

Amateur Radio Homebrew Experiments

Homebrew SSB SDR Rig

About Me



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Blog Archive

▼ 2018 (5)

► August (1)

▶ June (1)

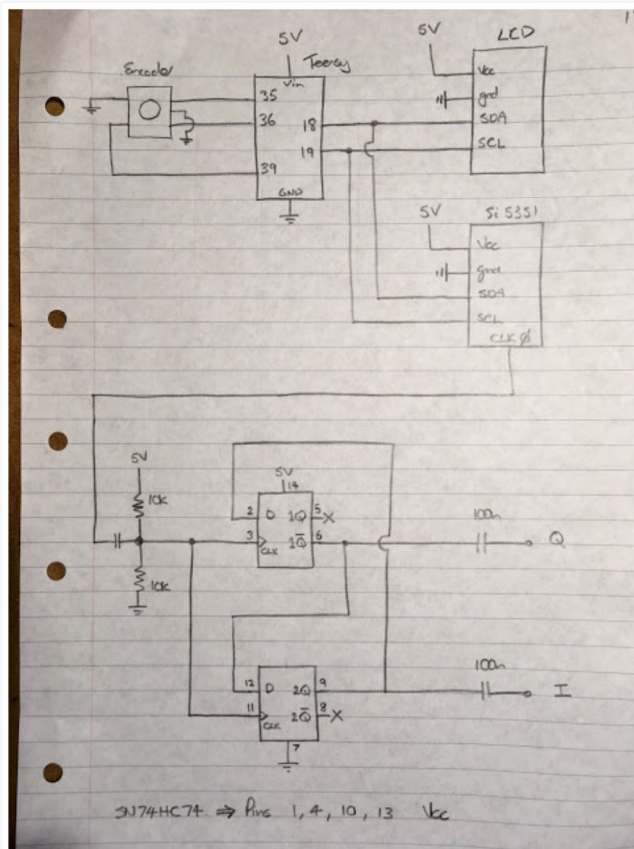
▼ March (2)

Homebrew SSB SDR Rig

Si5351 DDS VFO/BFO Example Software

► January (1)

► 2017 (5)



```
#include <Wire.h>           // I2C comms
#include <si5351.h>          // Si5351 library
#include <LiquidCrystal_I2C.h> // LCD library
```

```
// Rotary Encoder
static const int pushPin = 39;
static const int rotBPin = 36;
static const int rotAPin = 35;
volatile int rotState = 0;
```

```

volatile int rotAval = 1;
volatile int rotBval = 1;
volatile int rotAcc = 0;

// Instantiate the Objects
LiquidCrystal_I2C lcd(0x3F, 16, 2);    // set the LCD address to either 0x27 or 0x3F for a 16
chars and 2 line display
Si5351 si5351;

void setup()
{
    // Set up input switches
    pinMode(rotAPin, INPUT);
    pinMode(rotBPin, INPUT);
    pinMode(pushPin, INPUT);
    digitalWrite(rotAPin, HIGH);
    digitalWrite(rotBPin, HIGH);
    digitalWrite(pushPin, HIGH);

    // Set up interrupt pins
    attachInterrupt(digitalPinToInterrupt(rotAPin), ISRrotAChange, CHANGE);
    attachInterrupt(digitalPinToInterrupt(rotBPin), ISRrotBChange, CHANGE);

    // Initialise the lcd
    lcd.begin();
    lcd.backlight();

    // Initialise the DDS
    si5351.init(SI5351_CRYSTAL_LOAD_8PF, 0);
    si5351.set_pll(SI5351_PLL_FIXED, SI5351_PLLA);
    si5351.drive_strength(SI5351_CLK0, SI5351_DRIVE_8MA);
    si5351.set_freq((freq * 100ULL), SI5351_PLL_FIXED, SI5351_CLK0);

    UpdateDisplay();
}

void loop()
{
    if (freq != oldfreq)
    {
        UpdateDisplay();
        SendFrequency();
        oldfreq = freq;
    }

    if (digitalRead(pushPin) == LOW)
    {
        delay(10);
        while (digitalRead(pushPin) == LOW)
        {
            if (updatedisplay == 1)
            {
                UpdateDisplay();
                updatedisplay = 0;
            }
        }
        delay(50);
    }
}

// Interrupt routines
void ISRrotAChange()
{
    if (digitalRead(rotAPin))
    {
        rotAval = 1;
        UpdateRot();
    }
    else
    {
        rotAval = 0;
        UpdateRot();
    }
}

```

```

void ISRrotBChange()
{
    if (digitalRead(rotBPin))
    {
        rotBval = 1;
        UpdateRot();
    }
    else
    {
        rotBval = 0;
        UpdateRot();
    }
}

void UpdateRot()
{
    switch (rotState)
    {
        case 0: // Idle state, look for direction
            if (!rotBval)
            {
                rotState = 1; // CW 1
            }
            if (!rotAval)
            {
                rotState = 11; // CCW 1
            }
            break;

        case 1: // CW, wait for A low while B is low
            if (!rotBval)
            {
                if (!rotAval)
                {
                    // either increment radixindex or freq
                    if (digitalRead(pushPin) == LOW)
                    {
                        updatedisplay = 1;
                        if (radix == 1000000)
                            radix = 100000;
                        else if (radix == 100000)
                            radix = 10000;
                        else if (radix == 10000)
                            radix = 1000;
                        else if (radix == 1000)
                            radix = 100;
                        else if (radix == 100)
                            radix = 10;
                        else if (radix == 10)
                            radix = 1;
                        else
                            radix = 1000000;
                    }
                    else
                    {
                        freq = (freq + radix);
                        if (freq > bandEnd)
                            freq = bandEnd;
                    }
                }
                rotState = 2; // CW 2
            }
            }
        else if (rotAval)
        {
            rotState = 0; // It was just a glitch on B, go back to start
            break;
        }

        case 2: // CW, wait for B high
            if (rotBval)
            {
                rotState = 3; // CW 3
            }
            break;

        case 3: // CW, wait for A high
            if (rotAval)
            {
                rotState = 0; // back to idle (detent) state
            }
            break;

        case 11: // CCW, wait for B low while A is low
            if (!rotAval)
            {
                if (!rotBval)
                {

```

```

// either decrement radixindex or freq
if (digitalRead(pushPin) == LOW)
{
    updatedisplay = 1;
    if (radix == 1)
        radix = 10;
    else if (radix == 10)
        radix = 100;
    else if (radix == 100)
        radix = 1000;
    else if (radix == 1000)
        radix = 10000;
    else if (radix == 10000)
        radix = 100000;
    else if (radix == 100000)
        radix = 1000000;
    else
        radix = 1;
}
else
{
    freq = (freq - radix);
    if (freq < bandStart)
        freq = bandStart;
}
rotState = 12;           // CCW 2
}
}
else if (rotBval)
    rotState = 0;         // It was just a glitch on A, go back to start
break;

case 12:                 // CCW, wait for A high
    if (rotAval)
        rotState = 13;   // CCW 3
    break;

case 13:                 // CCW, wait for B high
    if (rotBval)
        rotState = 0;    // back to idle (detent) state
    break;
}
}
}

