GPU H/W and S/W

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Arithmetic Intensity

 $\label{eq:arithmetic Intensity (AI) = } \frac{Number \ of \ floating-point \ operations \ (FLOPs)}{Bytes \ of \ memory \ transferred}$



Code example: CUDA K-mean

```
__global__ void assignClusters(const float *points, const float *centroids, int *assign
   int idx = blockIdx.x * blockDim.x + threadIdx.x;
   if (idx < n_points) {</pre>
       int best_cluster = 0;
       float min_dist = FLT_MAX;
       for (int c = 0; c < k; c++) {
            float dist = 0.0f;
            for (int d = 0; d < dim; d++) {
                float diff = points[idx * dim + d] - centroids[c * dim + d];
                dist += diff * diff; // 1 FLOP multiply + 1 FLOP add per dimension
            if (dist < min_dist) {</pre>
                min_dist = dist;
                best cluster = c;
       assignments[idx] = best_cluster;
```

FLOPS = dim x (1 sub + 1 mul + 1 add) = dim x 3 FLOPS per point = k clusters x dim x 3 Total FLOPS. = n * K * dim * 3

Memory load:

Point data loads: n*dim floats

Centroid data loads: k*dim floats

Store: n

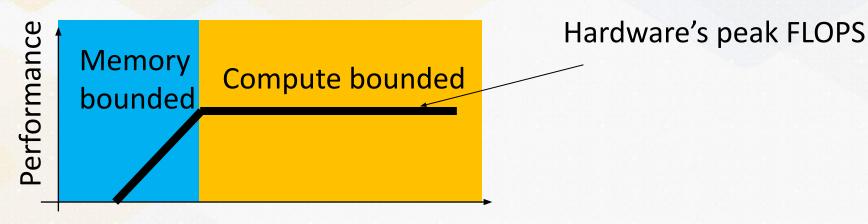
= n *dim * 4 + n*4

Can you find Arithmetic Intensity?

Code examples: (Perplexity AI, 2025)



Roofline Model



X-axis: arithmetic intensity (FLOPS/BYTES)

 A Visual performance model to determine whether an application (or a processor) is limited by the compute bandwidth or memory bandwidth



What to count for Memory Bytes

- Roofline model: use theoretical minimal memory bytes
- What if we count based on transactional size?
- Based on what to bring from memory or caches

```
#define N 4096

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#define STRIDE 2

__global___ void matAdd(float *A, float *B, float *C) {
    int idx = blockIdx.x * blockDim.x + threadIdx.x;
    if (idx < N)
        C[idx] = A[idx] + B[idx];
}

#define N 4096

#define STRIDE 2
```



Transactional size

- Between cache: cache block size
- From memory: minimum memory transaction size
- Significant performance impats

