

# ZONGJIE LIU

Northwestern Polytechnical University

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## EDUCATION

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<b>Northwestern Polytechnical University</b>	Sept. 2021 – Present
<b>Supervisor:</b> Prof. Zhongjie Meng	
Master in Control Engineering	Rank: 6/55
<b>Xidian University</b>	Sept. 2017 – Jul. 2021
B.E. in Aerospace Science and Technology	GPA: 3.6/4.0, Rank: 15/63

## PUBLICATION

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<b>[Aerospace Science and Technology]</b>	<b>Fixed-time attitude control for aircraft with strongly constrained actuators</b>
	<b>Zongjie Liu, Zongjie Meng</b>
	<i>Aerospace Science and Technology</i> , <b>SCI Q1, IF: 5.6</b> , 2023

## MANUSCRIPT

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<b>Impedance-Based Stable Control for Autonomous Airship with Strong Wind-Gust Disturbance</b>
Jianwei Ma, Zhongjie Meng, <b>Zongjie Liu</b> ( <i>Under Review</i> )

## RESEARCH EXPERIENCE

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- **Group of Rigid-Flexible Coupled Aircraft Control, Northwestern Polytechnical University** *Xi'an, China*  
*Graduate Researcher*      *Supervisor: Prof. Zhongjie Meng*      Sept. 2021 – Present  
Research on automatic control of aircraft with constrained actuators.
  - **Group of Aerospace Technology in Electronics, Xidian University** *Xi'an, China*  
*Undergraduate Researcher*      *Advisor: Prof. Kai Xie*      Feb. 2020 – Mar. 2021  
Research on hardware design and embedded systems.

## SELECTED PROJECTS

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- **Controller Design for Trans-medium Aircraft with Strongly Constrained Actuators**    Mar. 2022 – Present
    - **Role:** Core Member
    - **Aim:** to conduct a corrective attitude control system by using strongly constrained actuators (the Reaction Control System, RCS) to satisfy the safety of the fuselage of a trans-medium aircraft before transmitting from air to water.
      - \* Finished modeling of the object aircraft and the strongly constrained actuators;
      - \* Designed an efficient algorithm on thrust allocation to deal with discrete and restricted output of the RCS;
      - \* Proposed a control scheme to achieve rapid attitude adjustment and the performance of this scheme was verified by a Monte Carlo simulation experiment;
      - \* Completed an embedded code implementation of the whole algorithm.
    - **Outcome:**
      - ✓ Produced a first author journal paper, Fixed-time attitude control for aircraft with strongly constrained actuators, which was accepted in *Aerospace Science and Technology*.

- **Controller Design for Autonomous Airships** **Sept. 2021 – Mar. 2022**
  - **Role:** Core Member
  - **Aim:** to design controllers to improve the control performance of a kind of airship which consists of flexible airbags, ropes, and pods in strong winds.
    - \* Contributed to the design of a control command distribution system for longitudinal and lateral channels of an airship for heterogeneous actuators;
    - \* Collected information and had a sharp insight into the concept of impedance control;
    - \* Participated in the design of the controller for airship that can adapt to the strong wind-gust disturbances.
  - **Outcome:**
    - ✓ Produced a third-author paper, Impedance-Based Stable Control for Autonomous Airship with Strong Wind-Gust Disturbance, which was Under Review.
- **Wireless Energy-carrying Communication based on Optical Carrier.** **Jun. 2020 – Dec. 2020**
  - **Role:** Core Member (*In charge of the design of the receiver part*)
  - **Aim:** to design a device which transmits data and power by light.
    - \* Finished the hardware circuit design of the receiver part;
    - \* Competed ultra-low-power programming based on MSP430.
  - **Outcome:**
    - ✓ Produced a sixth-author patent, Secondary dumping type micro-power wireless data binding device and method, which was filed in Apr 2022.
    - ✓ Produced one set of theoretical prototype and two sets of test prototype, the device has been put into production.

## SELECTED AWARDS

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- Outstanding Graduate Student of the 2022-2023 academic year
- First-class Scholarship for graduate student, Northwestern Polytechnical University 2021 & 2022
- Third-class Scholarship for Academic Excellence, Xidian University 2018 & 2019 & 2020&2021
- 2<sup>nd</sup> prize (Top 5%, National Level), National Undergraduate Electronics Design Contest 2019
- 2<sup>nd</sup> prize (Top 8%, Provincial Level), Shaanxi Province Engineering Colleges Intercollege League 2019

## PATENTS

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- Zhongjie Meng, Jianwei Ma, **Zongjie Liu**, Junjie Lu, and De Chen. A Control System and Method for a Tether Grabber Based on Polar Coordinates and Control Weights, CN202210190443.6, filed May 27, 2023
- Kai Xie, Jiangwen Song, Xiaodan Liu, Lei Quan, Lulu Gu, **Zongjie Liu**, Yunchong Guo, Bichen Wu, Kaihen Gu. Secondary dumping type micro-power wireless data binding device and method, CN202110812159.3, filed Apr 05, 2022

## MISC.

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- **Extra Experience:** **Jul. 2022 – Apr. 2023**  
Research-related administrative assistant (Assisting the secretariat in collating research profile)
- **Language:** English (Fluent, IELTS 6.5), Mandarin (Native)
- **Programming:** Python, MATLAB, C
- **Tool:** LaTeX, GIT, Zotero, Altium Designer