### Plonk Arithmetization

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#### **Distributed Lab**

# zkdl-camp.github.io

github.com/ZKDL-Camp



### Plan

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### Introduction. PlonK: Five Ws

### What is PlonK?

#### PlonK is a type of zkSNARK:

- Groth16
- Halo2
- Marlin
- PlonK
- . . .

#### Who and When invented Plonk?

Ariel Gabizon, Zachary Williamson, Oana Ciobotaru introduced paper "PLONK: Permutations over Lagrange-bases for Oecumenical Noninteractive arguments of Knowledge" in 2019

### PlonK: Permutations over Lagrange-bases for Oecumenical Noninteractive arguments of Knowledge

Ariel Gabizon\* Aztec Zachary J. Williamson Aztec

Oana Ciobotaru

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Figure: PlonK Paper. Date in Paper reflects the last update :)

### Why use Plonk?

#### Focus on what you want:

- ZKP for different tasks?
- Efficient proving times?
- Small-medium proof sizes?
- Flexibility?



#### Where Plonk is used?

#### zkVMs love Plonk!

- Aztek Protocol (Noir)
  - zkSync
  - Dusk Network
  - Mina Protocol



### PlonK Arithmetization

#### **Arithmetization**

**Goal:** Write some program (computation) into math processing-prone form.

#### Example

Public Input:  $x \in \mathbb{F}$ Private Input:  $e \in \mathbb{F}$ Output:  $e \times x + x - 1$ 

Let's split our program into the sequence of gates with left, right operands and output - circuit.

#### Example

We need three gates to encode our program:

- 1. **Gate** #1: left e, right x, output  $u = e \times x$
- 2. **Gate** #2: left u, right x, output v = u + x
- 3. **Gate** #3: left v, right x, output w = v + (-1)

#### **Execution Trace**

Then, form execution trace table — a matrix T with columns L, R and O.

#### Example

| Α | В | С |
|---|---|---|
| 2 | 3 | 6 |
| 6 | 3 | 9 |
| 9 | X | 8 |

#### Remark

Notice how the last row has no value in B column (marked by X) — this is reasoned by the fact it is not a variable, but rather a constant, meaning it doesn't depend on execution.

### **Encode the Program**

Suppose you were given random matrix T. How could you tell if it is suitable for your circuit?

#### Solution

Encode the circuit. Check T using encoding:

- 1. Gates (gate constraints) using matrix Q.
- 2. Wires (copy constraints) using matrix V.

#### Definition (Gate Matrix)

Q matrix has one row per each gate with columns  $Q_L$ ,  $Q_R$ ,  $Q_O$ ,  $Q_M$ ,  $Q_C$ . If columns A, B and C of the execution trace table form valid evaluation of the circuit,

$$A_i Q_{Li} + B_i Q_{Ri} + A_i B_i Q_{Mi} + C_i Q_{Oi} + Q_{ci} = 0$$

### Q Matrix

#### Example

For our program, we would have a following Q table:

| $Q_L$ | $Q_R$ | $Q_M$ | $Q_O$ | $Q_c$ |
|-------|-------|-------|-------|-------|
| 0     | 0     | 1     | -1    | 0     |
| 1     | 1     | 0     | -1    | 0     |
| 1     | 0     | 0     | -1    | -1    |

You can verify that our claim holds for aforementioned trace matrix:

$$2 \times 0 + 3 \times 0 + 2 \times 3 \times 1 + 6 \times (-1) + 0 = 0$$
$$6 \times 1 + 3 \times 1 + 6 \times 3 \times 0 + 9 \times (-1) + 0 = 0$$
$$9 \times 1 + 0 \times 0 + 9 \times 0 \times 0 + 8 \times (-1) + (-1) = 0$$

#### V Matrix

#### **Definition**

 ${\it V}$  consists of indices of all inputs and intermediate values, so that if  ${\it T}$  is a valid trace,

$$\forall i,j,k,l: (V_{i,j}=V_{k,l}) \Rightarrow (T_{i,j}=T_{k,l})$$

#### Example

For our program, V would look like following:

| L | R | 0 |
|---|---|---|
| 0 | 1 | 2 |
| 2 | 1 | 3 |
| 3 |   | 4 |

Here 0 is an index of e, 1 is an index of x, 2 — u, 3 — v and 4 — output w.

