

Covariate-shift Robust Adaptive Transfer Learning for High-dimensional Regression

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- Background and Motivation
- Key Contributions

2 Covariate-shift Robust Transfer Learning

- TransFusion: Transfer Learning with a Fused Regularization
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Transfer Learning

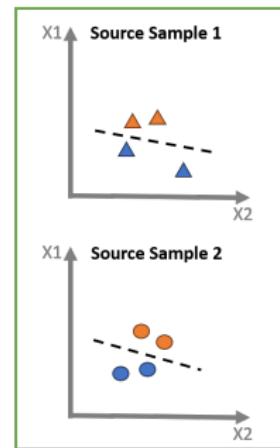
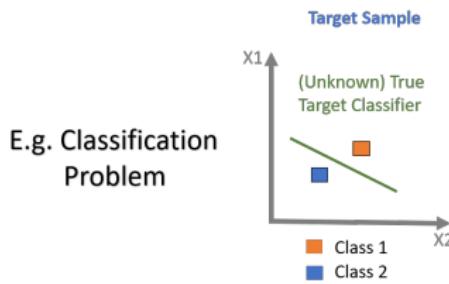
■ **Target sample:** $(\mathbf{X}^{(0)}, \mathbf{y}^{(0)}) \sim P^{(0)}(\mathbf{x}, \mathbf{y}) = P^{(0)}(\mathbf{y}|\mathbf{x})P^{(0)}(\mathbf{x})$.

■ **Source samples:**

$$(\mathbf{X}^{(k)}, \mathbf{y}^{(k)}) \sim P^{(k)}(\mathbf{x}, \mathbf{y}) = P^{(k)}(\mathbf{y}|\mathbf{x})P^{(k)}(\mathbf{x}), k = 1, \dots, K.$$

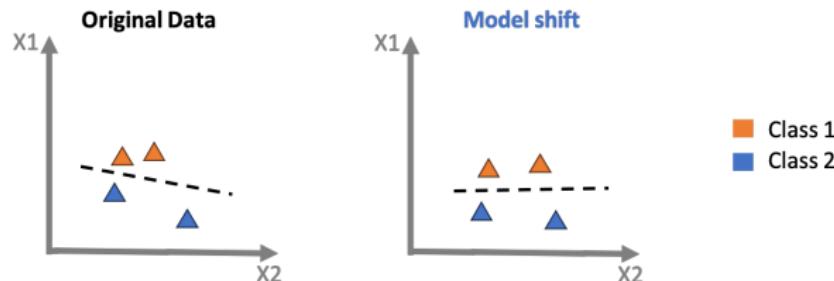
■ **Goal of transfer learning:**

Learn the target model $P^{(0)}(\mathbf{y}|\mathbf{x})$, by incorporating source information.



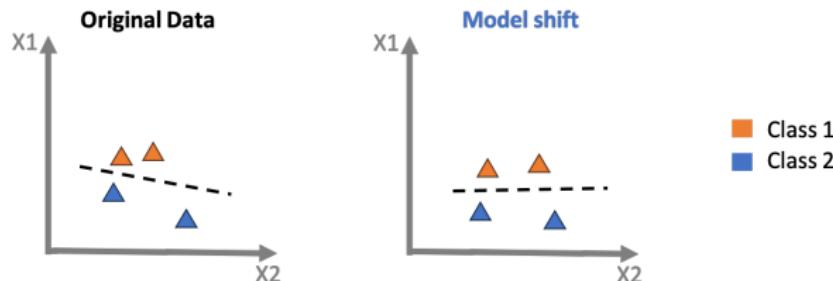
Model shift in Transfer Learning

- **Model shift:** $P^{(i)}(y|x) \neq P^{(j)}(y|x), i, j = 0, 1, \dots, K.$



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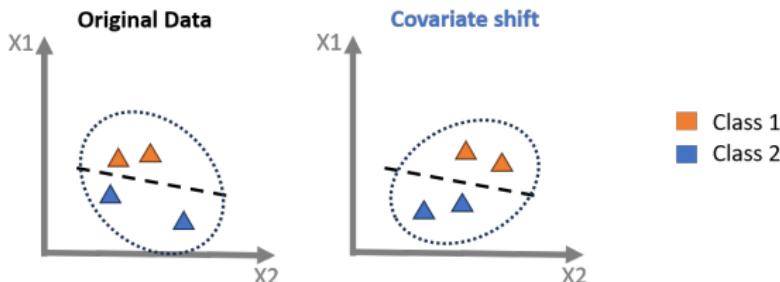
- **Typical strategy to deal with HD model shift:**

“Pooling training + debiasing”

- Linear model: Li et al. (2022a,b)
- Generalized linear model: Tian et al. (2022)
- Quantile regression model: Jin et al. (2022), Cao and Song (2024)
- ...

