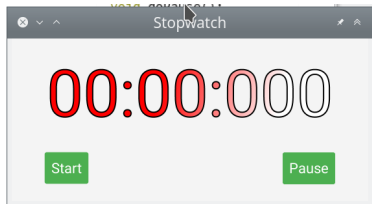


SCXML

State Chart XML

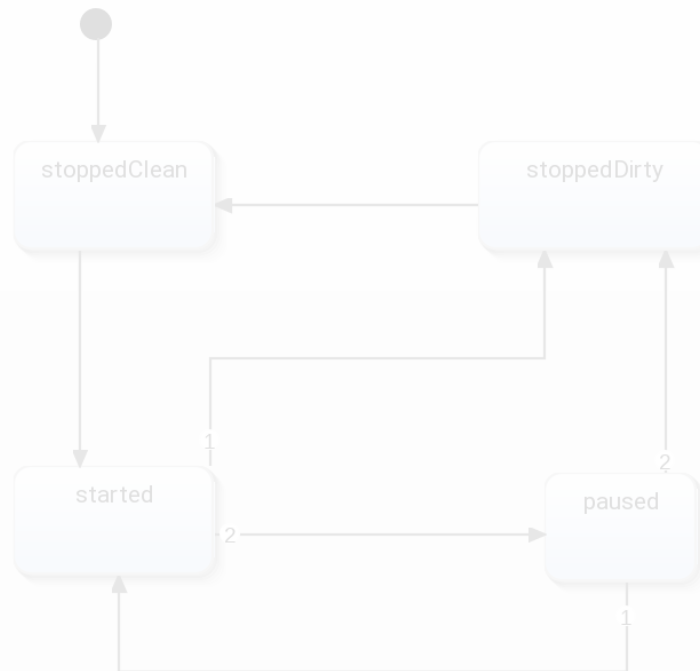
Au delà du transducteur à état fini

Stopwatch

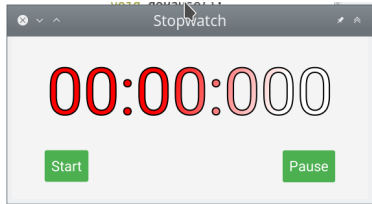


interface:
in event leftButton
in event rightButton
out event start
out event stop
out event reset
out event pause
out event resume

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void

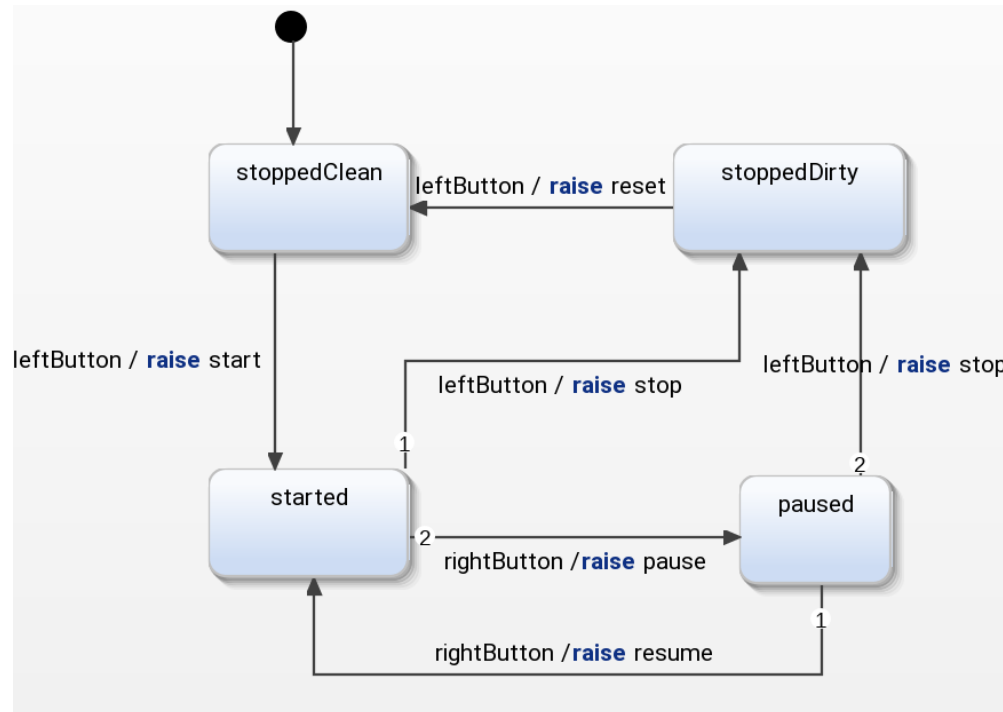


Stopwatch

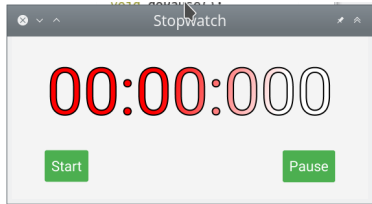


interface:
in event leftButton
in event rightButton
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out event resume

