PREV CLASS NEXT CLASS

FRAMES NO FRAMES

ALL CLASSES

SUMMARY: NESTED | FIELD | CONSTR | METHOD

DETAIL: FIELD | CONSTR | METHOD

pacsim

# **Class PacUtils**

java.lang.Object pacsim.PacUtils

public class PacUtils
extends java.lang.Object

Multi-modal AI Simulator Utilities

# **Constructor Summary**

**Constructors** 

**Constructor and Description** 

PacUtils()

# **Method Summary**

All Methods Static Methods Concrete M	ethods
Modifier and Type	Method and Description
static PacFace	<pre>anyRandomForGhost(java.awt.Point curr, PacCell[] [] cell) Choose a random direction where the next cell is not a ghost or wall cell NOTE: this method should be used when in CHASE or SCATTER mode,</pre>
static PacFace	<pre>avoidTarget(java.awt.Point p, java.awt.Point t, PacCell[][] cell) Choose an available direction that maximizes the distance from a given target</pre>
static PacCell[][]	<pre>cloneGrid(PacCell[][] array) Clone a PacCell grid</pre>
static java.util.List <java.awt.point></java.awt.point>	<pre>clonePointList(java.util.List<java.awt.point> list) Clone a list of Point objects</java.awt.point></pre>
static double	<pre>euclideanDistance(int x1, int y1, int x2, int y2) Compute the Euclidean distance between two points</pre>
static double	<pre>euclideanDistance(java.awt.Point p1, java.awt.Point p2) Compute the Euclidean distance between two points</pre>

static PacFace	<pre>euclideanShortestToTarget(java.awt.Point curr, PacFace face, java.awt.Point target, PacCell[] [] cell) Chose the available direction that most closely approaches a target, using the Euclidean distance measure, but not the opposite of the current direction; ties are broken randomly NOTE: This method returns null if the only option is to reverse.</pre>
static java.util.List <java.awt.point></java.awt.point>	findGhosts(PacCell[][] state) Find all the ghosts on the current board
static PacmanCell	<pre>findPacman(PacCell[][] state) Find Pac-Man if he is on the board (for simulation experiments)</pre>
static StartCell	<pre>findStart(PacCell[][] state) Find the start cell, if any (for search problems)</pre>
static boolean	<pre>food(int x, int y, PacCell[][] c) Determine whether the current cell contains a food pellet</pre>
static boolean	<pre>foodRemains(PacCell[][] state) Determine whether any food remains on the board</pre>
static boolean	<pre>goody(int x, int y, PacCell[][] c) Determine whether the current cell contains either food or a power pellet</pre>
static int	manhattanDistance(int x1, int y1, int x2, int y2) Compute the Manhattan distance between two point locations
static int	<pre>manhattanDistance(java.awt.Point p1, java.awt.Point p2) Compute the Manhattan distance between two point locations</pre>
static PacFace	<pre>manhattanShortestToTarget(java.awt.Point curr, PacFace face, java.awt.Point target, PacCell[] [] cell) Chose the available direction that most closely approaches a target, using the Manhattan distance measure, but not the opposite of the current direction; ties are broken randomly</pre>
static PacCell[][]	<pre>moveGhost(java.awt.Point curr, java.awt.Point next, PacCell[][] array) Move a ghost on an input grid This method does nothing if a ghost cannot be found at location curr or if next is not immediately adjacent.</pre>
static PacCell[][]	<pre>movePacman(java.awt.Point curr, java.awt.Point next, PacCell[][] array) Move Pacman on an input grid This method does nothing if Pacman cannot be found at location curr or if next is not immediately adjacent.</pre>
static java.awt.Point	<pre>nearestFood(java.awt.Point p, PacCell[][] cell) Find the nearest food pellet, if any</pre>
static GhostCell	<pre>nearestGhost(java.awt.Point p, PacCell[][] cell) Find the nearest ghost, if any</pre>