Covariate Shift in Transfer Learning

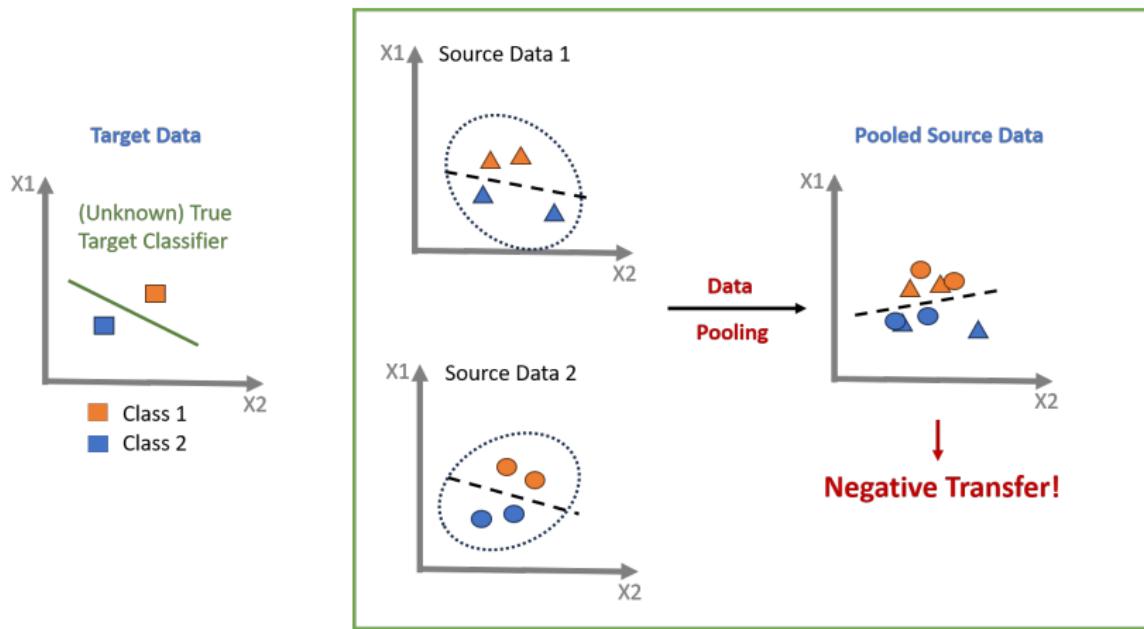
- **covariate shift:** $P^{(i)}(x) \neq P^{(j)}(x)$, $i, j = 0, 1, \dots, K$.



Under high-dimensionality, covariate shift is often inevitable.

Covariate Shift in Transfer Learning

- Impact of covariate shift on pooling training:



Covariate Shift in Transfer Learning

■ Existing works to deal with covariate shift:

- **Domain adaptation:** Chen et al. (2016), Redko et al. (2020), etc.
 - typically assumes no model shift;
 - struggles with high-dimensional covariates.
- **Constrained ℓ_1 -minimization:** Li et al. (2023), etc.
 - involves multiple nonsmooth constraints;
 - restricted parameter space/strong theoretical assumptions;
 - computationally intractable.

Covariate Shift in Transfer Learning

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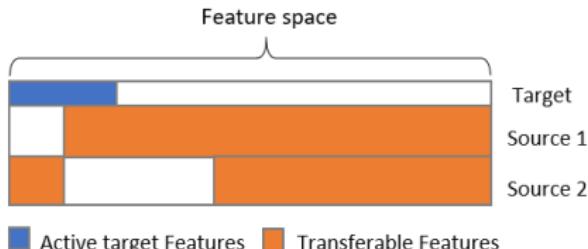
⇒ Our first question:

*How to develop a **computationally tractable** method that effectively handles model shift in **high-dimensional** transfer learning, while being robust to covariate shift?*

Feature-specific Transferable Structure

■ Feature-specific transferable structure:

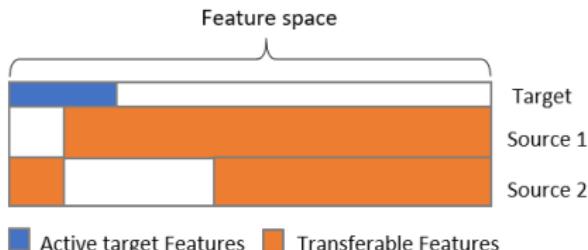
- In high-dimensional transfer learning, the transferable structure often varies across features within the same source sample.
- E.g. Whole brain functional connectivity pattern analysis (Li et al., 2018): Each source may have a distinct set of non-transferable features due to variations in brain conditions.



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- E.g. Whole brain functional connectivity pattern analysis (Li et al., 2018): Each source may have a distinct set of non-transferable features due to variations in brain conditions.



⇒ Our second question:

Is it possible to auto-detect nontransferable features/learn transferable structure for each source while transferring source information?

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Key Contributions of the work

In the **high-dimensional regression** context:

- To tackle the **covariate shift** issue, we
 - 1 develop a new transfer learning framework via fused regularization, named **TransFusion**;
 - 2 extend TransFusion to a distributed setting, called **D-TransFusion**.
- To further address the **feature-specific transferable structure**, we
 - 3 propose a feature-adaptive transfer learning framework, named **AdaTrans**, to auto-detect non-transferable feature.
- For each method, we establish the corresponding non-asymptotic bound.

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- TransFusion: Transfer Learning with a Fused Regularization
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High-dimensional Linear Regression Model



Sample-level **target** model (with sample size n_T):

$$\mathbf{y}^{(0)} = \mathbf{X}^{(0)}\boldsymbol{\beta}^{(0)} + \boldsymbol{\epsilon}^{(0)},$$

Sample-level **source** model (with sample size n_S):

$$\mathbf{y}^{(k)} = \mathbf{X}^{(k)}\boldsymbol{\beta}^{(k)} + \boldsymbol{\epsilon}^{(k)} \equiv \mathbf{X}^{(k)}(\boldsymbol{\beta}^{(0)} + \boldsymbol{\delta}^{(k)}) + \boldsymbol{\epsilon}^{(k)}, \quad k = 1, \dots, K.$$

- $E(\boldsymbol{\epsilon}^{(k)}) = \mathbf{0}$, $\text{Cov}(\boldsymbol{\epsilon}^{(k)}) = \sigma^2 \mathbf{I}$, $\boldsymbol{\epsilon}^{(k)} \perp\!\!\!\perp \mathbf{X}^{(k)}$, $k = 0, 1, \dots, K$.
- $\mathbf{X}_i^{(k)}$ i.i.d sub-Gaussian across i , with covariance matrix $\Sigma^{(k)}$.
- $p \geq n_S \geq n_T$, $\boldsymbol{\beta}^{(0)} \in \mathbb{R}^p$ is high-dimensional yet sparse.
- **Covariate shift**: $\text{Cov}(\mathbf{X}_i^{(k)}) = \Sigma^{(k)}$ varies across k .
- **Model shift**: $\boldsymbol{\delta}^{(k)} \in \mathbb{R}^p$ varies across k ; take $\boldsymbol{\delta}^{(0)} = \mathbf{0}$.