```

```

void UpdateDisplay()
{
    lcd.cursor();           // Turn on the cursor
    lcd.setCursor(0, 0);
    lcd.print(" ");
    lcd.setCursor(0, 0);
    lcd.print(freq);
    lcd.setCursor(10, 0);
    lcd.print("ZL2CTM");

    lcd.setCursor(0, 1);
    lcd.print(" ");
    lcd.setCursor(0, 1);

    if (freq > 9999999)
    {
        if (radix == 1)
            lcd.setCursor(7, 0);
        if (radix == 10)
            lcd.setCursor(6, 0);
        if (radix == 100)
            lcd.setCursor(5, 0);
        if (radix == 1000)
            lcd.setCursor(4, 0);
        if (radix == 10000)
            lcd.setCursor(3, 0);
        if (radix == 100000)
            lcd.setCursor(2, 0);
        if (radix == 1000000)
            lcd.setCursor(1, 0);
    }
    if (freq <= 9999999)
    {

```

```

if (radix == 1)
  lcd.setCursor(6, 0);
if (radix == 10)
  lcd.setCursor(5, 0);
if (radix == 100)
  lcd.setCursor(4, 0);
if (radix == 1000)
  lcd.setCursor(3, 0);
if (radix == 10000)
  lcd.setCursor(2, 0);
if (radix == 100000)
  lcd.setCursor(1, 0);
if (radix == 1000000)
  lcd.setCursor(0, 0);
}
}

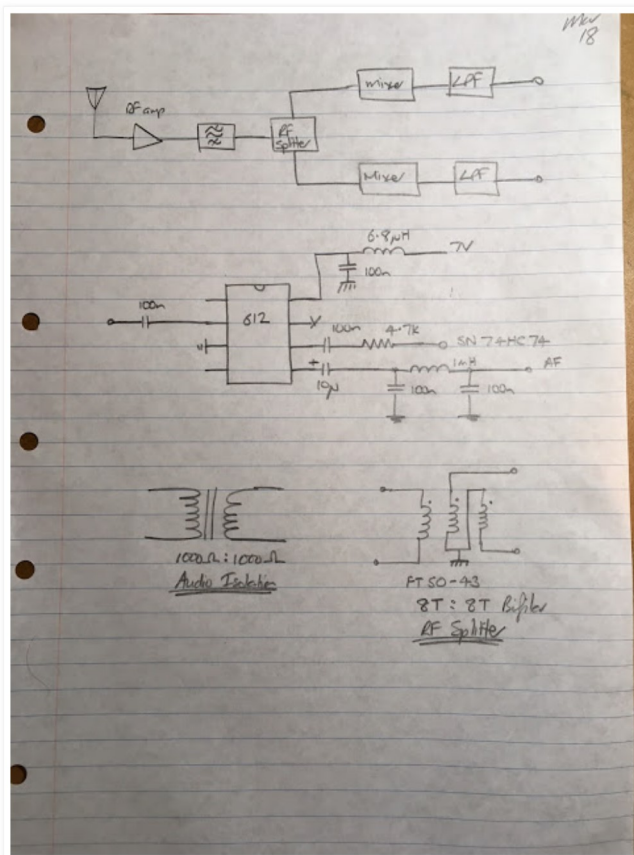
```

```

void SendFrequency()
{
  si5351.set_freq((freq * 4) * 100ULL, SI5351_PLL_FIXED, SI5351_CLK0);
}

```

Dual Quadrature NE612 Direct Conversion Front End



Antenna RF Amplifier

Please note the collector inductor below is 1mH NOT 1uH

18

Ant Amp

let $I_c = 10\text{mA}$ $\beta = 100$ $V_E = \frac{1}{10} V_{cc}$

$R_E = \frac{\frac{1}{10} \times 12.8\text{V}}{10\text{mA}} = 12.8 \quad (120\Omega)$

$R_B = \frac{(\frac{1}{10} \times 12.8\text{V}) + 0.7}{10 \times \frac{10\text{mA}}{100}} = 1980 \quad (2000\Omega)$

$R_1 = \frac{12.8\text{V} - [(\frac{1}{10} \times 12.8\text{V}) + 0.7]}{11 \times \frac{10\text{mA}}{100}} = 9836 \quad (10\text{k})$

check $C_c < 100\Omega @ 3.5\text{MHz}$ $X_c = \frac{1}{2\pi f C}$

$X_c = \frac{1}{2\pi \times 3.5\text{MHz} \times 100\text{nF}}$

$= 0.45\Omega \quad \checkmark$

Feedback

- LTSpice suggests $1\text{k}\Omega + 10\text{nF}$
- In circuit tests $510\Omega + 10\text{nF}$

80m/20m Bandpass Filter

BPFs

Appendix 2 to Solid State Design for the Radio Amateur

80m

L. 39T Red T68-2
C. 120pF // 0-50pF trim cap

20m

L. 20T Yellow T68-6
C. 10pF // 0-50pF trim cap

Gain

parallel cap

X

```

#include <Wire.h>           // I2C comms
#include <si5351.h>         // Si5351 library
#include <LiquidCrystal_I2C.h> // LCD library
#include <Audio.h>          // Teensy audio library

// Define Constants and Variables
static const long bandStart = 1000000; // start of HF band
static const long bandEnd = 30000000; // end of HF band
static const long bandInit = 3690000; // where to initially set the frequency
volatile long oldfreq = 0;
volatile long freq = bandInit;
volatile long radix = 1000; // how much to change the frequency by, clicking the rotary
encoder will change this.
volatile int updatedisplay = 0;

// Rotary Encoder
static const int pushPin = 39;
static const int rotBPin = 36;
static const int rotAPin = 35;
volatile int rotState = 0;
volatile int rotAval = 1;
volatile int rotBval = 1;
volatile int rotAcc = 0;

// Instantiate the Objects
LiquidCrystal_I2C lcd(0x3F, 16, 2); // Set the LCD address to either 0x27 or 0x3F for a 16
chars and 2 line display
Si5351 si5351; // The Si5351 DDS
AudioControlSGTL5000 audioShield; // The Teensy audio CODEC on the audio shield

// Audio shield
AudioInputI2S audiInput; // What we call the input to the audio shield
AudioOutputI2S audioOutput; // What we call the output of the audio
shield
AudioConnection patchCord5(audiInput, 0, audioOutput, 0); // Left channel in to left
channel out
AudioConnection patchCord10(audiInput, 1, audioOutput, 1); // Right channel in to right
channel out

void setup()
{
    // Setup input switches
    pinMode(rotAPin, INPUT);
    pinMode(rotBPin, INPUT);
    pinMode(pushPin, INPUT);
    digitalWrite(rotAPin, HIGH);
    digitalWrite(rotBPin, HIGH);
    digitalWrite(pushPin, HIGH);

    // Setup interrupt pins
    attachInterrupt(digitalPinToInterrupt(rotAPin), ISRrotAChange, CHANGE);
    attachInterrupt(digitalPinToInterrupt(rotBPin), ISRrotBChange, CHANGE);

    // Setup the lcd
    lcd.begin();
    lcd.backlight();

    // Setup the DDS
    si5351.init(SI5351_CRYSTAL_LOAD_8PF, 0);
    si5351.set_pll(SI5351_PLL_FIXED, SI5351_PLLA);
    si5351.drive_strength(SI5351_CLK0, SI5351_DRIVE_8MA);
    si5351.set_freq((freq * 100ULL), SI5351_PLL_FIXED, SI5351_CLK0);

    // Setup the audio shield
    AudioNoInterrupts();
    AudioMemory(16);
    audioShield.enable();
    audioShield.inputSelect(AUDIO_INPUT_LINEIN);
    audioShield.volume(0.7);
    audioShield.unmuteLineout();
    AudioInterrupts();

    UpdateDisplay();
}

void loop()

