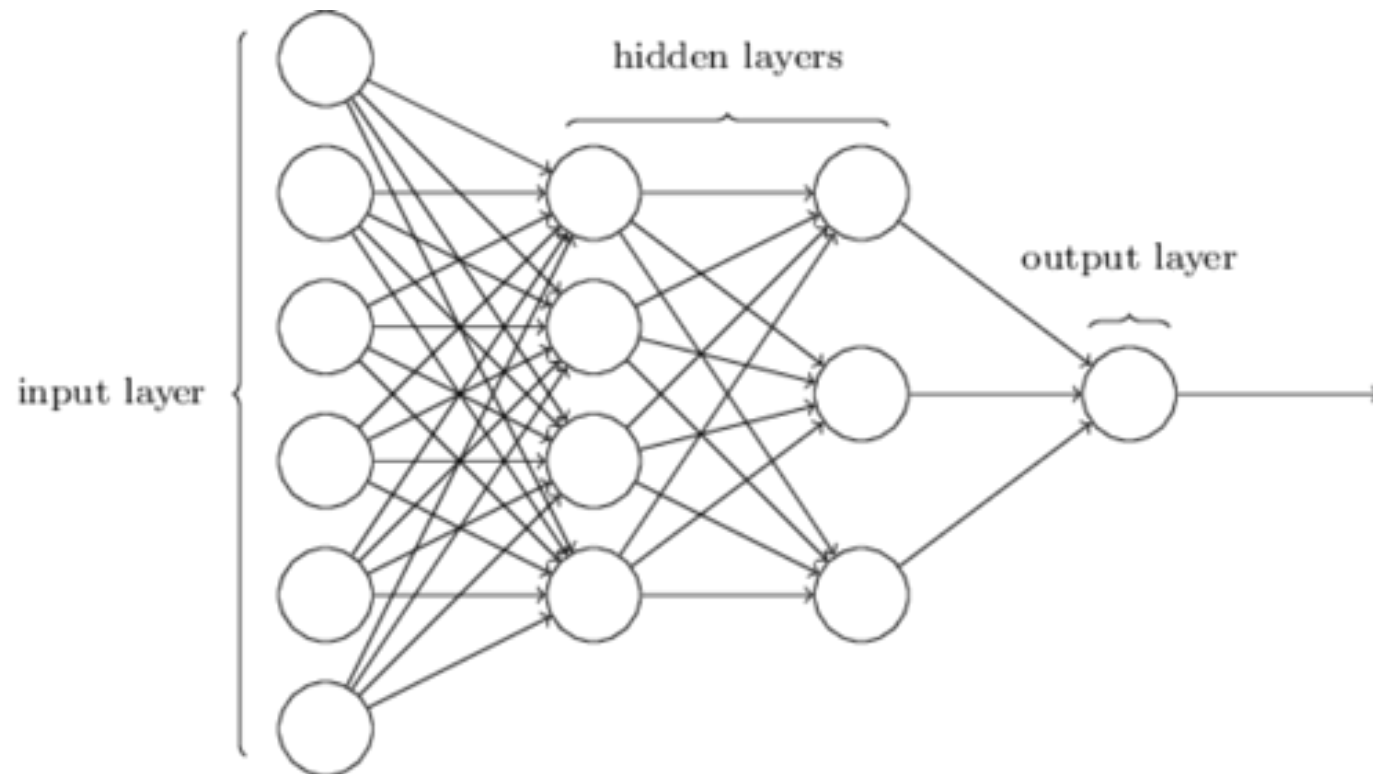
- A perceptron has one or more inputs, a bias, an activation function, and a single output
- The perceptron receives inputs, multiplies them by some weight, and then passes them into an activation function to produce an output



- Once we have the output from this model, it is compared to a known label and weights are adjusted accordingly
- Process is repeated multiple times (until an acceptable error rate)