Objective function of TransFusion

Formulation: Estimate $\beta := ((\beta^{(0)})^\top, (\beta^{(1)})^\top, \dots, (\beta^{(K)})^\top)^\top \in \mathbb{R}^{(K+1)p}$ by solving

$$\operatorname{argmin}_{\beta \in \mathbb{R}^{(K+1)p}} \left\{ \frac{1}{2N} \sum_{k=0}^K \|y^{(k)} - \mathbf{x}^{(k)} \beta^{(k)}\|_2^2 + \lambda_0 \left(\|\beta^{(0)}\|_1 + \sum_{k=1}^K \nu \|\beta^{(k)} - \beta^{(0)}\|_1 \right) \right\},$$

Reformulation: Estimate $((\beta^{(0)})^\top, (\delta^{(1)})^\top, \dots, (\delta^{(K)})^\top)^\top \in \mathbb{R}^{(K+1)p}$ by solving

$$\operatorname{argmin}_{\beta \in \mathbb{R}^{(K+1)p}} \left\{ \frac{1}{2N} \left(\sum_{k=0}^K \|y^{(k)} - \mathbf{x}^{(k)} (\beta^{(0)} + \delta^{(k)})\|_2^2 \right) + \lambda_0 \left(\|\beta^{(0)}\|_1 + \sum_{k=1}^K \nu \|\delta^{(k)}\|_1 \right) \right\},$$

- $N = Kn_S + n_T$ is the total sample size, λ_0 and ν are the tuning parameters.
- The first term measures the average fitness of the models.
- λ_0 and $\lambda_0\nu$ respectively take charge of achieving sparsity of $\beta^{(0)}$ and shrinking the contrast $\delta^{(k)} = \beta^{(k)} - \beta^{(0)}$ for information transfer.

Two-step TransFusion Estimator

Step 1. Joint training:

- 1 Obtain $\hat{\beta} := ((\hat{\beta}^{(0)})^\top, (\hat{\beta}^{(1)})^\top, \dots, (\hat{\beta}^{(K)})^\top)^\top \in \mathbb{R}^{(K+1)p}$ using a newly advocated proximal gradient descent-based algorithm with message-passing iteration.
- 2 Construct the first-step TransFusion estimator

$$\hat{\beta}_{\text{TF1}}^{(0)} = \sum_{k=1}^K \frac{n_S}{N} \hat{\beta}^{(k)} + \frac{n_T}{N} \hat{\beta}^{(0)}.$$

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Step 2. Local debiasing:

- 3 If necessary, correct the bias of $\hat{\beta}_{TF1}^{(0)}$ using the target sample through

$$\hat{\delta} \in \operatorname{argmin}_{\delta \in \mathbb{R}^p} \left\{ \frac{1}{2n_T} \left\| \mathbf{y}^{(0)} - \mathbf{X}^{(0)} \hat{\beta}_{TF1}^{(0)} - \mathbf{X}^{(0)} \delta \right\|_2^2 + \tilde{\lambda} \|\delta\|_1 \right\},$$

- 4 Define the second-step TransFusion estimator

$$\hat{\beta}_{TF2}^{(0)} = \hat{\beta}_{TF1}^{(0)} + \hat{\delta}.$$

Theoretical Guarantee for TransFusion

Theorem (Error rate of TransFusion estimators)

Consider the parameter space

$$\Theta(s, h) = \left\{ B = (\beta^{(0)}, \beta^{(1)}, \dots, \beta^{(K)}) : \|\beta^{(0)}\|_0 \leq s, \left\| \beta^{(k)} - \beta^{(0)} \right\|_1 \leq h \right\}.$$

Under mild conditions,

- if $ns \gg (K^2 h^2 \vee s) \log p$, with a proper choice of λ_0 , with probability at least $1 - c_1 \exp(-c_2 n_T) - c_3 \exp(-c_4 \log p)$, we have

$$\|\hat{\beta}_{TF1}^{(0)} - \beta^{(0)}\|_2^2 \lesssim \frac{s \log p}{N} + h \sqrt{\frac{\log p}{n_S}} + \epsilon_D^2.$$

- if $n_T \gtrsim s \log p$, $n_S \gg K^2(h^2 \vee s) \log p$ and $h \sqrt{\log p / n_T} = o(1)$, with probability at least $1 - c_2 \exp(-c_3 \log p)$, we have

$$\|\hat{\beta}_{TF2}^{(0)} - \beta^{(0)}\|_2^2 \lesssim \frac{s \log p}{N} + h \sqrt{\frac{\log p}{n_T}},$$

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- $\varepsilon_D = \|\sum_{k=1}^K \frac{n_S}{N} (\beta^{(k)} - \beta^{(0)})\|_1$: **task diversity** which measures the bias introduced by averaging.

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- **Baseline**: target-only lasso with rate $O(s \log p / n_T)$.