```

```

{
  if (freq != oldfreq)
  {
    UpdateDisplay();
    SendFrequency();
    oldfreq = freq;
  }

  if (digitalRead(pushPin) == LOW)
  {
    delay(10);
    while (digitalRead(pushPin) == LOW)
    {
      if (updatedisplay == 1)
      {
        UpdateDisplay();
        updatedisplay = 0;
      }
    }
    delay(50);
  }
}

// Interrupt routines
void ISRrotAChange()
{
  if (digitalRead(rotAPin))
  {
    rotAval = 1;
    UpdateRot();
  }
  else
  {
    rotAval = 0;
    UpdateRot();
  }
}

void ISRrotBChange()
{
  if (digitalRead(rotBPin))
  {
    rotBval = 1;
    UpdateRot();
  }
  else
  {
    rotBval = 0;
    UpdateRot();
  }
}

void UpdateRot()
{
  switch (rotState)
  {
    case 0: // Idle state, look for direction
      if (!rotBval)
        rotState = 1; // CW 1
      if (!rotAval)
        rotState = 11; // CCW 1
      break;

    case 1: // CW, wait for A low while B is low
      if (!rotBval)
      {
        if (!rotAval)
        {
          // either increment radixindex or freq
          if (digitalRead(pushPin) == LOW)
          {
            updatedisplay = 1;
            if (radix == 1000000)
              radix = 100000;
            else if (radix == 100000)

```



```

        radix = 10000;
    else if (radix == 10000)
        radix = 1000;
    else if (radix == 1000)
        radix = 100;
    else if (radix == 100)
        radix = 10;
    else if (radix == 10)
        radix = 1;
    else
        radix = 1000000;
    }
    else
    {
        freq = (freq + radix);
        if (freq > bandEnd)
            freq = bandEnd;
    }
    rotState = 2;           // CW 2
}
}
else if (rotAval)
    rotState = 0;           // It was just a glitch on B, go back to start
break;

case 2:                    // CW, wait for B high
    if (rotBval)
        rotState = 3;       // CW 3
    break;

case 3:                    // CW, wait for A high
    if (rotAval)
        rotState = 0;       // back to idle (detent) state
    break;

case 11:                   // CCW, wait for B low while A is low
    if (!rotAval)
    {
        if (!rotBval)
        {
            // either decrement radixindex or freq
            if (digitalRead(pushPin) == LOW)
            {
                updatedisplay = 1;
                if (radix == 1)
                    radix = 10;
                else if (radix == 10)
                    radix = 100;
                else if (radix == 100)
                    radix = 1000;
                else if (radix == 1000)
                    radix = 10000;
                else if (radix == 10000)
                    radix = 100000;
                else if (radix == 100000)
                    radix = 1000000;
                else
                    radix = 1;
            }
        }
        else
        {
            freq = (freq - radix);
            if (freq < bandStart)
                freq = bandStart;
        }
        rotState = 12;       // CCW 2
    }
}
else if (rotBval)
    rotState = 0;           // It was just a glitch on A, go back to start
break;

case 12:                   // CCW, wait for A high
    if (rotAval)
        rotState = 13;       // CCW 3
    break;

case 13:                   // CCW, wait for B high
    if (rotBval)

```

```

        rotState = 0;                // back to idle (detent) state
        break;
    }
}

void UpdateDisplay()
{
    lcd.cursor();                    // Turn on the cursor
    lcd.setCursor(0, 0);
    lcd.print(" ");
    lcd.setCursor(0, 0);
    lcd.print(freq);
    lcd.setCursor(10, 0);
    lcd.print("ZL2CTM");

    lcd.setCursor(0, 1);
    lcd.print(" ");
    lcd.setCursor(0, 1);

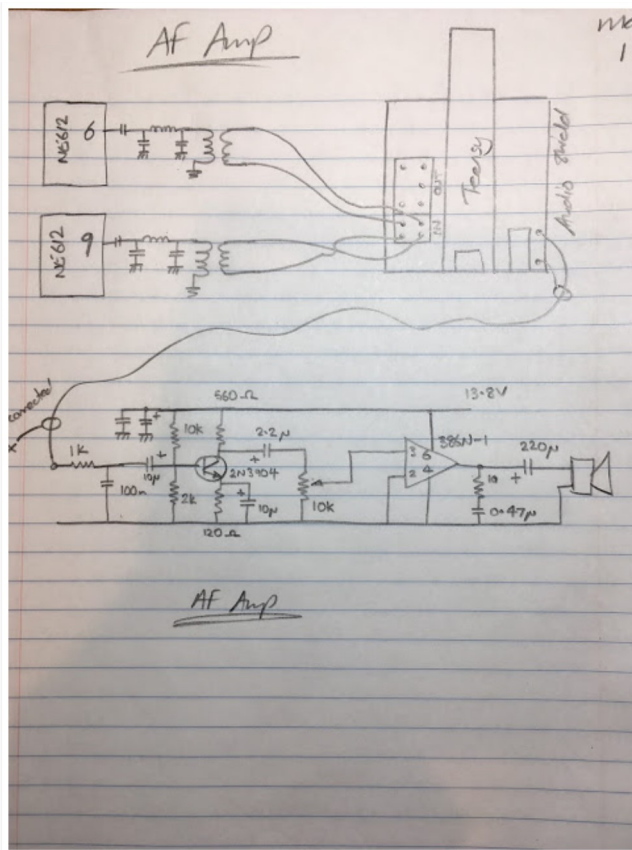
    if (freq > 9999999)
    {
        if (radix == 1)
            lcd.setCursor(7, 0);
        if (radix == 10)
            lcd.setCursor(6, 0);
        if (radix == 100)
            lcd.setCursor(5, 0);
        if (radix == 1000)
            lcd.setCursor(4, 0);
        if (radix == 10000)
            lcd.setCursor(3, 0);
        if (radix == 100000)
            lcd.setCursor(2, 0);
        if (radix == 1000000)
            lcd.setCursor(1, 0);
    }

    if (freq <= 9999999)
    {
        if (radix == 1)
            lcd.setCursor(6, 0);
        if (radix == 10)
            lcd.setCursor(5, 0);
        if (radix == 100)
            lcd.setCursor(4, 0);
        if (radix == 1000)
            lcd.setCursor(3, 0);
        if (radix == 10000)
            lcd.setCursor(2, 0);
        if (radix == 100000)
            lcd.setCursor(1, 0);
        if (radix == 1000000)
            lcd.setCursor(0, 0);
    }
}

void SendFrequency()
{
    si5351.set_freq((freq * 4) * 100ULL, SI5351_PLL_FIXED, SI5351_CLK0);
}