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void



Notion of behavior of the FSM



Q is a set of State

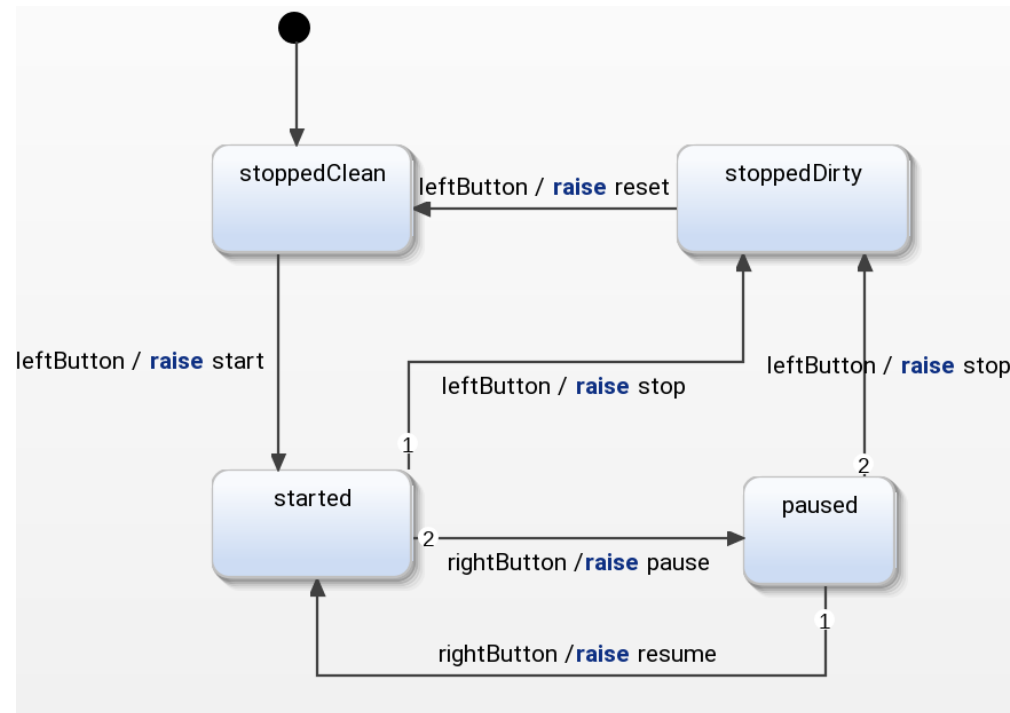
$q_0 \in Q$ is the initial state

\mathcal{F} is the set of final states

Σ_I is the input alphabet

Σ_O is the output alphabet

$\delta : Q \times \Sigma_I \times \Sigma_O \times Q$



- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void

A finite state transducer is defined by $\langle Q, q_0, \mathcal{F}, \Sigma_I, \Sigma_O, \delta \rangle$

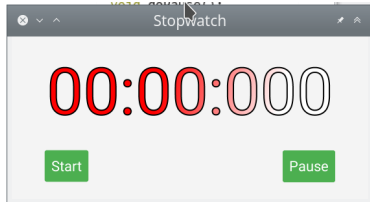
Consider an automaton $\langle Q, q_0, \Sigma_I \times \Sigma_O, \delta' \rangle$ where

$(s, (i, o), s') \in \delta'$ iff $(s, i, o, s') \in \delta$.

The language accepted by this automaton is the **language of the FSM at state q_0**

