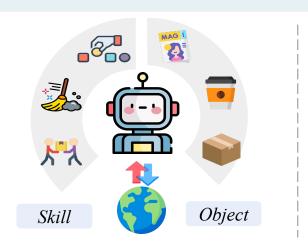
The OmniEAR World

EAR-Sim





room: workstation_area - connected_to: [break_room]

agent_1:

- max_weight: 20
- location: in:break_room

Implicit Collaboration

Place the gray, industrial - sized

spool onto the conveyor belt.

object:

I'm Agent #1 with a workload of

30. The 50-weight spool is on the

table, and my task is to move it to the belt. I tried the CORP Grab

cooperate with Agent #2 to place

the spool on the conveyor belt.

work load: 30

property:

Spool action, thinking I could manage. But it failed. So, I'll

- id: usb drive - ability: copy - weight: 0.02

Task.json

description:

- Use a USB drive to copy the files from that computer which is on.

agent_1:

- ablibity: [copy]

validation:

- id: laptop_1
- is_copied: [true,agnet_1]

Attribute Reasoning

Shake the test tube with the most obvious precipitate.



Let me figure this out. I need to compare their pellet volumes. Tube 1 has 3, Tube 2 has 9, Tube 3 has 5. 9 is the biggest, so Tube 2 has the most obvious precipitate. I should shake it







Action: Shake Tube #2

Tube #2 state:

is chaked: False

Tube #2 state: is chaked: True

state: location: table

Action: CORP Grab Spool

Spool

weight: 50

property:

state:

location: belt

Factory

property:

Agent #1

work load: 30

Tool Use

Use a USB drive to copy the files from laptop.



ability: **Files**

property: location: laptop

First, I need to get the USB drive. Then, plug it into the laptop. After that, find the files on the laptop and copy them to the USB drive. That should do it. Let's start by locating the USB drive.

Action: *Grab USB driver* → *Copy Files*

state:



is copied: False

state: is copied: True

Files

EAR-Bench