# Neural Networks

Neural Networks: Layers of perceptrons added together



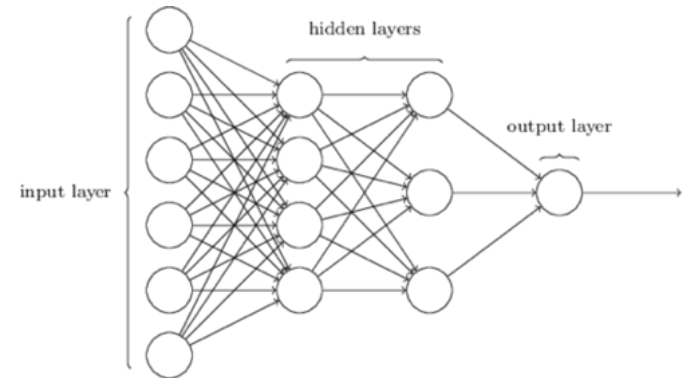


# Neural Networks

$$\text{output} = \begin{cases} 0 & \text{if } \sum_j w_j x_j \leq \text{threshold} \\ 1 & \text{if } \sum_j w_j x_j > \text{threshold} \end{cases}$$



$$\text{output} = \begin{cases} 0 & \text{if } \sum_j w_j x_j + b \leq 0 \\ 1 & \text{if } \sum_j w_j x_j + b > 0 \end{cases}$$

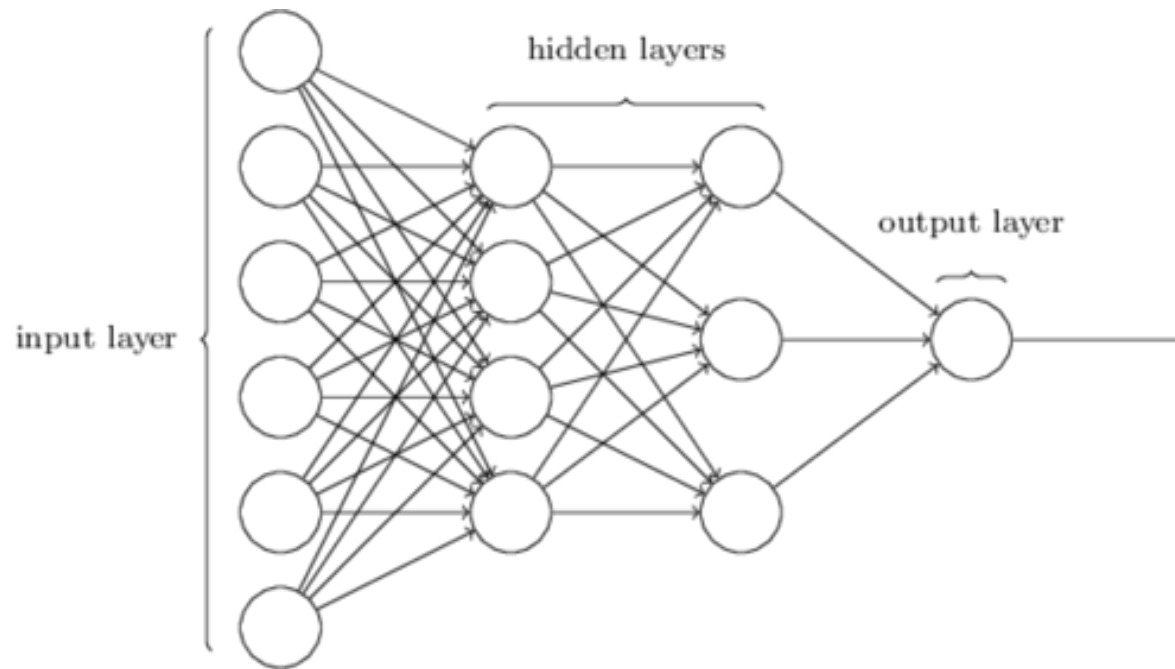


$$b \equiv -\text{threshold}$$

Bias is a measure of how easy it is to get the perceptron to *fire or get an output of 1*. For a perceptron with a really big bias, it's extremely easy for the perceptron to output a 1. But if the bias is very negative, then it's difficult for the perceptron to output a 1.

