

Model Contingency [2] of World on Data (Discriminative)

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July 22, 2018

1. Introduction

At an abstract level, the goal of computer vision problems is to use the observed image data to infer something about the world. For example, it might observe adjacent frames [5] of a video sequence and infer the camera motion, or it might observe a facial image and infer the identity. There are two distinct approaches to modeling the relationship between the world state w and the data x , corresponding to modeling the posterior $\Pr(w|x)$ [3], or the likelihood $\Pr(x|w)$ [1]. The two model types result in different approaches to inference. For the discriminative model [4], it describe the posterior $\Pr(w|x)$ directly.

2. Descriptions

It defines a probability distribution over the world state w and make its parameters contingent on the data x . Since the world state is univariate and continuous, it chose the univariate normal. It fixes the variance, σ^2 and make the mean μ a linear function $\phi_0 + \phi_1 x$ of the data. So it can be seen in Equation 1.

$$\Pr(w|x, \theta) = \text{Norm}_x[\phi_0 + \phi_1 x, \sigma^2] \quad (1)$$

where $\theta = \phi_0, \phi_1, \sigma^2$ are the unknown parameters of the model (Figure 1). This model is referred to as linear regression.

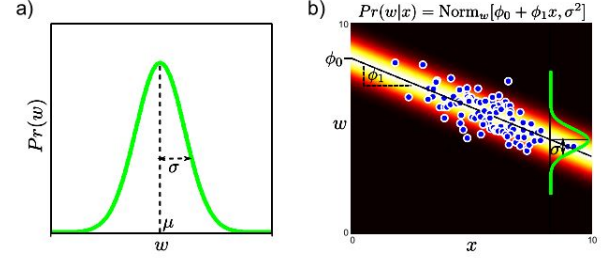


Figure 1. Regression by modeling the posterior $\Pr(w|x)$ (discriminative). a) We model the world state w as normally distributed. b) We make the normal parameters a function of the observations x : the mean is a linear function $\mu = \phi_0 + \phi_1 x$ of the observations, and the variance σ^2 is fixed. The learning algorithm fits the parameters $\theta = \phi_0, \phi_1, \sigma^2$ to example training pairs $x_i, w_{i=1}^I$ (blue dots). In inference we take a new observation x and compute the posterior distribution $\Pr(w|x)$ over the state.

The learning algorithm estimates the model parameters θ from paired training examples $x_i, w_{i=1}^I$. For example, in the MAP approach [6], it need seek in Equation 2.

$$\begin{aligned} \hat{\theta} &= \text{argmax}_{\theta} [\Pr(\theta|w_{1..I}, x_{1..I})] \\ &= \text{argmax}_{\theta} [\Pr(w_{1..I}|x_{1..I}, \theta) \Pr(\theta)] \\ &= \text{argmax}_{\theta} [\prod_{i=1}^I \Pr(w_i|x_i, \theta) \Pr(\theta)] \end{aligned} \quad (2)$$

where assumed that the I training pairs $x_i, w_{i=1}^I$ are independent, and defined a suitable prior $\Pr(\theta)$.

References

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