

view_frames Result
Recorded at time: 1731742388.460

map

Broadcaster: /lio_sam_imuPreintegration
Average rate: 100.198 Hz
Most recent transform: 1731742388.456 (0.004 sec old)
Buffer length: 4.990 sec

odom

Broadcaster: /lio_sam_imuPreintegration
Average rate: 100.198 Hz
Most recent transform: 1731742388.456 (0.004 sec old)
Buffer length: 4.990 sec

base footprint

Broadcaster: /lio_sam_mapOptimization
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1731742388.460 sec old)
Buffer length: 0.000 sec

velodyne

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1731742388.460 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1731742388.460 sec old)
Buffer length: 0.000 sec

column_four

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1731742388.460 sec old)
Buffer length: 0.000 sec

column_one

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1731742388.460 sec old)
Buffer length: 0.000 sec

column_three

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1731742388.460 sec old)
Buffer length: 0.000 sec

column_two

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1731742388.460 sec old)
Buffer length: 0.000 sec

two_ply_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1731742388.460 sec old)
Buffer length: 0.000 sec

velodyne_base_link

Broadcaster: /base to camera
Average rate: 10.196 Hz
Most recent transform: 1731742388.490 (-0.030 sec old)
Buffer length: 4.904 sec

camera_link

Broadcaster: /base to gyro
Average rate: 10.196 Hz
Most recent transform: 1731742388.495 (-0.035 sec old)
Buffer length: 4.904 sec

gyro_link

Broadcaster: /base link to IMU_link
Average rate: 10.196 Hz
Most recent transform: 1731742388.512 (-0.052 sec old)
Buffer length: 4.904 sec

IMU

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1731742388.431 (0.028 sec old)
Buffer length: 4.900 sec

front_steer_left_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1731742388.431 (0.028 sec old)
Buffer length: 4.900 sec

front_steer_right_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1731742388.431 (0.028 sec old)
Buffer length: 4.900 sec

left_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1731742388.431 (0.028 sec old)
Buffer length: 4.900 sec

right_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1731742388.431 (0.028 sec old)
Buffer length: 4.900 sec

left_front_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1731742388.431 (0.028 sec old)
Buffer length: 4.900 sec

right_front_link