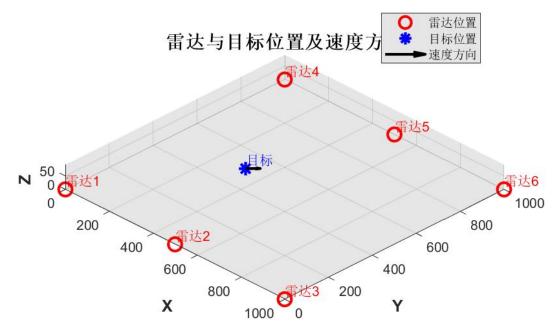
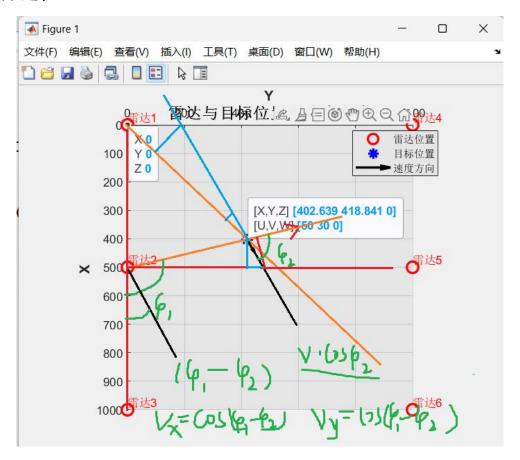
任务汇报:

雷达与目标关系图



还原过程



测量数据

```
雷达编号 直线距离 (m) 朝向雷达的速度 (m/s)
        586.9686
                       54.1523
1
2
        421.7509
                       16.0893
3
        714.9934
                       -25.4748
4
        730.9409
                       9.2835
5
                       -30.0411
        606.3136
6
        837.2323
                       -51.6157
雷达编号 方位角 (度) 俯仰角 (度)
1
        44.1962
                   8.0753
2
        101.6245
                       11.2741
3
        145.2202
                       6.6221
                       6.4770
4
        -54.9919
5
        -97.9752
                       7.8160
        -134.4393
                       5.6519
雷达编号 相对位置 (X, Y, Z)
                           直线距离 (m)
1
       (416.6583, 405.1288, 82.4538)
                                       586.9686
        (-83.3417, 405.1288, 82.4538)
2
                                       421.7509
3
        (-583.3417, 405.1288, 82.4538) 714.9934
        (416.6583, -594.8712, 82.4538)
4
                                       730.9409
5
        (-83.3417, -594.8712, 82.4538)
                                       606.3136
        (-583.3417, -594.8712, 82.4538) 837.2323
测量的速度:
测量的速度: 54.9213
测量的速度: 16.5354
测量的速度: -35.7283
测量的速度: -10.3346
测量的速度: -30.1181
测量的速度: -51.378
雷达编号 Vx (m/s)
                   Vy (m/s)
                               Vz (m/s)
       54.6594
                                   7.9774
1
                   -13.1799
2
                   -25.9555
                                   11.1025
       49.2752
3
       52.5362
                   -20.5441
                                   6.5490
4
       51.7451
                   22.5035
                               6.4061
                   21.4029
5
       52.0315
                               7.7229
       55.2862
                   11.7115
                               5.5928
```