```

AF Amplifier



```
// Libraries
#include <Wire.h> // I2C comms library
#include <si5351.h> // Si5351Jason library
#include <LiquidCrystal_I2C.h> // LCD library
#include <Audio.h> // Teensy audio library

// Number of Filter Coefficients
#define NO_HILBERT_COEFFS 70 // Used to define the Hilbert transform filter arrays.
// More typical than 'const int'.

// Define Constants and Variables
static const long bandStart = 1000000; // start of HF band
static const long bandEnd = 30000000; // end of HF band
static const long bandInit = 3690000; // where to initially set the frequency
volatile long oldfreq = 0;
volatile long freq = bandInit;
volatile long radix = 1000; // how much to change the frequency by clicking the rotary
encoder will change this.
volatile int updatedisplay = 0;

// Rotary Encoder
static const int pushPin = 39;
static const int rotBPin = 36;
static const int rotAPin = 35;
volatile int rotState = 0;
volatile int rotAval = 1;
volatile int rotBval = 1;
volatile int rotAcc = 0;

// Iowa Hills Hilbert transform filter coefficients
const short Hilbert_Plus_45_Coeffs[NO_HILBERT_COEFFS] = {
  (short)(32768 * -0.000287988910943357),
  (short)(32768 * -0.000383511439791303),
  (short)(32768 * -0.000468041804899774),
  (short)(32768 * -0.000529324432676899),
  (short)(32768 * -0.000569479602046985),
  (short)(32768 * -0.000616670267768531),
  (short)(32768 * -0.000731530748681977),

```

```
(short)(32768 * -0.001002372095321225),
(short)(32768 * -0.001525299390682192),
(short)(32768 * -0.002370114347025230),
(short)(32768 * -0.003539247773172147),
(short)(32768 * -0.004932965382552984),
(short)(32768 * -0.006337182914262393),
(short)(32768 * -0.007448193692118567),
(short)(32768 * -0.007940501940620482),
(short)(32768 * -0.007570802072162988),
(short)(32768 * -0.006296120449841751),
(short)(32768 * -0.004371955618154949),
(short)(32768 * -0.002391875073164555),
(short)(32768 * -0.001236984700413469),
(short)(32768 * -0.001922560128827416),
(short)(32768 * -0.005356720327533458),
(short)(32768 * -0.012055656297010635),
(short)(32768 * -0.021882952959947619),
(short)(32768 * -0.033888748300090733),
(short)(32768 * -0.046312736456333638),
(short)(32768 * -0.056783367797647665),
(short)(32768 * -0.062699937453677912),
(short)(32768 * -0.061735375084135742),
(short)(32768 * -0.052358513976237808),
(short)(32768 * -0.034257179158167443),
(short)(32768 * -0.008554500746482946),
(short)(32768 * 0.022249911747384360),
(short)(32768 * 0.054622962942346594),
(short)(32768 * 0.084568844473140448),
(short)(32768 * 0.108316122839950818),
(short)(32768 * 0.122979341462627859),
(short)(32768 * 0.127056096658453188),
(short)(32768 * 0.120656295327679283),
(short)(32768 * 0.105420364259485699),
(short)(32768 * 0.084152608145489444),
(short)(32768 * 0.060257510644444748),
(short)(32768 * 0.037105711921879434),
(short)(32768 * 0.017464092086704748),
(short)(32768 * 0.003100559033325746),
(short)(32768 * -0.005373489802481697),
(short)(32768 * -0.008418211280310166),
(short)(32768 * -0.007286730644726664),
(short)(32768 * -0.003638388931163832),
(short)(32768 * 0.000858330713630433),
(short)(32768 * 0.004847436504682235),
(short)(32768 * 0.007476399317750315),
(short)(32768 * 0.008440227567663121),
(short)(32768 * 0.007898970420636600),
(short)(32768 * 0.006314366257036837),
(short)(32768 * 0.004261033495040515),
(short)(32768 * 0.002261843500794377),
(short)(32768 * 0.000680212977485724),
(short)(32768 * -0.000319493110301691),
(short)(32768 * -0.000751893569425181),
(short)(32768 * -0.000752248417868501),
(short)(32768 * -0.000505487955986662),
(short)(32768 * -0.000184645628631330),
(short)(32768 * 0.000087913008490067),
(short)(32768 * 0.000253106348867209),
(short)(32768 * 0.000306473486382603),
(short)(32768 * 0.000277637042003169),
(short)(32768 * 0.000207782317481292),
(short)(32768 * 0.000132446796990356),
(short)(32768 * 0.000072894261560354)
```

```
};
```

```
// Iowa Hills Hilbert transform filter coefficients
```

```
const short Hilbert_Minus_45_Coeffs[NO_HILBERT_COEFFS] = {
    (short)(32768 * -0.000072894261560345),
    (short)(32768 * -0.000132446796990344),
    (short)(32768 * -0.000207782317481281),
    (short)(32768 * -0.000277637042003168),
    (short)(32768 * -0.000306473486382623),
    (short)(32768 * -0.000253106348867259),
    (short)(32768 * -0.000087913008490148),
    (short)(32768 * 0.000184645628631233),
    (short)(32768 * 0.000505487955986583),
    (short)(32768 * 0.000752248417868491),
    (short)(32768 * 0.000751893569425298),
    (short)(32768 * 0.000319493110301983),
```

```
(short)(32768 * -0.000680212977485245),
(short)(32768 * -0.002261843500793748),
(short)(32768 * -0.004261033495039842),
(short)(32768 * -0.006314366257036280),
(short)(32768 * -0.007898970420636345),
(short)(32768 * -0.008440227567663343),
(short)(32768 * -0.007476399317751102),
(short)(32768 * -0.004847436504683540),
(short)(32768 * -0.000858330713632029),
(short)(32768 * 0.003638388931162351),
(short)(32768 * 0.007286730644725833),
(short)(32768 * 0.008418211280310565),
(short)(32768 * 0.005373489802483816),
(short)(32768 * -0.00310055903321630),
(short)(32768 * -0.017464092086698697),
(short)(32768 * -0.037105711921871905),
(short)(32768 * -0.060257510644436532),
(short)(32768 * -0.084152608145481672),
(short)(32768 * -0.105420364259479538),
(short)(32768 * -0.120656295327675800),
(short)(32768 * -0.127056096658453216),
(short)(32768 * -0.122979341462631633),
(short)(32768 * -0.108316122839958146),
(short)(32768 * -0.084568844473150454),
(short)(32768 * -0.054622962942358168),
(short)(32768 * -0.022249911747396132),
(short)(32768 * 0.008554500746472333),
(short)(32768 * 0.034257179158159054),
(short)(32768 * 0.052358513976232306),
(short)(32768 * 0.061735375084133286),
(short)(32768 * 0.062699937453678217),
(short)(32768 * 0.056783367797650072),
(short)(32768 * 0.046312736456337288),
(short)(32768 * 0.033888748300094730),
(short)(32768 * 0.021882952959951244),
(short)(32768 * 0.012055656297013388),
(short)(32768 * 0.005356720327535105),
(short)(32768 * 0.001922560128828006),
(short)(32768 * 0.001236984700413229),
(short)(32768 * 0.002391875073163812),
(short)(32768 * 0.004371955618154038),
(short)(32768 * 0.006296120449840938),
(short)(32768 * 0.007570802072162439),
(short)(32768 * 0.007940501940620253),
(short)(32768 * 0.007448193692118624),
(short)(32768 * 0.006337182914262643),
(short)(32768 * 0.004932965382553323),
(short)(32768 * 0.003539247773172483),
(short)(32768 * 0.002370114347025498),
(short)(32768 * 0.001525299390682370),
(short)(32768 * 0.001002372095321316),
(short)(32768 * 0.000731530748682004),
(short)(32768 * 0.000616670267768521),
(short)(32768 * 0.000569479602046963),
(short)(32768 * 0.000529324432676881),
(short)(32768 * 0.000468041804899765),
(short)(32768 * 0.000383511439791304),
(short)(32768 * 0.000287988910943362)
};
```