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- $h \sqrt{\log p / n_T}$: rate of estimating $\delta^{(k)}$'s using the target sample.
- **Baseline**: target-only lasso with rate $O(s \log p / n_T)$.
- $\hat{\beta}_{TF1}^{(0)}$ is preferred when ε_D or n_T is small, while $\hat{\beta}_{TF2}^{(0)}$ is preferred when ε_D is non-negligible and n_T is adequately large.

Why TF is Robust to Covariate Shifts?

TransFusion utilizes task-specific parameters with a series of fused regularizers, resulting in

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The bias can be amplified by a factor (Li et al., 2022)

$$C_\Sigma := 1 + \max_{j \leq p} \max_k \left\| e_j^\top \left(\Sigma^{(k)} - \Sigma^{(0)} \right) \left(\sum_{1 \leq k \leq K} \frac{1}{K} \Sigma^{(k)} \right)^{-1} \right\|_1,$$

which could diverge with rate \sqrt{p} .

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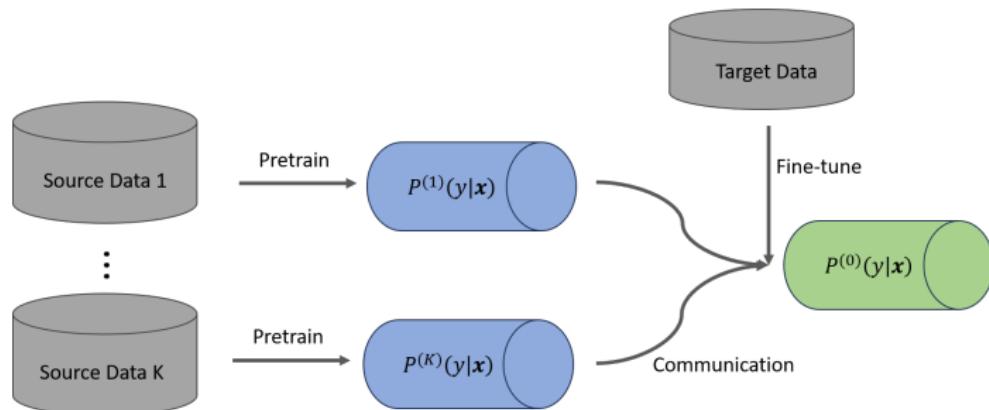
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Distributed Transfer Learning in One-shot

Distributed setting: Source datasets are distributed across different machines.

- Privacy concern: raw data cannot be shared across machines;
- Communication bottleneck: inter-machine data communication is a significant source of latency;
- Pretraining & Fine-tuning strategy: quickly adapt to downstream tasks.



Two-step D-TransFusion Estimator

Step 1: The k th source machine computes an initial estimator $\tilde{\beta}^{(k)}$ using $(\mathbf{X}^{(k)}, \mathbf{y}^{(k)})$ and sends it to the target machine. Then the target machine solves

$$\hat{\beta}_D \in \underset{\beta \in \mathbb{R}^{(K+1)p}}{\operatorname{argmin}} \left\{ \frac{n_S}{2N} \sum_{k=1}^K \|\tilde{\beta}^{(k)} - \beta^{(k)}\|_2^2 + \frac{1}{2N} \|\mathbf{y}^{(0)} - \mathbf{X}^{(0)} \beta^{(0)}\|_2^2 \right. \\ \left. + \lambda_0 \left(\|\beta^{(0)}\|_1 + \sum_{k=1}^K \nu \|\tilde{\beta}^{(k)} - \beta^{(0)}\|_1 \right) \right\},$$

and obtains $\hat{\beta}_{\text{D-TF1}}^{(0)} = \frac{n_S}{N} \sum_{k=1}^K \hat{\beta}_D^{(k)} + \frac{n_T}{N} \hat{\beta}_D^{(0)}$.

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- Only one-shot communication with the summary statistic is required.
- D-TransFusion has the same rate as TransFusion under mild conditions.

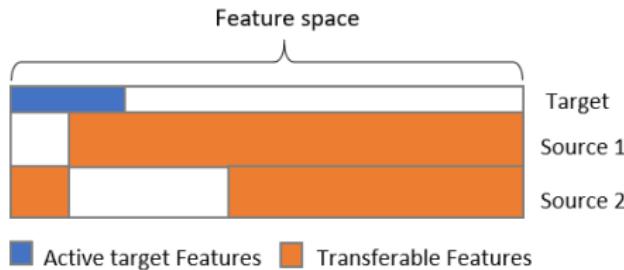
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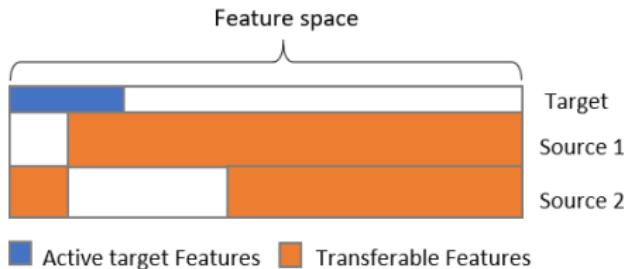
Intuition of AdaTrans

On base of TransFusion, consider the **feature-specific transferable structure**:



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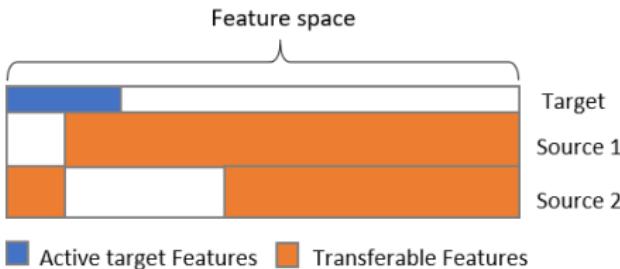
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Intuition of AdaTrans

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The transferability of the j th feature in the k -th source task can be assessed by the magnitude of model shift $\delta_j^{(k)}$. Ideally, we should...