#### **Custom Gates**

Default Plonk: addition and multiplication gates. How to make it more *interesting*?

#### Solution

 ${\it Q}$  with it's 5 columns already allows for custom gates, however it is possible to include out own columns.

#### Example

Our entire program may be encoded as one custom gate.

$$2 \times 0 + 3 \times 1 + 2 \times 3 \times 1 + 8 \times (-1) + (-1) = 0$$

### **Public Inputs**

Also need to encode public inputs.

#### Idea

Consider, as if we added new *selector* rows to Q and tied them in V and T.

#### Example

|    | $Q_L$ | $Q_R$ | $Q_M$ | $Q_o$ | $Q_c$ |
|----|-------|-------|-------|-------|-------|
| Q: | -1    | 0     | 0     | 0     | 3     |
|    | -1    | 0     | 0     | 0     | 8     |
|    | 1     | 1     | 1     | -1    | 1     |
|    | 1     | -1    | 0     | 0     | 0     |

|    | L | R | 0 |
|----|---|---|---|
|    | 0 |   |   |
| V: | 1 |   |   |
|    | 2 | 0 | 3 |
|    | 1 | 3 |   |

|   | Α | В | C |
|---|---|---|---|
|   | 3 |   |   |
| : | 8 |   |   |
|   | 2 | 3 | 8 |
|   | 8 | 8 |   |

Now Q and V are not independent of evaluations.

#### Solution

We introduce another one-column matrix named  $\Pi$  (public inputs).

### Wrap-Up

#### Example

With only Q modified, we have:

| only Q modified, we have: |       |       |       |       |       |
|---------------------------|-------|-------|-------|-------|-------|
|                           | $Q_L$ | $Q_R$ | $Q_M$ | $Q_o$ | $Q_c$ |
|                           | -1    | 0     | 0     | 0     | 0     |
| Q:                        | -1    | 0     | 0     | 0     | 0     |
|                           | 1     | 1     | 1     | -1    | 1     |
|                           | 1     | -1    | 0     | 0     | 0     |

#### Definition (Interim Summary)

Matrix T with columns A, B and C encodes correct execution of the program, if the following two conditions hold:

1. 
$$\forall i : A_i Q_{Li} + B_i Q_{Ri} + A_i B_i Q_{Mi} + C_i Q_{Oi} + Q_{ci} + \Pi_i = 0$$

2. 
$$\forall i, j, k, l : (V_{i,j} = V_{k,l}) \Rightarrow (T_{i,j} = T_{k,l})$$

## Polynomial Form

### Matrices to Polynomials

Encode matrices into a few equations on polynomials.

Let  $\omega$  be a primitive N-th root of unity and let  $\Omega = \{\omega^j : 0 \leq j < N\}$ . Let  $a, b, c, q_L, q_R, q_M, q_O, q_C, \pi$  be polynomials of degree at most N that interpolate corresponding columns from matrices at the domain  $\Omega$ . This means, that  $\forall j : a(\omega^j) = A_j$  and the same for other columns.

#### **Proposition**

Now we can reduce down our first condition to checking valid execution trace into the following claim over polynomials:

$$\exists t \in \mathbb{F}[X] : aq_L + bq_R + abq_M + cq_O + q_C + \pi = z_\Omega t,$$

where  $z_{\Omega}(X)$  is the vanishing polynomial  $X^{N}-1$ .

### Copy constraints in polynomial form.

Spoiler: we can use the concept of permutation to encode V wirings.

A permutation is a rearrangement of the set:

$$\mathcal{I} = \{(i,j) : \text{such that } 0 \le i < N, \text{ and } 0 \le j < 3\}$$

Permutation of the set is commonly denoted as  $\sigma$ .

