



# Mining Big Data

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# Outline

## 1 Introduction

- Big Data
- Supervised Learning

## 2 Stochastic Optimization

- Time Reduction
- Space Reduction

## 3 Distributed Optimization

- Distributed Gradient Descent
- ADMM

## 4 Online Learning

- Full-Information Setting
- Bandit Setting

## 5 Summary



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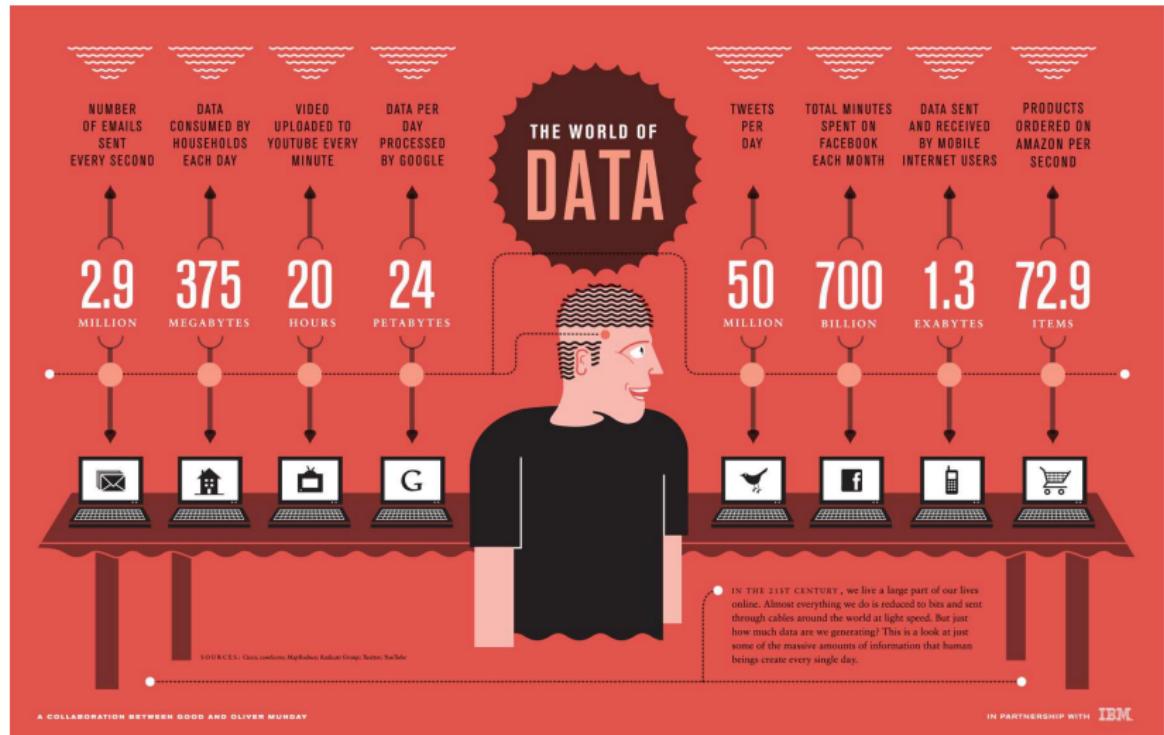
## 4 Online Learning

- Full-Information Setting
- Bandit Setting

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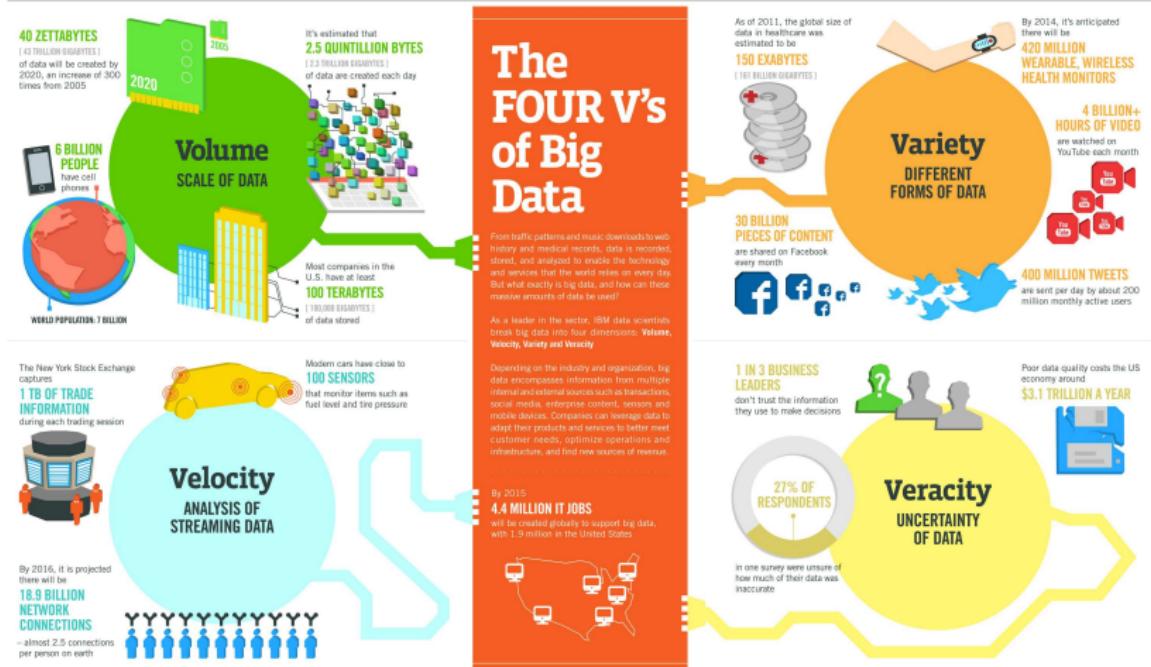


