

Aqua

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# Chapter 1

## Developer documentation

### 1.1 Requirements

The project uses cmake and g++ for compilation. SFML requires these packages:

libxrandr-dev libxcursor-dev libudev-dev libopenal-dev libflac-dev libvorbis-dev libgl1-mesa-dev libegl1-mesa-dev  
libdrm-dev libgbm-dev

### 1.2 Compilation

Use cmake for compilation:

```
cmake -B build -DCMAKE_BUILD_TYPE=Release  
cmake --build build --config Release
```

### 1.3 Optimization

If not debugging, it is recommended to compile as Release, it can yield a substantial performance increase.





## Chapter 2

# Hierarchical Index

### 2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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## Chapter 3

# Class Index

### 3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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## Chapter 4

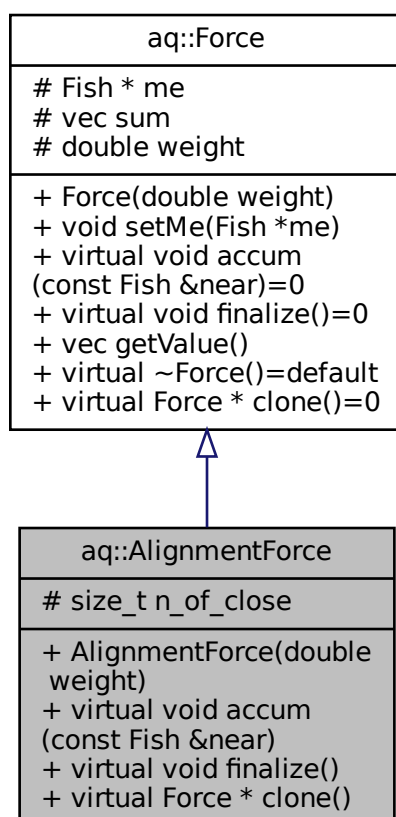
# Class Documentation

### 4.1 aq::AlignmentForce Class Reference

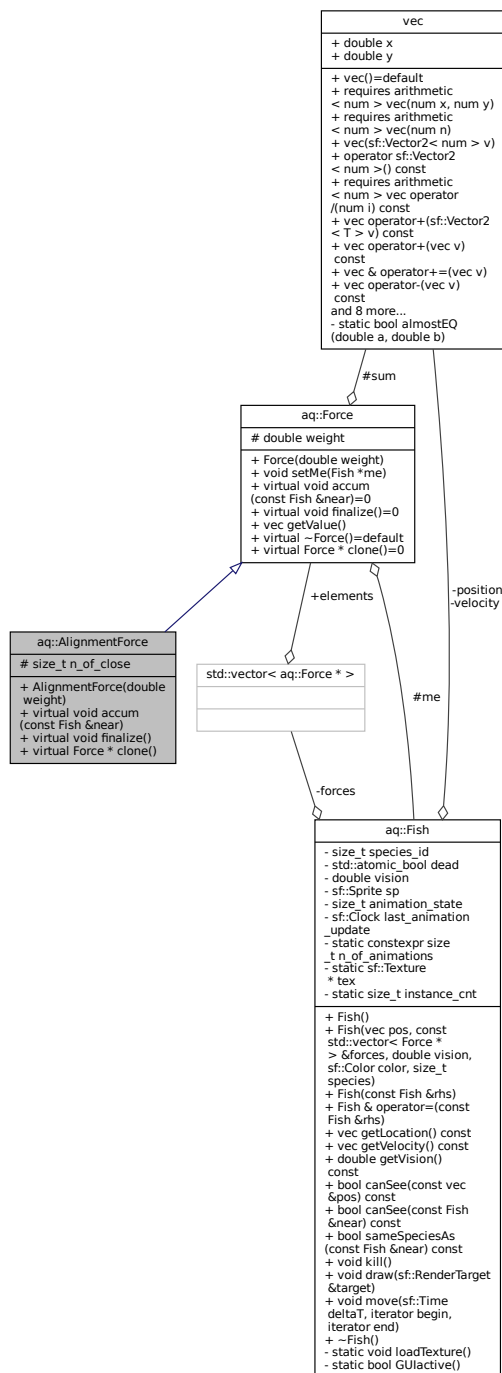
[Fish](#) want to swim in the same direction and speed.

```
#include <forces.hpp>
```

Inheritance diagram for aq::AlignmentForce:



Collaboration diagram for `aq::AlignmentForce`:



## Public Member Functions

- **AlignmentForce** (double weight)
- virtual void **accum** (const **Fish** &near)  
Should be called for each fish in the vicinity.
- virtual void **finalize** ()  
After accumulation finalize the calculation.

- virtual [Force](#) \* [clone](#) ()  
*Clones the force.*

## Protected Attributes

- `size_t n_of_close {0}`

### 4.1.1 Detailed Description

[Fish](#) want to swim in the same direction and speed.

### 4.1.2 Member Function Documentation

#### 4.1.2.1 clone()

```
virtual Force* aq::AlignmentForce::clone ( ) [inline], [virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the me pointer reset

Implements [aq::Force](#).

The documentation for this class was generated from the following file:

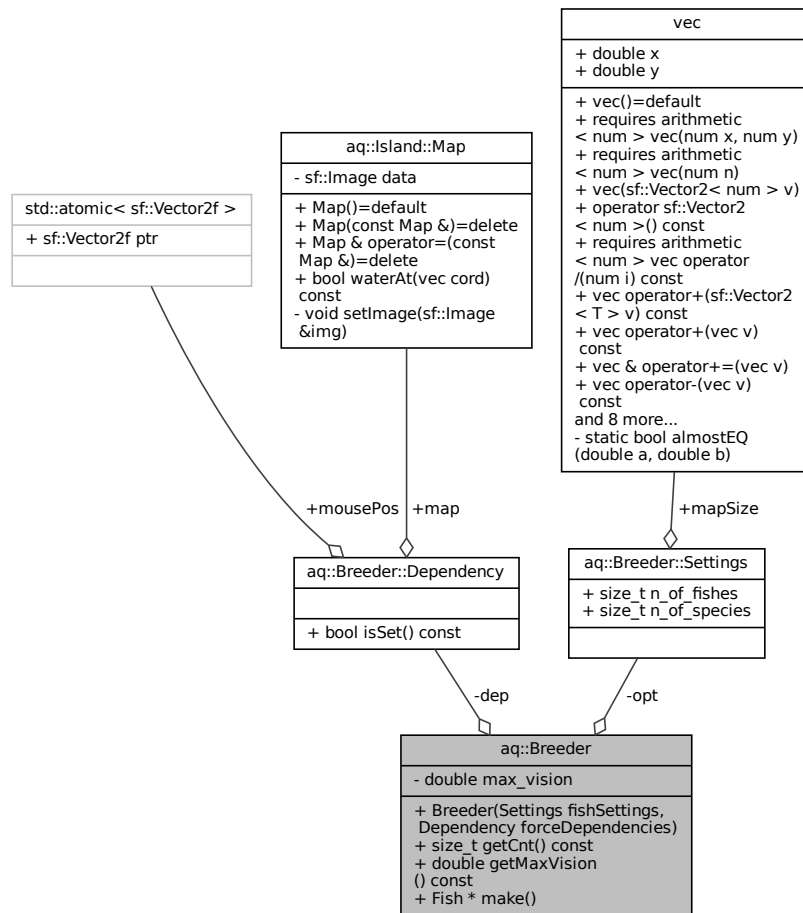
- inc/forces.hpp

## 4.2 aq::Breeder Class Reference

[Fish](#) generator.

```
#include <breeder.hpp>
```

Collaboration diagram for `aq::Breeder`:



## Classes

- struct [Dependency](#)
- struct [Settings](#)

## Public Member Functions

- **Breeder** ([Settings](#) fishSettings, [Dependency](#) forceDependencies)
- `size_t` **getCnt** () const
- `double` **getMaxVision** () const  
Returns the furthest distance a fish can see.
- [Fish](#) \* **make** ()  
Generates the fishes.

## Private Attributes

- `const` [Settings](#) **opt**
- `const` [Dependency](#) **dep**
- `double` **max\_vision** = 0



## 4.2.1 Detailed Description

[Fish](#) generator.

## 4.2.2 Member Function Documentation

### 4.2.2.1 getMaxVision()

```
double aq::Breeder::getMaxVision ( ) const [inline]
```

Returns the furthest distance a fish can see.

#### Warning

Only callable after fish generation!

### 4.2.2.2 make()

