


```
hello_world::devices  
::motor::DM_J4310::setInput
```



```
graph LR; A["hello_world::devices  
::motor::DM_J4310::setInput"] --> B["hello_world::devices  
::motor::DM_J4310::torq2raw"]
```

```
hello_world::devices  
::motor::DM_J4310::torq2raw
```