# Big Data



<https://infographiclist.files.wordpress.com/2011/09/world-of-data.jpeg>

# The Four V's of Big Data



Sources: McKinsey Global Institute, Twitter, Cisco, Gartner, EMC, SAS, IBM, NEPTEC, Gartner



[http://www.ibmbigdatahub.com/sites/default/files/infographic\\_file/4-Vs-of-big-data.jpg](http://www.ibmbigdatahub.com/sites/default/files/infographic_file/4-Vs-of-big-data.jpg)

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# Supervised Learning (I)

## Training

### Input

- A set of training data  $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ 
  - Classification v.s. Regression
  - Batch Setting v.s. Online Setting

### Output

- A function  $g(\cdot)$  such that  $y_i \approx g(\mathbf{x}_i), \forall i$

## Testing

Given a testing point  $\mathbf{x}$ , predict its label by  $g(\mathbf{x})$

## Assumption

Training and testing data are independent and identically distributed (i.i.d.)



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# Supervised Learning (II)

## Loss Function

Measure the discrepancy between  $y$  and  $g(\mathbf{x})$

- Binary loss:  $\ell(u, v) = \mathbf{1}(uv < 0)$
- Hinge loss:  $\ell(u, v) = \max(0, 1 - uv)$
- Squared loss:  $\ell(u, v) = (u - v)^2$

## Empirical Risk

$$\frac{1}{n} \sum_{i=1}^n \ell(y_i, g(\mathbf{x}_i))$$

## Risk

$$\mathbb{E}_{(\mathbf{x}, y)} [\ell(y, g(\mathbf{x}))]$$

Our goal is to minimize the risk instead of empirical risk.



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# What is Stochastic Optimization? (I)

Definition 1: A Special Objective [Nemirovski et al., 2009]

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \mathbb{E}_{\xi} [\ell(\mathbf{w}, \xi)] = \int_{\Xi} \ell(\mathbf{w}, \xi) dP(\xi)$$

where  $\xi$  is a random variable

- It is possible to generate an i.i.d. sample  $\xi_1, \xi_2, \dots$

## Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \mathbb{E}_{(\mathbf{x}, y)} [\ell(y, \mathbf{x}^\top \mathbf{w})]$$

$\ell(\cdot, \cdot)$  is a loss function, e.g., hinge loss  $\ell(u, v) = \max(0, 1 - uv)$

- Training data  $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$  are i.i.d.



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# What is Stochastic Optimization? (II)

Definition 2: A Special Access Model [Hazan and Kale, 2011]

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w})$$

- There exists a stochastic **oracle** that produces **unbiased gradient**  $\mathbf{m}(\cdot)$

$$\mathbb{E}[\mathbf{m}(\mathbf{w})] = \nabla f(\mathbf{w})$$

## Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

- Sampling a  $(\mathbf{x}_t, y_t)$  from  $\{(\mathbf{x}_i, y_i)\}_{i=1}^n$  uniformly at random

$$\mathbb{E}[\nabla \ell(y_t, \mathbf{x}_t^\top \mathbf{w})] = \nabla \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$



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# Time Reduction (I)

## Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W} \subseteq \mathbb{R}^d} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

- $n$  is the number of training data
- $d$  is the dimensionality

## Deterministic Optimization—Gradient Descent (GD)

```
1: for  $t = 1, 2, \dots, T$  do
2:    $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left( \frac{1}{n} \sum_{i=1}^n \nabla \ell(y_i, \mathbf{x}_i^\top \mathbf{w}_t) \right)$ 
3:    $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$ 
4: end for
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## The Challenge

- Time complexity per iteration:  $O(nd) + O(\text{poly}(d))$



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# Space Reduction (I)

## Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

- Matrix completion, multi-class classification
- Both  $m$  and  $n$  can be very large
- The optimal solution  $W_*$  is low-rank

## Collaborative Filtering—Matrix Completion

$$\min_{W \in \mathbb{R}^{m \times n}} F(W) = \sum_{(i,j) \in \Omega} (W_{ij} - M_{ij})^2 + \lambda \|W\|_*$$

- There are  $m$  users and  $n$  items
- $M \in \mathbb{R}^{m \times n}$  is the underlying user-item rating matrix
- $\Omega$  is the set of observed indices



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- Space complexity per iteration:  $O(mn)$



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# Space Reduction (III)

## Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

### Stochastic Proximal Gradient Descent (SPGD)

[Zhang et al., 2015]

1: **for**  $t = 1, 2, \dots, T$  **do**

2:    Generate a **low-rank** stochastic gradient  $\hat{G}_t$  of  $f(\cdot)$  at  $W_t$

$$W_{t+1} = \operatorname{argmin}_{W \in \mathbb{R}^{m \times n}} \frac{1}{2} \|W - (W_t - \eta_t \hat{G}_t)\|_F^2 + \eta_t \lambda \|W\|_*$$

4: **end for**

5: **return**  $W_{T+1}$

### The Advantage—Space Reduction

- Space complexity per iteration is **low**:  $O((m+n)r)$



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# Limitations

## Iteration Complexity

The number of iterations  $T$  to ensure

$$f(\mathbf{w}_T) - \min_{\mathbf{w} \in \Omega} f(\mathbf{w}) \leq \epsilon$$

## Iteration Complexity of GD and SGD

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{1}{\sqrt{\epsilon}}\right)$	$O\left(\sqrt{\kappa} \log \frac{1}{\epsilon}\right)$
SGD	$O\left(\frac{1}{\epsilon^2}\right)$	$O\left(\frac{1}{\mu\epsilon}\right)$

## Total Time Complexity of GD and SGD

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SGD	$O\left(\frac{1}{\epsilon^2}\right)$ $10^{12}$	$O\left(\frac{1}{\mu\epsilon}\right)$ $\frac{10^6}{\mu}$

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# Introduction (I)

## Empirical Risk Minimization in Distributed Setting

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \sum_{j=1}^k \sum_{i=1}^{n_j} \ell(y_i^j, \mathbf{w}^\top \mathbf{x}_i^j)$$

- $(\mathbf{x}_1^j, y_1^j) \dots (\mathbf{x}_{n_j}^j, y_{n_j}^j)$  are training data in the  $j$ -th machine

 $(\mathbf{x}_1^1, y_1^1)$  $(\mathbf{x}_1^2, y_1^2)$ 

...

 $(\mathbf{x}_1^k, y_1^k)$  $\dots$   
 $(\mathbf{x}_{n_1}^1, y_{n_1}^1)$  $\dots$   
 $(\mathbf{x}_{n_2}^k, y_{n_2}^k)$  $\dots$   
 $(\mathbf{x}_{n_k}^k, y_{n_k}^k)$

# Introduction (II)

## General Distributed Optimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \sum_{j=1}^k f_j(\mathbf{w})$$

- For empirical risk minimization, we have

$$f_j(\mathbf{w}) = \sum_{i=1}^{n_j} \ell(y_i^j, \mathbf{w}^\top \mathbf{x}_i^j)$$

 $f_1(\mathbf{w})$  $f_2(\mathbf{w})$  $\dots$  $f_k(\mathbf{w})$ 

# Outline

## 1 Introduction

- Big Data
- Supervised Learning

## 2 Stochastic Optimization

- Time Reduction
- Space Reduction

## 3 Distributed Optimization

- **Distributed Gradient Descent**
- ADMM

## 4 Online Learning

- Full-Information Setting
- Bandit Setting

## 5 Summary



# Distributed Gradient Descent

## Gradient Descent