static java.awt.Point	<pre>nearestGoody(java.awt.Point p, PacCell[][] cell) Find the nearest food or power pellet cell, if any</pre>
static java.awt.Point	<pre>nearestGoodyButNot(java.awt.Point p, java.awt.Point tgt, PacCell[][] cell) Find the nearest food or power pellet cell, but not a particular goody</pre>
static java.awt.Point	<pre>nearestPower(java.awt.Point p, PacCell[][] cell) Find the nearest power cell, if any</pre>
static java.awt.Point	<pre>nearestUnoccupied(java.awt.Point p, PacCell[] [] cell) Find the nearest unoccupied cell; if cannot find one, then choose a random unoccupied cell</pre>
static PacCell	<pre>neighbor(PacFace face, PacCell pc, PacCell[][] cell) Find the immediate neighbor of a given cell in a particular direction</pre>
static PacCell	<pre>neighbor(PacFace face, java.awt.Point p, PacCell[] [] cell) Find the immediate neighbor of a given cell location in a particular direction</pre>
static int	<pre>numFood(PacCell[][] state) Determine how many food dots remain on the board</pre>
static int	<pre>numPower(PacCell[][] state) Determine how many power pellets remain on the board</pre>
static boolean	oppositeFaces (PacFace a, PacFace b)  Determine whether two facing directions are opposites
static boolean	<pre>power(int x, int y, PacCell[][] c) Determine whether the current cell contains a power pellet</pre>
static PacFace	<pre>randomNotReverse(java.awt.Point curr, PacFace face, java.awt.Point target, PacCell[][] cell) Choose a random available direction but not the opposite of the current direction</pre>
static PacFace	<pre>randomOpenForGhost(java.awt.Point curr, PacCell[] [] cell) Choose a random direction where the next cell is not a ghost, wall, or Pac-Man NOTE: this method should be used when in FEAR mode (so can't go to Pac-Man cell)</pre>
static PacFace	<pre>randomOpenForPacman(java.awt.Point curr, PacCell[] [] cell) Choose a random facing direction that is not in the direction of a ghost, house, or wall cell</pre>
static PacFace	reverse(PacFace face) Find the opposite facing direction
static boolean	<pre>unoccupied(int x, int y, PacCell[][] c) Determine whether a particular cell is unoccupied</pre>

# Methods inherited from class java.lang.Object

clone, equals, finalize, getClass, hashCode, notify, notifyAll, toString, wait, wait, wait

## Constructor Detail

### **PacUtils**

public PacUtils()

## **Method Detail**

#### findStart

```
public static StartCell findStart(PacCell[][] state)
```

Find the start cell, if any (for search problems)

## Parameters:

state - the cell array to examine

#### Returns:

the Start Cell, if any

#### findPacman

```
public static PacmanCell findPacman(PacCell[][] state)
```

Find Pac-Man if he is on the board (for simulation experiments)

### Parameters:

state - the cell array to examine

#### Returns:

the Pac-Man cell, if any

## findGhosts

```
public static java.util.List<java.awt.Point> findGhosts(PacCell[][] state)
```

Find all the ghosts on the current board

### Parameters:

state - the cell array to examine

## Returns:

a list containing the ghost cells, if any

## **foodRemains**

```
public static boolean foodRemains(PacCell[][] state)

Determine whether any food remains on the board

Parameters:
state - the cell array to examine

Returns:
T/F
```

### numFood

```
public static int numFood(PacCell[][] state)

Determine how many food dots remain on the board

Parameters:
state - the cell array to examine

Returns:
```

number of remaining food dots

## numPower

```
public static int numPower(PacCell[][] state)

Determine how many power pellets remain on the board

Parameters:
state - the cell array to examine

Returns:
number of remaining power pellets
```

# neighbor

the immediate neighbor of the cell in the input direction, if any

## neighbor

#### manhattanDistance

the immediate neighbor of the cell in the input direction, if any

#### Parameters:

```
p1 - the first point
p2 - the second point
```

#### Returns:

non-negative integer distance

### manhattanDistance

Compute the Manhattan distance between two point locations

#### Parameters:

```
x1 - x-coordinate of first point
y1 - y-coordinate of first point
x2 - x-coordinate of second point
y2 - y-coordinate of second point
Returns:
non-negative integer distance
```

## man hattan Shortest To Target

Chose the available direction that most closely approaches a target, using the Manhattan distance measure, but not the opposite of the current direction; ties are broken randomly

#### Parameters:

```
curr - the current location
face - the current facing direction
target - the target location
cell - the cell array to examine
Returns:
a facing direction
```

#### euclideanDistance

#### **Parameters:**

```
p1 - the first point
p2 - the second point
```

#### Returns:

a real-valued distance

## euclideanDistance

Compute the Euclidean distance between two points

#### Parameters:

```
x1 - x-coordinate of first point
y1 - y-coordinate of first point
x2 - x-coordinate of second point
y2 - y-coordinate of second point
Returns:
```

## euclideanShortestToTarget

a real-valued distance

Chose the available direction that most closely approaches a target, using the Euclidean distance measure, but not the opposite of the current direction; ties are broken randomly NOTE: This method returns null if the only option is to reverse. In such case, it is usually best to reverse direction and then call this method again.