- apply stronger penalties to transferable features with negligible $\delta_j^{(k)}$;
 \rightarrow shrink $\delta_j^{(k)}$ to 0, i.e. pool $\beta_j^{(k)}$ and $\beta_j^{(0)}$, if the j -th feature from the k -th source is informative/transferable
- prevents excessive penalties to non-transferable features with large $\delta_j^{(k)}$.
 \rightarrow prevent introducing bias from non-transferable signals

Key Idea of AdaTrans

Estimate $\beta^{(0)}$ by solving

$$\operatorname{argmin}_{\boldsymbol{\beta} \in \mathbb{R}^{(K+1)p}} \left\{ \frac{1}{2N} \sum_{k=0}^K \|\mathbf{y}^{(k)} - \mathbf{X}^{(k)}(\boldsymbol{\beta}^{(0)} + \boldsymbol{\delta}^{(k)})\|_2^2 + \sum_{j=1}^p \hat{w}_{0j} |\beta_j^{(0)}| + \sum_{k=1}^K \sum_{j=1}^p \hat{w}_{kj} |\delta_j^{(k)}| \right\},$$

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Choice of weight?

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$$\operatorname{argmin}_{\beta \in \mathbb{R}^{(K+1)p}} \left\{ \frac{1}{2N} \sum_{k=0}^K \|\mathbf{y}^{(k)} - \mathbf{X}^{(k)}(\beta^{(0)} + \delta^{(k)})\|_2^2 + \sum_{j=1}^p \hat{w}_{0j} |\beta_j^{(0)}| + \sum_{k=1}^K \sum_{j=1}^p \hat{w}_{kj} |\delta_j^{(k)}| \right\},$$

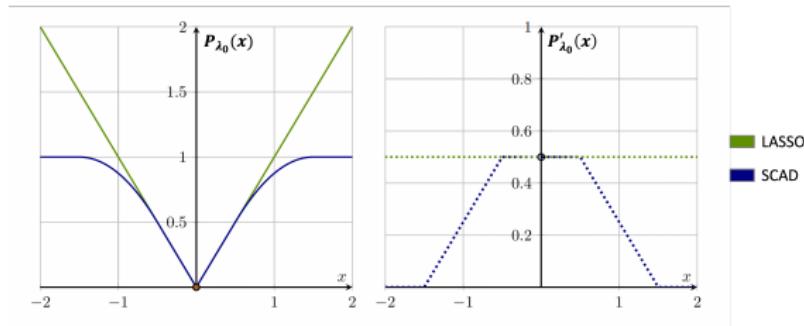
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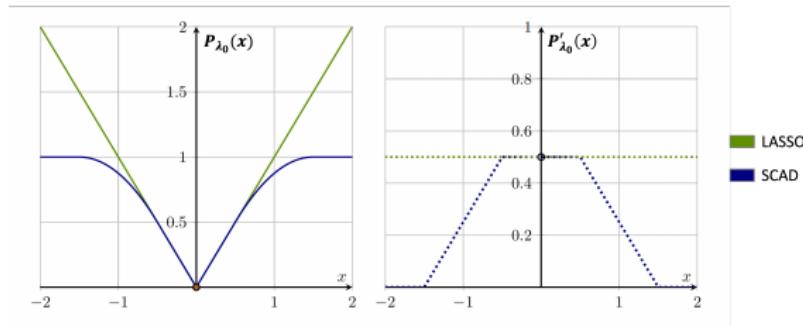


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Choice of weight? \Rightarrow Folded-concave penalty function $P_{\lambda_0}(\cdot)$:



Borrowing the idea of local linear approximation, take $\hat{w}_{0j} \propto P'_{\lambda_0}(\hat{\beta}_{\text{init},j}^{(0)})$ and $\hat{w}_{kj} \propto P'_{\lambda_0}(\hat{\delta}_{\text{init},j}^{(k)})$, where $\hat{\beta}_{\text{init},j}^{(0)}$ and $\hat{\delta}_{\text{init},j}^{(k)}$ are initial estimators of $\beta_j^{(0)}$ and δ_j .

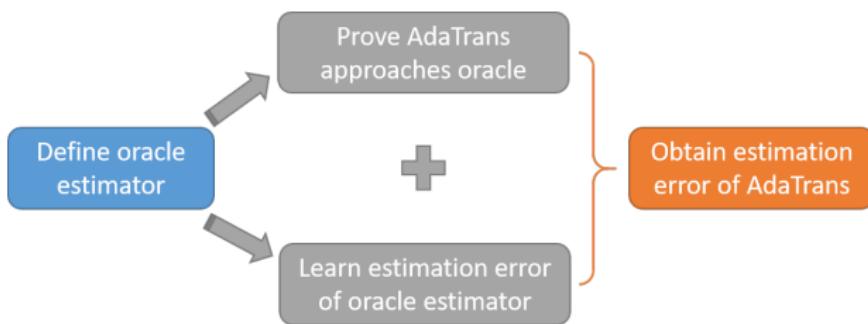
Outline

3 Adaptive Covariate-shift Robust Transfer Learning

- AdaTrans: Feature-wise Adaptive Transfer Learning
- Oracle AdaTrans and Theoretical Guarantee of AdaTrans

Developing Theory for AdaTrans

Recall that under certain conditions, folded-concave penalization can obtain an **oracle estimator**, where the sparsity and transferable structures are known.