```
1: for  $t = 1, 2, \dots, T$  do
2:    $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left( \sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$ 
3:    $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$ 
4: end for
```

## Distributed Gradient Descent

```
1: for  $t = 1, 2, \dots, T$  do
2:   Server: send  $\mathbf{w}_t$  to each worker
3:   Each worker  $j$ : calculate  $\nabla f_j(\mathbf{w}_t)$  and send it to server
4:   Server:  $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left( \sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$ 
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6: end for
```



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```
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```

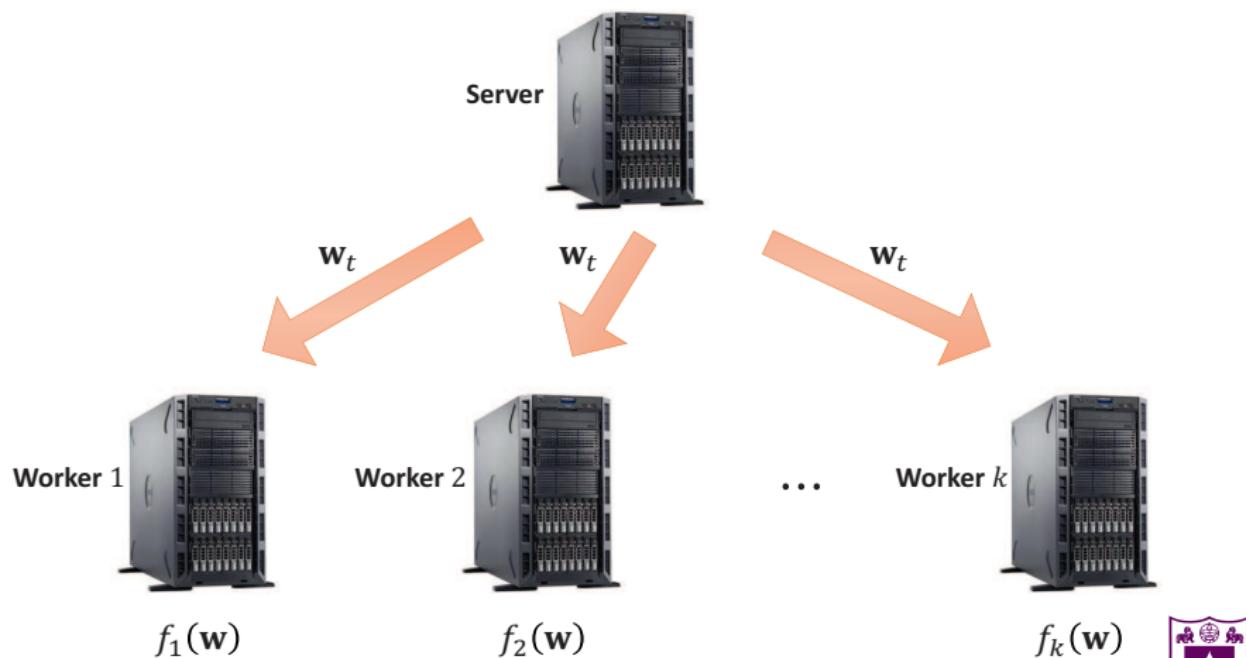
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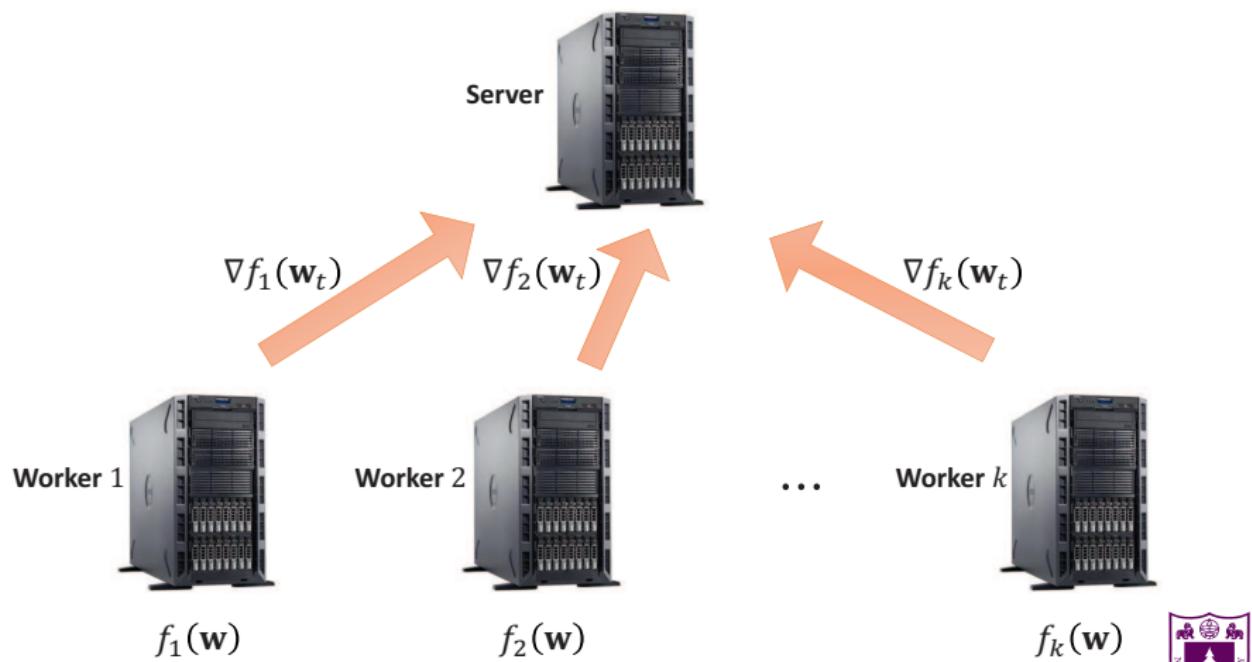
# Step 1

Server: send  $\mathbf{w}_t$  to each worker



## Step 2

Each worker  $j$ : calculate  $\nabla f_j(\mathbf{w}_t)$  and send it to server



# Steps 3 and 4

- Server:  $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left( \sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$
- Server:  $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$



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# Reformulation of the Distributed Optimization (I)