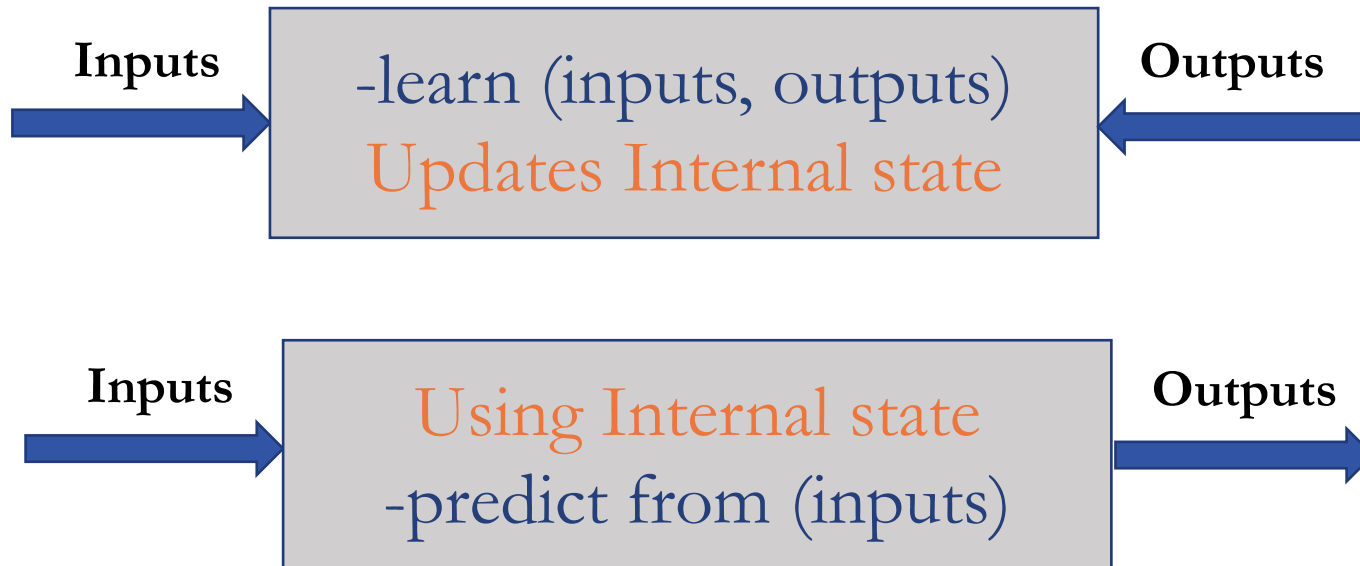
# Neural Networks

Neural networks, if sufficiently wide and deep can approximate any function



A hidden layer that is fully connected to the preceding layer is designated dense.

# Supervised Neural Network



# Simple Example: Neural Network

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Input	Desired Output
0	0
1	2
2	4
3	6
4	8

$$y = W * x$$

*W is called the **weights** of the network*

Model form = Linear (layers)

# Simple Example: Neural Network

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Input	Desired Output
0	0
1	2
2	4
3	6
4	8

1. Model Initialization:  
random

Random Initialization  $y = 3 * x$   
(3 is generated at random initially)

$$y = W * x$$

$W$  is called the **weights** of the network

# Simple Example: Neural Network

Random Initialization  $y = 3 * x$

Input	Actual Output of Model
0	0
1	3
2	6
3	9
4	12

$$y = W * x$$

$W$  is called the **weights** of the network

2. Forward Propagate: Start from input, pass them through network layer and calculate the actual output (prediction)

Forward Propagation  
Input > Network > Output

# Simple Example: Neural Network

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Input	Actual Output of Model	Desired Output
0	0	0
1	3	2
2	6	4
3	9	6
4	12	8

3. Loss Function:  
Performance metric on how the NN manages to reach its goal of generating outputs close to desired values