// Instantiate the Objects

```
LiquidCrystal_I2C lcd(0x3F, 16, 2);    // Name for the LCD. Set the LCD address to either 0x27
or 0x3F for a 16 chars and 2 line display
Si5351 si5351;                        // Name for the Si5351 DDS
AudioControlSGTL5000 audioShield;    // Name for the Teensy audio CODEC on the audio
shield
```

```
// Audio shield
AudioInputI2S    audioInput;          // Name for the input to the audio
shield
AudioOutputI2S    audioOutput;        // Name for the output of the audio
shield
// Receiver
AudioFilterFIR    RX_Hilbert_Plus_45; // Name for the RX +45 Hilbert
transform
AudioFilterFIR    RX_Hilbert_Minus_45; // Name for the RX +45 Hilbert
transform
AudioMixer4        RX_Summer;         // Name for the RX summer
```

```
// Audio connections
AudioConnection patchCord5(audioInput, 0, RX_Hilbert_Plus_45, 0); // Left channel in
Hilbert transform +45
AudioConnection patchCord10(audioInput, 1, RX_Hilbert_Minus_45, 0); // Right channel in
Hilbert transform -45
AudioConnection patchCord15(RX_Hilbert_Plus_45, 0, RX_Summer, 0); // Hilbert
transform +45 to receiver summer
AudioConnection patchCord20(RX_Hilbert_Minus_45, 0, RX_Summer, 1); // Hilbert
transform -45 to receiver summer
AudioConnection patchCord25(RX_Summer, 0, audioOutput, 0); // Receiver summer
to receiver LPF
```

```
void setup()
{
  // Setup input switches
  pinMode(rotAPin, INPUT);
  pinMode(rotBPin, INPUT);
  pinMode(pushPin, INPUT);
  digitalWrite(rotAPin, HIGH);
  digitalWrite(rotBPin, HIGH);
  digitalWrite(pushPin, HIGH);

  // Setup interrupt pins
  attachInterrupt(digitalPinToInterrupt(rotAPin), ISRrotAChange, CHANGE);
  attachInterrupt(digitalPinToInterrupt(rotBPin), ISRrotBChange, CHANGE);

  // Setup the lcd
  lcd.begin();
  lcd.backlight();

  // Setup the DDS
  si5351.init(SI5351_CRYSTAL_LOAD_8PF, 0);
  si5351.set_pll(SI5351_PLL_FIXED, SI5351_PLLA);
  si5351.drive_strength(SI5351_CLK0, SI5351_DRIVE_8MA);
  si5351.set_freq((freq * 100ULL), SI5351_PLL_FIXED, SI5351_CLK0);

  // Setup the audio shield
  AudioNoInterrupts();
  AudioMemory(16);
  audioShield.enable();
  audioShield.volume(0.7); // Constant. Use external volume control on the audio amp
  AudioInterrupts();

  // Setup transceiver mode
  Turn_On_Receiver();
  UpdateDisplay();
}
}
```

```
void loop()
{
  if (freq != oldfreq) // Check to see if the frequency has changed. If so, update
  everything.
  {
    UpdateDisplay();
    SendFrequency();
    oldfreq = freq;
  }

  if (digitalRead(pushPin) == LOW) // Update cursor, but also stop it from flickering
  {
    delay(10);
    while (digitalRead(pushPin) == LOW)
    {
      if (updatedisplay == 1)
      {
        UpdateDisplay();
        updatedisplay = 0;
      }
    }
    delay(50);
  }
}
}
```

```
void Turn_On_Receiver()
{
  AudioNoInterrupts();
```

```

audioShield.inputSelect(AUDIO_INPUT_LINEIN);
audioShield.lineInLevel(5);           // Default is 5
audioShield.unmuteHeadphone();
RX_Hilbert_Plus_45.begin(Hilbert_Plus_45_Coeffs, NO_HILBERT_COEFFS);
RX_Hilbert_Minus_45.begin(Hilbert_Minus_45_Coeffs, NO_HILBERT_COEFFS);

if (freq <= 9999999)      // LSB
{
  RX_Summer.gain(0, 1);
  RX_Summer.gain(1, -1);
}
if (freq > 9999999)      // USB
{
  RX_Summer.gain(0, 1);
  RX_Summer.gain(1, 1);
}

AudioInterrupts();
}

// Interrupt routines
void ISRrotAChange()
{
  if (digitalRead(rotAPin))
  {
    rotAval = 1;
    UpdateRot();
  }
  else
  {
    rotAval = 0;
    UpdateRot();
  }
}

void ISRrotBChange()
{
  if (digitalRead(rotBPin))
  {
    rotBval = 1;
    UpdateRot();
  }
  else
  {
    rotBval = 0;
    UpdateRot();
  }
}

void UpdateRot()
{
  switch (rotState)
  {
    case 0:           // Idle state, look for direction
      if (!rotBval)
        rotState = 1;           // CW 1
      if (!rotAval)
        rotState = 11;          // CCW 1
      break;

    case 1:           // CW, wait for A low while B is low
      if (!rotBval)
      {
        if (!rotAval)
        {
          // either increment radixindex or freq
          if (digitalRead(pushPin) == LOW)
          {
            updatedisplay = 1;
            if (radix == 1000000)
              radix = 100000;
            else if (radix == 100000)
              radix = 10000;
            else if (radix == 10000)
              radix = 1000;
          }
        }
      }
    }
  }
}

```

```

        else if (radix == 1000)
            radix = 100;
        else if (radix == 100)
            radix = 10;
        else if (radix == 10)
            radix = 1;
        else
            radix = 1000000;
    }
    else
    {
        freq = (freq + radix);
        if (freq > bandEnd)
            freq = bandEnd;
    }
    rotState = 2;           // CW 2
}
}
else if (rotAval)
    rotState = 0;           // It was just a glitch on B, go back to start
break;

case 2:                     // CW, wait for B high
    if (rotBval)
        rotState = 3;       // CW 3
    break;

case 3:                     // CW, wait for A high
    if (rotAval)
        rotState = 0;       // back to idle (detent) state
    break;

case 11:                   // CCW, wait for B low while A is low
    if (!rotAval)
    {
        if (!rotBval)
        {
            // either decrement radixindex or freq
            if (digitalRead(pushPin) == LOW)
            {
                updatedisplay = 1;
                if (radix == 1)
                    radix = 10;
                else if (radix == 10)
                    radix = 100;
                else if (radix == 100)
                    radix = 1000;
                else if (radix == 1000)
                    radix = 10000;
                else if (radix == 10000)
                    radix = 100000;
                else if (radix == 100000)
                    radix = 1000000;
                else
                    radix = 1;
            }
        }
        else
        {
            freq = (freq - radix);
            if (freq < bandStart)
                freq = bandStart;
        }
        rotState = 12;       // CCW 2
    }
}
else if (rotBval)
    rotState = 0;           // It was just a glitch on A, go back to start
break;

case 12:                   // CCW, wait for A high
    if (rotAval)
        rotState = 13;       // CCW 3
    break;

case 13:                   // CCW, wait for B high
    if (rotBval)
        rotState = 0;       // back to idle (detent) state
    break;
}