## General Distributed Optimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \sum_{j=1}^k f_j(\mathbf{w})$$

## Global Consensus Problem

$$\min_{\mathbf{y} \in \mathcal{W}, \{\mathbf{w}_j = \mathbf{y}\}_{j=1}^k} \sum_{j=1}^k f_j(\mathbf{w}_j)$$

## The Lagrangian

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle$$



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# Reformulation of the Distributed Optimization (II)

## The Augmented Lagrangian [Roux et al., 2012]

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle + \frac{1}{2\gamma} \|\mathbf{w}_j - \mathbf{y}\|_2^2$$

## Alternating Direction Method of Multipliers (ADMM)

- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Server: send  $\mathbf{y}^t$  and  $\lambda_j^t$  to worker  $j = 1, \dots, k$
- 3:   Each worker  $j$ : calculate  $\mathbf{w}_j^{t+1}$  and send it to server

$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \lambda_j^t - \mathbf{w}\|_2^2, \quad j = 1, \dots, k$$

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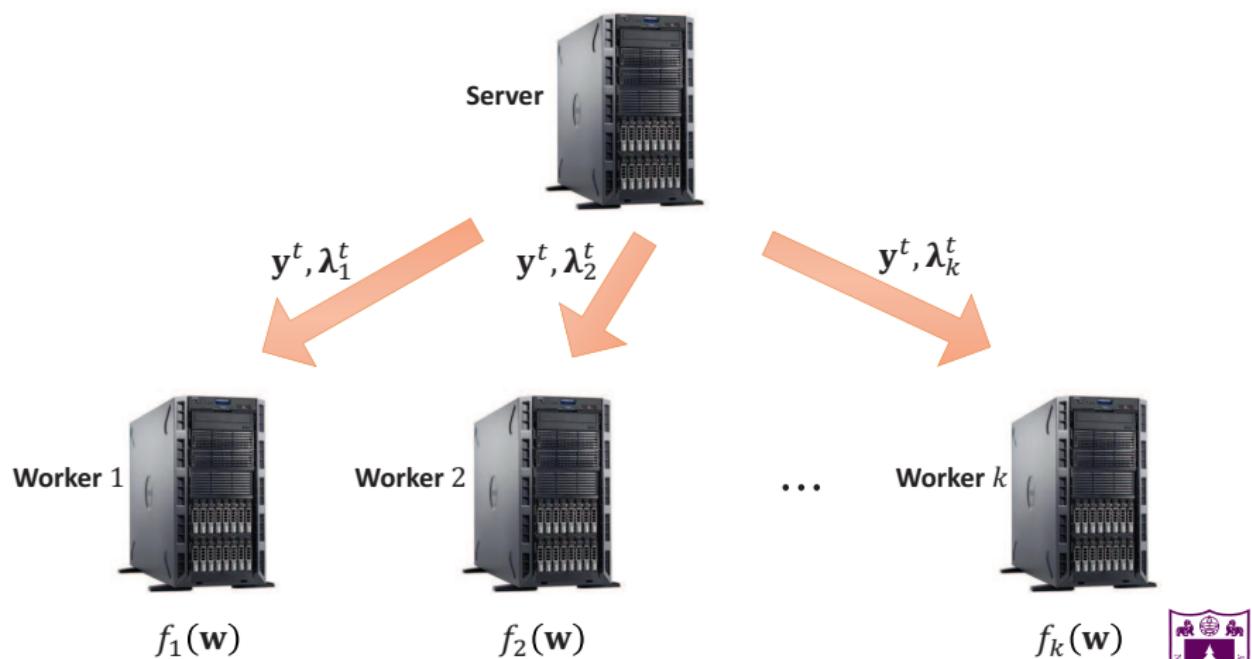
$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \lambda_j^t - \mathbf{w}\|_2^2, \quad j = 1, \dots, k$$

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- 6: **end for**



# Step 1

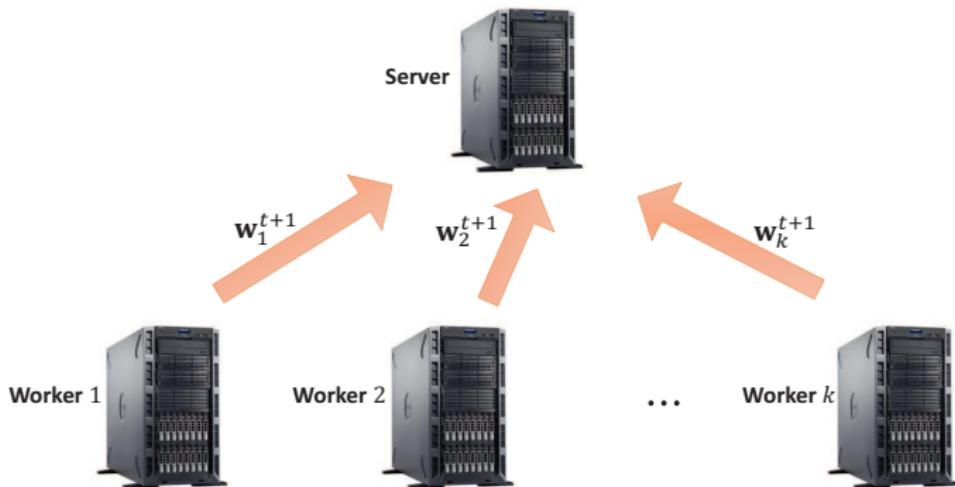
Server: send  $\mathbf{y}^t$  and  $\lambda_j^t$  to worker  $j = 1, \dots, k$



## Step 2

Each worker  $j$ : calculate  $\mathbf{w}_j^{t+1}$  and send it to server