Loss = Desired output – Actual output (predicted)

# Simple Example: Neural Network

Input	Actual Output of Model	Desired Output	Absolute Error
0	0	0	0
1	3	2	1
2	6	4	2
3	9	6	3
4	12	8	4
Total:	..	..	10

Loss = Absolute value (Desired output – Actual output)

Loss = How much precision do we lose (minimize this)



# Simple Example: Neural Network

Input	Actual Output of Model	Desired Output	Absolute Error	Squared Error
0	0	0	0	0
1	3	2	1	1
2	6	4	2	4
3	9	6	3	9
4	12	8	4	16
Total:	..	..	10	30

Loss = Sum of squares of absolute errors

Loss = How much precision do we lose when the real output is replaced by the actual predicted?

# Loss Function in Neural Networks

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- Goal is minimizing the loss function (to reach as close as possible to 0) when we take the total of the sum of squared errors



We can transform this to an optimization process that aims to minimize the loss function

# Simple Example: Neural Network

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4. Optimization: We can use any optimization technique that modifies the internal weights of neural networks to minimize loss function

$$y = W * x$$

One Method: Take values of  $W$  from -100 to +100 at a step of 0.001 and run model to get which  $W$  has the smallest sum of squared errors over the dataset

What if the model has large number of parameters? How about precision?

# Simple Example: Neural Network

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4. Optimization: We can use any optimization technique that modifies the internal weights of neural networks to minimize loss function

Differentiation: Derivative of the loss function (gives the rate at which this function changes its values at a point)

Effect of Derivative: How much the total error will change if we change the internal weight of the neural network with a certain small value ( $\delta W$ ).

# Simple Example: Neural Network

Input	Desired Output	W=3 Actual	sq error(3)	W=3.0001 Actual	sq error (3.001)
0	0	0	0	0	0
1	2	3	1	3.0001	1.0002
2	4	6	4	6.0002	4.0008
3	6	9	9	9.0003	9.0018
4	8	12	16	12.0004	16.0032
Total:	..	..	30	..	30.006

$$\delta W = 0.0001$$

Error is increased by 0.006

We really care about the rate of change of error relative to change in weight

# Simple Example: Neural Network

Input	Desired Output	W=3 Actual	sq error(3)	W=3.0001 Actual	sq error (3.001)
0	0	0	0	0	0
1	2	3	1	3.0001	1.0002
2	4	6	4	6.0002	4.0008
3	6	9	9	9.0003	9.0018
4	8	12	16	12.0004	16.0032
Total:	..	..	30	..	30.006

$$\delta W = 0.0001$$

Derivative = rate of change in total error due change in weight  
 =  $0.006 / 0.0001 = 60$  times increase with increase in W by 0.0001

# Loss Function: Derivative

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Derivative: rate of change of error due to change in weight

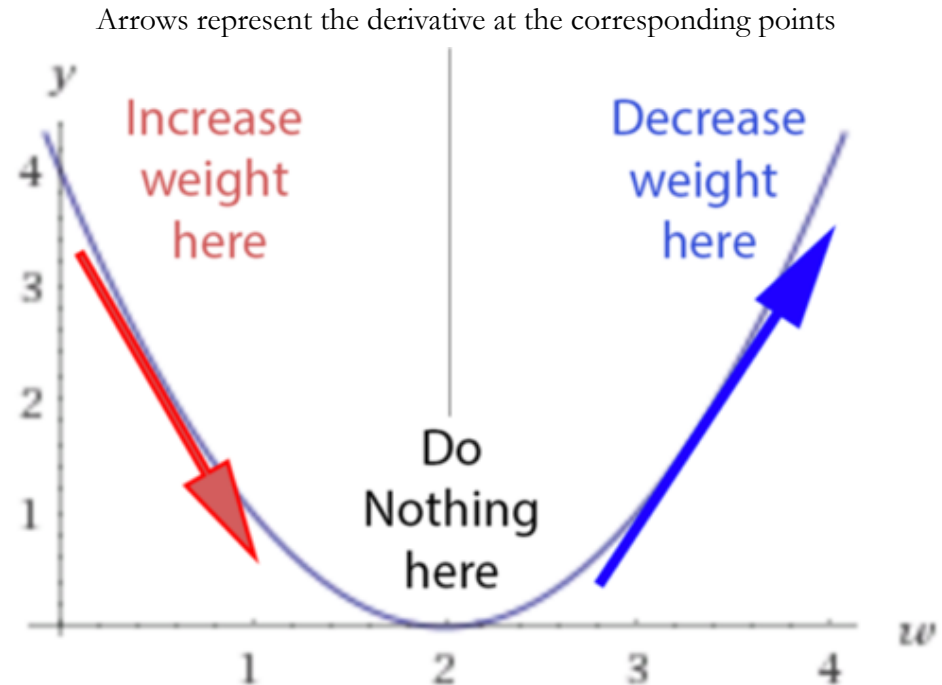
Loss function:

- If  $w=2$ , we have a loss of 0 (loss =0, derivative =0)= perfect model
- If  $w>2$  (positive loss function), derivative = +ve, increase in weight will increase loss even more
- If  $w<2$  (positive loss function), derivative = -ve, increase in weight will decrease the loss function

# Loss Function

## Let's check the derivative

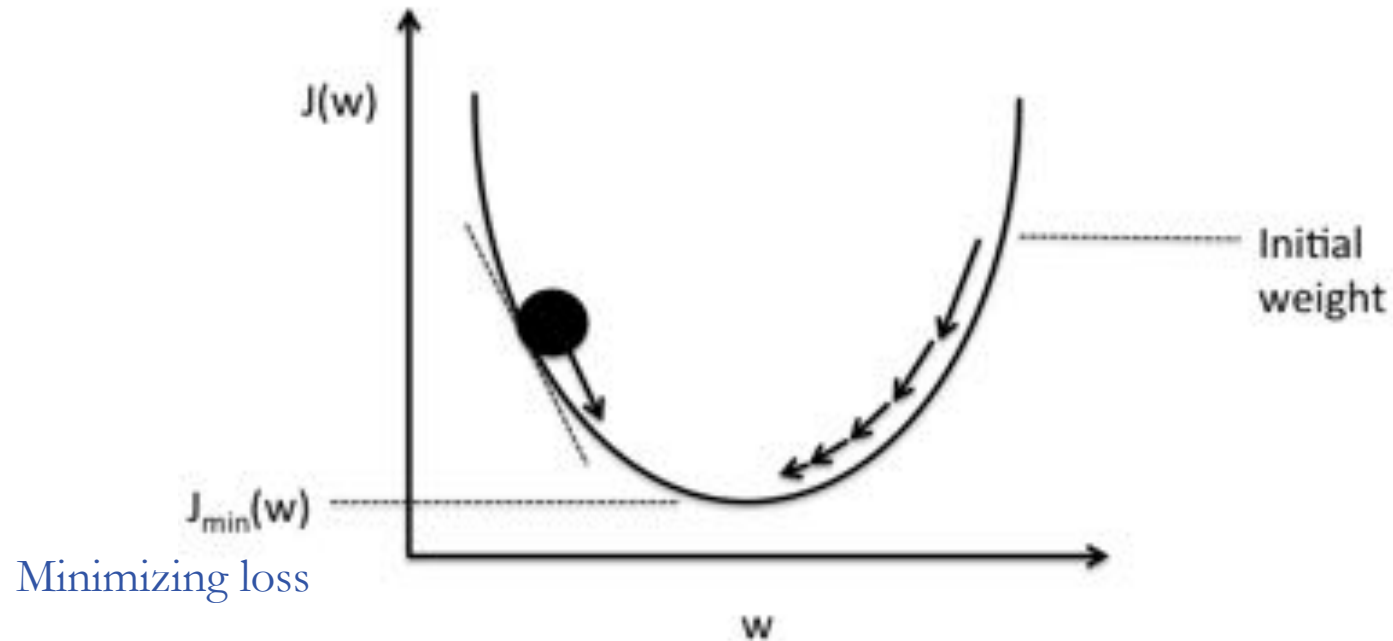
- If it is positive, meaning the error increases if we increase the weights  $>$  then we should decrease the weight ( $w$ )