Oracle AdaTrans Estimator

How to define oracle estimator for AdaTrans?

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1 Define **sparsity structure**:

- Active target feature set: $S_0 = \{j : \beta_j^{(0)} \neq 0\}$,
- Inactive target feature set: $S_0^c = \{j : \beta_j^{(0)} = 0\}$;

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2 Define transferability structure:

- Non-transferable set: $S_k = \{j : \delta_j^{(k)} \neq 0\}, k = 1, \dots, K$,
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3 Define oracle AdaTrans estimator $\hat{\beta}_{\text{ora}}^{(0)}, \hat{\delta}_{\text{ora}}^{(1)}, \dots, \hat{\delta}_{\text{ora}}^{(K)}$ via

$$\begin{aligned} & \min_{\beta^{(0)}, \{\delta^{(k)}\}_{k=1}^K} \frac{1}{N} \sum_{k=0}^K \|y^{(k)} - \mathbf{X}^{(k)}(\beta^{(0)} + \delta^{(k)})\|_2^2 \\ & \text{s.t.} \quad \beta_{S_0^c}^{(0)} = 0, \quad \delta_{S_k^c}^{(k)} = 0, \forall k = 1, \dots, K. \end{aligned} \tag{1}$$

Oracle AdaTrans Estimator

Theorem (Solution of oracle AdaTrans estimator)

If $|S_0| < n_T$ and $\max_{1 \leq k \leq K} |S_k| < n_S$, the solution to problem (1) satisfies

$$\hat{\beta}_{\text{ora}, S_0}^{(0)} = [\tilde{\mathbf{X}}_{S_0}^\top \tilde{\mathbf{X}}_{S_0}]^{-1} \tilde{\mathbf{X}}_{S_0}^\top \mathbf{y} \quad \text{and} \quad \hat{\beta}_{\text{ora}, S_0^c}^{(0)} = \mathbf{0}. \quad (2)$$

- $\tilde{\mathbf{X}}_{S_0} = ((\mathbf{X}_{S_0}^{(0)})^\top, (\mathbf{X}_{S_0}^{(1)})^\top, \dots, (\mathbf{X}_{S_0}^{(K)})^\top)^\top$.
- $\tilde{\mathbf{X}}_{S_0}^{(k)} = (\mathbf{I} - \mathbf{H}_{S_k}^{(k)}) \mathbf{X}_{S_0}^{(k)}$, where $\mathbf{H}_{S_k}^{(k)} := \mathbf{X}_{S_k}^{(k)} [(\mathbf{X}_{S_k}^{(k)})^\top \mathbf{X}_{S_k}^{(k)}]^{-1} (\mathbf{X}_{S_k}^{(k)})^\top$.

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- $\tilde{\mathbf{X}}_{S_0}^{(k)}$ is indeed the projection of the **active target feature** onto the **null space** of the **non-transferable** feature in the k -th source sample.

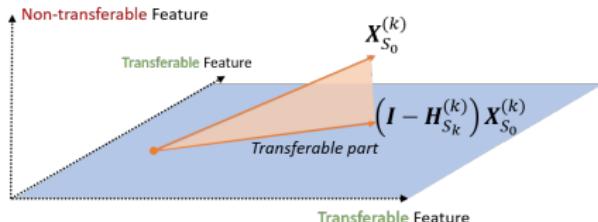
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Estimation Error of Oracle AdaTrans

Theorem (Estimation error of oracle AdaTrans)

If $|S_0| < n_T$, $\max_{1 \leq k \leq K} |S_k| < n_S$ and $N \geq \log p$, the error of $\hat{\beta}_{\text{ora}}^{(0)}$ satisfies

$$\|\hat{\beta}_{\text{ora}}^{(0)} - \beta^{(0)}\|_2 \lesssim \kappa_F \left\| \left(\frac{\mathbf{X}_{S_0}^\top \mathbf{X}_{S_0}}{N} \right)^{-1} \right\|_\infty \sqrt{\frac{s \log s}{N}}, \quad (3)$$

with probability larger than $1 - \exp(-c_1 \log p)$, where \mathbf{X}_{S_0} is column-submatrix indexed by S_0 of the full-sample design matrix \mathbf{X} , and

$$\kappa_F := \frac{\left\| [\tilde{\mathbf{X}}_{S_0}^\top \tilde{\mathbf{X}}_{S_0}]^{-1} \tilde{\mathbf{X}}_{S_0}^\top \epsilon \right\|_\infty}{\left\| [\mathbf{X}_{S_0}^\top \mathbf{X}_{S_0}]^{-1} \mathbf{X}_{S_0}^\top \epsilon \right\|_\infty}.$$

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- κ_F measures the transferability of source datasets. For $k = 1, \dots, K$,
 - if $\mathbf{X}_{S_k}^{(k)} \perp \mathbf{X}_{S_0}^{(k)}$, all active features are transferable, then $\kappa_F = 1$;
 - if $S_0 \subset S_k$, all active features are non-transferable, then $\kappa_F \asymp \sqrt{N/n_T}$, and the final rate becomes $\sqrt{s \log s / n_T}$.