$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \boldsymbol{\lambda}_j^t - \mathbf{w}\|_2^2, \quad j = 1, \dots, k$$



$$\mathbf{w}_1^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_1(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \boldsymbol{\lambda}_1^t - \mathbf{w}\|_2^2 \quad \mathbf{w}_k^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_k(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \boldsymbol{\lambda}_k^t - \mathbf{w}\|_2^2$$



# Steps 3 and 4

- Server:  $\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left( \frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \boldsymbol{\lambda}_j^t) \right)$
- Server:  $\boldsymbol{\lambda}_j^{t+1} = \boldsymbol{\lambda}_j^t + \frac{1}{\gamma} (\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1}), j = 1, \dots, k$

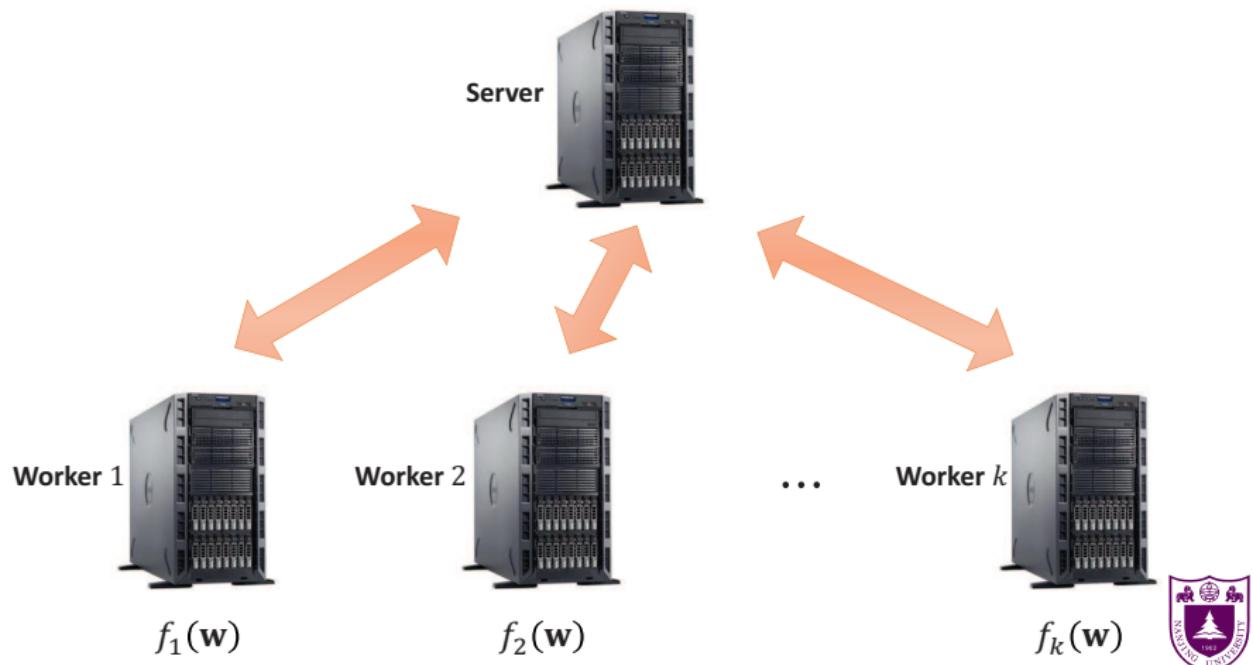


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# Challenges of Distributed Optimization

- Communication
- Synchronization



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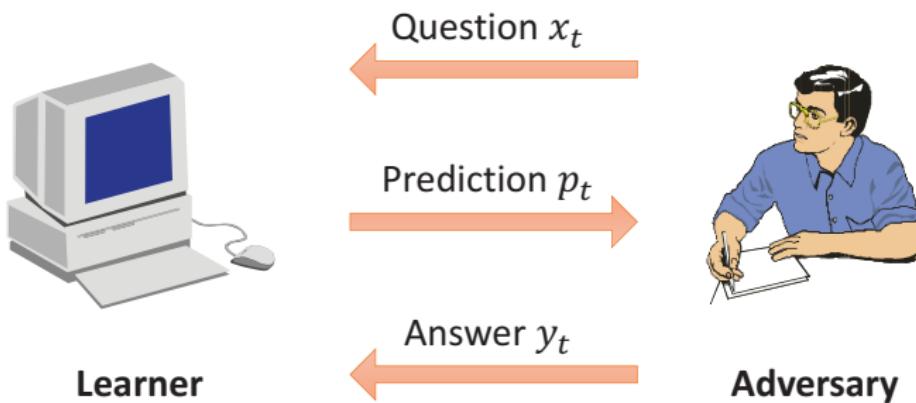
## 5 Summary



# Online Learning (I)

## Online Learning [Shalev-Shwartz, 2011]

- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Receive a question  $x_t \in \mathcal{X}$
- 3:   Predict  $p_t \in \mathcal{D}$
- 4:   Receive true answer  $y_t \in \mathcal{Y}$
- 5:   Suffer loss  $\ell(y_t, p_t)$
- 6: **end for**



# Online Learning (II)

## Online Learning [Shalev-Shwartz, 2011]