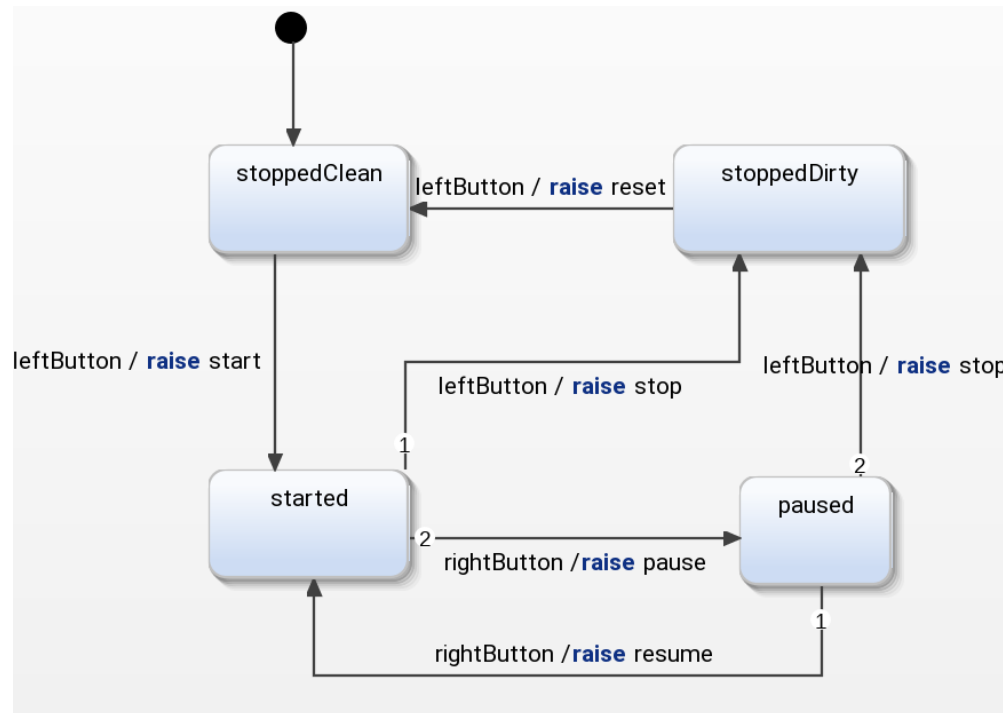
This language is sometimes called '**behavior**'

Stopwatch

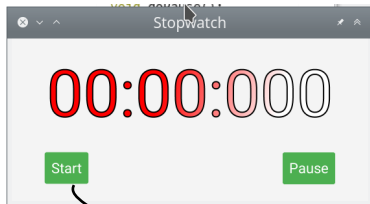


interface:
in event leftButton
in event rightButton
out event start
out event stop
out event reset
out event pause
out event resume

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void



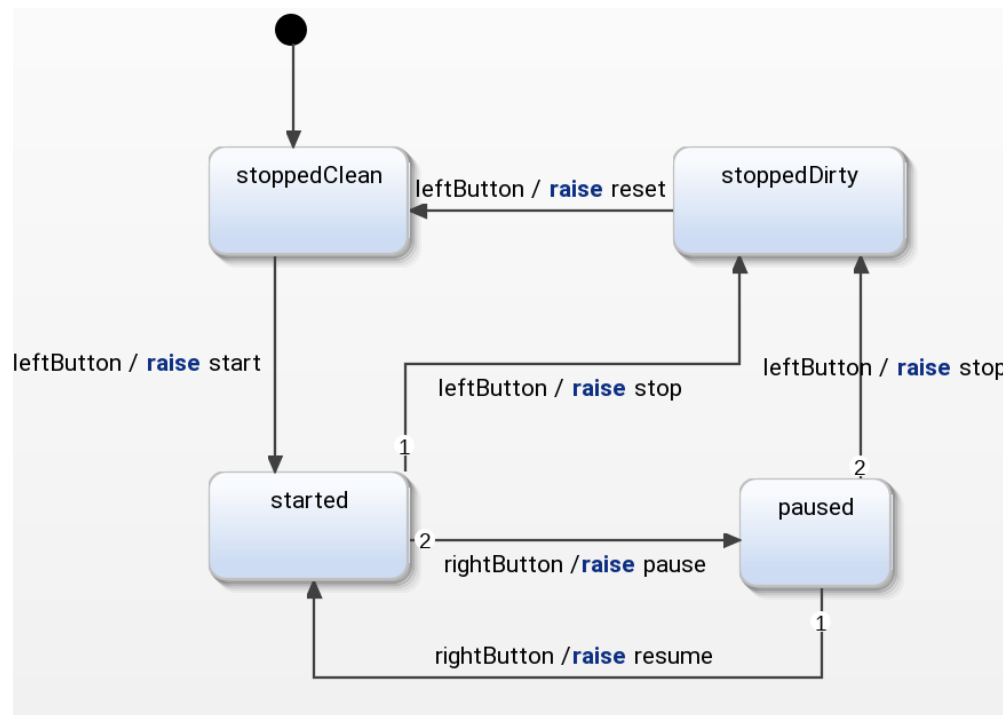
Stopwatch



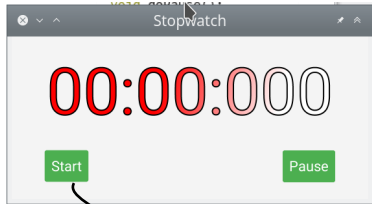
interface:
in event leftButton
in event rightButton
out event start
out event stop
out event reset
out event pause
out event resume

