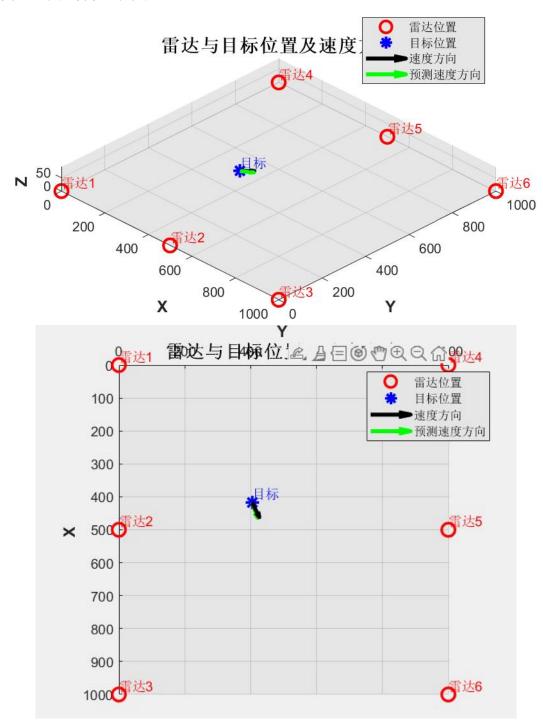
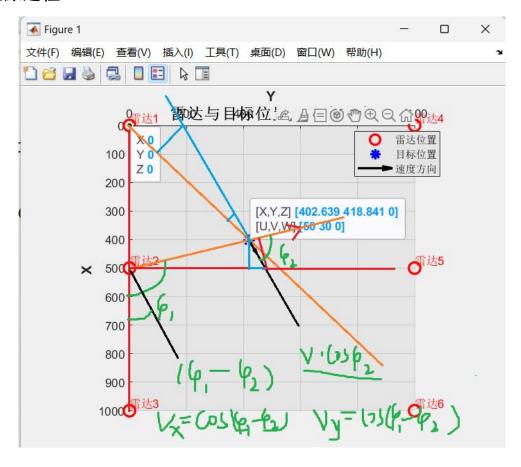
任务汇报:

雷达与目标关系图



还原过程



测量数据

设定的 V[50, 25,10]

目标位置为[400 + 20 * rand, 400 + 20 * rand, 80 + 4 * rand];

```
雷达编号 直线距离 (m) 朝向雷达的速度 (m/s)
       586.0639
                      -54.1762
1
2
       420.2198
                      -16.0648
3
       713.9317
                      25.5616
       731.9019
                      -9.2235
5
       607.2842
                      30.0506
       837.7995
                      51.6225
雷达编号 方位角 (度) 俯仰角 (度)
                  7.9348
       44.0932
1
2
       101.6280
                      11.1003
3
       145.2915
                      6.5068
       -55.0330
                      6.3464
5
                      7.6558
       -97.9375
       -134.3688
                      5.5415
雷达编号 相对位置 (X, Y, Z) 直线距离 (m)
       (416.8862, 403.8953, 80.9037)
                                      586.0639
1
       (-83.1138, 403.8953, 80.9037)
                                      420.2198
2
3
       (-583.1138, 403.8953, 80.9037) 713.9317
       (416.8862, -596.1047, 80.9037) 731.9019
4
       (-83.1138, -596.1047, 80.9037)
5
       (-583.1138, -596.1047, 80.9037) 837.7995
```

```
测量的速度:
```

测量的速度: -54.0354 测量的速度: -14.1732 测量的速度: 26.5748 测量的速度: -7.9724 测量的速度: 31.2992 测量的速度: 52.5591

雷达编号	Vx (m/s)	Vy (m/s)	Vz (m/s
1	54.6892	13.1391	7.8395
2	49.3145	25.9527	10.9334
3	52.5652	20.5057	6.4354
4	51.7478	22.5335	6.2774
5	52.0336	21.4538	7.5656
6	55.2849	11.7689	5.4839

平均速度:

Vx (m/s): 52.6059 Vy (m/s): 19.2256 Vz (m/s): 7.4225