- If it's negative, meaning the error decreases if we increase the weights, then we should increase the weight ( $w$ )
- If it's 0, we do nothing, we reach our stable point

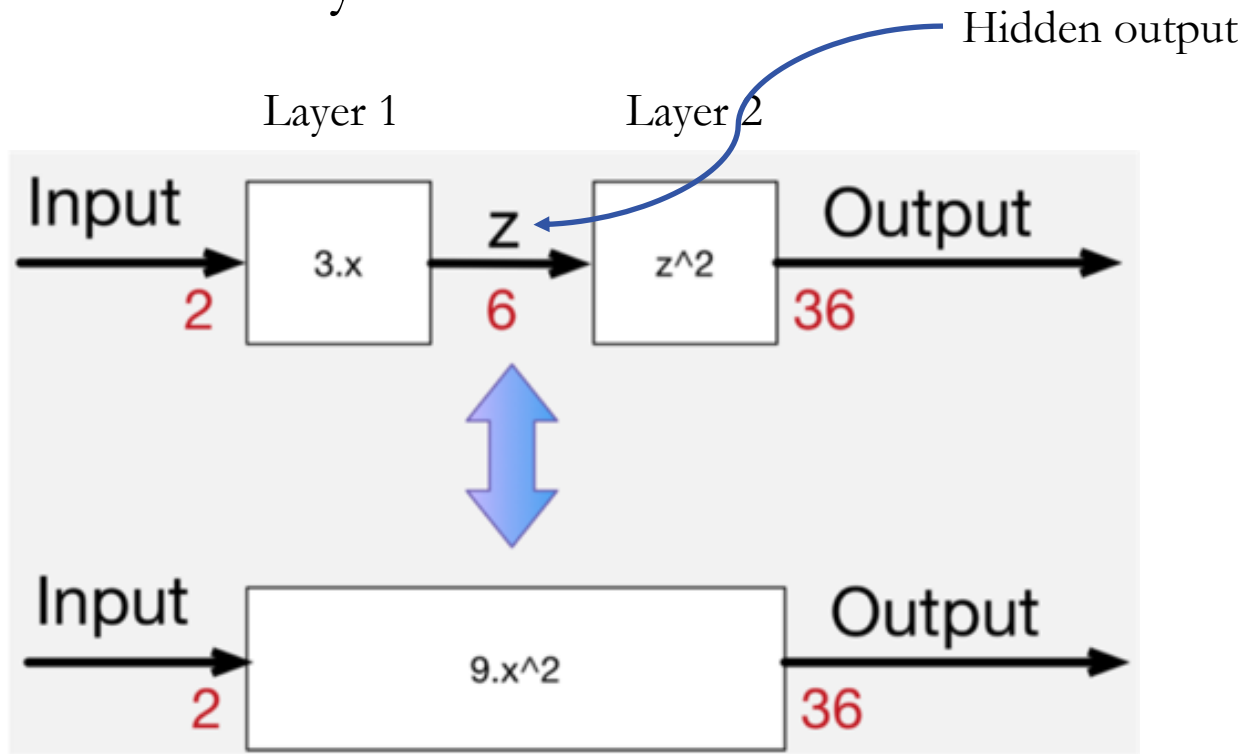


# Gradient Descent



# Back Propagation

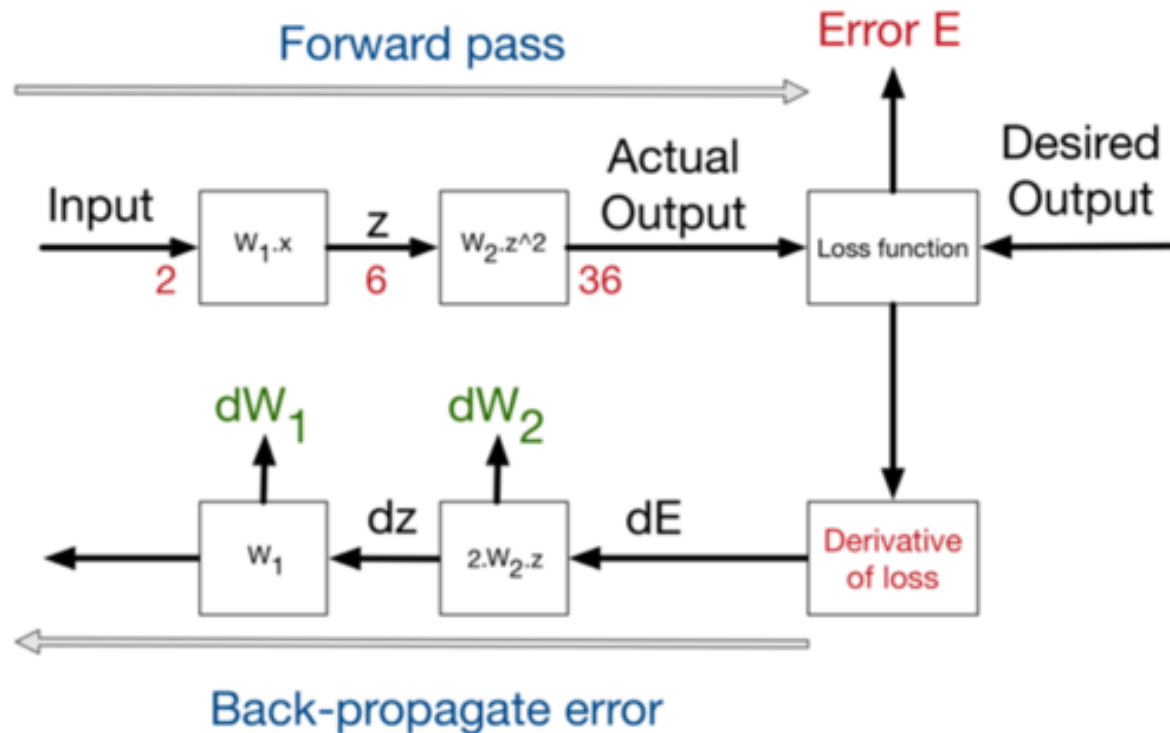
5. More layers = Reaches more variations in the functionality of the network



Composed functions are difficult =  
Derivatives have to be calculated for every composition (**not scalable and error prone**)

# Back Propagation

Input > Forward calls > Loss function > Derivative > Backpropagation



# Weight Update

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6. Weight update: The derivative is the rate of which the error changes relative to the weight changes

$$\text{New weight} = \text{old weight} - \text{Derivative Rate} * \text{Learning Rate}$$

Learning rate: constant (usually very small) in order to force the weight to get updated very smoothly and slowly

# Weight Update

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New weight = old weight – Derivative Rate \* Learning Rate

Learning rate: constant (usually very small) in order to force the weight to get updated very smoothly and slowly

Derivative rate = + ve (an increase in weight will increase the error) > new weight = smaller

Derivative rate = – ve (an increase in weight will decrease the error) > new weight = larger