```
Fish * Breeder::make ( )
```

Generates the fishes.

#### Returns

an array of the generated fishes, deletion is the callers responsibility

The documentation for this class was generated from the following files:

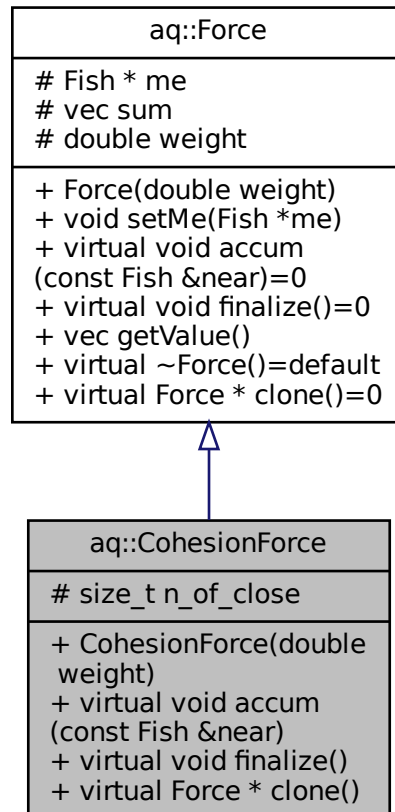
- inc/breeder.hpp
- src/breeder.cpp

### 4.3 aq::CohesionForce Class Reference

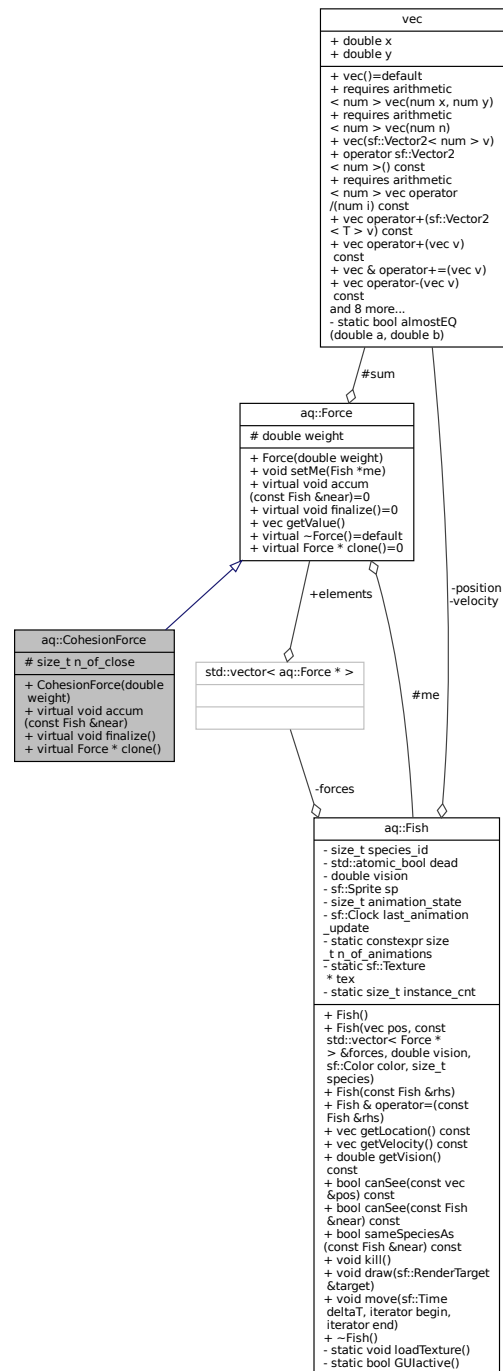
[Fish](#) want to stay close to each other.

```
#include <forces.hpp>
```

Inheritance diagram for aq::CohesionForce:



Collaboration diagram for aq::CohesionForce:



## Public Member Functions

- **CohesionForce** (double weight)
- virtual void **accum** (const **Fish** &near)
 

*Should be called for each fish in the vicinity.*
- virtual void **finalize** ()
 

*After accumulation finalize the calculation.*

- virtual [Force](#) \* [clone](#) ()  
*Clones the force.*

## Protected Attributes

- `size_t n_of_close {0}`

### 4.3.1 Detailed Description

[Fish](#) want to stay close to each other.

### 4.3.2 Member Function Documentation

#### 4.3.2.1 `clone()`

```
virtual Force* aq::CohesionForce::clone ( ) [inline], [virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the me pointer reset

Implements [aq::Force](#).

The documentation for this class was generated from the following file:

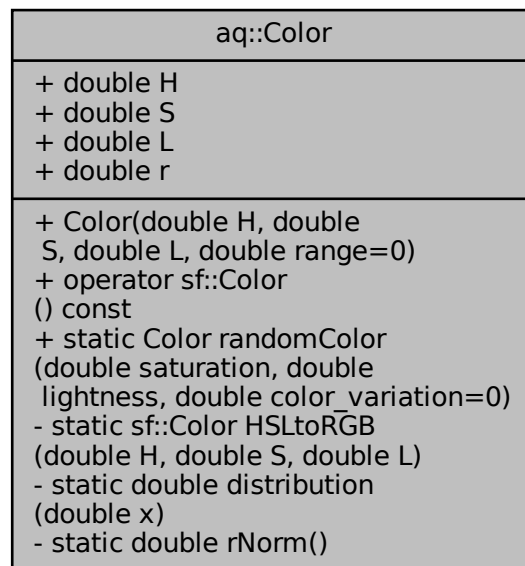
- `inc/forces.hpp`

## 4.4 [aq::Color](#) Class Reference

Represents a HSL color with some randomness.

```
#include <color.hpp>
```

Collaboration diagram for aq::Color:



## Public Member Functions

- [Color](#) (double H, double S, double L, double range=0)
- [operator sf::Color](#) () const  
*Converts to a RGB color with some randomness in the Hue.*

## Static Public Member Functions

- static [Color randomColor](#) (double saturation, double lightness, double color\_variation=0)  
*Generate a random color centered with a distribution.*

## Public Attributes

- double **H**
- double **S**
- double **L**
- double **r**

## Static Private Member Functions

- static sf::Color [HSLtoRGB](#) (double H, double S, double L)
- static double **distribution** (double x)
- static double **rNorm** ()

### 4.4.1 Detailed Description

Represents a HSL color with some randomness.

### 4.4.2 Constructor & Destructor Documentation

#### 4.4.2.1 Color()

```
aq::Color::Color (
    double H,
    double S,
    double L,
    double range = 0 ) [inline]
```

##### Parameters

<i>H</i>	Hue [0,360)
<i>S</i>	Saturation [0,1]
<i>L</i>	Lightness [0,1]
<i>range</i>	allowed +- from hue

### 4.4.3 Member Function Documentation

#### 4.4.3.1 HSLtoRGB()

```
sf::Color Color::HSLtoRGB (
    double H,
    double S,
    double L ) [static], [private]
```

Equations from [https://en.wikipedia.org/wiki/HSL\\_and\\_HSV](https://en.wikipedia.org/wiki/HSL_and_HSV)

#### 4.4.3.2 randomColor()

```
static Color aq::Color::randomColor (
    double saturation,
    double lightness,
    double color_variation = 0 ) [inline], [static]
```

Generate a random color centered with a distribution.

## Parameters

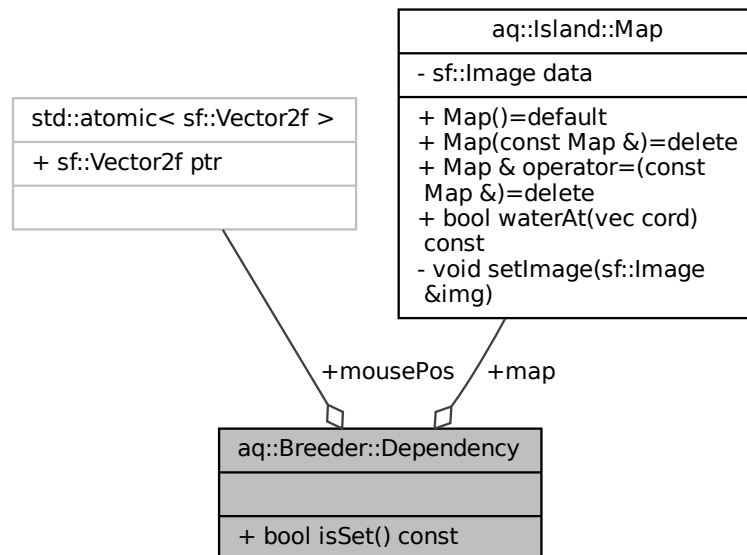
<i>hue_center</i>	[0,360)
<i>hue_range</i>	allowed +- from center
<i>color_variation</i>	randomness of rgb generated from the returned color

The documentation for this class was generated from the following files:

- inc/color.hpp
- src/color.cpp

## 4.5 aq::Breeder::Dependency Struct Reference

Collaboration diagram for aq::Breeder::Dependency:



### Public Member Functions

- bool **isSet** () const

### Public Attributes

- const [Island::Map](#) \* **map**
- const std::atomic< sf::Vector2f > \* **mousePos**

The documentation for this struct was generated from the following file:

- inc/breeder.hpp





## Public Member Functions

- **Engine** ([vec](#) window\_size, size\_t fish\_number, unsigned int seed)
- void **draw** ()
- void **startParallelLife** ()  
*Starts the background process for the calculations.*
- bool **isRunning** () const  
*Stops the background process for the calculations.*
- void **handleEvents** ()

## Private Member Functions

- void **zoomViewAt** ([vec](#) pixel, bool in)
- void **resetView** ()

## Private Attributes

- sf::RenderWindow \* **window**
- [Net](#) \* **net**
- [Island](#) \* **island**
- const float **zoomAmount** = 1.3F
- std::jthread **bgLife**
- std::atomic< sf::Vector2f > [mousePosition](#)  
*The position of the mouse for objects that cannot access the window.*

### 4.6.1 Detailed Description

The game engine setting up, running and shutting down the game.

