Table 4.1: Comparison Between Long Training and the Proposed Early Stopping Policy

Scenario	Metrics(%)	Synethetic Datasets						
	Metrics(70)	A.1	A.2	A.3	A.4	A.5	A.6	_
10k Epoches	Mean TPR	100	100	90.2	100	75.3	74.7	
	Mean FDR	0	0	0	42.7	38.6	42.3	Loss chances to be better
Simple Early Stopping	Mean TPR	<b>\$</b>	<b>\$</b>	▼50.7	<b>\$</b>	▼16.3	<b>\$</b>	
	Mean FDR	<b>\$</b>	<b>\$</b>	<b>\$</b>	<b>\$</b>	<b>▼</b> 20.6	<b>▼</b> 2.4	→ Save Time
	Used Epoch(k)	1.5	1.2	1.7	5	1.9	4.2	Save Time

Individual Settings: Framework: INVASE; Hyperparameter:  $\lambda = 0.1$ ; Activation: ReLU.

Notations: ♦ denotes no difference, ▼ indicates a decrease, ▲ signifies an increase.

## Analysis of Performance Influencing Factors in INVASE

## Selection Probabilty Stability-based Early Stopping Policy

Advantages: Save unnecessary time Aviod performance degradation • Easy to apply

Drawbacks: Still risk of getting sub-optimal explainer Need to take efforts to decide appropriate parameters

Table 4.1: Comparison Between Long Training and the Proposed Early Stopping Policy

Scenario	Metrics(%)	Synethetic Datasets						
	Metrics(70)	A.1	A.2	A.3	A.4	A.5	A.6	-
10k Epoches	Mean TPR	100	100	90.2	100	75.3	74.7	
	Mean FDR	0	0	0	42.7	38.6	42.3	→ Loss chances to be better
	Mean TPR	$\Diamond$	<b>\$</b>	▼50.7	<b>♦</b>	▼16.3	<b>\$</b>	
Simple Early Stopping	Mean FDR	<b>♦</b>	<b>♦</b>	<b>\$</b>	<b>♦</b>	<b>▼</b> 20.6	<b>▼</b> 2.4	→ Save Time
	Used Epoch(k)	1.5	1.2	1.7	5	1.9	4.2	→ Save Time

Individual Settings: Framework: INVASE; Hyperparameter:  $\lambda = 0.1$ ; Activation: ReLU.

Notations: ♦ denotes no difference, ▼ indicates a decrease, ▲ signifies an increase.

# Analysis of Performance Influencing Factors in INVASE

### Selection Probabilty Stability-based Early Stopping Policy

Table 4.1: Comparison Between Long Training and the Proposed Early Stopping Policy

Scenario	7.5	Synethetic Datasets						
	Metrics(%)	A.1	A.2	A.3	A.4	A.5	A.6	-
10k Epoches	Mean TPR	100	100	90.2	100	75.3	74.7	
	Mean FDR	0	0	0	42.7	38.6	42.3	Loss chances to be better
Simple Early Stopping	Mean TPR	<b>\$</b>	<b>\$</b>	▼50.7	<b>♦</b>	▼16.3	<b>♦</b>	
	Mean FDR	<b>\$</b>	<b>\$</b>	<b>♦</b>	<b>♦</b>	<b>▼</b> 20.6	<b>▼</b> 2.4	→ Save Time
	Used Epoch(k)	1.5	1.2	1.7	5	1.9	4.2	→ Save Time

Individual Settings: Framework: INVASE; Hyperparameter:  $\lambda = 0.1$ ; Activation: ReLU.

Notations: ♦ denotes no difference, ▼ indicates a decrease, ▲ signifies an increase.

#### Advantages:

- Save unnecessary time
- Aviod performance degradation
- Easy to apply

#### Drawbacks:

- Still risk of getting sub-optimal explainer
- Need to take efforts to decide appropriate parameters

## Analysis of Performance Influencing Factors in INVASE

## **Post-Training Selection Policy**

Table 4.2: Comparison Between Long Training and Post-Training Selection Policy

Scenario	Metrics(%)	Synethetic Datasets							
	Wietrics (70)	A.1	A.2	A.3	A.4	A.5	A.6		
10k Epoches	Mean TPR	100	100	90.2	100	75.3	74.7		
	Mean FDR	0	0	0	42.7	38.6	42.3		
Post-Training Selection	Mean TPR	<b>\$</b>	<b>\$</b>	<b>\$</b>	<b>\$</b>	<b>▼</b> 2.4	▼3.3		
Policy	Mean FDR	<b>\$</b>	<b>♦</b>	<b>♦</b>	<b>▼</b> 3.3	<b>▼</b> 15.9	<b>▼</b> 4.7		

INVASE settings: **Hyperparameter:**  $\lambda = 0.1$ ; **Activation**: ReLU.

Early Stopping Policy settings: I = 10k, m = 100, r = 500, k = 7

Notations: ♦ denotes no difference, ▼ indicates a decrease, ▲ signifies an increase.