

ECS 174 Project 1

April 27, 2019

1 Short Answer Problems

1.1 1

For example if f and g are 3 by 3 filter, h is the original matrix with size of 100 by 100. By associative property of convolution,

If we apply filter g and then filter f to image h respectively, we will have $100 * 100 * 3 * 3 + 100 * 100 * 3 * 3 = 1800$ multiplications. However, if we apply the associative property of convolution,

$$f * (g * h) = (f * g) * h$$

we combine the two filters first and then apply the combined filter to the image. By doing this, we have $3 * 3 * 3 = 27$ multiplications to create the 3 by 3 combined filter and then it takes $100 * 100 * 3 * 3 = 900$ multiplications to filter the image. totally 927 multiplications, which is much more efficient than the previous method.

1.2 2

[1,1,1,1,1,0,1,1]

1.3 3

Additive Gaussian noise might not preserve image brightness since the intensity of all pixels will go up.

1.4 4

Assumption:

The time for producing one unit of product is the same for all assemblies, regardless of whether there is flaw in the assembly.

Method:

Step 1: Prerecord an assembly process which we are sure that there is no flaw on. Denote the time between two products passing the camera as t . Take out 10 key images with equal amount of time distance and denote those ten pictures as the standard pictures $s_1, s_2, s_3, \dots, s_{10}$

Step 2: During each t time laps, take out 10 key images for every $t / 10$ time laps. Label those 10 key images as $t_1, t_2, t_3, \dots, t_{10}$

Step 3: Compare image t_i to s_i , for all $i = 1, 2, 3, \dots, 10$.

step 3.1: Cluster based on intensity similarity to separate the product from the background of the belt, in order to reduce the difference or noise from the conveyor belt.

step 3.2: Smooth the pictures to suppress noise by using Gaussian filter. Enhance the edges by using contrast filter and localize the edges. step 3.3: Compare the pictures with edges by using subtraction.