The documentation for this class was generated from the following files:

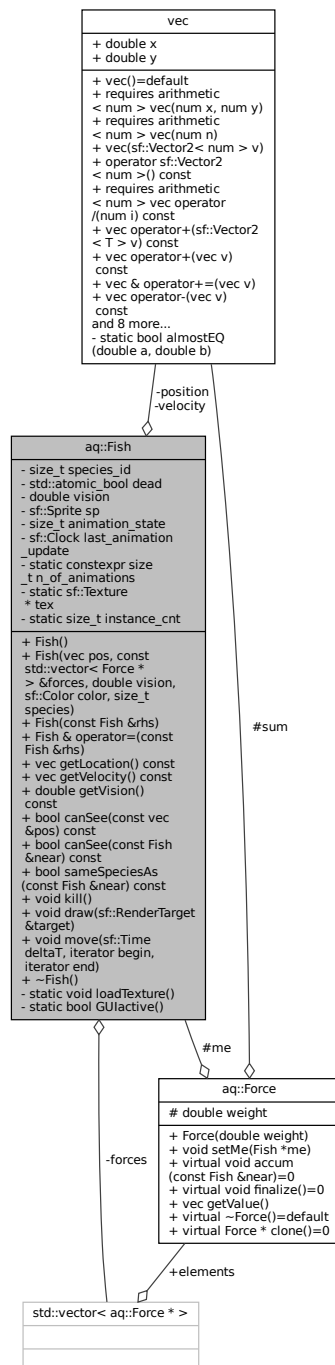
- inc/engine.hpp
- src/engine.cpp
- src/event\_handler.cpp

## 4.7 aq::Fish Class Reference

Represents a fish.

```
#include <fish.hpp>
```

Collaboration diagram for `aq::Fish`:



## Public Member Functions

- **Fish** (`vec` pos, const `std::vector< Force * >` &forces, double vision, `sf::Color` color, `size_t` species)
- **Fish** (const `Fish` &rhs)
- `Fish & operator=` (const `Fish` &rhs)
- `vec getLocation` () const
- `vec getVelocity` () const

- double **getVision** () const
- bool **canSee** (const [vec](#) &pos) const
- bool **canSee** (const [Fish](#) &near) const
- bool **sameSpeciesAs** (const [Fish](#) &near) const
- void **kill** ()  
*Kills the fish.*
- void **draw** (sf::RenderTarget &target)
- template<typename iterator >  
void **move** (sf::Time deltaT, iterator begin, iterator end)  
*Moves the fish according to it's internal forces.*

## Static Private Member Functions

- static void **loadTexture** ()  
*Loads the textures.*
- static bool **GUIactive** ()

## Private Attributes

- [vec](#) **position**
- [vec](#) **velocity**
- std::vector< [Force](#) \* > **forces**
- size\_t **species\_id**
- std::atomic\_bool **dead** {false}
- double **vision**
- sf::Sprite **sp**
- size\_t **animation\_state** {0}
- sf::Clock **last\_animation\_update**

## Static Private Attributes

- static constexpr size\_t **n\_of\_animations** = 4
- static sf::Texture \* **tex** = nullptr
- static size\_t **instance\_cnt** = 0  
*Number of instances for texture deletion.*

### 4.7.1 Detailed Description

Represents a fish.

It has a position, a velocity and stores the forces acting on it. It statically stores some textures and can be drawn to the screen.

### 4.7.2 Member Function Documentation

#### 4.7.2.1 kill()

```
void aq::Fish::kill ( ) [inline]
```

Kills the fish.

Changes the texture to a skeleton, it will no longer move or effect other fish

#### 4.7.2.2 loadTexture()

```
void Fish::loadTexture ( ) [static], [private]
```

Loads the textures.

Only loads them if they haven't been loaded yet and if there is a GUI

#### 4.7.2.3 move()

```
template<typename iterator >
void aq::Fish::move (
    sf::Time deltaT,
    iterator begin,
    iterator end ) [inline]
```

Moves the fish according to it's internal forces.

##### Template Parameters

<i>iterator</i>	for a container of fish that effect *this
-----------------	---

##### Parameters

<i>deltaT</i>	time passed since last move call
---------------	----------------------------------

The documentation for this class was generated from the following files:

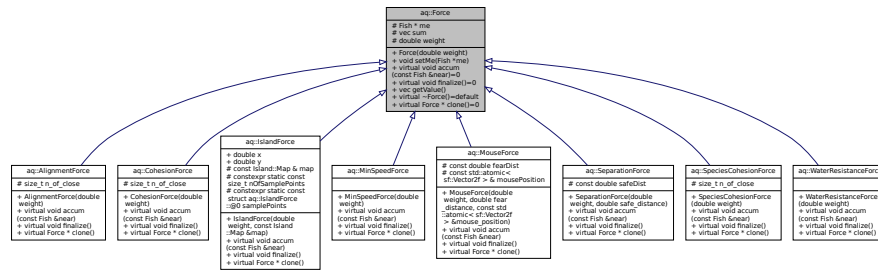
- inc/fish.hpp
- src/fish.cpp

## 4.8 aq::Force Class Reference

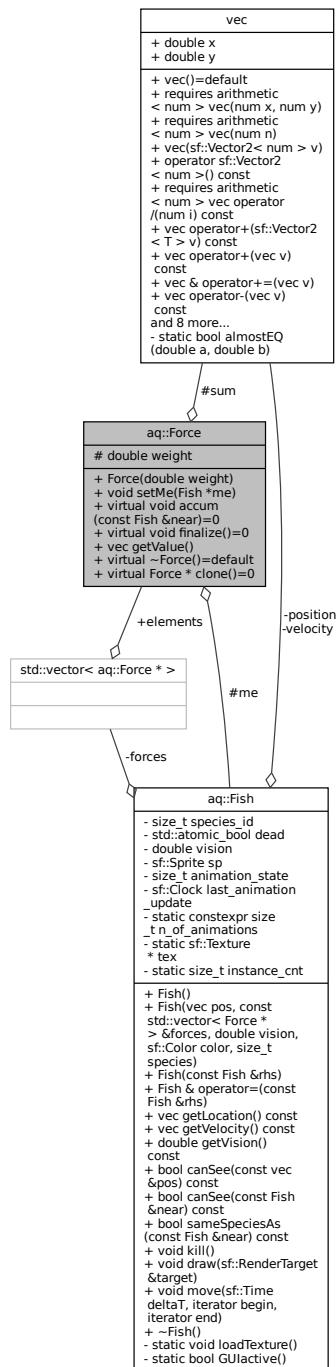
A force that can be applied to a fish.

```
#include <force.hpp>
```

Inheritance diagram for aq::Force:



Collaboration diagram for `aq::Force`:



## Public Member Functions

- **Force** (double weight)
- void **setMe** (**Fish** \*me)  
*Sets the fish that is containing this force.*
- virtual void **accum** (const **Fish** &near)=0  
*Should be called for each fish in the vicinity.*

- virtual void `finalize` ()=0  
*After accumulation finalize the calculation.*
- `vec` `getValue` ()  
*Returns the calculated value of the force and resets it.*
- virtual `Force` \* `clone` ()=0  
*Clones the force.*

## Protected Attributes

- `Fish` \* `me` {nullptr}
- `vec` `sum` {0, 0}
- double `weight`

### 4.8.1 Detailed Description

A force that can be applied to a fish.

Order of operations:

1. `accum`
2. `finalize`
3. `getValue`

### 4.8.2 Member Function Documentation

#### 4.8.2.1 `clone()`

```
virtual Force* aq::Force::clone ( ) [pure virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the `me` pointer reset

Implemented in `aq::IslandForce`, `aq::MouseForce`, `aq::MinSpeedForce`, `aq::WaterResistanceForce`, `aq::SpeciesCohesionForce`, `aq::CohesionForce`, `aq::AlignmentForce`, and `aq::SeparationForce`.

#### 4.8.2.2 setMe()