Derivative = 0 (we are in a stable minimum) > No update on weights

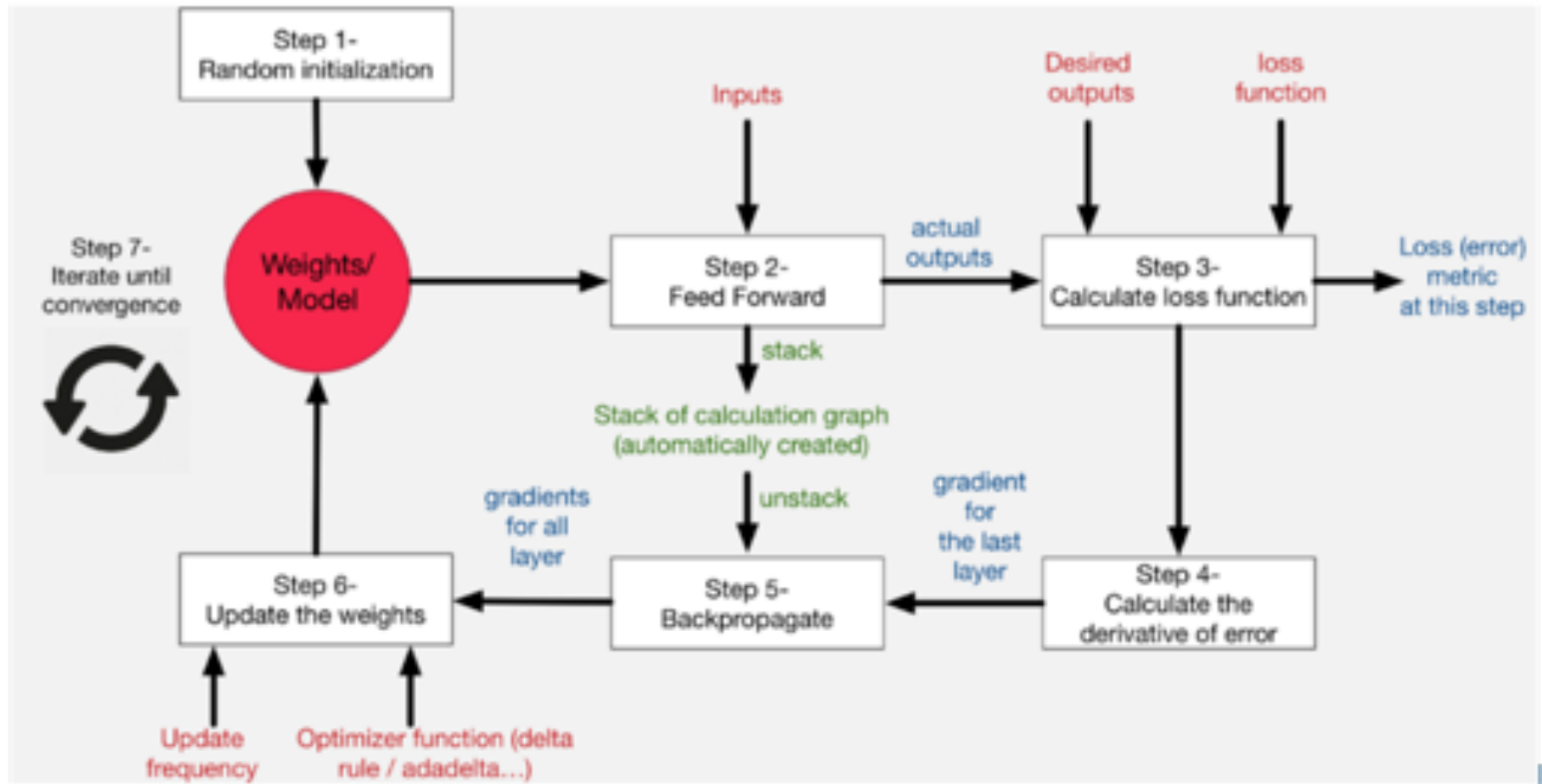
# Iterate until Convergence

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7. Iteration until convergence: Since weights are updated with small delta at a time, it takes several iterations in order to learn

- How many iterations are needed to converge (depends on)
  - How strong is the learning rate? High learning rate = faster learning, but with higher chance of instability
  - Meta-parameters of the network (how many layers, how complex the non-linear functions are). The more variables = the more it takes time to converge (but higher precision)
  - Optimization methods used: some weight update rules are proven to be faster than others
  - Random initialization of network
  - Quality of the training set. If input and output has no correlation, the NN will not learn a random correlation

# Learning Process on Neural Networks





Thanks  
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