Theoretical Guarantee of AdaTrans

Theorem (Oracle property of AdaTrans)

Consider the parametric space

$$\Theta_1 = \left\{ \left\| \delta_{S_k}^{(k)} \right\|_{\min} \geq h_k^\wedge, \left\| \delta_{S_k^c}^{(k)} \right\|_{\max} = 0, k = 1, \dots, K; \left\| \beta_{S_0}^{(0)} \right\|_{\min} \geq h_0^\wedge, \left\| \beta_{S_0^c}^{(0)} \right\|_{\max} = 0 \right\}.$$

Suppose for some $a > a_2 \geq 0$, the initial estimators satisfy

$$\left\| \hat{\beta}_{init}^{(0)} - \beta^{(0)} \right\|_\infty \leq \frac{a_2}{2} \lambda_0, \quad \left\| \hat{\delta}_{init}^{(k)} - \delta^{(k)} \right\|_\infty \leq \frac{a_2}{2} \lambda_1;$$

the minimal target signal $h_0^\wedge \geq a\lambda_0 \gtrsim \sqrt{\frac{\log p}{N}}$, and the non-transferable signal $h_k^\wedge \geq a\lambda_1 \gtrsim \sqrt{\frac{n_s}{N} \frac{\log p}{N}}$, and $n_s \gtrsim \log p$. Then by choosing $w_{0j} = \mathcal{P}'_{\lambda_0}(\hat{\beta}_{init,j}^{(0)})/\lambda_0$ and $w_{kj} = \mathcal{P}'_{\lambda_1}(\hat{\delta}_{init,j}^{(k)})/\lambda_1$, with probability larger than $1 - \exp(-c_1 \log p)$, we obtain the oracle AdaTrans.

Outline

4 Numerical Studies

- Simulation Examples for TransFusion
- Simulation Examples for AdaTrans

Simulation settings for TransFusion

Recall the regression models

$$\mathbf{y}^{(0)} = \mathbf{X}^{(0)}\boldsymbol{\beta}^{(0)} + \boldsymbol{\epsilon}^{(0)}, \quad \mathbf{y}^{(k)} = \mathbf{X}^{(k)}(\boldsymbol{\beta}^{(0)} + \boldsymbol{\delta}^{(k)}) + \boldsymbol{\epsilon}^{(k)}, \quad k = 1, \dots, K.$$

General setup:

- Target task: $n_T = 150$, $s = 10$, $\boldsymbol{\beta}^{(0)} = (\mathbf{1}_s^\top, \mathbf{0}_{p-s}^\top)^\top$, $\boldsymbol{\epsilon}_i^{(0)} \sim N(0, 1)$.
- Source task: $n_S = 200$, $K \in \{1, 3, 5, 7, 9\}$, $\boldsymbol{\epsilon}_i^{(k)} \sim N(0, 1)$.

Model shift:

- $\boldsymbol{\delta}_j^{(k)} \sim N(0.1, 0.2^2)$ for $1 \leq j \leq 50$ and $\boldsymbol{\delta}_j^{(k)} = 0$ otherwise.

Covariate shift:

- Homogeneous design (without covariate shift): Each $\mathbf{X}_i^{(k)} \sim N(0, \mathbf{I})$.
- Heterogeneous design (with covariate shift): Each $\mathbf{X}_i^{(k)} \sim N(0, \boldsymbol{\Sigma}^{(k)})$, with $\boldsymbol{\Sigma}^{(k)} = (\mathbf{A}^{(k)})^\top (\mathbf{A}^{(k)}) + \mathbf{I}$, where $\mathbf{A}^{(k)}$ is a random matrix with each entry equals 0.3 with probability 0.3 and equals 0 with probability 0.7.

Methods to be compared

- Lasso (baseline): LASSO regression on the target task.
- TransLasso (first-step) (Li et al., 2022): pooled estimator.
- TransLasso (two-step) (Li et al., 2022): debiased estimator.
- TransHDGLM (Li et al., 2023).
- TransFusion (first-step): the first step TransFusion estimator $\hat{\beta}_{TF1}^{(0)}$.
- TransFusion (two-step): the debiased TransFusion estimator $\hat{\beta}_{TF2}^{(0)}$.

Simulation Results: TransFusion

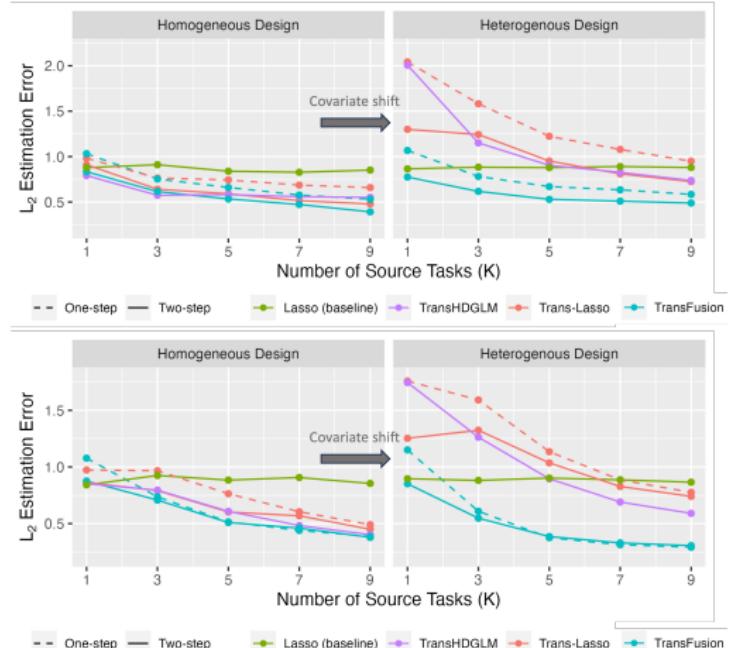


Figure: Estimation errors with/without covariate shift. Upper panel: task diversity $\epsilon_D \neq 0$; lower panel: $\epsilon_D = 0$.