```
void Force::setMe (
    Fish * me )
```

Sets the fish that is containing this force.

#### Warning

Must be set before using the force

The documentation for this class was generated from the following files:

- inc/force.hpp
- src/force.cpp

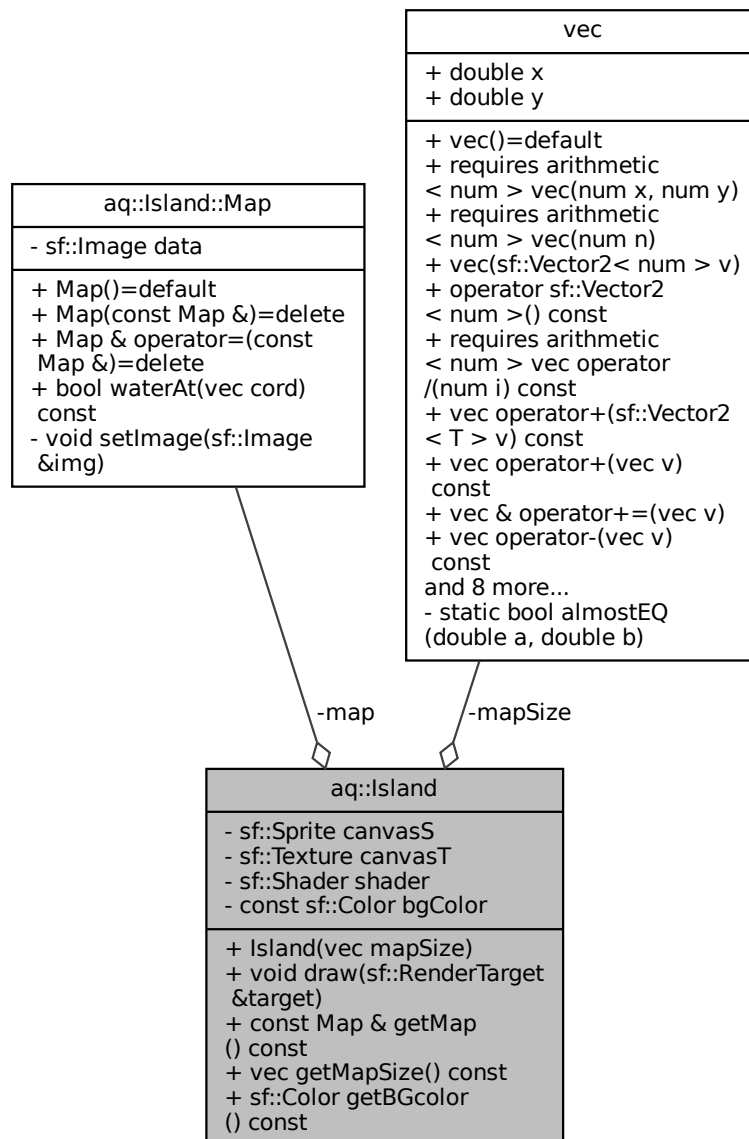
## 4.9 aq::Island Class Reference

Responsible for handleing the island shader.

```
#include <island.hpp>
```



Collaboration diagram for aq::Island:



## Classes

- struct [Map](#)

*A non-copyable class that represents the map of the islands.*

## Public Member Functions

- [Island](#) ([vec](#) mapSize)  
*Loads the openGL(GLSL) shader.*
- void **draw** (sf::RenderTarget &target)

- const `Map` & `getMap` () const
- `vec` `getMapSize` () const
- `sf::Color` `getBGcolor` () const

## Private Attributes

- `sf::Sprite` `canvasS`
- `sf::Texture` `canvasT`
- `sf::Shader` `shader`
- `vec` `mapSize`
- `Map` `map`
- const `sf::Color` `bgColor` = `sf::Color`(19, 109, 21)

### 4.9.1 Detailed Description

Responsible for handling the island shader.

### 4.9.2 Constructor & Destructor Documentation

#### 4.9.2.1 `Island()`

```
Island::Island (
    vec mapSize ) [explicit]
```

Loads the openGL(GLSL) shader.

#### Exceptions

<i>if</i>	an error occurs while loading and compiling the shader
-----------	--

The documentation for this class was generated from the following files:

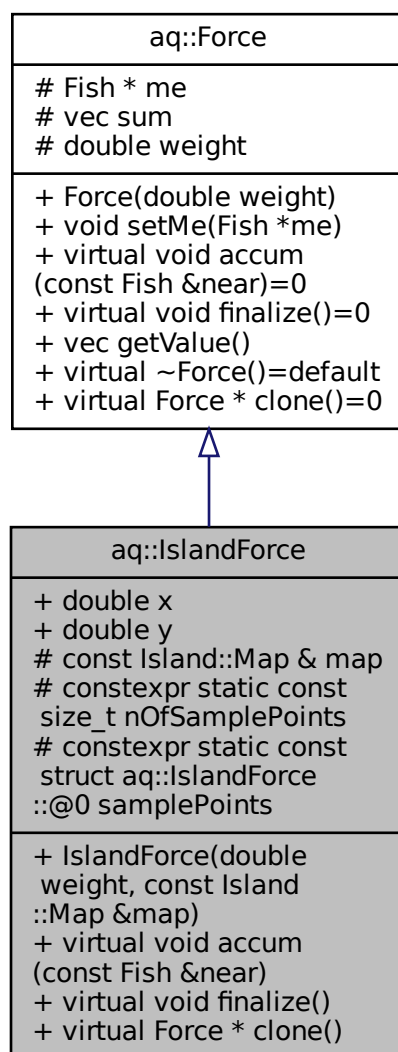
- `inc/island.hpp`
- `src/island.cpp`

## 4.10 `aq::IslandForce` Class Reference

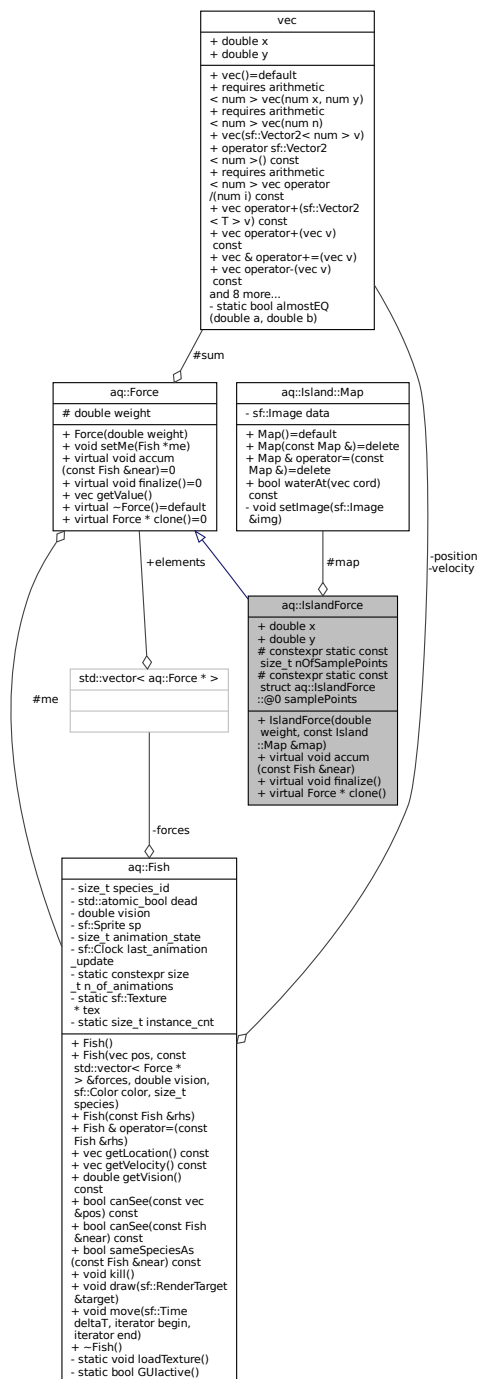
`Fish` want to stay in the water.

```
#include <forces.hpp>
```

Inheritance diagram for aq::IslandForce:



Collaboration diagram for `aq::IslandForce`:



## Public Member Functions

- **IslandForce** (double weight, const `Island::Map` &map)
- virtual void **accum** (const `Fish` &near)

*Should be called for each fish in the vicinity.*

- virtual void **finalize** ()

*After accumulation finalize the calculation.*

- virtual [Force](#) \* [clone](#) ()  
*Clones the force.*

## Protected Attributes

- const [Island::Map](#) & [map](#)

## Static Protected Attributes

- constexpr static const size\_t [nOfSamplePoints](#) = 36
- struct {  
    double [x](#)  
    double [y](#)  
} [samplePoints](#) [[nOfSamplePoints](#)]

### 4.10.1 Detailed Description

[Fish](#) want to stay in the water.

### 4.10.2 Member Function Documentation

#### 4.10.2.1 [clone\(\)](#)

```
virtual Force* aq::IslandForce::clone ( ) [inline], [virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the me pointer reset

Implements [aq::Force](#).

### 4.10.3 Member Data Documentation

**4.10.3.1**

```
constexpr { ... } aq::IslandForce::samplePoints[nOfSamplePoints] [static], [protected]
```

**Initial value:**

```
=
    {{1.000, 0.000}, {0.940, 0.342}, {0.766, 0.643}, {0.500, 0.866}, {0.174, 0.985}, {-0.174, 0.985},
    {-0.500, 0.866}, {-0.766, 0.643}, {-0.940, 0.342}, {-1.000, 0.000}, {-0.940, -0.342}, {-0.766,
    -0.643}, {-0.500, -0.866}, {-0.174, -0.985}, {0.174, -0.985}, {0.500, -0.866}, {0.766, -0.643},
    {0.940, -0.342}, {0.667, 0.000}, {0.577, 0.333}, {0.333, 0.577}, {0.000, 0.667}, {-0.333, 0.577},
    {-0.577, 0.333}, {-0.667, 0.000}, {-0.577, -0.333}, {-0.333, -0.577}, {-0.000, -0.667}, {0.333,
    -0.577}, {0.577, -0.333}, {0.333, 0.000}, {0.167, 0.289}, {-0.167, 0.289}, {-0.333, 0.000}, {-0.167,
    -0.289}, {0.167, -0.289}}
```

The documentation for this class was generated from the following file:

- inc/forces.hpp

**4.11 aq::Net::LocalizedIterator Class Reference**

Iterates over the cells in the visual range of a fish.

```
#include <net.hpp>
```



- Generated by Doxygen

- [LocalizedIterator](#) **operator++** (int)
- bool **operator!=** (const [LocalizedIterator](#) &rhs)

### Private Member Functions

- [vec](#) **currCord** () const
- void **updatelters** ()

### Private Attributes

- [Net](#) & **net**
- const [vec](#) **centerCord**
- cell::iterator **currIter**
- cell::iterator **currEnd**
- size\_t **idx** {0}

#### 4.11.1 Detailed Description

Iterates over the cells in the visual range of a fish.

