

Weiestrass Theorem: S is compact $\implies f$ has a global max and a global min in S .

If f is convex, then $\{\mathbf{x}: f(\mathbf{x}) \leq a\}$ is convex.

Epigraph E_f is convex $\iff f$ is convex.

Directional derivative at \mathbf{x} along \mathbf{d} :

$$\nabla f(\mathbf{x})^T \mathbf{d} = \lim_{\lambda \rightarrow 0} \frac{f(\mathbf{x} + \lambda \mathbf{d}) - f(\mathbf{x})}{\lambda}.$$

f is convex if and only if $f(\mathbf{x}) + \nabla f(\mathbf{x})^T(\mathbf{y} - \mathbf{x}) \leq f(\mathbf{y})$.

f is a convex and continuously differentiable function, then \mathbf{x}^* is a global minimiser $\iff \nabla f(\mathbf{x}^*)^T(\mathbf{x} - \mathbf{x}^*) \geq 0$.

Eigenvalue Test: If \mathbf{A} is a **symmetric real** matrix, then \mathbf{A} is positive semidefinite \iff all eigenvalues of \mathbf{A} are non-negative.

If \mathbf{A} is a **symmetric** matrix, then \mathbf{A} is positive definite $\iff \Delta_k < 0$ and negative definite $\iff (-1)^k \Delta_k > 0$.

Taylor's Theorem: If f has continuous 2nd order partial derivatives and if the set

$$[\mathbf{x}, \mathbf{y}] := \{\lambda \mathbf{x} + (1 - \lambda) \mathbf{y}: \lambda \in [0, 1]\}$$

is in the interior of D_f , then $\exists \mathbf{z} \in [\mathbf{x}, \mathbf{y}]$ s.t.

$$f(\mathbf{y}) = f(\mathbf{x}) + \nabla f(\mathbf{x})^T(\mathbf{y} - \mathbf{x}) + \frac{1}{2}(\mathbf{y} - \mathbf{x})^T H_f(\mathbf{z})(\mathbf{y} - \mathbf{x}).$$

H_f is semidefinite $\iff f$ is convex/concave;
 H_f is definite $\implies f$ is strictly convex/concave;
 H_f is indefinite $\implies f$ is neither convex nor concave.

Coercive Function: $\lim_{\|\mathbf{x}\| \rightarrow \infty} f(\mathbf{x}) = \infty$.

$$\|\mathbf{x}\|_\infty \leq \|\mathbf{x}\| \leq \sqrt{2} \|\mathbf{x}\|_\infty, \text{ where } \|\mathbf{x}\|_\infty = \max\{|x_i|\}.$$

$\nabla f(\mathbf{x}^*) = 0$ and $H_f(\mathbf{x}^*)$ is positive definite $\implies \mathbf{x}^*$ is a **strict** local minimiser.

If f is convex, then a local minimiser of f is a global minimiser. If f is strictly convex, then it has a unique global minimiser.

If f is convex, then any stationary point of f is a global minimiser.

$q(\mathbf{x}) = \frac{1}{2} \mathbf{x}^T \mathbf{Q} \mathbf{x} + \mathbf{c}^T \mathbf{x}$ is a quadratic function where \mathbf{Q} is symmetric.

If q is defined over a convex set, then \mathbf{x}^* is a

global minimiser $\iff \mathbf{Q} \mathbf{x}^* = -\mathbf{c}$.

Bisection Method:

$$[a_{k+1}, b_{k+1}] = \begin{cases} [a_k, \frac{a_k+b_k}{2}], & \text{if } f(\frac{a_k+b_k}{2}) f(a_k) < 0 \\ [\frac{a_k+b_k}{2}, b_k], & \text{if } f(\frac{a_k+b_k}{2}) f(a_k) > 0 \end{cases}$$

Take $x_k = \frac{a_k+b_k}{2}$. At termination, $|x^* - x_k| \leq \frac{|a_k-b_k|}{2} \leq \epsilon$, so we need

$$k = \left\lceil \frac{\log \left(\frac{b_1-a_1}{\epsilon} \right)}{\log 2} \right\rceil$$

Newton's Method: $x_{k+1} = x_k - \frac{f'(x_k)}{f''(x_k)}$ until $|f'(x_k)| < \epsilon$.

Golden Section Method:

Set $[a_0, b_0] = [a, b]$ and take $\alpha = \frac{\sqrt{5}-1}{2}$. Compute

$$\lambda_0 = b - \alpha(b - a) \\ \mu_0 = a + \alpha(b - a).$$

If $f(\lambda_k) > f(\mu_k)$, then

$$\begin{aligned} a_{k+1} &= \lambda_k & b_{k+1} &= b_k \\ \lambda_{k+1} &= \mu_k & \mu_{k+1} &= \lambda_k + \alpha(b_k - \lambda_k). \end{aligned}$$