```
1: for  $t = 1, 2, \dots, T$  do
2:   Receive a question  $x_t \in \mathcal{X}$ 
3:   Predict  $p_t \in \mathcal{D}$ 
4:   Receive true answer  $y_t \in \mathcal{Y}$ 
5:   Suffer loss  $\ell(y_t, p_t)$ 
6: end for
```

## An Example—Online Classification

```
1: for  $t = 1, 2, \dots, T$  do
2:   Receive a question  $\mathbf{x}_t \in \mathcal{X} \subseteq \mathbb{R}^d$ 
3:   Predict  $p_t \in \mathcal{D} = \{0, 1\}$ 
4:   Receive true answer  $y_t \in \mathcal{Y} = \{0, 1\}$ 
5:   Suffer loss  $\ell(y_t, p_t) = |y_t - p_t|$ 
6: end for
```



# Online Learning (III)

Online Learning [Shalev-Shwartz, 2011]

- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Receive a question  $x_t \in \mathcal{X}$
- 3:   Predict  $p_t \in \mathcal{D}$
- 4:   Receive true answer  $y_t \in \mathcal{Y}$
- 5:   Suffer loss  $\ell(y_t, p_t)$
- 6: **end for**

Cumulative Loss

$$\text{Cumulative Loss} = \sum_{t=1}^T \ell(y_t, p_t)$$



# Online Learning (VI)

Online Learning [Shalev-Shwartz, 2011]

- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Receive a question  $x_t \in \mathcal{X}$
- 3:   Predict  $p_t \in \mathcal{D}$
- 4:   Receive true answer  $y_t \in \mathcal{Y}$
- 5:   Suffer loss  $\ell(y_t, p_t)$
- 6: **end for**

Regret with respect to a hypothesis class  $\mathcal{H}$

$$\text{Regret} = \sum_{t=1}^T \ell(y_t, p_t) - \min_{h \in \mathcal{H}} \sum_{t=1}^T \ell(y_t, h(x_t))$$

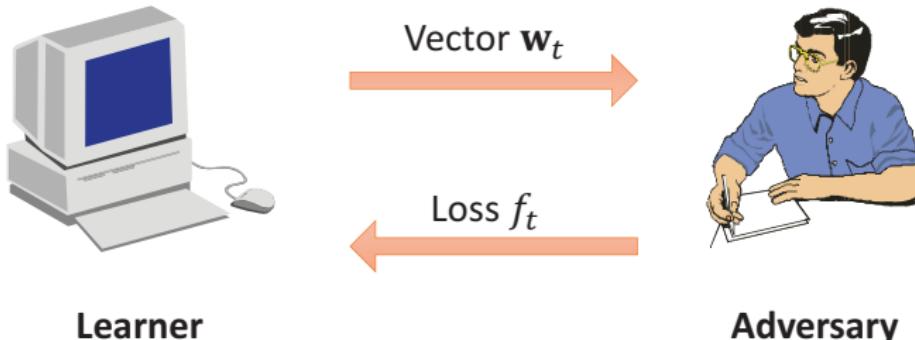
$$h : \mathcal{X} \mapsto \mathcal{D}$$



# Online Convex Optimization (I)

Online Convex Optimization [Shalev-Shwartz, 2011]

- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Predict a vector  $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3:   Receive a convex loss function  $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4:   Suffer loss  $f_t(\mathbf{w}_t)$
- 5: **end for**



Learner

Adversary



# Online Convex Optimization (II)

## Online Convex Optimization [Shalev-Shwartz, 2011]

```
1: for  $t = 1, 2, \dots, T$  do
2:   Predict a vector  $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$ 
3:   Receive a convex loss function  $f_t : \mathcal{W} \rightarrow \mathbb{R}$ 
4:   Suffer loss  $f_t(\mathbf{w}_t)$ 
5: end for
```

## An Example—Online SVM

