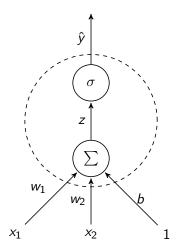
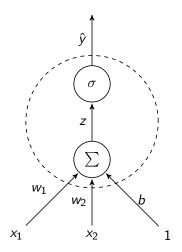
CS114B Lab 5

Kenneth Lai

March 3, 2022

Graphical Representation of a Linear Classifier





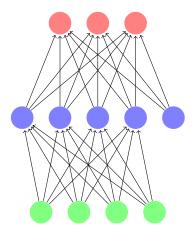
► (Artificial) neurons are basically linear classifiers!

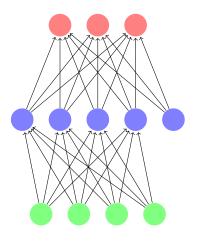
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- ► (Artificial) neurons are basically linear classifiers!
 - Neurons compute their output based on a linear combination of inputs
 - Outputs are not necessarily classification decisions (\hat{y}) , but can be inputs to other neurons

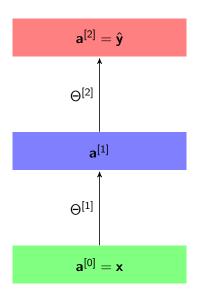
Suppose that our neurons are grouped into a sequence of layers

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- ▶ Also suppose that these layers are fully connected (every neuron in one layer is connected to every non-bias neuron in the next layer, and no others)

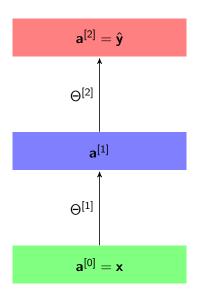




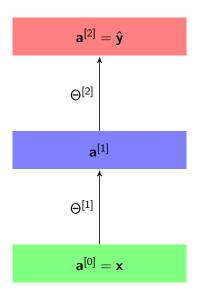
- Output layer
- ► Hidden layer(s)
- ► Input layer



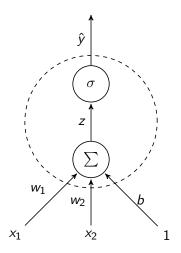
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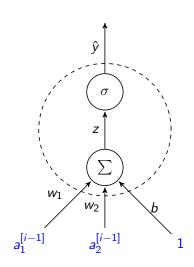


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 - Outputs of the hidden layers are vectors

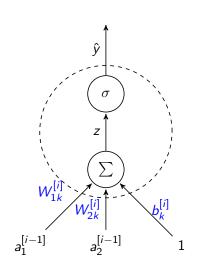


- Output layer
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 - Outputs of the hidden layers are vectors
 - In particular, they can be seen as intermediate representations of the input

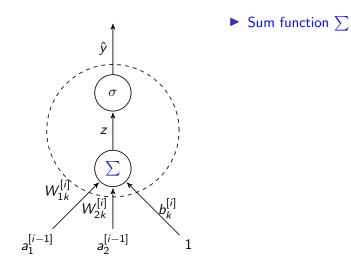


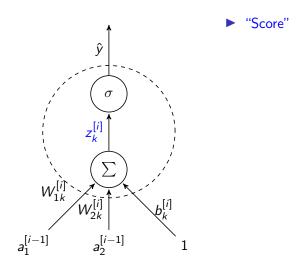


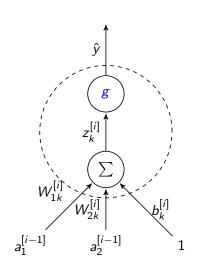
▶ Inputs to neuron k in layer i = outputs of neurons in layer i - 1 (and dummy node 1)



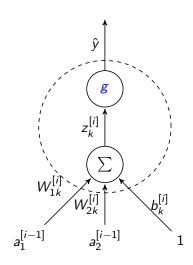
► Weights (and bias term)



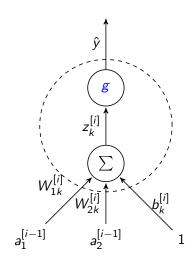




Activation function g

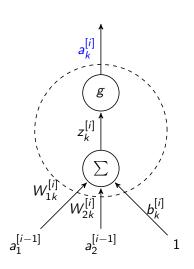


- ► Activation function *g*
 - Output neuron: logistic or softmax

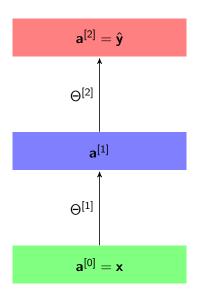


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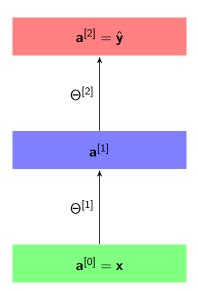
- Output neuron: logistic or softmax
- Hidden neuron: typically logistic, tanh, ReLU, etc.



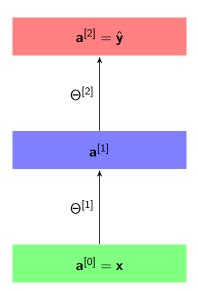
► Activation (output of neuron *k* in layer *i*)



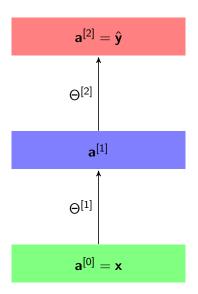
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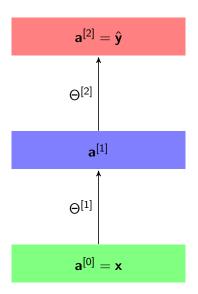
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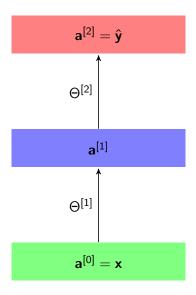
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- Same as for logistic regression, except replace x with a^[1]
- ▶ $(\nabla L)^{[1]} = ?$

- **•** ...
- ► (calculus—see supplement slides)
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- For an output layer \mathcal{L} :

$$\delta^{[\mathcal{L}]} = \hat{\mathbf{y}} - \mathbf{y}$$
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 - - ▶ Let ⊙ denote the element-wise (Hadamard) product

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- W does not include the bias b

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- lackbox We can compute $\delta^{[\mathcal{L}]}$ for an output layer \mathcal{L}
- ▶ Key idea: if we have already computed $\delta^{[i+1]}$ for some layer i+1, then we can use it to calculate $\delta^{[i]}$ for the previous layer i

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- ▶ Because L is not necessarily convex anymore, we are not guaranteed to reach a global minimum
 - But it works well enough in practice

Further Reading

- ► Goodfellow, I., Bengio, Y., and Courville, A. (2016). *Deep Learning*. MIT Press.
- Nielsen, M. A. (2015). Neural Networks and Deep Learning. Determination Press USA.