```



```

}

void UpdateDisplay()
{
    lcd.cursor();                // Turn on the cursor
    lcd.setCursor(0, 0);
    lcd.print(" ");
    lcd.setCursor(0, 0);
    lcd.print(freq);
    lcd.setCursor(10, 0);
    lcd.print("ZL2CTM");

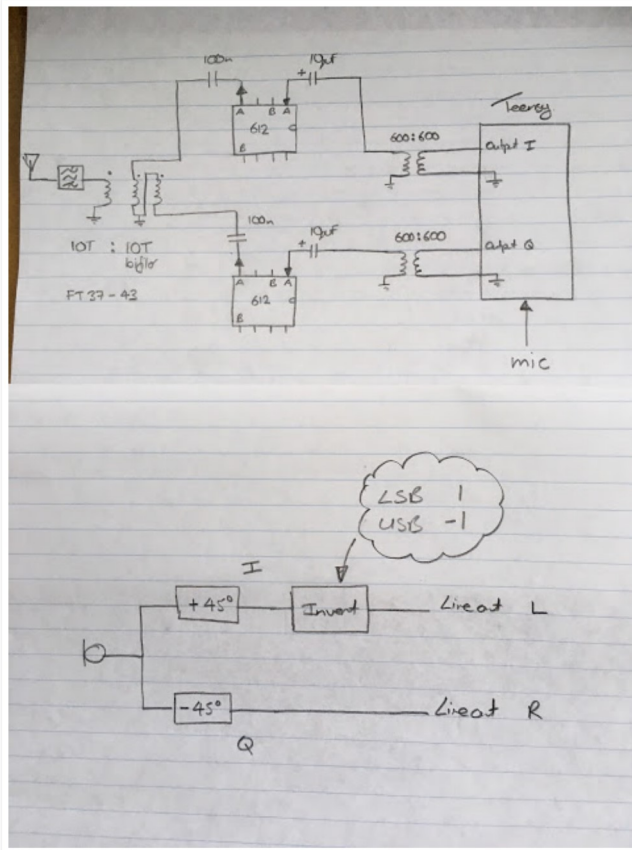
    lcd.setCursor(0, 1);
    lcd.print(" ");
    lcd.setCursor(0, 1);

    if (freq > 9999999)
    {
        if (radix == 1)
            lcd.setCursor(7, 0);
        if (radix == 10)
            lcd.setCursor(6, 0);
        if (radix == 100)
            lcd.setCursor(5, 0);
        if (radix == 1000)
            lcd.setCursor(4, 0);
        if (radix == 10000)
            lcd.setCursor(3, 0);
        if (radix == 100000)
            lcd.setCursor(2, 0);
        if (radix == 1000000)
            lcd.setCursor(1, 0);
    }
    if (freq <= 9999999)
    {
        if (radix == 1)
            lcd.setCursor(6, 0);
        if (radix == 10)
            lcd.setCursor(5, 0);
        if (radix == 100)
            lcd.setCursor(4, 0);
        if (radix == 1000)
            lcd.setCursor(3, 0);
        if (radix == 10000)
            lcd.setCursor(2, 0);
        if (radix == 100000)
            lcd.setCursor(1, 0);
        if (radix == 1000000)
            lcd.setCursor(0, 0);
    }
}

void SendFrequency()
{
    si5351.set_freq((freq * 4) * 100ULL, SI5351_PLL_FIXED, SI5351_CLK0);
}

