### Lecture 08 Gradient Computation

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### 梯度计算

▶ 梯度的作用

▶ 常见梯度项

→ gradient

#### 非结构化网格

- ▶ 格林高斯梯度, Green-Gauss Gradient
- ▶ 最小二乘, Least-Square Gradient
- ▶ 梯度插值

# 非正交 computing gradients in cartesian grides

▶ 一组

$$\left(\frac{\mathrm{d}\phi}{\mathrm{d}\mathrm{x}}\right)_{\mathrm{e}} = \frac{\phi_{\mathrm{E}} - \phi_{\mathrm{P}}}{\mathrm{x}_{\mathrm{E}} - \mathrm{x}_{\mathrm{P}}}$$

▶ 二维

$$\left(\frac{\partial \phi}{\partial x}\right)_{P} = \frac{\phi_{E} - \phi_{W}}{x_{E} - x_{W}}$$

$$\left(\frac{\partial \phi}{\partial x}\right)_{P} = \frac{\phi_{N} - \phi_{S}}{x_{N} - x_{S}}$$

### 非正交 Green-Gauss Gradient

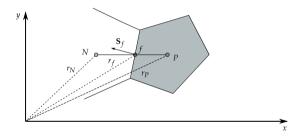
▶ 体心处梯度

$$(
abla \phi)_{ ext{P}} = rac{1}{V_{ ext{P}}} \sum_{ ext{f}} \phi_{ ext{f}} \cdot \mathbf{S}_{ ext{f}}$$

- ▶ 两种方法计算  $\phi_{\rm f}$
- ▶ 1. face-based
- ▶ 2. vertex-based

#### ▶ 公式

$$\phi_{\rm f} = \gamma \phi_{\rm P} + (1 - \gamma)\phi_{\rm N}$$



▶ 其中 γ

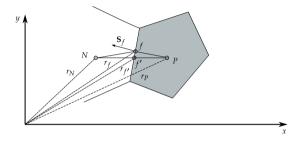
$$\gamma = \frac{|\mathbf{r}_{N} - \mathbf{r}_{f}|}{|\mathbf{r}_{N} - \mathbf{r}_{P}|} = \frac{d_{Nf}}{d_{NP}}$$

▶ 特殊情况

$$\phi_{\rm f} = \frac{\phi_{\rm P} + \phi_{\rm N}}{2}$$

▶ 二阶精度

 $\triangleright$  skewness,  $\phi_{f'}$ 



#### ▶ 泰勒公式

$$\phi_{f} = \phi_{f'} + \text{correction}$$
$$= \phi_{f'} + \nabla \phi_{f'} \cdot (\mathbf{r}_{f} - \mathbf{r}_{f'})$$

#### ▶ 泰勒公式

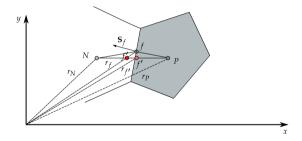
$$\phi_{\mathbf{f}} = \gamma \{\phi_{\mathbf{P}} + (\nabla \phi)_{\mathbf{P}}(\mathbf{r_f} - \mathbf{r_P})\} + (\mathbf{1} - \gamma)\{\phi_{\mathbf{N}} + (\nabla \phi)_{\mathbf{N}} \cdot (\mathbf{r_f} - \mathbf{r_N})\}$$

$$= \phi_{\mathbf{f}'} + \underbrace{\gamma(\nabla \phi)_{\mathbf{P}} \cdot (\mathbf{r_f} - \mathbf{r_P}) + (1 - \gamma)(\nabla \phi)_{\mathbf{N}} \cdot (\mathbf{r_f} - \mathbf{r_N})}_{\text{correction}}$$

### 计算方法 1face-based gradient computation

- ▶ 1. 计算  $\phi_{f'} = \gamma \phi_P + (1 \gamma)\phi_N$
- ▶ 2. 计算  $(\nabla \phi)_P = \frac{1}{V_P} \sum_f \phi_{f'} \cdot \mathbf{S}_f$
- ▶ 3. 计算更新的  $\phi_f = \phi_{f'} + \gamma(\nabla \phi)_P \cdot (\mathbf{r}_f \mathbf{r}_P) + (1 \gamma)(\nabla \phi)_N \cdot (\mathbf{r}_f \mathbf{r}_N)$
- ▶ 4. 更新  $(\nabla \phi)_P = \frac{1}{V_P} \sum_f \phi_f \cdot \mathbf{S}_f$
- ▶ 5. 重复3

#### ▶ 另外两种方法



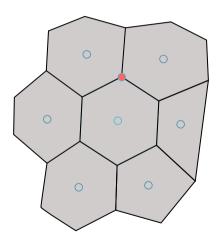
### 计算方法 2face-based gradient computation

- ▶ 1. 计算  $\phi_{f'} = 0.5\phi_P + 0.5\phi_N$
- ▶ 2. 计算  $(\nabla \phi)_P = \frac{1}{V_P} \sum_f \phi_{f'} \cdot \mathbf{S}_f$
- ▶ 3. 计算更新的  $\phi_f = \phi_{f'} + 0.5(\nabla \phi)_P \cdot (\mathbf{r}_f \mathbf{r}_P) + 0.5(\nabla \phi)_N \cdot (\mathbf{r}_f \mathbf{r}_N)$
- ▶ 4. 更新  $(\nabla \phi)_P = \frac{1}{V_P} \sum_f \phi_f \cdot \mathbf{S}_f$
- ▶ 5. 重复3

### 计算方法 3face-based gradient computation

- ▶ 1. 计算  $\phi_{f'} = \gamma \phi_P + (1 \gamma)\phi_N$
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- ▶ 4. 更新  $(\nabla \phi)_P = \frac{1}{V_P} \sum_f \phi_f \cdot \mathbf{S}_f$
- ▶ 5. 重复3

▶ 顶点值



▶ 顶点值

$$\phi_n = \frac{\sum_{i=1}^n \frac{\phi_i}{d_i}}{\sum_{i=1}^n \frac{1}{d_i}}$$

▶ 面心值

$$\phi_{\rm n} = \frac{\phi_1 + \phi_2}{2}$$