


hello_world::devices
::motor::DM_J4310::raw2torq



```
graph LR; A["hello_world::devices<br/>::motor::DM_J4310::raw2torq"] --> B["hello_world::devices<br/>::motor::_Uint2Float"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a gray background and contains the text 'hello_world::devices' followed by '::motor::DM_J4310::raw2torq' on a new line. The right box has a white background and contains the text 'hello_world::devices' followed by '::motor::_Uint2Float' on a new line. The blue arrow originates from the right side of the left box and points towards the left side of the right box.

hello_world::devices
::motor::_Uint2Float