The documentation for this class was generated from the following files:

- inc/net.hpp
- src/iter.cpp

## 4.12 aq::Island::Map Struct Reference

A non-copyable class that represents the map of the islands.

```
#include <island.hpp>
```

Collaboration diagram for aq::Island::Map:

aq::Island::Map
- sf::Image data
+ Map()=default + Map(const Map &)=delete + Map & operator=(const Map &)=delete + bool waterAt(vec cord) const - void setImage(sf::Image &img)



## Public Member Functions

- **Map** (const [Map](#) &)=delete
- [Map](#) & **operator=** (const [Map](#) &)=delete
- bool **waterAt** ([vec](#) cord) const

## Private Member Functions

- void **setImage** (sf::Image &img)

## Private Attributes

- sf::Image **data**

## Friends

- class **Island**

### 4.12.1 Detailed Description

A non-copyable class that represents the map of the islands.

The documentation for this struct was generated from the following files:

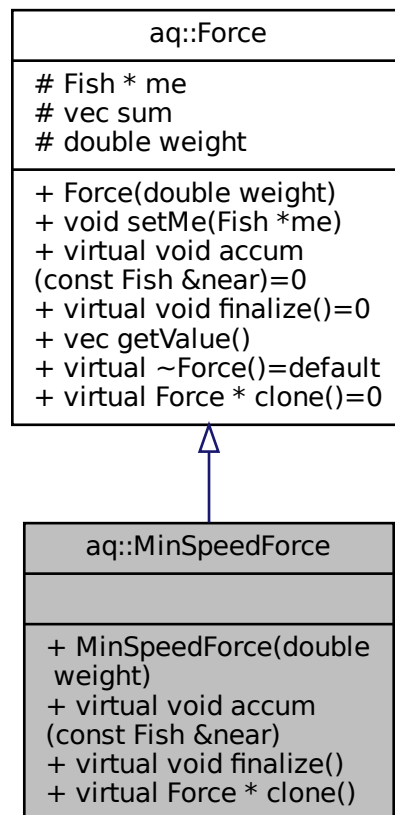
- inc/island.hpp
- src/island.cpp

## 4.13 aq::MinSpeedForce Class Reference

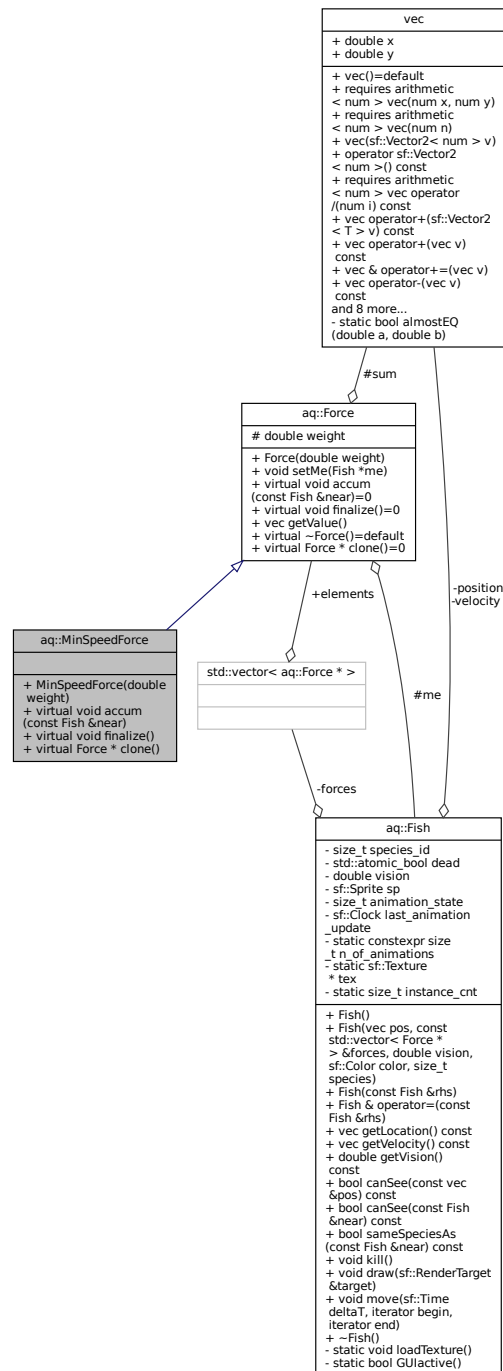
[Fish](#) dont want to go too slow.

```
#include <forces.hpp>
```

Inheritance diagram for aq::MinSpeedForce:



Collaboration diagram for aq::MinSpeedForce:



## Public Member Functions

- **MinSpeedForce** (double weight)
- virtual void **accum** (const **Fish** &near)
  - Should be called for each fish in the vicinity.*
- virtual void **finalize** ()
  - After accumulation finalize the calculation.*

- virtual [Force](#) \* [clone](#) ()  
*Clones the force.*

## Additional Inherited Members

### 4.13.1 Detailed Description

[Fish](#) dont want to go too slow.

### 4.13.2 Member Function Documentation

#### 4.13.2.1 clone()

```
virtual Force* aq::MinSpeedForce::clone ( ) [inline], [virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the me pointer reset

Implements [aq::Force](#).

The documentation for this class was generated from the following file:

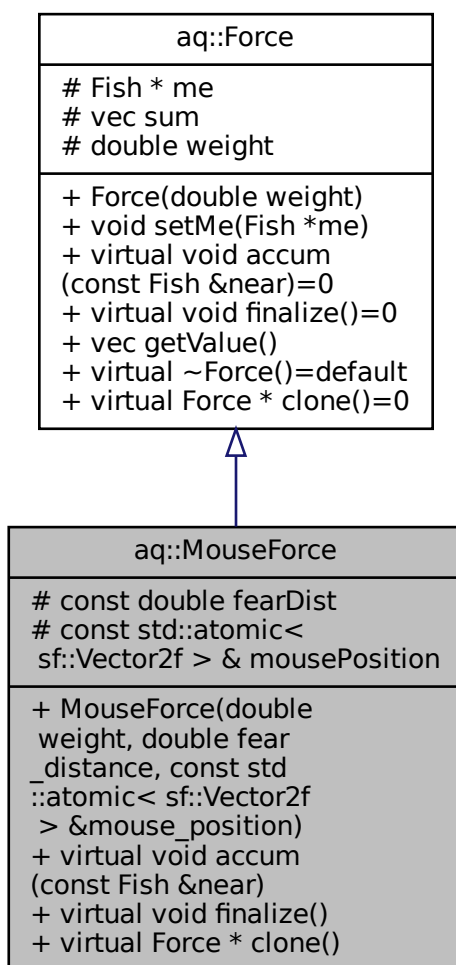
- inc/forces.hpp

## 4.14 [aq::MouseForce](#) Class Reference

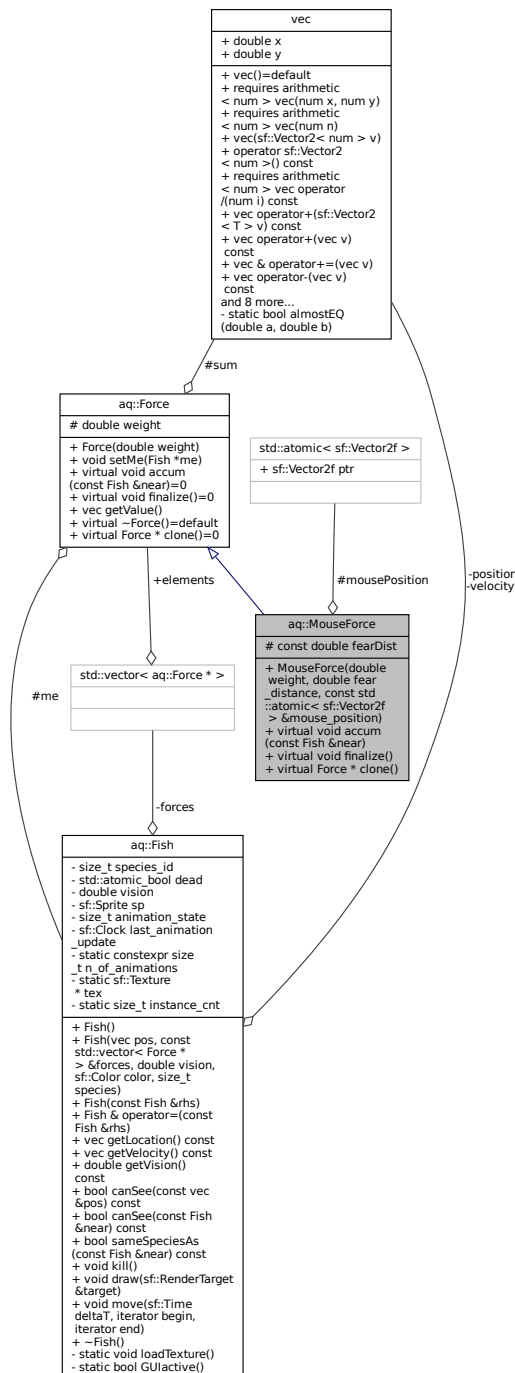
[Fish](#) fear the mouse.