```

Transmit Test Configuration



Transmit Test Code

Note, the formatting has been messed up from cutting and pasting. Use auto format after pasting into the Arduino IDE)

```
// Libraries
#include <Wire.h>           // I2C comms library
#include <si5351.h>         // Si5351 Jason library
#include <LiquidCrystal_I2C.h> // LCD library
#include <Audio.h>         // Teensy audio library

// Number of Filter Coefficients
#define NO_HILBERT_COEFFS 70 // Used to define the Hilbert transform filter arrays.
// More typical than 'const int'.

// Define Constants and Variables
static const long bandStart = 1000000; // start of HF band
static const long bandEnd = 30000000; // end of HF band
static const long bandInit = 3690000; // where to initially set the frequency
//static const long bandInit = 14190000; // where to initially set the frequency
volatile long oldfreq = 0;
volatile long freq = bandInit;
volatile long radix = 1000; // how much to change the frequency by clicking the rotary
encoder will change this.
volatile int updatedisplay = 0;

static const int Mic_Gain = 0; // Range is 0-63dB.
static const int Lineout_Gain = 20; // Range is 13-31. 13 = 3.16 Vp-p, 31 = 1.16 Vp-p

// Rotary Encoder
static const int pushPin = 39;
static const int rotBPin = 36;
static const int rotAPin = 35;
volatile int rotState = 0;
volatile int rotAval = 1;
volatile int rotBval = 1;
```

```
volatile int rotAcc = 0;
```

```
// Iowa Hills Hilbert transform filter coefficients
const short Hilbert_Plus_45_Coeffs[NO_HILBERT_COEFFS] = {
    (short)(32768 * -0.000287988910943357),
    (short)(32768 * -0.000383511439791303),
    (short)(32768 * -0.000468041804899774),
    (short)(32768 * -0.000529324432676899),
    (short)(32768 * -0.000569479602046985),
    (short)(32768 * -0.000616670267768531),
    (short)(32768 * -0.000731530748681977),
    (short)(32768 * -0.001002372095321225),
    (short)(32768 * -0.001525299390682192),
    (short)(32768 * -0.002370114347025230),
    (short)(32768 * -0.003539247773172147),
    (short)(32768 * -0.004932965382552984),
    (short)(32768 * -0.006337182914262393),
    (short)(32768 * -0.007448193692118567),
    (short)(32768 * -0.007940501940620482),
    (short)(32768 * -0.007570802072162988),
    (short)(32768 * -0.006296120449841751),
    (short)(32768 * -0.004371955618154949),
    (short)(32768 * -0.002391875073164555),
    (short)(32768 * -0.001236984700413469),
    (short)(32768 * -0.001922560128827416),
    (short)(32768 * -0.005356720327533458),
    (short)(32768 * -0.012055656297010635),
    (short)(32768 * -0.021882952959947619),
    (short)(32768 * -0.033888748300090733),
    (short)(32768 * -0.046312736456333638),
    (short)(32768 * -0.056783367797647665),
    (short)(32768 * -0.062699937453677912),
    (short)(32768 * -0.061735375084135742),
    (short)(32768 * -0.052358513976237808),
    (short)(32768 * -0.034257179158167443),
    (short)(32768 * -0.008554500746482946),
    (short)(32768 * 0.022249911747384360),
    (short)(32768 * 0.054622962942346594),
    (short)(32768 * 0.084568844473140448),
    (short)(32768 * 0.108316122839950818),
    (short)(32768 * 0.122979341462627859),
    (short)(32768 * 0.127056096658453188),
    (short)(32768 * 0.120656295327679283),
    (short)(32768 * 0.105420364259485699),
    (short)(32768 * 0.084152608145489444),
    (short)(32768 * 0.060257510644444748),
    (short)(32768 * 0.037105711921879434),
    (short)(32768 * 0.017464092086704748),
    (short)(32768 * 0.003100559033325746),
    (short)(32768 * -0.005373489802481697),
    (short)(32768 * -0.008418211280310166),
    (short)(32768 * -0.007286730644726664),
    (short)(32768 * -0.003638388931163832),
    (short)(32768 * 0.000858330713630433),
    (short)(32768 * 0.004847436504682235),
    (short)(32768 * 0.007476399317750315),
    (short)(32768 * 0.008440227567663121),
    (short)(32768 * 0.007898970420636600),
    (short)(32768 * 0.006314366257036837),
    (short)(32768 * 0.004261033495040515),
    (short)(32768 * 0.002261843500794377),
    (short)(32768 * 0.000680212977485724),
    (short)(32768 * -0.000319493110301691),
    (short)(32768 * -0.000751893569425181),
    (short)(32768 * -0.000752248417868501),
    (short)(32768 * -0.000505487955986662),
    (short)(32768 * -0.000184645628631330),
    (short)(32768 * 0.000087913008490067),
    (short)(32768 * 0.000253106348867209),
    (short)(32768 * 0.000306473486382603),
    (short)(32768 * 0.000277637042003169),
    (short)(32768 * 0.000207782317481292),
    (short)(32768 * 0.000132446796990356),
    (short)(32768 * 0.000072894261560354)
};
```

```
// Iowa Hills Hilbert transform filter coefficients
const short Hilbert_Minus_45_Coeffs[NO_HILBERT_COEFFS] = {
```

```
(short)(32768 * -0.000072894261560345),
(short)(32768 * -0.000132446796990344),
(short)(32768 * -0.000207782317481281),
(short)(32768 * -0.000277637042003168),
(short)(32768 * -0.000306473486382623),
(short)(32768 * -0.000253106348867259),
(short)(32768 * -0.000087913008490148),
(short)(32768 * 0.000184645628631233),
(short)(32768 * 0.000505487955986583),
(short)(32768 * 0.000752248417868491),
(short)(32768 * 0.000751893569425298),
(short)(32768 * 0.000319493110301983),
(short)(32768 * -0.000680212977485245),
(short)(32768 * -0.002261843500793748),
(short)(32768 * -0.004261033495039842),
(short)(32768 * -0.006314366257036280),
(short)(32768 * -0.007898970420636345),
(short)(32768 * -0.008440227567663343),
(short)(32768 * -0.007476399317751102),
(short)(32768 * -0.004847436504683540),
(short)(32768 * -0.000858330713632029),
(short)(32768 * 0.003638388931162351),
(short)(32768 * 0.007286730644725833),
(short)(32768 * 0.008418211280310565),
(short)(32768 * 0.005373489802483816),
(short)(32768 * -0.003100559033321630),
(short)(32768 * -0.017464092086698697),
(short)(32768 * -0.037105711921871905),
(short)(32768 * -0.060257510644436532),
(short)(32768 * -0.084152608145481672),
(short)(32768 * -0.105420364259479538),
(short)(32768 * -0.120656295327675800),
(short)(32768 * -0.127056096658453216),
(short)(32768 * -0.122979341462631633),
(short)(32768 * -0.108316122839958146),
(short)(32768 * -0.084568844473150454),
(short)(32768 * -0.054622962942358168),
(short)(32768 * -0.022249911747396132),
(short)(32768 * 0.008554500746472333),
(short)(32768 * 0.034257179158159054),
(short)(32768 * 0.052358513976232306),
(short)(32768 * 0.061735375084133286),
(short)(32768 * 0.062699937453678217),
(short)(32768 * 0.056783367797650072),
(short)(32768 * 0.046312736456337288),
(short)(32768 * 0.033888748300094730),
(short)(32768 * 0.021882952959951244),
(short)(32768 * 0.012055656297013388),
(short)(32768 * 0.005356720327535105),
(short)(32768 * 0.001922560128828006),
(short)(32768 * 0.001236984700413229),
(short)(32768 * 0.002391875073163812),
(short)(32768 * 0.004371955618154038),
(short)(32768 * 0.006296120449840938),
(short)(32768 * 0.007570802072162439),
(short)(32768 * 0.007940501940620253),
(short)(32768 * 0.007448193692118624),
(short)(32768 * 0.006337182914262643),
(short)(32768 * 0.004932965382553323),
(short)(32768 * 0.003539247773172483),
(short)(32768 * 0.002370114347025498),
(short)(32768 * 0.001525299390682370),
(short)(32768 * 0.001002372095321316),
(short)(32768 * 0.000731530748682004),
(short)(32768 * 0.000616670267768521),
(short)(32768 * 0.000569479602046963),
(short)(32768 * 0.000529324432676881),
(short)(32768 * 0.000468041804899765),
(short)(32768 * 0.000383511439791304),
(short)(32768 * 0.000287988910943362)
};
```

```
// Instantiate the Objects
LiquidCrystal_I2C lcd(0x3F, 16, 2); // Name for the LCD. Set the LCD address to either 0x27
or 0x3F for a 16 chars and 2 line display
Si5351 si5351; // Name for the Si5351 DDS
AudioControlSGTL5000 audioShield; // Name for the Teensy audio CODEC on the audio
shield
```

```

// Audio shield
AudioInputI2S      audioInput;                // Name for the input to the audio
shield (either line-in or mic)
AudioOutputI2S      audioOutput;              // Name for the output of the audio
shield (either headphones or line-out)

// Transmitter
AudioFilterFIR      TX_Hilbert_Plus_45;        // Name for the TX +45 Hilbert
transform
AudioFilterFIR      TX_Hilbert_Minus_45;      // Name for the TX +45 Hilbert
transform
AudioMixer4          TX_I_Sideband_Switch;    // Name for the sideband
switching summer for the I channel

// Audio connections
AudioConnection      patchCord50(audioInput, 0, TX_Hilbert_Plus_45, 0);    // Mic audio
to Hilbert transform +45
AudioConnection      patchCord55(audioInput, 0, TX_Hilbert_Minus_45, 0);    // Mic audio
to Hilbert transform -45
AudioConnection      patchCord60(TX_Hilbert_Plus_45, 0, TX_I_Sideband_Switch, 0); //
Hilbert transform +45 to receiver summer
AudioConnection      patchCord65(TX_I_Sideband_Switch, 0, audioOutput, 0);    // Output
to the NE612
AudioConnection      patchCord70(TX_Hilbert_Minus_45, 0, audioOutput, 1);    // Output to
the NE612

void setup()
{
    // Setup input switches
    pinMode(rotAPin, INPUT);
    pinMode(rotBPin, INPUT);
    pinMode(pushPin, INPUT);
    digitalWrite(rotAPin, HIGH);
    digitalWrite(rotBPin, HIGH);
    digitalWrite(pushPin, HIGH);

    // Setup interrupt pins
    attachInterrupt(digitalPinToInterrupt(rotAPin), ISRrotAChange, CHANGE);
    attachInterrupt(digitalPinToInterrupt(rotBPin), ISRrotBChange, CHANGE);

    // Setup the lcd
    lcd.begin();
    lcd.backlight();

    // Setup the DDS
    si5351.init(SI5351_CRYSTAL_LOAD_8PF, 0);
    si5351.set_pll(SI5351_PLL_FIXED, SI5351_PLLA);
    si5351.drive_strength(SI5351_CLK0, SI5351_DRIVE_8MA);
    si5351.set_freq((freq * 100ULL), SI5351_PLL_FIXED, SI5351_CLK0);

    // Setup the audio shield
    AudioNoInterrupts();
    AudioMemory(16);
    audioShield.enable();
    AudioInterrupts();

    // Setup transceiver mode
    Turn_On_Transmitter();
    UpdateDisplay();
}

void loop()
{
    if (freq != oldfreq)    // Check to see if the frequency has changed. If so, update
everything.
    {
        UpdateDisplay();
        SendFrequency();
        oldfreq = freq;
    }

    if (digitalRead(pushPin) == LOW) // Update cursor, but also stop it from flickering
    {
        delay(10);
        while (digitalRead(pushPin) == LOW)
        {
            if (updatedisplay == 1)
            {

