

hello\_world::devices  
::motor::DM\_J4310::DM\_J4310

hello\_world::devices  
::motor::Motor::setInput

hello\_world::devices  
::motor::DM\_J4310::setInput

hello\_world::devices  
::motor::Motor::curr2torq

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graph LR; A["hello_world::devices<br/>::motor::DM_J4310::DM_J4310"] --> D["hello_world::devices<br/>::motor::Motor::curr2torq"]; B["hello_world::devices<br/>::motor::Motor::setInput"] --> D; C["hello_world::devices<br/>::motor::DM_J4310::setInput"] --> D;
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The diagram illustrates a directed graph with three source nodes on the left and one target node on the right. The target node is shaded gray, while the source nodes are white with black borders. Three blue arrows point from each source node to the target node. The source nodes contain the following text: 1. 'hello\_world::devices' followed by '::motor::DM\_J4310::DM\_J4310' on the next line. 2. 'hello\_world::devices' followed by '::motor::Motor::setInput' on the next line. 3. 'hello\_world::devices' followed by '::motor::DM\_J4310::setInput' on the next line. The target node contains the text: 'hello\_world::devices' followed by '::motor::Motor::curr2torq' on the next line.