```
#include <forces.hpp>
```

Inheritance diagram for aq::MouseForce:



Collaboration diagram for `aq::MouseForce`:



## Public Member Functions

- **MouseForce** (double weight, double fear\_distance, const std::atomic< sf::Vector2f > &mouse\_position)
- virtual void **accum** (const **Fish** &near)
  - Should be called for each fish in the vicinity.*
- virtual void **finalize** ()
  - After accumulation finalize the calculation.*

- virtual [Force](#) \* [clone](#) ()  
*Clones the force.*

## Protected Attributes

- const double **fearDist**
- const std::atomic< sf::Vector2f > & **mousePosition**

### 4.14.1 Detailed Description

[Fish](#) fear the mouse.

### 4.14.2 Member Function Documentation

#### 4.14.2.1 clone()

```
virtual Force* aq::MouseForce::clone ( ) [inline], [virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the me pointer reset

Implements [aq::Force](#).

The documentation for this class was generated from the following file:

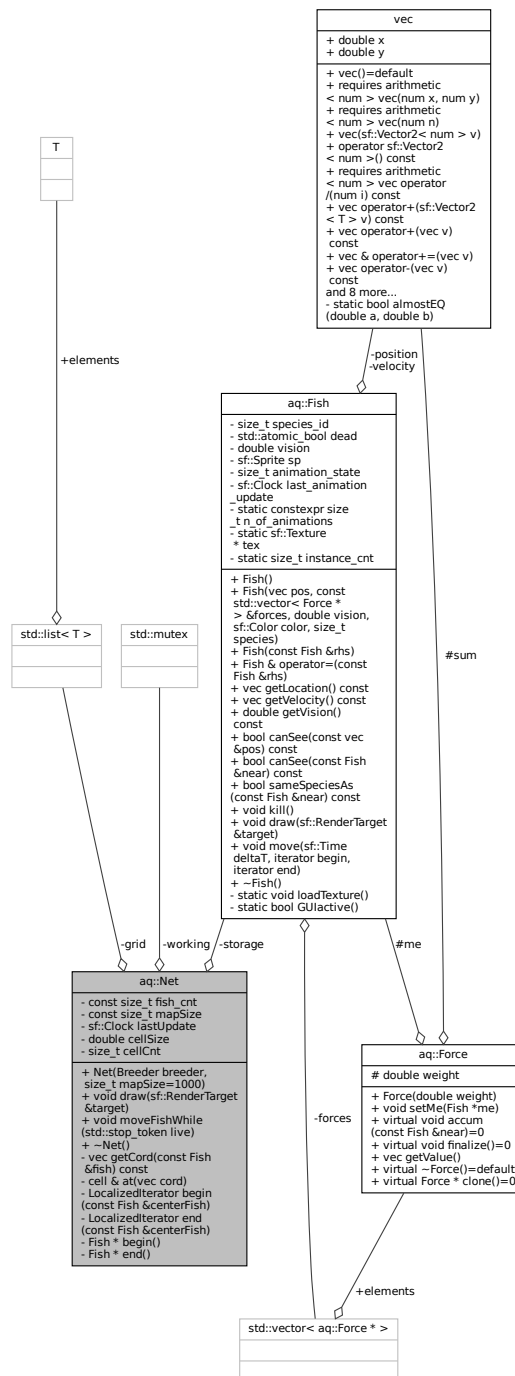
- inc/forces.hpp

## 4.15 aq::Net Class Reference

The net stores the fish and provides a cell based LUT.

```
#include <net.hpp>
```

Collaboration diagram for aq::Net:





## Classes

- class [LocalizedIterator](#)  
*Iterates over the cells in the visual range of a fish.*

## Public Types

- using **cell** = std::list< [Fish](#) \* >

## Public Member Functions

- **Net** ([Breeder](#) breeder, size\_t mapSize=1000)
- void **draw** (sf::RenderTarget &target)
- void [moveFishWhile](#) (std::stop\_token live)  
*Infinitely loop that moves the fish until another thread sets live to false.*

## Private Member Functions

- [vec](#) **getCord** (const [Fish](#) &fish) const
- cell & **at** ([vec](#) cord)
- [LocalizedIterator](#) **begin** (const [Fish](#) &centerFish)
- [LocalizedIterator](#) **end** (const [Fish](#) &centerFish)
- [Fish](#) \* **begin** ()
- [Fish](#) \* **end** ()

## Private Attributes

- const size\_t **fish\_cnt**
- [Fish](#) \* **storage**
- const size\_t **mapSize**
- sf::Clock **lastUpdate**
- std::mutex **working**
- cell \*\* **grid**
- double **cellSize**
- size\_t **cellCnt**

### 4.15.1 Detailed Description

The net stores the fish and provides a cell based LUT.

### 4.15.2 Member Function Documentation

#### 4.15.2.1 moveFishWhile()

```
void Net::moveFishWhile (
    std::stop_token live )
```

Infinitely loop that moves the fish until another thread sets live to false.

##### Returns

after live is set to false and the last iteration is finished

The documentation for this class was generated from the following files:

- inc/net.hpp
- src/net.cpp

## 4.16 shader::PerlinNoise Class Reference

Simple 2D perlin noise shader.

Collaboration diagram for shader::PerlinNoise:

shader::PerlinNoise
+ uniform vec2 u_map_size + uniform float u_edge_ratio + uniform vec2 u_seed + uniform int u_octaves + uniform float u_gridSize + uniform float u_amplitude + uniform float u_water_level + uniform float u_sand_level + uniform float u_bw_mode + uniform vec4 col_low_water and 8 more...
+ float interpolate(float a, float b, float w) + float cap(float value) + vec2 randomGradient(ivec2 cord) + float dotGridGradient(ivec2 cord, vec2 pos) + float perlin(vec2 pos) + float fractalNoise(vec2 pos) + vec4 colorFromHeight(float height) + vec2 slope(vec2 pos) + float edgeCurve(vec2 pos) + void main()

## Public Member Functions

- float [interpolate](#) (float a, float b, float w)  
*Smoothly interpolates between two values.*
- float [cap](#) (float value)  
*Caps a value between [0, 1].*
- vec2 [randomGradient](#) (ivec2 cord)  
*Computes a pseudo random gradient vector for a given integer coordinate.*
- float [dotGridGradient](#) (ivec2 cord, vec2 pos)  
*Computes the dot product of a random gradient vector and a given position.*
- float [perlin](#) (vec2 pos)  
*2D Perlin noise*
- float [fractalNoise](#) (vec2 pos)  
*Computes a fractal sum of perlin noise.*
- vec4 [colorFromHeight](#) (float height)  
*Computes a color based on the height.*
- vec2 [slope](#) (vec2 pos)
- float [edgeCurve](#) (vec2 pos)
- void [main](#) ()  
*Main function.*

## Public Attributes

- uniform vec2 [u\\_map\\_size](#)  
*Size of the map.*
- uniform float [u\\_edge\\_ratio](#)  
*Point where the edge starts to curve up.*
- uniform vec2 [u\\_seed](#)  
*Seed used as offset.*
- uniform int [u\\_octaves](#)  
*Number of patterns to sum.*
- uniform float [u\\_gridSize](#)  
*Size of the grid.*
- uniform float [u\\_amplitude](#)  
*Start amplitude of the noise.*
- uniform float [u\\_water\\_level](#)  
*Threshold for water [0, 1].*
- uniform float [u\\_sand\\_level](#)  
*Threshold for sand [0, 1].*
- uniform float [u\\_bw\\_mode](#)  
*B&W mask mode toggle, 0 or 1.*
- uniform vec4 [col\\_low\\_water](#)  
*Color for deep water.*
- uniform vec4 [col\\_high\\_water](#)  
*Color for shallow water.*
- uniform vec4 [col\\_low\\_sand](#)  
*Color for low sand.*
- uniform vec4 [col\\_high\\_sand](#)  
*Color for high sand.*
- uniform vec4 [col\\_low\\_grass](#)

*Color for low grass.*

- uniform vec4 `col_high_grass`

*Color for high grass.*

- uniform vec2 `u_resolution`

*Size of the window.*

- uniform vec2 `u_top_left`

*Top left corner of the visible area.*

- uniform vec2 `u_bottom_right`

*Bottom right corner of the visible area.*

### 4.16.1 Detailed Description

Simple 2D perlin noise shader.

Code based on the the Perlin noise wikipedia page: [https://en.wikipedia.org/wiki/Perlin\\_noise](https://en.wikipedia.org/wiki/Perlin_noise)

Remarks

**Fragment-Shader**

### 4.16.2 Member Function Documentation

#### 4.16.2.1 colorFromHeight()

```
vec4 shader::PerlinNoise::colorFromHeight (
    float height ) [inline]
```

Computes a color based on the height.

Parameters

<i>height</i>	in [0, 1]
---------------	-----------

#### 4.16.2.2 fractalNoise()

```
float shader::PerlinNoise::fractalNoise (
    vec2 pos ) [inline]
```

Computes a fractal sum of perlin noise.

