

### A Random Walk Through Time Series Techniques



## Overview

### **OVERVIEW**



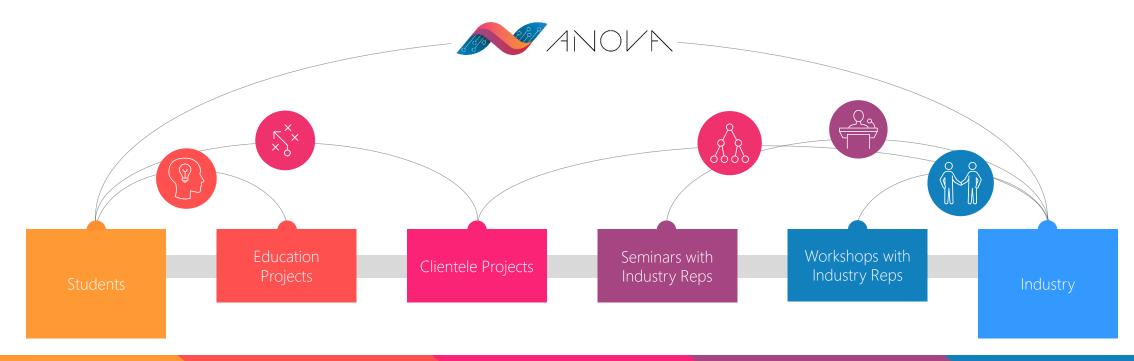
#### WHO WE ARE:

ANOVA is a society that aims to bridge the disconnect between academia and the technical industry through fostering a community of technically adept students via projects, workshops and talks



#### STORY TO DATE:

- Founded in December 2017
- Member base of over 300 students
- Worked with over 8 industry clients
- Ran industry seminars with BCG Digital Ventures, IBM, Accenture, Quantium, Minerva Collective
- 4 educational projects to upskills students in programming and data science



### Outline



Intellify is a data science consultancy that works in the price optimization space

To optimize your price, you need to first be able to forecast your price

Our task was to forecast the demand component for Fast Moving Consumer Goods (FMCG)

Dataset contains 60 products in stores across America





# Setting Up

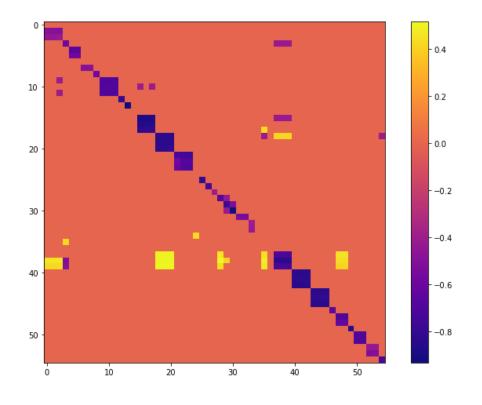
### Initial Look into the Data



We built a correlation matrix of the products to see the correlation between quantities bought of each product on a week by week basis

Big issue is that a lot of the data was missing at sporadic moments

We focused our attention to a subset of products, specifically the pizza category of products, as they were the most correlated and one of the few products with complete data



### MAPE



Important to be smart about the metric you use to evaluate your models

Since products were in different units, the forecast errors for one product can be larger than forecast errors for another product just because they are in different units

Hence, we use the MAPE as our metric for model evaluation

MAPE: Mean Absolute Percentage Error

- Scale Invariant
- Heavier penalties on negative errors (Actual <
   Forecast) underforecasts to overforecasts (an upper limit of 100% for underforecasts but no limit for overforecasts</li>

$$\mathrm{M} = rac{100\%}{n} \sum_{t=1}^n \left| rac{A_t - F_t}{A_t} 
ight|,$$

where  $A_t$  is the actual value and  $F_t$  is the forecast value.

### Wold Decomposition



#### Stationarity of data

- Imposes a structure on the time series
- Certain statistical properties (constant mean, variance or the unconditional joint probability distribution does not change over time.

#### Wold Decomposition Theorem

- Powerful theorem stating that any stationary time series can be expressed as

$$Y_t = \sum_{j=0}^\infty b_j arepsilon_{t-j} + \eta_t,$$

 $Y_t$  is the time series being considered,

 $arepsilon_t$  is an uncorrelated sequence which is the innovation process to the process  $Y_t$  – that is, a white noise process that is input to the linear filter  $\{b_j\}$ .

b is the  $\emph{possibly}$  infinite vector of moving average weights (coefficients or parameters)

 $\eta_t$  is a deterministic time series, such as one represented by a sine wave.