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void

```
leftButton.setOnAction(new EventHandler<ActionEvent>() {  
    @Override  
    public void handle(ActionEvent event) {  
        theFSM.getSCInterface().raiseLeftButton();  
    }  
});
```



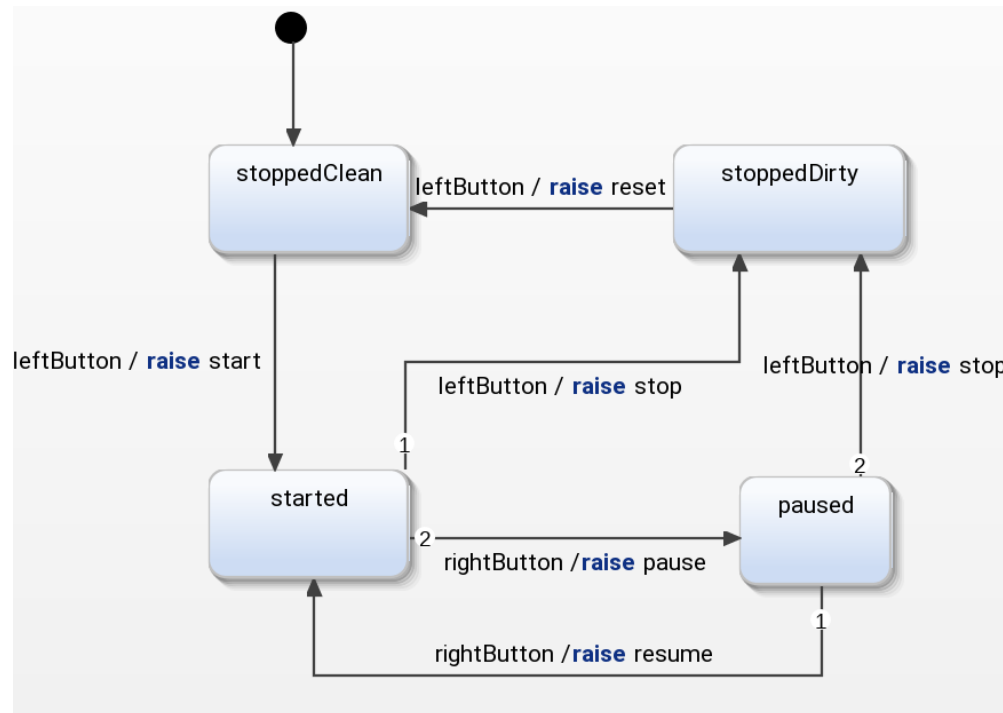
Stopwatch



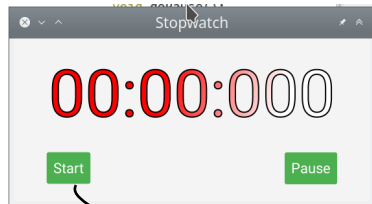
interface:
in event leftButton
in event rightButton
out event start
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out event reset
out event pause
out event resume

```
leftButton.setOnAction(new EventHandler<ActionEvent>() {
    @Override
    public void handle(ActionEvent event) {
        theFSM.getSCInterface().raiseLeftButton();
    }
});
```

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void



Stopwatch



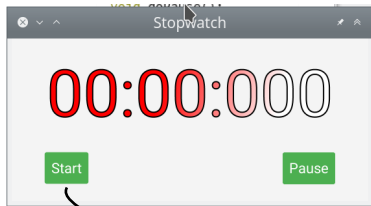
`leftButton.setOnAction(new EventHandler<ActionEvent>() {`

```
@Override
public
    theod
    }
});
```