Simulation Results: D-TransFusion

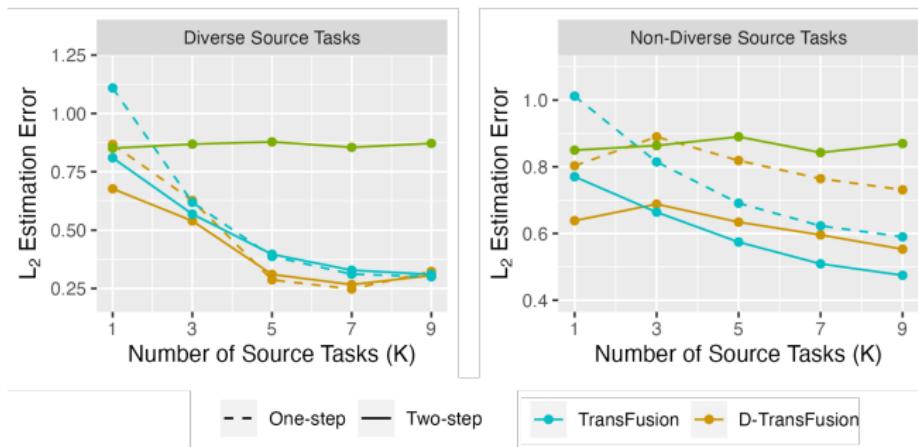


Figure: Estimation errors with $\epsilon_D = 0$ (left panel) and $\epsilon_D \neq 0$ (right panel).

Outline

4 Numerical Studies

- Simulation Examples for TransFusion
- Simulation Examples for AdaTrans

Simulation Settings for AdaTrans

Recall the regression models

$$\mathbf{y}^{(0)} = \mathbf{X}^{(0)}\boldsymbol{\beta}^{(0)} + \boldsymbol{\epsilon}^{(0)}, \quad \mathbf{y}^{(k)} = \mathbf{X}^{(k)}(\boldsymbol{\beta}^{(0)} + \boldsymbol{\delta}^{(k)}) + \boldsymbol{\epsilon}^{(k)}, \quad k = 1, \dots, K.$$

General setup:

- Target task: $n_T = 50$, $s = 8$, $\boldsymbol{\beta}^{(0)} = (\mathbf{1}_s^\top, \mathbf{0}_{p-s}^\top)^\top$, $\boldsymbol{\epsilon}_i^{(0)} \sim N(0, 1)$.
- Source task: $n_S = 200$, $K = 2$, $\boldsymbol{\epsilon}_i^{(k)} \sim N(0, 1)$.

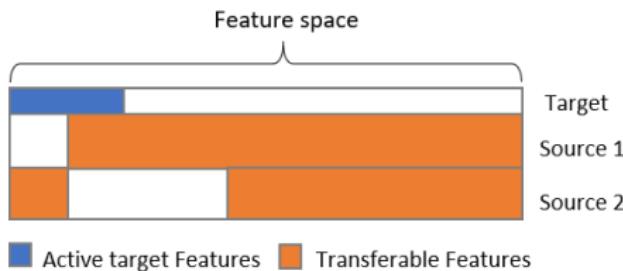
Covariate shift: Same as TransFusion.

Simulation Settings for AdaTrans

Model shift:

We generate two source samples with non-overlapping transferable features:

- First source: the non-transferable $\delta^{(k)}$ is nonzero for the first $s/2$ elements;
- Second source: the non-transferable $\delta^{(k)}$ is nonzero from $(s/2 + 1)$ -th to 25th elements.



Methods to be compared

- Lasso (baseline): LASSO regression on the target task.
- TransGLM (Tian and Feng, 2022): TransLasso with source detection.
- AdaTrans: AdaTrans estimator.
- Oracle AdaTrans: Oracle AdaTrans estimator.

Simulation Results: AdaTrans

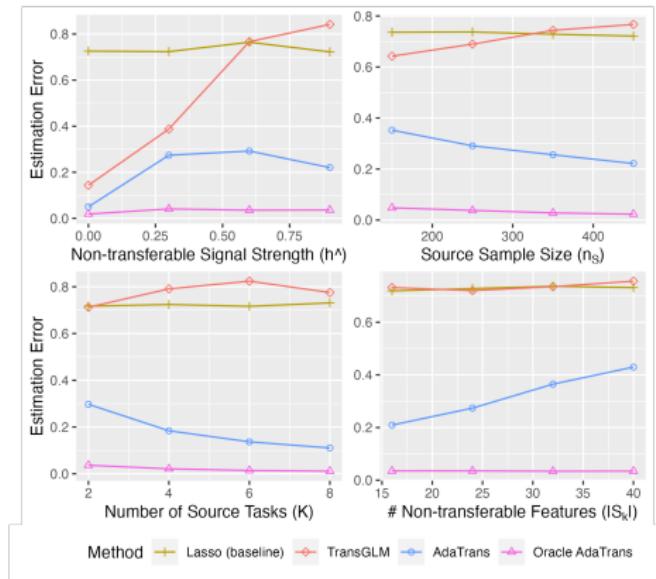


Figure: Estimation errors of different transfer learning methods.

- AdaTrans can also auto-detect and filter out non-transferable features.

Conclusion

We proposed a new transfer learning framework that is robust to covariate shift and adaptive to feature-specific transferable structure.

- **TransFusion:** Conducting a fused-regularization based “joint training + debiasing” to achieve covariate-shift robustness.
- **D-TransFusion:** Incorporating intermediate estimators from different machines into TransFusion with one-shot communication.
- **AdaTrans:** Utilizing folded-concave penalization to auto-detect transferable structure while estimating parameters.
- Non-asymptotic bounds of estimation errors for all proposed estimators are established.

Thank You!