

A 邻接矩阵 D, 度矩阵

$L = D - A$ 拉普拉斯矩阵

$L_{\text{sym}} = D^{-\frac{1}{2}} L D^{-\frac{1}{2}}$ 归一化拉普拉斯矩阵

谱图理论

1. L 和 L_{sym} 半正定

设 $G_{ij} = \begin{cases} 1 & (i,j) \text{ 为边} \\ -1 & (i,j) \text{ 为边} \end{cases}$

$$L = D - A = \sum_{i,j} G_{ij}$$

G_{ij} 的 (i,j) 和 (j,i) 与 $-A$ 相同,

其 (i,i) 与 (j,j) 的合为 D

$$\therefore \frac{\vec{x}^T L \vec{x}}{\vec{x}^T \vec{x}} = \frac{\sum_{i,j} G_{ij} x_i x_j}{\vec{x}^T \vec{x}}$$

$$= \vec{x}^T \begin{pmatrix} 1 & & \\ x_i - x_j & & \\ x_j - x_i & & \\ \vdots & & \end{pmatrix} = x_i(x_i - x_j) - x_j(x_j - x_i) \\ = (x_i - x_j)^2 \geq 0 \\ \therefore \text{半正定}$$

$$2. L_{\text{sym}} \in [0, 2]$$

$$\text{令 } G(i,j) = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$D+A = \sum G(i,j)$$

$$\frac{\vec{x}^T (D+A) \vec{x}}{\vec{x}^T \vec{x}} = \frac{\vec{x}^T (\sum G(i,j)) \vec{x}}{\vec{x}^T \vec{x}}$$

$$\vec{x}^T (\sum G(i,j)) \vec{x} = \vec{x}^T \begin{pmatrix} x_i + x_j \\ x_j + x_i \\ \vdots \end{pmatrix} = (x_i + x_j)^2 \geq 0$$

$$(D+A)_{\text{sym}} = D^{-\frac{1}{2}} (D+A) D^{\frac{1}{2}} = I + D^{-\frac{1}{2}} A D^{\frac{1}{2}}$$

$$= \sum \left(\frac{x_i}{d_i} + \frac{x_j}{d_j} \right)^2 \geq 0$$

$$\vec{x}^T (D+A)_{\text{sym}} \vec{x} = \sum \left(\frac{x_i}{d_i} + \frac{x_j}{d_j} \right)^2 \geq 0$$

$$\vec{x}^T (I + D^{-\frac{1}{2}} A D^{\frac{1}{2}}) \vec{x} = \vec{x}^T \vec{x} + \vec{x}^T D^{-\frac{1}{2}} A D^{\frac{1}{2}} \vec{x} \geq 0$$

$$2\vec{x}^T \vec{x} \geq \vec{x}^T \vec{x} - \vec{x}^T D^{-\frac{1}{2}} A D^{\frac{1}{2}} \vec{x}$$

$$2\vec{x}^T \vec{x} \geq \vec{x}^T (I - D^{-\frac{1}{2}} A D^{\frac{1}{2}}) \vec{x}$$

$$I - D^{-\frac{1}{2}} A D^{\frac{1}{2}} = L_{\text{sym}}$$

$$\therefore \frac{2\vec{x}^T \vec{x}}{\vec{x}^T \vec{x}} \geq \frac{\vec{x}^T (I - D^{-\frac{1}{2}} A D^{\frac{1}{2}}) \vec{x}}{\vec{x}^T \vec{x}}$$

$$\therefore 2 \geq L_{\text{sym}} \geq 0$$

$$\hookrightarrow L_{\text{sym}} \in \mathbb{R}^{D,2}$$

图的卷积

$g_{\theta} * X = U g_{\theta} U^T X$ 其复杂度太高

所以改成 $g_{\theta} * X \approx \sum_{k=0}^K \theta_k T_k(\tilde{L}) X$

再近似成 $g_{\theta} * X \approx \theta (I + U^{-\frac{1}{2}} A U^{-\frac{1}{2}}) X$

$$F(A) = L / L_{\text{sym}}$$

$$F(A) = U A U^T = L_{\text{sym}} - I$$

$$g_{\theta} * X = U g_{\theta}(A) U^T X = U (\sum T_k(A)) U^T X$$

$$= \sum_{k=0}^K \theta_k U T_k(A) U^T X = \sum_{k=0}^K \theta_k T_k(U A U^T) X$$

$$= \sum_{k=0}^K \theta_k T_k(L_{\text{sym}} - I) X$$

$$g_{\theta}(A) = \theta_0 I^0 + \theta_1 I^1 + \dots + \theta_n I^n$$

$$U g_{\theta}(A) U^T = g_{\theta}(U A U^T) = g_{\theta}(F(A))$$

$$(U A U^T)^k = U A U^T U A U^T \dots U A U^T = U A^k U^T$$

切比雪夫
多项式

$$T_n(x) = 2xT_{n-1}(x) - T_{n-2}(x)$$
$$T_n(\cos\theta) = \cos n\theta \quad [1.1]$$

$$T_0 = 1$$
$$T_1 = x$$
$$K=2$$

$$L_{\text{sym}} = D^{-\frac{1}{2}} L D^{\frac{1}{2}} = I - D^{-\frac{1}{2}} A D^{\frac{1}{2}}$$

$$\therefore g_{\theta}^* x = \sum_{k=0}^K \theta_k T_k (-D^{-\frac{1}{2}} A D^{\frac{1}{2}}) x$$

$$\approx \theta_0 T_0 (L_{\text{sym}} - I) x + \theta_1 T_1 (L_{\text{sym}} - I) x$$

$$= \theta_0 T_0 x - \theta_1 D^{-\frac{1}{2}} A D^{\frac{1}{2}} x$$

$$\text{令 } \theta_0 = -\theta_1$$

$$= \theta_1 (I + D^{-\frac{1}{2}} A D^{\frac{1}{2}}) x$$

归化

$$\bar{D}^{-\frac{1}{2}} \hat{A} \bar{D}^{-\frac{1}{2}} x$$

\bar{D}, \hat{A} 为加上自环

快速卷积公式

$$H^{(l+1)} = f(H^{(l)}, A) = \sigma(\hat{D}^{-\frac{1}{2}} \bar{A} \hat{D}^{-\frac{1}{2}} H^{(l)} W^{(l)})$$

推广到 C 个输入, 特征信号 X 和下一个滤波器中, 特征映射公式为

$$Z = \hat{D}^{-\frac{1}{2}} \bar{A} \hat{D}^{-\frac{1}{2}} X \Theta$$