- This means that any stationary time series has a linear representation, so that a lot of the models we will apply have theoretical justifications!

## Dickey Fuller Test



We can use the Dickey Fuller Test to test for stationarity of data

- Note: A small caveat as it is not the only way to test whether is a dataset nonstationary

Simple Example

$$y_t = \rho y_{t-1} + u_t$$

Subtract the lag of y from both sides

$$\Delta y_t = \delta y_{t-1} + u_t$$

Regress and test if the coefficient is 0 with the null hypothesis being the data is **not stationary** 

## Dickey Fuller Test



```
In [12]: from statsmodels.tsa.stattools import adfuller
    products = ["Prod_one", "Prod_two", "Prod_three"]
    """
    Run ADF test on each product and check test.
    """
    for prod in products:
        print("P-value for {} is {:.5f}".format(prod, adfuller((final_trans[prod]))[1]))

P-value for Prod_one is 0.00000
P-value for Prod_two is 0.00000
P-value for Prod_three is 0.00000
We have stationarity!
```

With this, we operate under the assumption of stationarity and move on to apply time series models



## Models

### AR and MA Models



#### Autoregressive Model

#### How it works:

☐ Today's value is a linear combination of previous values

$$y_t = c + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \dots + \phi_p y_{t-p} + \varepsilon_t,$$

#### Notes:

 We can further extend this framework to more models

#### Autoregressive Moving Average Model

#### How it works:

 Today's value is a linear combination of past forecast errors which are assumed to be normally distributed

$$y_t' = c + \phi_1 y_{t-1}' + \dots + \phi_p y_{t-p}' + \theta_1 arepsilon_{t-1} + \dots + \theta_q arepsilon_{t-q} + arepsilon_t,$$

#### Notes:

 We can have further modifications such as ARIMA

#### Moving Average Model

#### How it works:

 Today's value is a linear combination of past forecast errors which are assumed to be normally distributed

$$y_t = c + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2} + \dots + \theta_q \varepsilon_{t-q},$$

#### Notes:

 Do not confuse with moving average smoothing

## Choosing optimal lags



To prevent overfitting, we need to be careful about the parameters of our model

- We need to be careful of bias-variance tradeoff in our model
- Common strategy is to compute the **Akaike Information Criterion** (AIC)
- AIC = Likelihood of model + Penalty for number of parameters of model

A common model selection technique is to compute the AIC for different lags of the model and select the minimum model with minimum AIC

### Code Example of Model



```
▶ In [26]: def aic_selection(data, p_lag, q_lag):
               Forward selection based on the AIC.
               Parameters
               -----
               data: series
                   The data to test for.
               p lag: int scalar
                   Maximum number of lags to test for AR.
               g lag: int scalar
                   Maximum number of lags to test for MA.
               Returns
               results: tuple
                   Tuple containing optimal p,q, and AIC score.
               best score = np.inf
               opt p, opt q = 0, 0
               range_p, range_q= range(p_lag), range(q_lag)
               # Iterate through and fit different lags.
               for p in opt p:
                   for q in opt q:
                           model=sm.tsa.statespace.SARIMAX(y, order=(i, 0, k)).fit()
                           score=model.aic
                           if (score best score):
                               best_score = model.aic
                               opt_p, opt_q = p, q
                       except ValueError:
                           pass
               return (opt p, opt q, best score)
```

```
Select best ARMA model based on AIC, MAPE for each product
products = ["Prod_one", "Prod_two", "Prod_three"]
results = {}

for prod in products:
    y = data_time(train_data,prod)
    opt_p, opt_q, best_score = aic_selection(y, 3, 3)
    results.update({prod: [opt_p, opt_q, best_score.round(2)]})
```

	Product	Optimal P	Optimal Q	AIC
0	Prod_one	1	0	1912.13
1	Prod_two	1	0	1840.05
2	Prod_three	1	2	1856.30

## Vector Autoregressive Models



Vector Autoregressive Models (VAR) can capture linear interdependencies between time series