- `setOnAction(EventHandler<ActionEvent> value) : void - ButtonBase`
- `setOnContextMenuRequested(EventHandler<? super ContextMenuEvent> value) : void - Node`
- `setOnDragDetected(EventHandler<? super MouseEvent> value) : void - Node`
- `setOnDragDone(EventHandler<? super DragEvent> value) : void - Node`
- `setOnDragDropped(EventHandler<? super DragEvent> value) : void - Node`
- `setOnDragEntered(EventHandler<? super DragEvent> value) : void - Node`
- `setOnDragExited(EventHandler<? super DragEvent> value) : void - Node`
- `setOnDragOver(EventHandler<? super DragEvent> value) : void - Node`
- `setOnInputMethodTextChanged(EventHandler<? super InputMethodEvent> value) : void - Node`
- `setOnKeyPressed(EventHandler<? super KeyEvent> value) : void - Node`
- `setOnKeyReleased(EventHandler<? super KeyEvent> value) : void - Node`
- `setOnKeyTyped(EventHandler<? super KeyEvent> value) : void - Node`
- `setOnMouseClicked(EventHandler<? super MouseEvent> value) : void - Node`
- `setOnMouseDragEntered(EventHandler<? super MouseDragEvent> value) : void - Node`
- `setOnMouseDragExited(EventHandler<? super MouseDragEvent> value) : void - Node`
- `setOnMouseDragged(EventHandler<? super MouseEvent> value) : void - Node`
- `setOnMouseDragOver(EventHandler<? super MouseDragEvent> value) : void - Node`
- `setOnMouseDragReleased(EventHandler<? super MouseDragEvent> value) : void - Node`
- `setOnMouseEntered(EventHandler<? super MouseEvent> value) : void - Node`
- `setOnMouseExited(EventHandler<? super MouseEvent> value) : void - Node`
- `setOnMouseMoved(EventHandler<? super MouseEvent> value) : void - Node`
- `setOnMousePressed(EventHandler<? super MouseEvent> value) : void - Node`
- `setOnMouseReleased(EventHandler<? super MouseEvent> value) : void - Node`
- `setOnRotate(EventHandler<? super RotateEvent> value) : void - Node`
- `setOnRotationFinished(EventHandler<? super RotateEvent> value) : void - Node`
- `setOnRotationStarted(EventHandler<? super RotateEvent> value) : void - Node`

- `doReset() : void`
- `doResume() : void`
- `doPause() : void`
- `doStop() : void`
- `doStart() : void`

Stopwatch



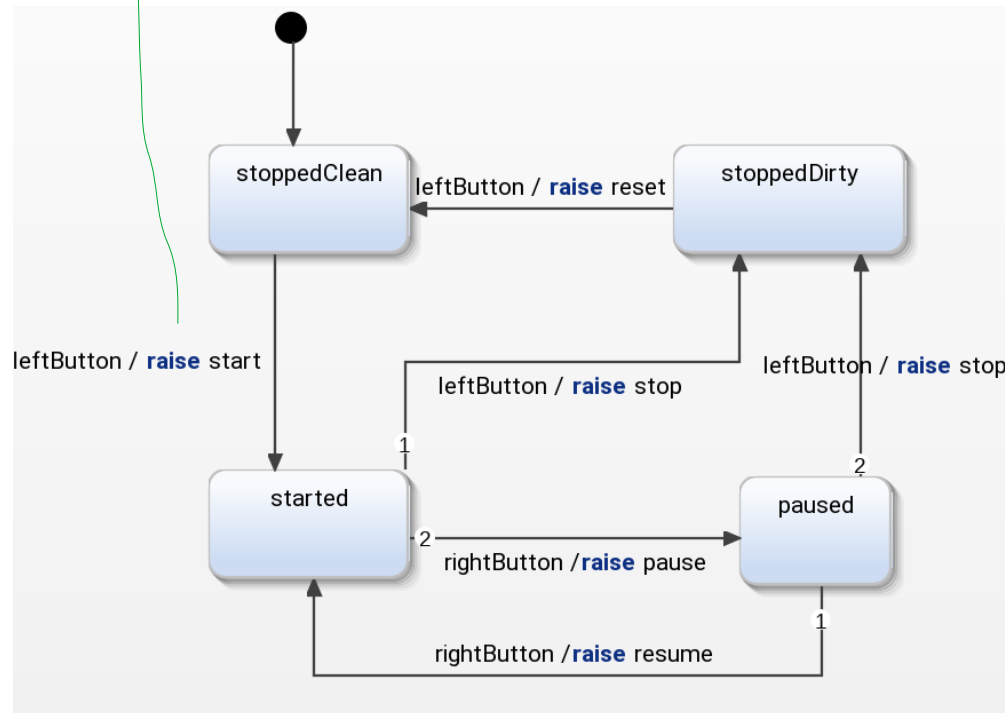
```
leftButton.setOnAction(new EventHandler<ActionEvent>() {
    @Override
    public void handle(ActionEvent event) {
        theFSM.getSCInterface().raiseLeftButton();
    }
});
```

interface:

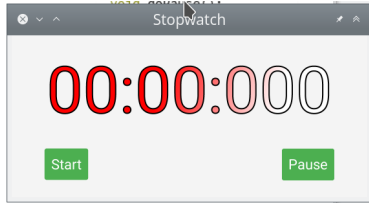
- in event leftButton
- in event rightButton
- out event start
- out event stop
- out event reset
- out event pause
- out event resume

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void

```
@Override
public void onDoStartRaised() {
    doStart();
}
```