### Copy constraints in polynomial form.

#### Example

The matrix V induces a permutation of this set where  $\sigma((i,j))$  is equal to the indices of the next occurrence of the value at position (i,j). So, for our example:

$$\sigma((0,0)) = (2,1), \sigma((0,1)) = (0,3), \sigma((0,2)) = (0,2)$$

$$\sigma((0,3)) = (0,1), \sigma((2,1)) = (0,0), \sigma((3,1)) = (2,2)$$

**Permutation Check.** Having defined permutation, we can now reduce a condition 2 of valid execution trace matrix into the following check:

$$\forall (i,j) \in \mathcal{I} : T_{i,j} = T_{\sigma(i,j)}$$

You may have noticed how this can be reformulated as equality of *A* and *B*:

$$A = \{((i,j), T_{i,j}) : (i,j) \in \mathcal{I}\}$$
$$B = \{(\sigma((i,j)), T_{i,j}) : (i,j) \in \mathcal{I}\}$$

We can reduce this check down to polynomial equations.

Suppose we have sets  $A=\{a_0,a_1\}$  and  $B=\{b_0,b_1\}$ . We can consider polynomials  $A'=\{a_0+X,a_1+X\}, B'=\{b_0+X,b_1+X\}$ . So, A'=B', only if  $(a_0+X)(a_1+X)=(b_0+X)(b_1+X)$ . This is true because of linear polynomial unique factorization property, working as prime factors. Now, we can utilize Schwartz-Zippel lemma to replace the latter formula with  $(a_0+\gamma)(a_1+\gamma)=(b_0+\gamma)(b_1+\gamma)$  for some random  $\gamma$  with overwhelming probability. If we wish to generalize this for arbitrary sets  $A=\{a_0,\ldots,a_{k-1}\}$  and  $B=\{b_0,\ldots,b_{k-1}\}$ , apply the following check:

$$\prod_{i=0}^{k-1}(a_i+\gamma)=\prod_{i=0}^{k-1}(b_i+\gamma)$$

Let  $\Omega$  be a domain of the form  $\{1, \omega, \dots, \omega^{k-1}\}$  for some k-th root of unity  $\omega$ . Let f and g be polynomials that interpolate the following values at  $\Omega$ :

$$f: (a_0 + \gamma, ..., a_{k-1} + \gamma)$$
  
 $g: (b_0 + \gamma, ..., b_{k-1} + \gamma)$ 

Then  $\prod_{i=0}^{k-1}(a_i+\gamma)=\prod_{i=0}^{k-1}(b_i+\gamma)$  if and only if exists a polynomial  $Z\in\mathbb{F}[X]$  such that for all  $h\in\Omega$  we have  $Z(\omega^0)=1$  and  $Z(h)f(h)=g(h)Z(\omega h)$ .

Now that we can encode equality of sets of field elements, let's expand this to sets of tuples of field elements. Let  $A = \{(a_0, a_1), (a_2, a_3)\}$  and  $B = \{(b_0, b_1), (b_2, b_3)\}$ , then, similarly:

$$A' = \{a_0 + a_1 Y + X, a_2 + a_3 Y + X\}$$
$$B' = \{b_0 + b_1 Y + X, b_2 + b_3 Y + X\}$$
$$A = B \leftrightarrow A' = B'$$

As before, we can leverage Schwartz-Zippel lemma to reduce this down into sampling random  $\beta$  and  $\gamma$  and checking equality of:

$$(a_0 + \beta a_1 + \gamma)(a_2 + \beta a_3 + \gamma) = (b_0 + \beta b_1 + \gamma)(b_2 + \beta b_3 + \gamma)$$

Let's make (i,j) into one field element, so that we can use statement above for encoding.

Recall that  $i \in [0; N-1]$  and  $j \in [0; 2]$ ; we can take 3N-th primitive root of unity  $\eta$  and define our field element as  $a_0 = \eta^{3i+j}$ :

$$A = \{ (\eta^{3i+j}, T_{i,j}) : (i,j) \in \mathcal{I} \}$$

$$B = \{ (\eta^{3k+l}, T_{i,j}) : (i,j) \in \mathcal{I}, \sigma((i,j)) = (k,l) \}$$

