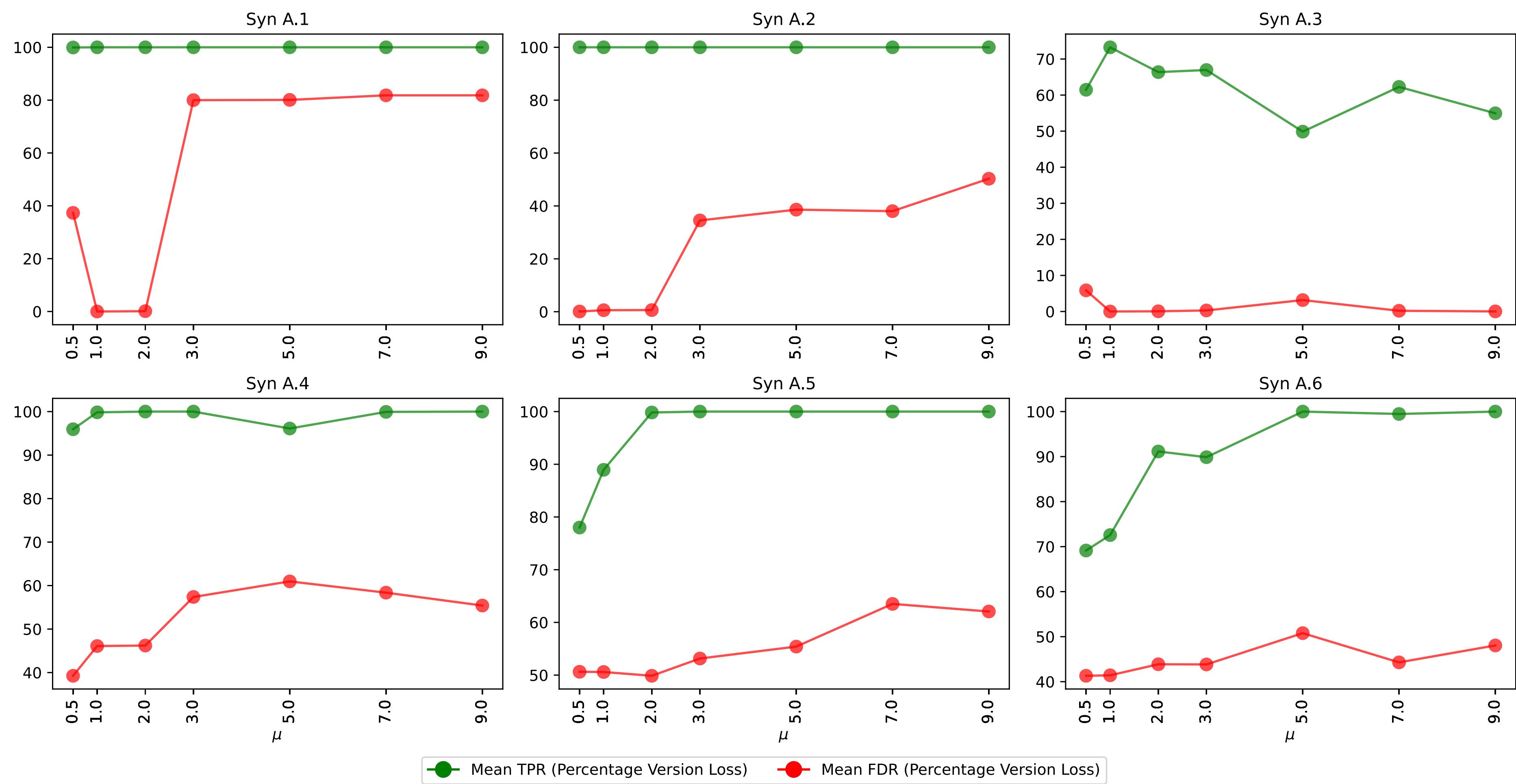


Exploration of Potential Improvements to INVA SE

Application of Perceptual Version Loss



Individual Settings: **Activation:** ReLU; **Policy:** Post-Training Selection Policy ($I = 10k$, $m = 100$, $r = 500$, $k = 7$)

◆ Sensitivity is significantly reduced

- Effective tuning range for the hyperparameter is significantly expanded
 - INVASE: around 1
 - Percentage version: around 10