```
1: for  $t = 1, 2, \dots, T$  do
2:   Predict a vector  $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$ 
3:   Receive a training instance  $(\mathbf{x}_t, y_t)$ 
4:   Suffer loss  $f_t(\mathbf{w}_t) = \ell(y_t, \mathbf{x}_t^\top \mathbf{w}_t) = \max(0, 1 - y_t \mathbf{x}_t^\top \mathbf{w}_t)$ 
5: end for
```



# Online Convex Optimization (III)

## Online Convex Optimization [Shalev-Shwartz, 2011]

```
1: for  $t = 1, 2, \dots, T$  do
2:   Predict a vector  $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$ 
3:   Receive a convex loss function  $f_t : \mathcal{W} \rightarrow \mathbb{R}$ 
4:   Suffer loss  $f_t(\mathbf{w}_t)$ 
5: end for
```

## Regret

$$\text{Regret} = \sum_{t=1}^T f_t(\mathbf{w}_t) - \min_{\mathbf{w} \in \mathcal{W}} \sum_{t=1}^T f_t(\mathbf{w})$$



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# Online Gradient Descent

## Full-Information Setting

The learner observes not only  $f_t(\mathbf{w}_t)$  but also  $f_t(\cdot)$ .

Online Gradient Descent [Zinkevich, 2003, Hazan et al., 2007]

- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Predict a vector  $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3:   Receive a convex loss function  $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4:   Suffer loss  $f_t(\mathbf{w}_t)$
- 5:    $\mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \nabla f_t(\mathbf{w}_t)$
- 6: **end for**

Regret Bound [Zinkevich, 2003, Hazan et al., 2007]

$$\text{Regret} = \sum_{t=1}^T f_t(\mathbf{w}_t) - \min_{\mathbf{w} \in \mathcal{W}} \sum_{t=1}^T f_t(\mathbf{w}) = O\left(\sqrt{T}\right) \text{ or } O(\log T)$$



# Online Gradient Descent

## Full-Information Setting

The learner observes not only  $f_t(\mathbf{w}_t)$  but also  $f_t(\cdot)$ .

## Online Gradient Descent [Zinkevich, 2003, Hazan et al., 2007]

- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Predict a vector  $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3:   Receive a convex loss function  $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4:   Suffer loss  $f_t(\mathbf{w}_t)$
- 5:    $\mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \nabla f_t(\mathbf{w}_t)$
- 6: **end for**

## Regret Bound [Zinkevich, 2003, Hazan et al., 2007]

$$\text{Regret} = \sum_{t=1}^T f_t(\mathbf{w}_t) - \min_{\mathbf{w} \in \mathcal{W}} \sum_{t=1}^T f_t(\mathbf{w}) = O\left(\sqrt{T}\right) \text{ or } O(\log T)$$



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# Outline

## 1 Introduction

- Big Data
- Supervised Learning

## 2 Stochastic Optimization

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- Space Reduction

## 3 Distributed Optimization

- Distributed Gradient Descent
- ADMM

## 4 Online Learning

- Full-Information Setting
- Bandit Setting

## 5 Summary



# Bandit Setting

## Bandit Setting

The learner only observes not only  $f_t(\mathbf{w}_t)$ .

### Generation Process of the Loss Functions

- Stochastic:  $f_1, \dots, f_t$  are i.i.d. sampled
- Adversarial
  - Oblivious:  $f_t$  is independent of  $\mathbf{w}_1, \dots, \mathbf{w}_{t-1}$
  - Nonoblivious:  $f_t$  may depend on  $\mathbf{w}_1, \dots, \mathbf{w}_{t-1}$

### Types of the Loss Functions

- Convex
- Linear
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# Multi-armed Bandit



<http://blog.mynaweb.com/wp-content/uploads/2013/02/Bandits.png>



# Stochastic Multi-armed Bandit

## Setting

- There are  $K$  arms
- Successive pulls of arm  $i$  yield rewards  $X_1^i, X_2^i, \dots$ 
  - Those rewards are i.i.d. according to an unknown distribution  $D_i$  with **unknown** mean  $\mu_i$

## The Learning Process