Let  $\eta$  be a 3N-th primitive root of unity,  $\beta$  and  $\gamma$  random field elements. Let  $\mathcal{D}=\{1,\eta,\eta^2,\ldots,\eta^{3N-1}\}$ . Then let f and g interpolate at  $\mathcal{D}$ :

$$f : \{ T_{i,j} + \eta^{3i+j} \beta + \gamma : (i,j) \in \mathcal{I} \}$$
  
 
$$g : \{ T_{i,j} + \eta^{3k+l} \beta + \gamma : (i,j) \in \mathcal{I}, \sigma((i,j)) = (k,l) \}$$

So, 
$$\exists Z \in \mathbb{F}[X]$$
 s.t.  $\forall h \in \Omega$  we have  $Z(\eta^0) = 1$  and  $Z(h)f(h) = g(h)Z(\eta h) \leftrightarrow A = B$  w.h.p.

Notice, that  $\omega=\eta^3$  is a primitive *N*-th root of unity. Let  $\Omega=\{1,\omega,\omega^2,\ldots,\omega^{N-1}\}$ . We will define three polynomials, which interpolate following sets:

$$S_{\sigma 1}: \{\eta^{3k+l}: (i,0) \in \mathcal{I}, \sigma((i,0)) = (k,l)\}$$

$$S_{\sigma 2}: \{\eta^{3k+l}: (i,1) \in \mathcal{I}, \sigma((i,0)) = (k,l)\}$$

$$S_{\sigma 3}: \{\eta^{3k+l}: (i,2) \in \mathcal{I}, \sigma((i,0)) = (k,l)\}$$

### Copy constraints via polynomials

Let  $\omega$  be an N-th root of unity. Let  $\Omega = \{1, \omega, \omega^2, \dots, \omega^{N-1}\}$ . Let  $k_1$  and  $k_2$  be two field elements such that  $\omega^i \neq \omega^j k_1 \neq \omega^l k_2$  for all i, j, l. Let  $\beta$  and  $\gamma$  be random field elements. Let f and g be the polynomials that interpolate, respectively, the following values at  $\Omega$ :

$$f: \{ (T_{0,j} + \omega^{i}\beta + \gamma) (T_{1,j} + \omega^{i}k_{1}\beta + \gamma) (T_{2,j} + \omega^{i}k_{2}\beta + \gamma) : 0 \le i < N \}$$

$$g: \{ (T_{0,j} + S_{0,1}(\omega^{i})\beta + \gamma) (T_{0,j} + S_{0,2}(\omega^{i})\beta + \gamma) (T_{0,j} + S_{0,3}(\omega^{i})\beta + \gamma) \}$$

So,  $\exists Z \in \mathbb{F}[X]$  such that  $\forall d \in \mathcal{D}$  we have  $Z(\omega^0) = 1$  and  $Z(d)f(d) = g(d)Z(\omega d) \leftrightarrow A = B$  w.h.p.

### Summary | Matrices

#### **Definition**

Let T be a  $N \times 3$  matrix with columns A, B, C and  $\Pi$  a  $N \times 1$  matrix where N is the number of gates. They correspond to a valid execution instance with public input given by  $\Pi$  if and only if:

1. 
$$\forall i : A_i Q_{Li} + B_i Q_{Ri} + A_i B_i Q_{Mi} + C_i Q_{Oi} + Q_{Ci} + \Pi_i = 0$$

2. 
$$\forall i, j, k, l : V_{i,j} = V_{k,l} \implies T_{i,j} = T_{k,l}$$

3. 
$$\forall i > n : \Pi_i = 0$$

### Summary | Polynomials

#### **Definition**

Let  $z_{\Omega} = X^N - 1$ . Let T be a  $N \times 3$  matrix with columns A, B, C and  $\Pi$  a  $N \times 1$  matrix. They correspond to a valid execution instance with public input given by  $\Pi$  if and only if:

- 1.  $\exists t_1 \in \mathbb{F}[X] : aq_L + bq_R + abq_M + cq_O + q_C + \pi = z_\Omega t_1$
- 2.  $\exists t_2, t_3, z \in \mathbb{F}[X] : zf gz' = z_{\Omega}t_2 \text{ and } (z-1)L_1 = z_{\Omega}t_3$ , where  $z'(X) = z(X\omega)$ .

# Thank you for your attention



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