◆ Obviously not good at FDR

- Syn A.4 - A.6: FDR is around 40-60%

➡ Not Good

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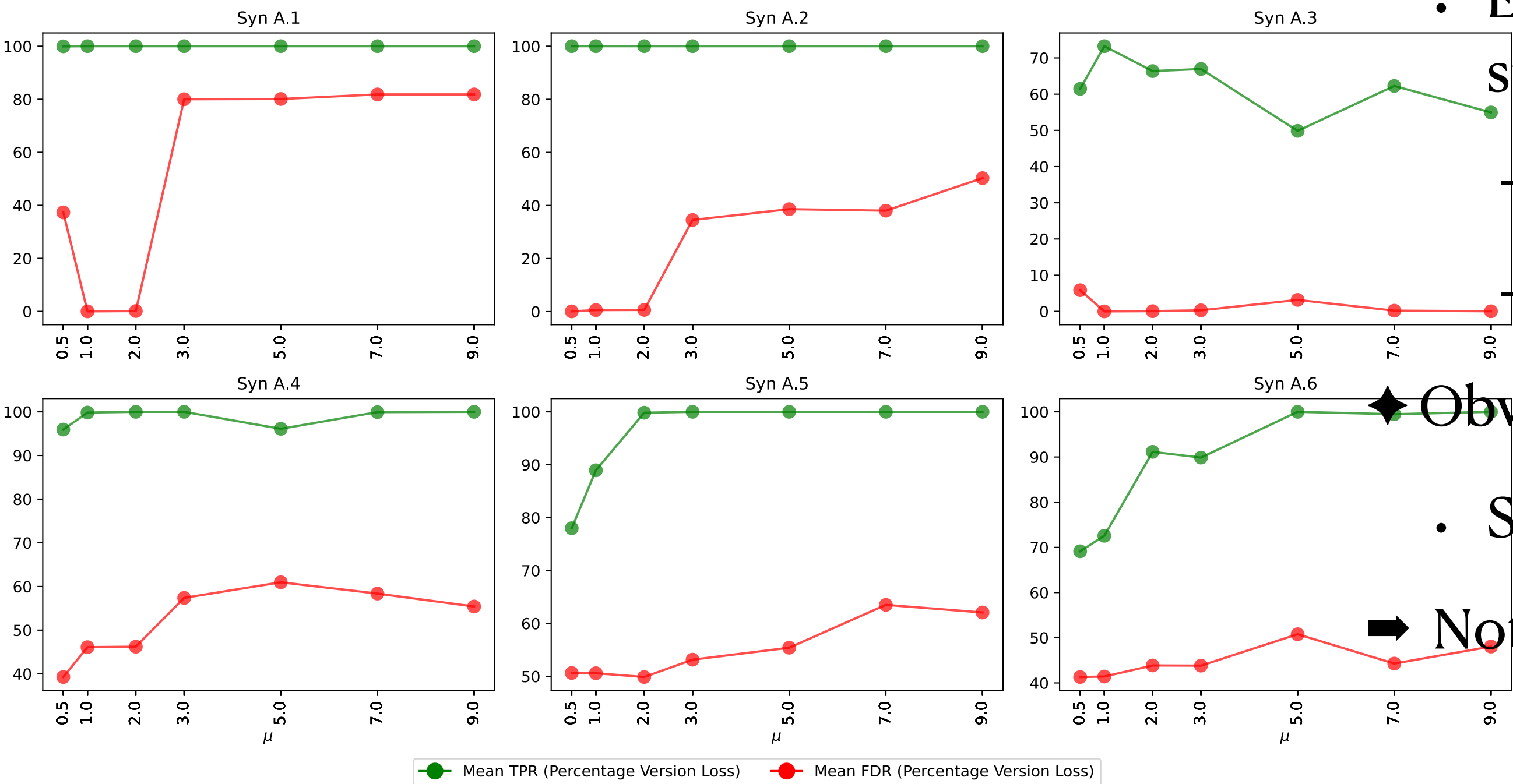
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Exploration of Potential Improvements to INVASE

Detailed Comparison of TPR and FDR

Table 5.1: Comparison between the revised loss functions and *INVASE*

Methods	(Mean, Std)	Synthetic Datasets					
		A.1	A.2	A.3	A.4	A.5	A.6
<i>INVASE</i>	TPR	(100, 0)	(100,0)	(100, 0)	(100, 0)	(73, 28)	(72, 28)
	FDR	(0, 0)	(0, 0)	(0, 0)	(39, 18)	(23, 16)	(5, 13)
Direct Replacement Version Loss	TPR	(100, 0)	(100, 0)	(91, 12)	(97, 13)	(83, 20)	(73, 25)
	FDR	(0, 0)	(0, 0)	(0, 0.7)	(13, 24)	(19, 18)	(7, 15)
Percentage Version Loss	TPR	(100, 0)	(100, 0)	(71, 17)	(100, 0)	(71, 25)	(90, 10)
	FDR	(0, 0)	(0, 0)	(0, 0)	(41, 16)	(23, 16)	(44, 7)

Attempts: **Activation:** ReLU or Selu; **Policy:** Post-Training Selection Policy ($I = 10k$, $m = 100$, $r = 500$, $k = 7$) or Early Stop Policy ($\delta = 3e - 3$, $T = 5$); **Maximum Iterations:** 10k
Hyperparameters: *INVASE*: $\lambda = 0$ to 1, step 0.1; **Direct Replacement Version Loss**: $\lambda^* = 0$ to 1, step 0.1;
Percentage Version Loss: $\mu = 0.5, 1, 2, 3, 5, 7, 9$.