- This can be quite useful for when we think one product's demand can help forecast another product's demand
- This is common when the products are **substitutes** or **complements** to each other
- 1) First we define a structural VAR

$$y_t = \gamma_{10} - \beta_{12} z_t + \gamma_{11} y_{t-1} + \gamma_{12} z_{t-1} + \epsilon_{yt}$$

$$z_t = \gamma_{20} - \beta_{21} y_t + \gamma_{21} y_{t-1} + \gamma_{22} z_{t-1} + \epsilon_{zt}$$

## Vector Autoregressive Models



1) First we define a **structural VAR**. We have an **identification issue** or **simultaneous equation bias** (y causes z and z causes y)

$$y_t = \gamma_{10} - \beta_{12}z_t + \gamma_{11}y_{t-1} + \gamma_{12}z_{t-1} + \epsilon_{yt}$$
$$z_t = \gamma_{20} - \beta_{21}y_t + \gamma_{21}y_{t-1} + \gamma_{22}z_{t-1} + \epsilon_{zt}$$

2) We re-express it like so

$$\underbrace{\begin{bmatrix} \beta_{11} & \beta_{12} \\ \beta_{21} & \beta_{22} \end{bmatrix}}_{B} \underbrace{\begin{bmatrix} y_t \\ z_t \end{bmatrix}}_{x_t} = \underbrace{\begin{bmatrix} \gamma_{10} \\ \gamma_{20} \end{bmatrix}}_{\Gamma_0} + \underbrace{\begin{bmatrix} \gamma_{11} & \gamma_{12} \\ \gamma_{21} & \gamma_{22} \end{bmatrix}}_{\Gamma_1} \underbrace{\begin{bmatrix} y_{t-1} \\ z_{t-1} \end{bmatrix}}_{x_{t-1}} + \underbrace{\begin{bmatrix} \varepsilon_{yt} \\ \varepsilon_{zt} \end{bmatrix}}_{\varepsilon_t}$$

$$Bx_t = \gamma_0 + \gamma_1 x_{t-1} + \epsilon_t$$

- 3) We now have a **reduced form VAR** after taking the inverse of B matrix.  $x_t = A_0 + A_1 x_{t-1} + e_t$
- 4) We can estimate as usual via OLS

$$y_t = \alpha_{10} + \alpha_{11}y_{t-1} + \alpha_{12}z_{t-1} + e_{yt}$$

$$z_t = \alpha_{20} + \alpha_{21}y_{t-1} + \alpha_{22}z_{t-1} + e_{zt}$$

## Vector Autoregressive Models



VAR(1) Model for 3 variables

: model.summary()