#### Parameters:

```
curr - the current location
face - the current facing direction
target - the target location
cell - the cell array to examine
Returns:
a facing direction
```

## avoidTarget

Choose an available direction that maximizes the distance from a given target

### Parameters:

```
p - the current location
t - the target location
cell - the cell array to examine
Returns:
a facing direction
```

#### randomNotReverse

Choose a random available direction but not the opposite of the current direction

## Parameters:

```
curr - the current cell location
face - the current facing direction
target - this parameter is not used
cell - the cell array to examine
Returns:
a facing direction
```

### randomOpenForPacman

```
public static PacFace randomOpenForPacman(java.awt.Point curr,
```

```
PacCell[][] cell)
```

Choose a random facing direction that is not in the direction of a ghost, house, or wall cell

#### Parameters:

```
curr - the current cell location
cell - the cell array to examine
```

#### Returns:

a facing direction

## randomOpenForGhost

Choose a random direction where the next cell is not a ghost, wall, or Pac-Man NOTE: this method should be used when in FEAR mode (so can't go to Pac-Man cell)

#### Parameters:

```
curr - the current location

cell - the cell array to examine
```

#### Returns:

a facing direction

## anyRandomForGhost

Choose a random direction where the next cell is not a ghost or wall cell NOTE: this method should be used when in CHASE or SCATTER mode,

#### Parameters:

```
curr - the current location
cell - the cell array to examine
Returns:
a facing direction
```

### nearestGoody

Find the nearest food or power pellet cell, if any

### Parameters:

```
p - the current location
cell - the cell array to examine
```

#### Returns:

the location of the nearest goody, or null

```
nearestFood
```

## nearestPower

## nearestGoodyButNot

the location of the nearest goody

## goody

Determine whether the current cell contains either food or a power pellet

Parameters:

x - the x-coordinate of the current cell

y - the y-coordinate of the current cell

c - the cell array to examine

## food

T/F

Returns:

Determine whether the current cell contains a food pellet

#### Parameters:

```
x - the x-coordinate of the current cell
y - the y-coordinate of the current cell
c - the cell array to examine
```

#### Returns:

T/F

## power

Determine whether the current cell contains a power pellet

## Parameters:

```
x - the x-coordinate of the current cell
y - the y-coordinate of the current cell
c - the cell array to examine
```

## Returns:

T/F

## nearestGhost

#### Parameters:

p - the current location

```
cell - the cell array to examine

Returns:
the nearest ghost
```

## nearestUnoccupied

Find the nearest unoccupied cell; if cannot find one, then choose a random unoccupied cell

#### **Parameters:**

```
p - the current cell location
cell - the cell array to examine
Returns:
```

the nearest or random unoccupied cell

## unoccupied

Determine whether a particular cell is unoccupied

### Parameters:

```
x - the x-coordinate of the input cell y - the y-coordinate of the input cell c - the input cell array
```

### Returns:

T/F

## oppositeFaces

Determine whether two facing directions are opposites

### Parameters:

```
a - the first facing directionb - the second facing direction
```

## Returns:

T/F

#### reverse

```
public static PacFace reverse(PacFace face)

Find the opposite facing direction

Parameters:
face - the input facing direction

Returns:
the opposite direction of face
```

```
cloneGrid
```

```
public static PacCell[][] cloneGrid(PacCell[][] array)

Clone a PacCell grid

Parameters:
array - the input grid

Returns:
a clone of the input
```

#### clonePointList

```
public static java.util.List<java.awt.Point> clonePointList(java.util.List<java.awt.Point> list)

Clone a list of Point objects

Parameters:
list - input list of Points

Returns:
newList, the cloned list
```

#### movePacman

Move Pacman on an input grid This method does nothing if Pacman cannot be found at location curr or if next is not immediately adjacent. Next must not be a wall cell. If next is occupied by a fearful ghost, this method moves it to its home cell, or if occupied, to the nearest unoccupied cell. If the next cell is a power pellet, this method sets all ghosts to fearful, effectively resetting the fear timer if they are already afraid. If the next cell is occupied by a non-fearful ghost, no move is made. This method preserves the underlying base costs and types for all cells moved into.

### Parameters:

```
curr - current Pacman position
next - next Pacman position
array - the input grid
Returns:
grid, the resulting grid after the move
```

## moveGhost

Move a ghost on an input grid This method does nothing if a ghost cannot be found at location curr or if next is not immediately adjacent. Next must not be a wall cell or another ghost. This method preserves the underlying base costs and types for all cells moved into and restores the underlying base cell for curr.

#### Parameters:

```
curr - current ghost position
next - next ghost position
array - the input grid
Returns:
grid, the resulting grid after the move
```

PACKAGE CLASS USE TREE DEPRECATED INDEX HELP

PREV CLASS NEXT CLASS FRAMES NO FRAMES ALL CLASSES

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