```
1: for  $t = 1, 2, \dots, T$  do
2:   pull arm  $i \in [K]$ 
3:   Receive reward  $X^i$  sampled from distribution  $D_i$ 
4: end for
```

## How to maximize the rewards?

Always pull arm  $i = \operatorname{argmax}_{i \in [K]} \mu_i$



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```

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Always pull arm  $i = \operatorname{argmax}_{i \in [K]} \mu_i$



# Exploitation-Exploration Dilemma

## A Naive Algorithm

### Exploration

- ① Pull each arm  $m = 100$  times
- ② Calculate the estimated mean  $\hat{\mu}_i$  each arm  $i$

### Exploitation

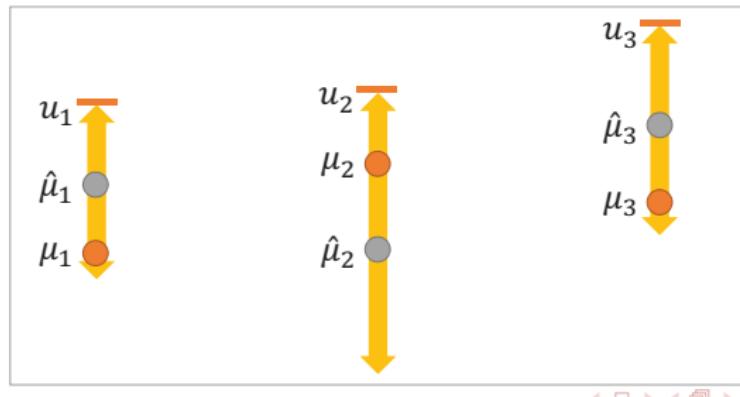
- ① Always pull arm  $i = \operatorname{argmax}_{i \in [K]} \hat{\mu}_i$



# Upper Confidence Bounds (I)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

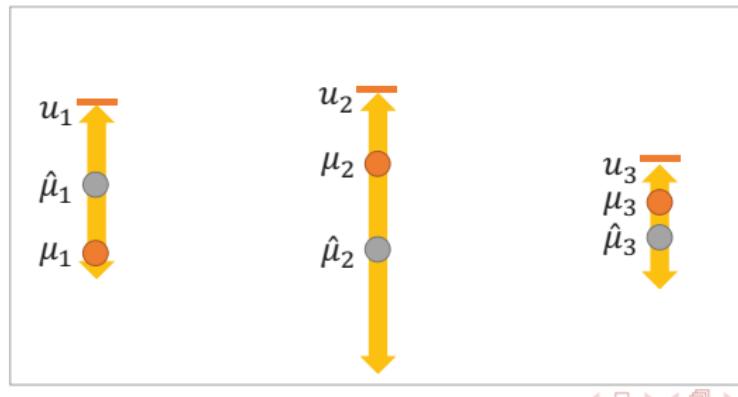
- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Pull arm  $i = \operatorname{argmax}_{i \in [K]} u_i$  (WHP,  $u_i \geq \mu_i$ )
- 3:   Receive reward  $X^i$  sampled from distribution  $\mathcal{D}_i$
- 4:   Update the upper bound  $u_i$  for arm  $i$
- 5: **end for**



# Upper Confidence Bounds (II)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

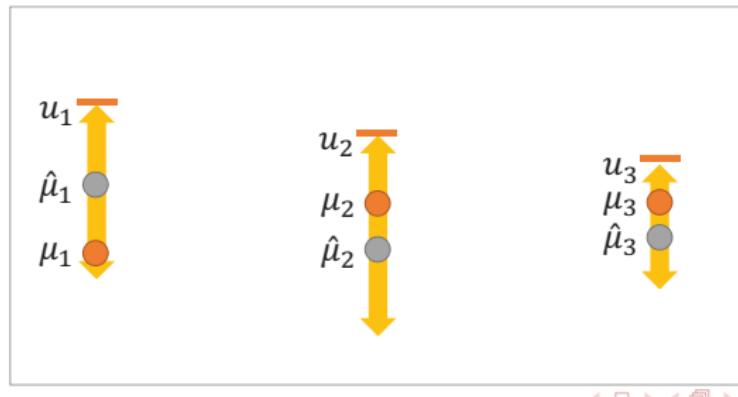
- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Pull arm  $i = \operatorname{argmax}_{i \in [K]} u_i$  (WHP,  $u_i \geq \mu_i$ )
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# Upper Confidence Bounds (III)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

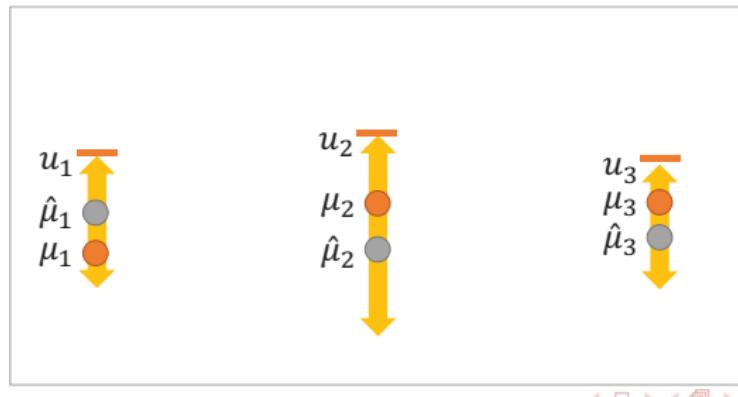
- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Pull arm  $i = \operatorname{argmax}_{i \in [K]} u_i$  (WHP,  $u_i \geq \mu_i$ )
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# Upper Confidence Bounds (IV)

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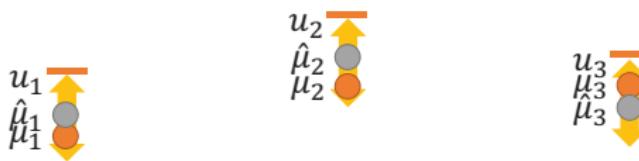
- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Pull arm  $i = \operatorname{argmax}_{i \in [K]} u_i$  (WHP,  $u_i \geq \mu_i$ )
- 3:   Receive reward  $X^i$  sampled from distribution  $\mathcal{D}_i$
- 4:   Update the upper bound  $u_i$  for arm  $i$
- 5: **end for**



# Upper Confidence Bounds (V)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

- 1: **for**  $t = 1, 2, \dots, T$  **do**
- 2:   Pull arm  $i = \operatorname{argmax}_{i \in [K]} u_i$  (WHP,  $u_i \geq \mu_i$ )
- 3:   Receive reward  $X^i$  sampled from distribution  $\mathcal{D}_i$
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# Summary

## Stochastic Optimization

- Stochastic Gradient Descent (SGD)—*Time Reduction*
- Stochastic Proximal Gradient Descent (SPGD)—*Space Reduction*

## Distributed Optimization

- Distributed Gradient Descent
- Alternating Direction Method of Multipliers (ADMM)

## Online Learning

- Full-Information Setting—Online Gradient Descent
- Bandit Setting—Exploitation-Exploration Dilemma



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