Returns

[0, 1]

### 4.16.2.3 **perlin()**

```
float shader::PerlinNoise::perlin (
    vec2 pos ) [inline]
```

2D Perlin noise

#### Parameters

<i>pos</i>	Position in 2D space
------------	----------------------

#### Returns

[-1, 1]

### 4.16.2.4 **randomGradient()**

```
vec2 shader::PerlinNoise::randomGradient (
    ivec2 cord ) [inline]
```

Computes a pseudo random gradient vector for a given integer coordinate.

#### Returns

Vector with length 1

The documentation for this class was generated from the following file:

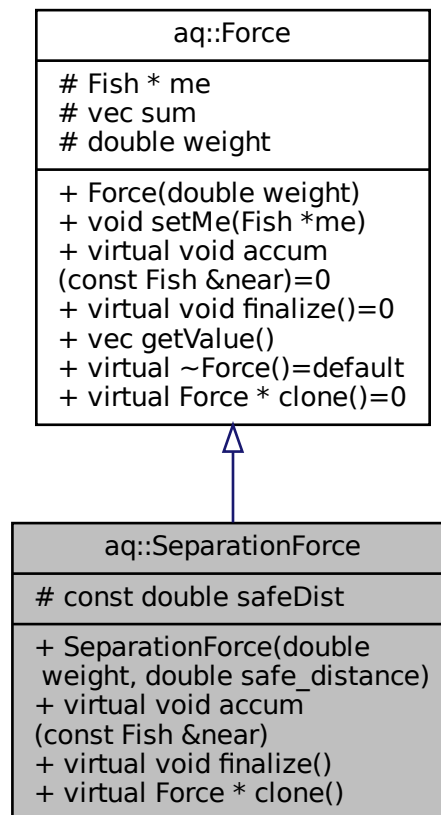
- `src/perlin.frag`

## 4.17 **aq::SeparationForce Class Reference**

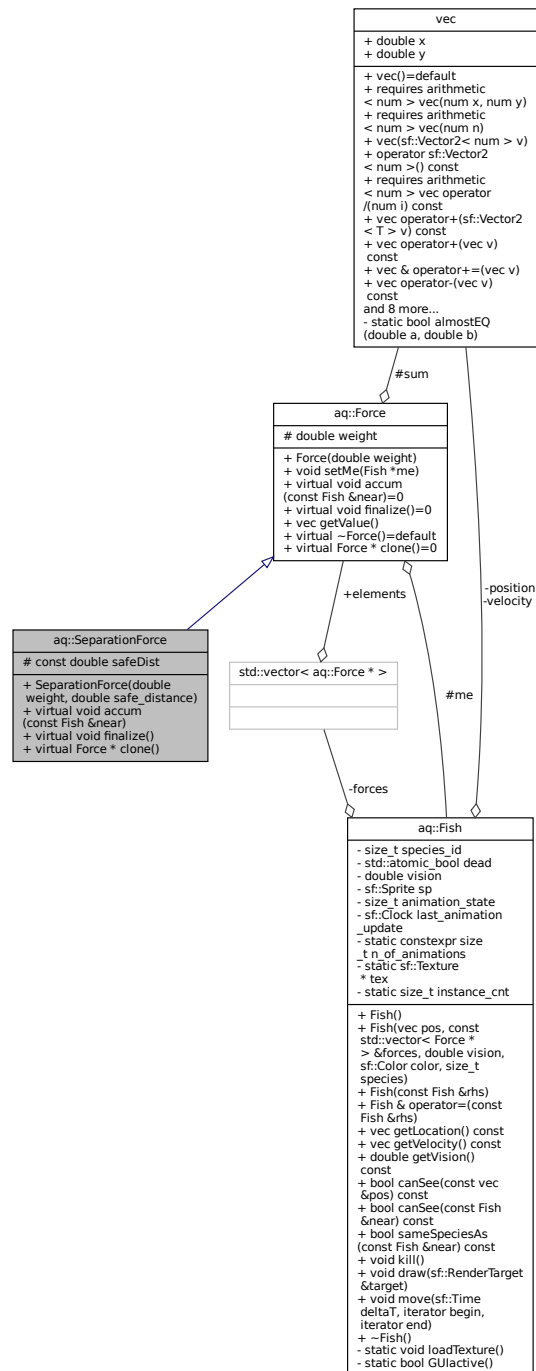
[Fish](#) want to keep a safe distance from each other.

```
#include <forces.hpp>
```

Inheritance diagram for `aq::SeparationForce`:



Collaboration diagram for `aq::SeparationForce`:



## Public Member Functions

- **SeparationForce** (double weight, double safe\_distance)
- virtual void **accum** (const **Fish** &near)
  - Should be called for each fish in the vicinity.*
- virtual void **finalize** ()
  - After accumulation finalize the calculation.*

- virtual [Force](#) \* [clone](#) ()  
*Clones the force.*

## Protected Attributes

- const double **safeDist**

### 4.17.1 Detailed Description

[Fish](#) want to keep a safe distance from each other.

### 4.17.2 Member Function Documentation

#### 4.17.2.1 [clone\(\)](#)

```
virtual Force* aq::SeparationForce::clone ( ) [inline], [virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the me pointer reset

Implements [aq::Force](#).

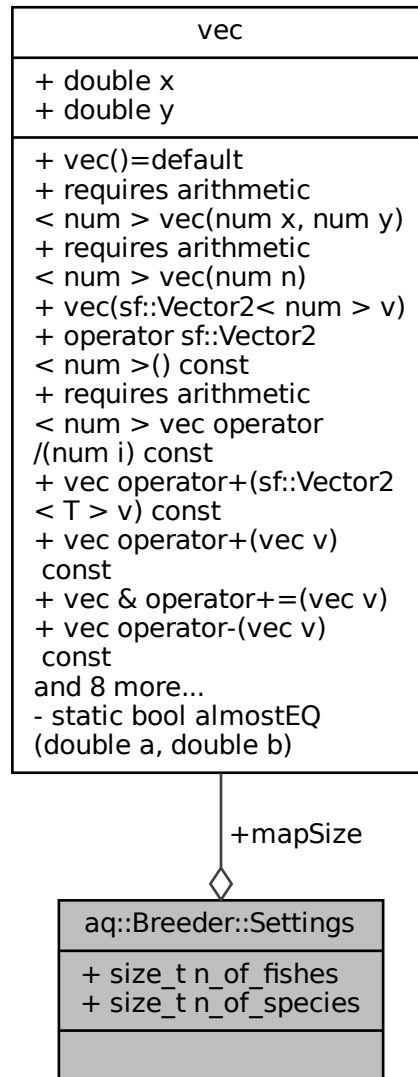
The documentation for this class was generated from the following file:

- inc/forces.hpp



## 4.18 aq::Breeder::Settings Struct Reference

Collaboration diagram for aq::Breeder::Settings:



### Public Attributes

- `size_t n_of_fishes` = 100
- `size_t n_of_species` = 1
- `vec mapSize`

The documentation for this struct was generated from the following file:

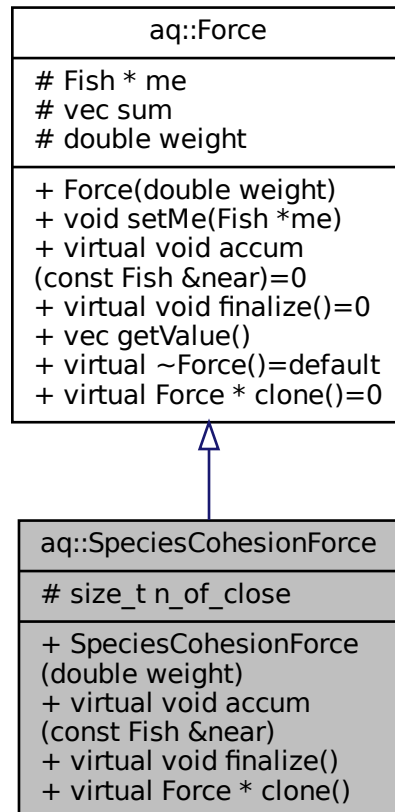
- `inc/breeder.hpp`

## 4.19 aq::SpeciesCohesionForce Class Reference

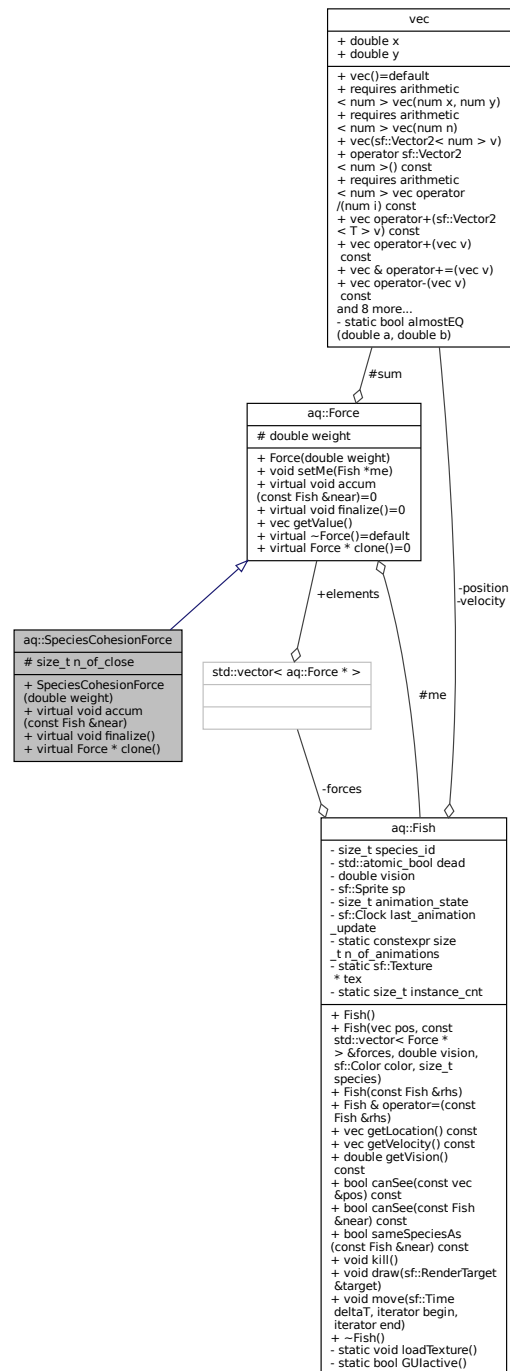
[Fish](#) want to stay close to fish of the same species.

