

hello_world::devices
::motor::DM_J4310::DM_J4310

hello_world::devices
::motor::Motor::setInput

hello_world::devices
::motor::DM_J4310::setInput

hello_world::devices
::motor::Motor::torq2curr

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graph LR; A["hello_world::devices<br/>::motor::DM_J4310::DM_J4310"] --> D["hello_world::devices<br/>::motor::Motor::torq2curr"]; B["hello_world::devices<br/>::motor::Motor::setInput"] --> D; C["hello_world::devices<br/>::motor::DM_J4310::setInput"] --> D;
```

The diagram illustrates a directed graph with three source nodes on the left and one target node on the right. The target node is shaded gray, while the source nodes are white with black borders. Three blue arrows point from each source node to the target node. The source nodes contain text representing a namespace and a specific object or method, while the target node contains text representing a namespace and a specific method.