

Ch3_Boxes

3.1.1 - Invariant of dot product across frame

$$[\underline{A} \cdot \underline{B}]_{s'} = \underline{A} \cdot \underline{B} = \underline{A}^T \underline{\eta} \underline{B}$$

$$[\underline{A} \cdot \underline{B}]_s = \underline{L} \underline{A} \cdot \underline{L} \underline{B}$$

$$= (\underline{A}^T \underline{L}^T) \underline{\eta} \underline{L} \underline{B}$$

$$= \underline{A}^T (\underline{L}^T \underline{\eta} \underline{L}) \underline{B}$$

$$= \underline{A}^T \underline{\eta} \underline{B}$$

$$\text{Aside: } \underline{C} \cdot \underline{D} = \underline{\eta} \underline{C}^T \underline{D}$$

$$\text{where } \underline{\eta} = \begin{pmatrix} -1 & & \\ & 1 & \\ & & 1 \end{pmatrix}$$

$$\text{Aside: } \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix}$$

$$= \begin{pmatrix} \gamma & \beta\gamma \\ \beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} -\gamma & -\beta\gamma \\ \beta\gamma & \gamma \end{pmatrix}$$

$$= \begin{pmatrix} -\gamma^2 + \beta^2\gamma^2 & -\beta\gamma^2 + \beta^2\gamma^2 \\ -\beta\gamma^2 + \beta^2\gamma^2 & -\beta^2\gamma^2 + \gamma^2 \end{pmatrix}$$

$$= \begin{pmatrix} -\gamma^2(1-\beta^2) & 0 \\ 0 & \gamma^2(1-\beta^2) \end{pmatrix} = \underline{\eta}$$

3.2.1 - Invariant magnitude of 4-velocity

$$\underline{u} \cdot \underline{u} = \begin{pmatrix} dt/d\tau \\ dx/d\tau \\ \vdots \end{pmatrix} \cdot \begin{pmatrix} dt/d\tau \\ dx/d\tau \\ \vdots \end{pmatrix}$$

$$= -\left(\frac{dt}{d\tau}\right)^2 + \left(\frac{dx}{d\tau}\right)^2 + \dots$$

$$= \frac{-dt^2 + dx^2 + dy^2 + dz^2}{d\tau^2}$$

$$= \left(\frac{ds}{d\tau}\right)^2 \quad \text{Invariance of } ds^2$$

$$= \left(\frac{ds'}{d\tau}\right)^2 \quad ds'^2 = -d\tau'^2 + d\sqrt{x'}^2 + d\sqrt{y'}^2 + d\sqrt{z'}^2$$

$$= -\left(\frac{d\tau}{d\tau}\right)^2 = -1$$

3.3.1 - Taylor expansion

$$\begin{aligned}
 (1 + (-v^2))^{-1/2} &= 1 + \left(-\frac{1}{2}\right)(-v^2) + \left(-\frac{1}{2}\right)\left(-\frac{3}{2}\right)\frac{1}{2}v^4 + \dots \\
 &= 1 + \frac{1}{2}v^2 + \frac{3}{8}v^4 + \dots
 \end{aligned}$$

3.4.1 - Velocity addition example

$$\text{frame } S' : \beta = v$$

$$V_1 = 0$$

$$V_2' = \frac{V_2 - \beta}{1 - \beta V_2} = \frac{U_2 - v}{1 - v V_2}$$

$$V_2' = \frac{-v - v}{1 + v^2} = \frac{-2v}{1 + v^2}$$

$$\Rightarrow \text{Mass } M_1$$

$$V_3 = 0$$

$$V_3' = \frac{V_3 - \beta}{1 - \beta V_3} = \frac{-\beta}{1} = -v$$