```
#include <forces.hpp>
```

Inheritance diagram for aq::SpeciesCohesionForce:



Collaboration diagram for aq::SpeciesCohesionForce:



## Public Member Functions

- **SpeciesCohesionForce** (double weight)
- virtual void **accum** (const **Fish** &near)  
Should be called for each fish in the vicinity.
- virtual void **finalize** ()  
After accumulation finalize the calculation.

- virtual [Force](#) \* [clone](#) ()  
*Clones the force.*

## Protected Attributes

- `size_t n_of_close {0}`

### 4.19.1 Detailed Description

[Fish](#) want to stay close to fish of the same species.

### 4.19.2 Member Function Documentation

#### 4.19.2.1 [clone\(\)](#)

```
virtual Force* aq::SpeciesCohesionForce::clone ( ) [inline], [virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the me pointer reset

Implements [aq::Force](#).

The documentation for this class was generated from the following file:

- `inc/forces.hpp`

## 4.20 [vec](#) Struct Reference

A 2D vector.

```
#include <vec.hpp>
```

Collaboration diagram for vec:

vec
+ double x + double y
+ vec()=default + requires arithmetic < num > vec(num x, num y) + requires arithmetic < num > vec(num n) + vec(sf::Vector2< num > v) + operator sf::Vector2 < num >() const + requires arithmetic < num > vec operator /(num i) const + vec operator+(sf::Vector2 < T > v) const + vec operator+(vec v) const + vec & operator+=(vec v) + vec operator-(vec v) const and 8 more... - static bool almostEQ (double a, double b)

## Public Member Functions

- template<typename num >  
requires arithmetic< num > **vec** (num x, num y)
- template<typename num >  
requires arithmetic< num > **vec** (num n)
- template<typename num >  
**vec** (sf::Vector2< num > v)
- template<typename num >  
**operator sf::Vector2< num > ()** const
- template<typename num >  
requires arithmetic< num > **vec operator/** (num i) const
- template<typename T >  
**vec operator+** (sf::Vector2< T > v) const
- **vec operator+** (vec v) const
- **vec & operator+=** (vec v)
- **vec operator-** (vec v) const
- template<typename T >  
**vec operator-** (sf::Vector2< T > v) const
- **vec & operator-=** (vec v)
- bool **operator==** (vec v) const

- *true if difference is less than 1.0E-10*
- `bool operator!= (vec v) const`
- `double len () const`
- `vec norm () const`  
*Returns a normalized vector.*
- `bool wholeEQ (vec v) const`  
*true if the whole part of the vector is equal*
- `sf::Vector2< ssize_t > whole () const`  
*Rounds down the coordinates.*

## Public Attributes

- `double x {0}`
- `double y {0}`

## Static Private Member Functions

- `static bool almostEQ (double a, double b)`

## Friends

- `template<typename num >`  
`requires arithmetic< num > friend vec operator* (vec v, num i)`
- `template<typename num >`  
`requires arithmetic< num > friend vec operator* (num i, vec v)`
- `template<typename T >`  
`vec operator+ (sf::Vector2< T > v1, vec v2)`
- `template<typename T >`  
`vec operator- (sf::Vector2< T > v1, vec v2)`
- `std::ostream & operator<< (std::ostream &os, vec v)`

### 4.20.1 Detailed Description

A 2D vector.

Internally uses double for the coordinates. Fully compatible with SFML's `sf::Vector2` class.

### 4.20.2 Member Function Documentation

#### 4.20.2.1 norm()

```
vec vec::norm ( ) const [inline]
```

Returns a normalized vector.

#### Returns

if the length is less than 1.0E-10 a random direction is chosen

## 4.20.2.2 wholeEQ()

```
bool vec::wholeEQ (
    vec v ) const [inline]
```

true if the whole part of the vector is equal

rounds down

The documentation for this struct was generated from the following file:

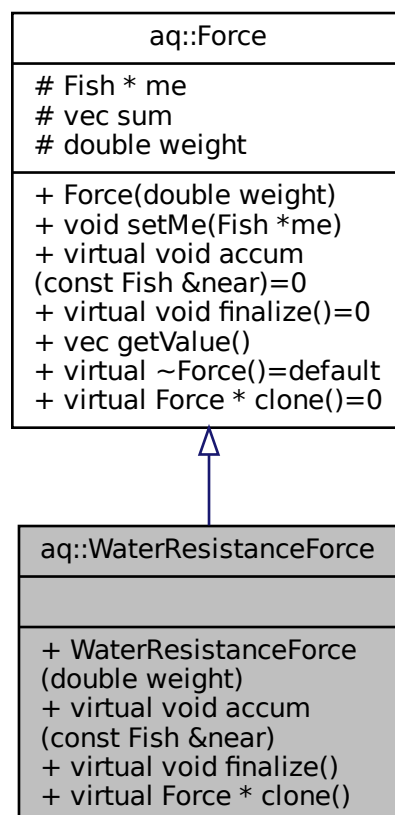
- inc/vec.hpp

## 4.21 aq::WaterResistanceForce Class Reference

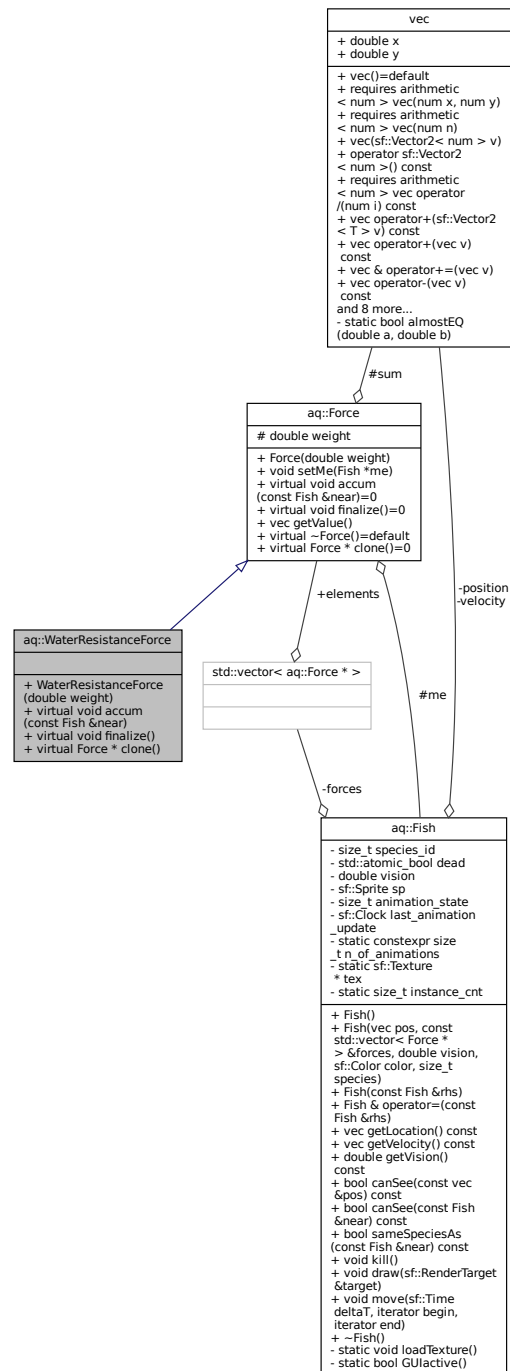
[Fish](#) get slowed down by the water.

```
#include <forces.hpp>
```

Inheritance diagram for aq::WaterResistanceForce:



Collaboration diagram for `aq::WaterResistanceForce`:



## Public Member Functions

- **WaterResistanceForce** (double weight)
- virtual void **accum** (const **Fish** &near)  
Should be called for each fish in the vicinity.
- virtual void **finalize** ()  
After accumulation finalize the calculation.



- virtual `Force * clone ()`  
*Clones the force.*

## Additional Inherited Members

### 4.21.1 Detailed Description

`Fish` get slowed down by the water.

### 4.21.2 Member Function Documentation

#### 4.21.2.1 `clone()`

```
virtual Force* aq::WaterResistanceForce::clone ( ) [inline], [virtual]
```

Clones the force.

#### Returns

A dynamically allocated copy of the force, with the me pointer reset

Implements `aq::Force`.

The documentation for this class was generated from the following file:

- `inc/forces.hpp`



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