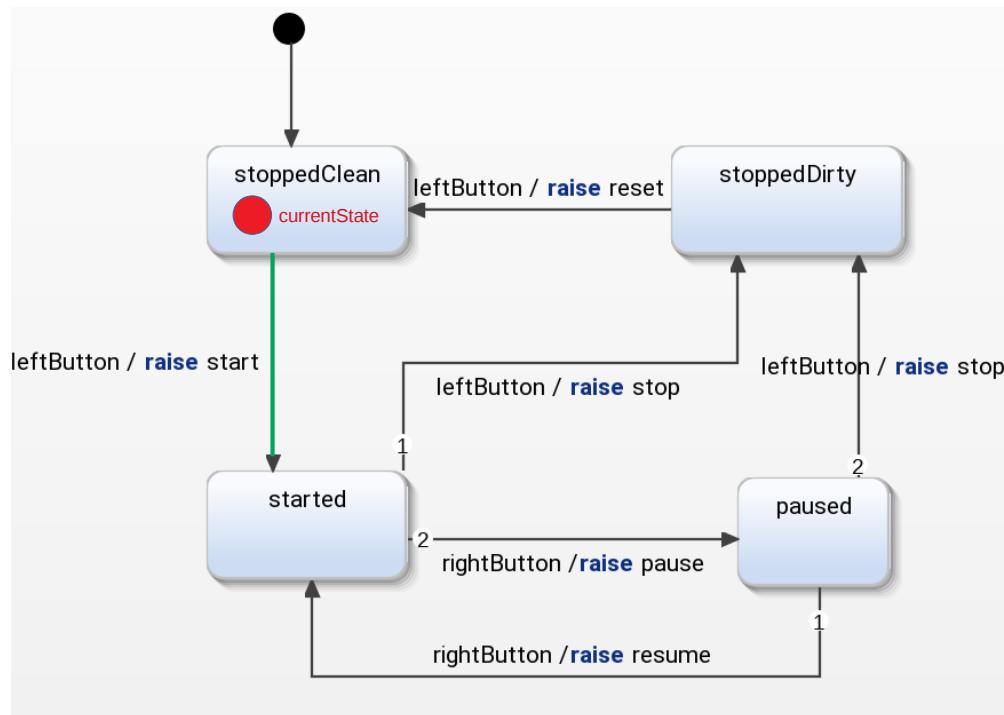


Stopwatch



interface:
in event leftButton
in event rightButton
out event start
out event stop
out event reset
out event pause
out event resume

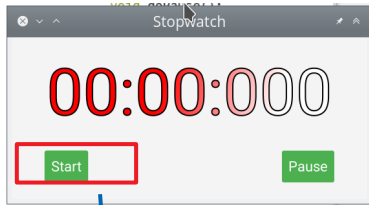
- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void



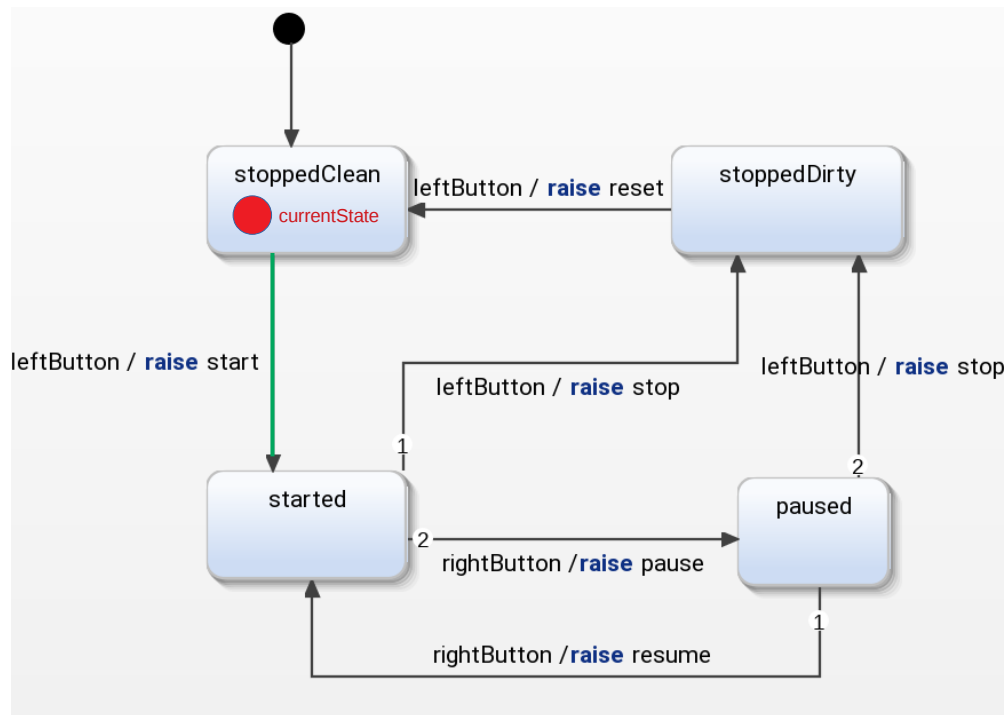
Stopwatch

interface:
in event leftButton
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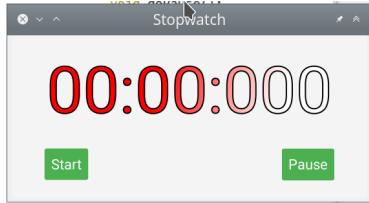
■ doReset() : void
 ■ doResume() : void
 ■ doPause() : void
 ■ doStop() : void
 ■ doStart() : void



