Código

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import numpy as np
import copy
import math
import public_tests as pt
import utils
import matplotlib.pyplot as plt
def zscore_normalize_features(X):
   computes X, zcore normalized by column
   Args:
     X (ndarray (m,n)) : input data, m examples, n features
   Returns:
     X_norm (ndarray (m,n)): input normalized by column
     mu (ndarray (n,)) : mean of each feature
     sigma (ndarray (n,)) : standard deviation of each feature
   mu = np.zeros(X.shape[1])
   sigma = np.zeros(X.shape[1])
   X_norm = np.zeros(X.shape)
   for i in range(X.shape[1]):
       mu[i] = np.mean(X[:, i])
       sigma[i] = np.std(X[:, i])
       X_{norm}[:, i] = (X[:, i] - mu[i]) / sigma[i]
   return (X_norm, mu, sigma)
def sigmoid(z):
   Compute the sigmoid of z
   Args:
       z (ndarray): A scalar, numpy array of any size.
   Returns:
       g (ndarray): sigmoid(z), with the same shape as z
   g = 1 / (1 + np.exp(-z))
   return g
# logistic regression
def compute_cost(X, y, w, b, lambda_=None):
```

```
Computes the cost over all examples
   Args:
     X : (ndarray Shape (m,n)) data, m examples by n features
     y : (array_like Shape (m,)) target value
     w : (array_like Shape (n,)) Values of parameters of the model
     b : scalar Values of bias parameter of the model
     lambda_: unused placeholder
   Returns:
     total_cost: (scalar) cost
   total\_cost = 0
   m = len(y)
   for i in range(m):
       aux = sigmoid(np.dot(w, X[i]) + b)
       total_cost += -y[i] * math.log(aux) - (1 - y[i]) * math.log(1 - aux)
   total_cost = total_cost / m
   return total_cost
def compute_gradient(X, y, w, b, lambda_=None):
   Computes the gradient for logistic regression
   Args:
     X : (ndarray Shape (m,n)) variable such as house size
     y : (array_like Shape (m,1)) actual value
     w : (array_like Shape (n,1)) values of parameters of the model
                                value of parameter of the model
     b : (scalar)
     lambda_: unused placeholder
   Returns
     dj_db: (scalar)
                                 The gradient of the cost w.r.t. the
parameter b.
     dj_dw: (array_like Shape (n,1)) The gradient of the cost w.r.t. the
parameters w.
   .....
   m = len(y)
   dj_dw = np.zeros(len(w))
   dj_db = 0
   for i in range(m):
       aux = sigmoid(np.dot(w, X[i]) + b) - y[i]
       dj_dw += aux * X[i]
       dj_db += aux
   dj_dw = dj_dw / m
   dj_db = dj_db / m
   return dj_db, dj_dw
# regularized logistic regression
def compute_cost_reg(X, y, w, b, lambda_=1):
```

```
Computes the cost over all examples
   Args:
     X : (array_like Shape (m,n)) data, m examples by n features
     y : (array_like Shape (m,)) target value
     w : (array_like Shape (n,)) Values of parameters of the model
     b : (array_like Shape (n,)) Values of bias parameter of the model
     lambda_ : (scalar, float) Controls amount of regularization
   Returns:
     total_cost: (scalar) cost
   total\_cost = 0
   m = len(y)
   for i in range(m):
       aux = sigmoid(np.dot(w, X[i]) + b)
       total\_cost += -y[i] * math.log(aux) - (1 - y[i]) * math.log(1 - aux)
   total_cost = total_cost / m
   total_cost += lambda_ / (2 * m) * np.sum(w ** 2)
   return total_cost
def compute_gradient_reg(X, y, w, b, lambda_=1):
   Computes the gradient for linear regression
   Args:
     X : (ndarray Shape (m,n)) variable such as house size
     y: (ndarray Shape (m,)) actual value
     w : (ndarray Shape (n,)) values of parameters of the model
     b: (scalar)
                               value of parameter of the model
     lambda_ : (scalar,float)
                               regularization constant
   Returns
     dj_db: (scalar)
                               The gradient of the cost w.r.t. the parameter
b.
     dj_dw: (ndarray Shape (n,)) The gradient of the cost w.r.t. the parameters
W.
   .....
   m = 1en(y)
   dj_dw = np.zeros(len(w))
   dj_db = 0
   for i in range(m):
       aux = sigmoid(np.dot(w, X[i]) + b) - y[i]
       dj_dw += aux * x[i]
       dj_db += aux
   dj_dw = dj_dw / m
   dj_db = dj_db / m
   dj_dw += lambda_ / m * w
   return dj_db, dj_dw
```

