Ch4_Notation

Essence of the chapter:

$$\begin{bmatrix} A'' \\ A'x \\ A'y \\ A'z \end{bmatrix} = \begin{bmatrix} A'_t & A'_x & A'_y & A'_z \\ A^x_t & A^x_x & A^x_y & A^x_z \\ A^y_t & A^y_x & A^y_y & A^y_z \\ A^z_t & A^z_x & A^z_y & A^z_z \\ A^z_t & A^z_x & A^z_y & A^z_z \\ A^z_t & A^z_x & A^z_y & A^z_z \end{bmatrix} \begin{bmatrix} A' \\ A^z \\ A^z \\ A^z \\ A^z \end{bmatrix}$$

Notation simplification:

Rewrite Lorentz

$$A^{\prime M} = \sum_{\nu} \Lambda^{M}_{\nu} A^{\nu}$$

Einstein summation convention:

If the same Greek-letter index appears exactly once as a superscript and exactly once as a subscript in any single term of an equation, we will assume that term is to be summed over all four possible values of that index.

$$A'^{M} = \bigwedge_{\nu}^{M} A^{\nu}$$

$$A^{M} = (\bigwedge_{\nu}^{-1})_{\nu}^{M} A^{\nu}$$

The Metric Tensor

$$\begin{vmatrix} \eta_{st} & \eta_{sx} & \eta_{sy} & \eta_{sz} \\ \eta_{st} & \eta_{sx} & \eta_{sy} & \eta_{sz} \\ \eta_{st} & \eta_{sx} & \eta_{sy} & \eta_{sz} \\ \eta_{st} & \eta_{zx} & \eta_{zy} & \eta_{zz} \end{vmatrix} = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

• dot preduct
$$\vec{A} \cdot \vec{B} = \eta_{\mu\nu} A^{\mu} B^{\nu}$$

 $\vec{A}^2 = \eta_{\mu\nu} A^{\mu} A^{\nu}$

EM field Tensor

(Skiped)

Free and Bound indices

$$p_{tot}^{\prime m} = p_{1}^{\prime m} + p_{2}^{\prime m} = \bigwedge_{v}^{m} p_{v}^{v} + \bigwedge_{r}^{m} p_{r}^{v}$$
$$= \bigwedge_{v}^{m} (p_{v}^{v} + p_{r}^{v})$$

- · M is called free indecies (free to assign)
- · V is called bound indecies "dummy"

Useful Identities

$$\frac{d}{d\tau}(\vec{A} \cdot \vec{A}) = 2 \eta_{NV} A^{\mu} \frac{dA^{\nu}}{d\tau} \quad [chain rule, so theres a 2]$$

· Also, the superscript in denominator should be viewed as a subscript