Inject an event

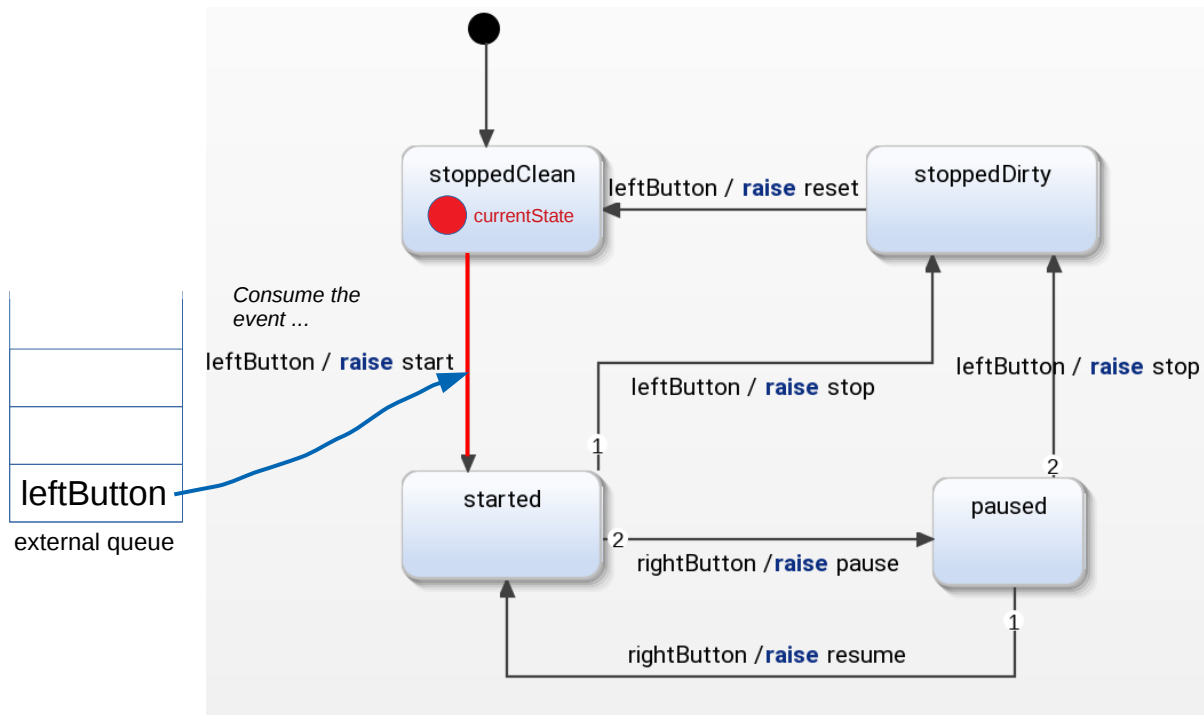


Stopwatch

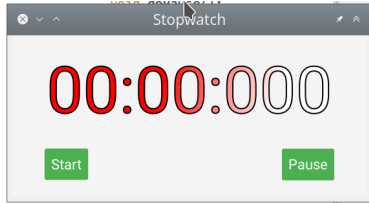


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out event resume

- doReset() : void
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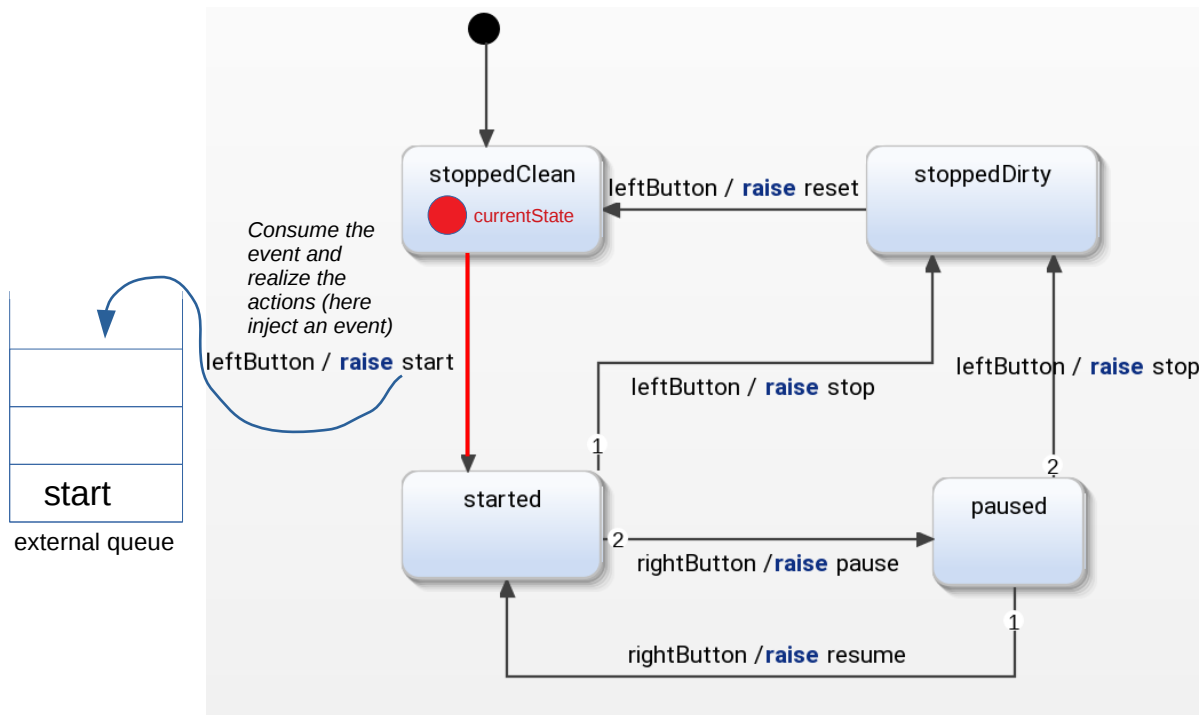