```
# gradient descent
def gradient_descent(X, y, w_in, b_in, cost_function, gradient_function, alpha,
num_iters, lambda_=None):
   Performs batch gradient descent to learn theta. Updates theta by taking
   num_iters gradient steps with learning rate alpha
   Args:
           (array_like Shape (m, n)
     X:
           (array_like Shape (m,))
     y :
     w_in : (array_like Shape (n,)) Initial values of parameters of the model
     b_in : (scalar)
                                    Initial value of parameter of the model
     cost_function:
                                    function to compute cost
     alpha: (float)
                                    Learning rate
     num_iters : (int)
                                    number of iterations to run gradient
descent
     lambda_ (scalar, float) regularization constant
   Returns:
     w : (array_like Shape (n,)) Updated values of parameters of the model after
         running gradient descent
     b : (scalar)
                                Updated value of parameter of the model after
         running gradient descent
     J_history : (ndarray): Shape (num_iters,) J at each iteration,
         primarily for graphing later
   J_history = np.zeros(num_iters)
   m = len(y)
   for i in range(num_iters):
       dj_db, dj_dw = gradient_function(X, y, w_in, b_in, lambda_)
       w_in -= alpha * dj_dw
       b_in -= alpha * dj_db
       J_history[i] = cost_function(X, y, w_in, b_in, lambda_)
   return w_in, b_in, J_history
# predict
def predict(X, w, b):
   Predict whether the label is 0 or 1 using learned logistic
   regression parameters w and b
   Args:
   X : (ndarray Shape (m, n))
   w : (array_like Shape (n,)) Parameters of the model
   b : (scalar, float)
                                  Parameter of the model
   Returns:
   p: (ndarray (m,1))
       The predictions for X using a threshold at 0.5
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```
m = X.shape[0]
    p = np.zeros(m)
    for i in range(m):
        p[i] = sigmoid(np.dot(w, X[i]) + b)
    p = p > 0.5
    return p
def test():
    pt.sigmoid_test(sigmoid)
    pt.compute_cost_test(compute_cost)
    pt.compute_gradient_test(compute_gradient)
    pt.predict_test(predict)
    pt.compute_cost_reg_test(compute_cost_reg)
    pt.compute_gradient_reg_test(compute_gradient_reg)
def load_data(path):
   data = np.loadtxt(path, delimiter=',')
   X = data[:, 0:2]
   y = data[:, 2]
    return X, y
def partA():
   X, y = load_data('data/ex2data1.txt')
   X_norm, mu, sigma = zscore_normalize_features(X)
    w = np.zeros(X_norm.shape[1])
    b = 0
    lambda_ = 0.01
    alpha = 0.01
    num\_iters = 10000
    w, b, J_history = gradient_descent(X_norm, y, w, b, compute_cost,
compute_gradient, alpha, num_iters, lambda_)
   # w = w / sigma
    # w = w - w * mu
    utils.plot_decision_boundary(w, b, X_norm, y)
    plt.show()
    res = predict(X_norm, w, b)
    print('Predict: ', np.sum(res) * 100 / res.size, '%', sep='')
def partB():
   X, y = load_data('data/ex2data2.txt')
   X_map = utils.map_feature(X[:, 0], X[:, 1])
   b = 0
    w = np.zeros(X_map.shape[1])
   lambda_ = 0.01
    alpha = 0.01
    num\_iters = 10000
```

```
w, b, J_history = gradient_descent(X_map, y, w, b, compute_cost_reg,
compute_gradient_reg, alpha, num_iters, lambda_)
    print('cost:', J_history[J_history.size - 1])

utils.plot_decision_boundary(w, b, X_map, y)
    plt.show()

res = predict(X_map, w, b)
    print('Predict: ', np.sum(res) * 100 / res.size, '%', sep='')

if __name__ == "__main__":
    test()
    partA()
    partB()
```