```

```

        UpdateDisplay();
        updatedisplay = 0;
    }
}
delay(50);
}
}

void Turn_On_Transmitter()
{
    AudioNoInterrupts();
    audioShield.inputSelect(AUDIO_INPUT_MIC);
    audioShield.micGain(Mic_Gain);
    audioShield.unmuteLineout();           // Output to the NE612s
    audioShield.lineOutLevel(Lineout_Gain);
    TX_Hilbert_Plus_45.begin(Hilbert_Plus_45_Coeffs, NO_HILBERT_COEFFS);
    TX_Hilbert_Minus_45.begin(Hilbert_Minus_45_Coeffs, NO_HILBERT_COEFFS);

    if (freq <= 9999999)    // LSB
    {
        TX_I_Sideband_Switch.gain(0, 1);
    }
    if (freq > 9999999)    // USB
    {
        TX_I_Sideband_Switch.gain(0, -1);
    }

    AudioInterrupts();
}

// Interrupt routines
void ISRrotAChange()
{
    if (digitalRead(rotAPin))
    {
        rotAval = 1;
        UpdateRot();
    }
    else
    {
        rotAval = 0;
        UpdateRot();
    }
}

void ISRrotBChange()
{
    if (digitalRead(rotBPin))
    {
        rotBval = 1;
        UpdateRot();
    }
    else
    {
        rotBval = 0;
        UpdateRot();
    }
}

void UpdateRot()
{
    switch (rotState)
    {
        case 0:                // Idle state, look for direction
            if (!rotBval)
                rotState = 1;    // CW 1
            if (!rotAval)
                rotState = 11;   // CCW 1
            break;

        case 1:                // CW, wait for A low while B is low
            if (!rotBval)
            {
                if (!rotAval)

```

```

{
  // either increment radixindex or freq
  if (digitalRead(pushPin) == LOW)
  {
    updatedisplay = 1;
    if (radix == 1000000)
      radix = 100000;
    else if (radix == 100000)
      radix = 10000;
    else if (radix == 10000)
      radix = 1000;
    else if (radix == 1000)
      radix = 100;
    else if (radix == 100)
      radix = 10;
    else if (radix == 10)
      radix = 1;
    else
      radix = 1000000;
  }
  else
  {
    freq = (freq + radix);
    if (freq > bandEnd)
      freq = bandEnd;
  }
  rotState = 2;          // CW 2
}
}
else if (rotAval)
  rotState = 0;          // It was just a glitch on B, go back to start
break;

case 2:                  // CW, wait for B high
  if (rotBval)
    rotState = 3;        // CW 3
  break;

case 3:                  // CW, wait for A high
  if (rotAval)
    rotState = 0;        // back to idle (detent) state
  break;

case 11:                 // CCW, wait for B low while A is low
  if (!rotAval)
  {
    if (!rotBval)
    {
      // either decrement radixindex or freq
      if (digitalRead(pushPin) == LOW)
      {
        updatedisplay = 1;
        if (radix == 1)
          radix = 10;
        else if (radix == 10)
          radix = 100;
        else if (radix == 100)
          radix = 1000;
        else if (radix == 1000)
          radix = 10000;
        else if (radix == 10000)
          radix = 100000;
        else if (radix == 100000)
          radix = 1000000;
        else
          radix = 1;
      }
    }
    else
    {
      freq = (freq - radix);
      if (freq < bandStart)
        freq = bandStart;
    }
    rotState = 12;        // CCW 2
  }
}
}
else if (rotBval)
  rotState = 0;          // It was just a glitch on A, go back to start
break;

```

```

case 12:                                // CCW, wait for A high
    if (rotAval)
        rotState = 13;                // CCW 3
    break;

case 13:                                // CCW, wait for B high
    if (rotBval)
        rotState = 0;                // back to idle (detent) state
    break;
}
}

void UpdateDisplay()
{
    lcd.cursor();                      // Turn on the cursor
    lcd.setCursor(0, 0);
    lcd.print(" ");
    lcd.setCursor(0, 0);
    lcd.print(freq);
    lcd.setCursor(10, 0);
    lcd.print("ZL2CTM");

    lcd.setCursor(0, 1);
    lcd.print(" ");
    lcd.setCursor(0, 1);

    if (freq > 9999999)
    {
        if (radix == 1)
            lcd.setCursor(7, 0);
        if (radix == 10)
            lcd.setCursor(6, 0);
        if (radix == 100)
            lcd.setCursor(5, 0);
        if (radix == 1000)
            lcd.setCursor(4, 0);
        if (radix == 10000)
            lcd.setCursor(3, 0);
        if (radix == 100000)
            lcd.setCursor(2, 0);
        if (radix == 1000000)
            lcd.setCursor(1, 0);
    }
    if (freq <= 9999999)
    {
        if (radix == 1)
            lcd.setCursor(6, 0);
        if (radix == 10)
            lcd.setCursor(5, 0);
        if (radix == 100)
            lcd.setCursor(4, 0);
        if (radix == 1000)
            lcd.setCursor(3, 0);
        if (radix == 10000)
            lcd.setCursor(2, 0);
        if (radix == 100000)
            lcd.setCursor(1, 0);
        if (radix == 1000000)
            lcd.setCursor(0, 0);
    }
}

void SendFrequency()
{
    si5351.set_freq((freq * 4) * 100ULL, SI5351_PLL_FIXED, SI5351_CLK0);
}

*****

```


Posted by Charlie Morris at [22:42](#)

Labels: [Hilbert Transform](#), [SDR](#), [Teensy](#), [ZL2CTM](#)

9 comments:



Andrey Begunov 21 March 2018 at 13:20

Charlie, thanks a lot for the great video and explanation of the SDR theory and practice, looking forward for future video! 73! UT9UF

[Reply](#)



Charlie Morris 21 March 2018 at 19:27

Cheers Andrey. My intent is to explain things in the videos and not here. My typing is waaaaay too slow!

73s
Charlie ZL2CTM

[Reply](#)



Jason 28 March 2018 at 18:50

Great job with the videos as always! I wanted to ask if you've done any segments walking through how you peak the BPF? If not, I think that would be a good addition. I know you spoke on the theory of it in the last video, but seeing thebprocthe is very helpful!

Thx
W4UNX

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Charlie Morris 28 March 2018 at 19:08

Thanks Jason. I might have tuned a BPF a while back, but I cannot recall which video. I'll certainly look to do it again.

73s
Charlie ZL2CTM

[Reply](#)



Bob 29 March 2018 at 17:03

Really enjoying this series Charlie. What is the source of the Liquid_crystal_I2C library?

[Reply](#)

[Replies](#)



Charlie Morris 30 March 2018 at 15:17

Thanks Bob. As for the library, I'm pretty sure I got it from here:

https://github.com/marcoschwartz/LiquidCrystal_I2C

Charlie



Bob 8 April 2018 at 10:17

This comment has been removed by the author.



Bob 30 May 2018 at 10:52

Charlie I have a working SSB SDR receiver!! Thx for blazing the trail with this series.

[Reply](#)



Dave Metzler 3 September 2018 at 14:51

Have you posted the complete Teensy SDR transceiver code anywhere?

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