Method:	OLS	-		
Date:	Tue, 11, Dec, 2018	3		
Time:	04:46:5	7		
No. of Equations	: 3.00000 155.000	BIC:	31.0664 30.9265	
Nobs:	155.000 -3037.19	HQIC:	30.9265 2.45272e+13	
Log likelihood:	-3037.19	FPE:	2.45272e+13	
AIC:	30.8308	Det(Omega_mle):	2.27223e+13	
Results for equa				
		std. error	t-stat	prob
const	288.619685	77.322744	3.733	0.000
Ll.Prod_one	0.227743 -0.313328	0.306026	0.744	
Ll.Prod_two	-0.313328	0.436219	-0.718	0.473
Ll.Prod_three		0.257581	3.721	0.000
	coefficient	std. error	t-stat	prob
const	252.519949			
		57.670685	4.379	
L1.Prod one	-0.001106	0 228247	-0.005	0.996
L1.Prod_one L1.Prod_two	-0.001106 -0.048135	0.228247 0.325351	-0.005 -0.148	0.882
L1.Prod_one L1.Prod_two L1.Prod_three	-0.001106 -0.048135 0.751965		-0.005 -0.148 3.914	0.996 0.882 0.000
L1.Prod_one L1.Prod_two L1.Prod_three	-0.001106 -0.048135 0.751965	0.228247 0.325351 0.192115	-0.005 -0.148 3.914	0.996 0.882 0.000
L1.Prod_one L1.Prod_two L1.Prod_three	-0.001106 -0.048135 0.751965	0.228247 0.325351 0.192115	-0.005 -0.148 3.914	0.996 0.882 0.000
L1.Prod_one L1.Prod_two L1.Prod_three	-0.001106 -0.048135 0.751965 	0.228247 0.325351 0.192115	-0.005 -0.148 3.914 	0.996 0.882 0.000
L1.Prod_one L1.Prod_two L1.Prod_three	-0.001106 -0.048135 0.751965 	0.228247 0.325351 0.192115	-0.005 -0.148 3.914 	0.996 0.882 0.000
L1.Prod_one L1.Prod_two L1.Prod_three  Results for equa  const L1.Prod_one	-0.001106 -0.048135 0.751965 	0.228247 0.325351 0.192115 std. error 63.591147 0.251679	-0.005 -0.148 3.914 	0.996 0.882 0.000 prob
L1.Prod_one L1.Prod_two L1.Prod_three	-0.001106 -0.048135 0.751965 	0.228247 0.325351 0.192115 std. error 63.591147 0.251679 0.358751	-0.005 -0.148 3.914 	0.996 0.882 0.000 
L1.Prod_one L1.Prod_two L1.Prod_three  Results for equa	-0.001106 -0.048135 0.751965 	0.228247 0.325351 0.192115 std. error 63.591147 0.251679	-0.005 -0.148 3.914 	0.996 0.882 0.000 prob 0.000 0.838 0.814 0.000
L1.Prod_one L1.Prod_two L1.Prod_three  Results for equa	-0.001106 -0.048135 0.751965 	0.228247 0.325351 0.192115 	-0.005 -0.148 3.914 	0.996 0.882 0.000 prob 0.000 0.838 0.814
L1.Prod_one L1.Prod_two L1.Prod_three  Results for equa	-0.001106 -0.048135 0.751965	0.228247 0.325351 0.192115 std. error 63.591147 0.251679 0.358751 0.211837	-0.005 -0.148 3.914 	0.996 0.882 0.000 prob 0.000 0.838 0.814
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L1.Prod_one L1.Prod_two L1.Prod_three	-0.001106 -0.048135 0.751965	0.228247 0.325351 0.192115 std. error 63.591147 0.251679 0.358751 0.211837 Prod_three 0.914308 0.922331	-0.005 -0.148 3.914 	0.996 0.882 0.000 prob 0.000 0.838 0.814 0.000



## Extensions

### 2 Tricks to Improve Forecasts



#### STATE CLUSTERING:

- We noticed that the behaviour of the demand for products had locality effects
- We segmented the dataset so that we only forecasted demand for products for each state

#### MODEL COMBINATION:

- Combine forecasts from multiple models
- Weaknesses of one model can be offset by strengths of another model

RESULTS:

Models improved by over 50% with MAPE scores of <15%

### Model Combination



Recall that if we had a 1-step ahead forecast from 2 different models, which we denote as  $\hat{y}_{t+1}^{(1)}$  and  $\hat{y}_{t+1}^{(2)}$ . Furthermore, we can compute the forecast errors which we denote as  $e_{t+1}^{(1)}$  and  $e_{t+1}^{(2)}$ . From this, letting  $\lambda$  be the weight parameter, we denote the combined forecast as

$$\hat{\mathbf{y}}_{t+1}^{c} = (1 - \lambda)\hat{\mathbf{y}}_{t+1}^{(1)} + \lambda\hat{\mathbf{y}}_{t+1}^{(2)}$$

From this, the variance of the combined forecast error is

$$Var(e_{t+1}^c) = (1 - \lambda)^2 \sigma_1^2 + \lambda^2 \sigma_2^2 + 2\lambda(1 - \lambda)\rho \sigma_1 \sigma_2$$

We can then optimise  $\lambda$  to minimise the variance, which gives us

$$\lambda^* = \frac{\sigma_1^2 - \rho \sigma_1 \sigma_2}{\sigma_1^2 + \sigma_2^2 - 2\rho \sigma_1 \sigma_2}$$

However, we need to use estimates so we have that

$$\hat{\lambda}^* = \frac{\hat{\sigma}_1^2 - \hat{\sigma}_{12}}{\hat{\sigma}_1^2 + \hat{\sigma}_2^2 - 2\hat{\sigma}_{12}}.$$

where we use  $\hat{\sigma}$  as an estimator for  $\sigma$ , to be the residuals in our estimated model.



# Conclusions

### Results and Considerations



- Lots of other models we tried out like exponential smoothing, Holt Winters
- This is all even before adding in regressors where we used dimensionality reduction
- Machine Learning techniques could be an option
- Models and techniques discussed today returned a MAPE score of <15, which beats the benchmark MAPE of 25



# Questions