Stopwatch

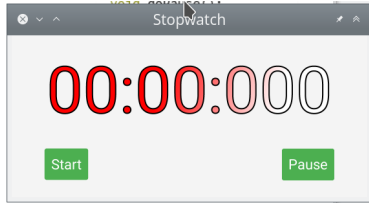


interface:
in event leftButton
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out event pause
out event resume

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void

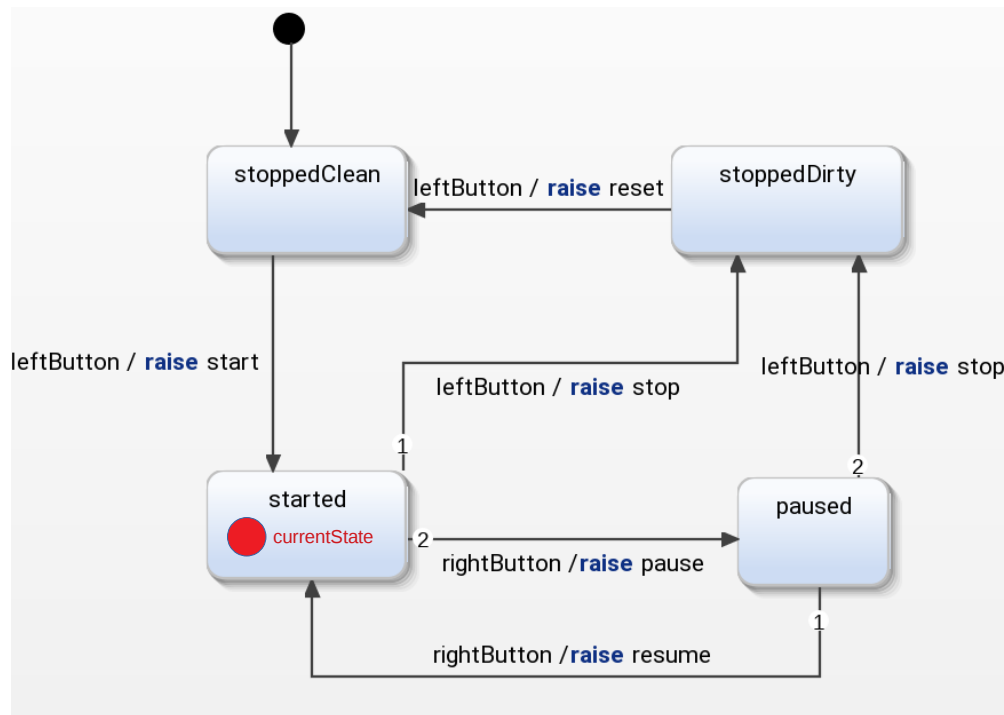


Stopwatch

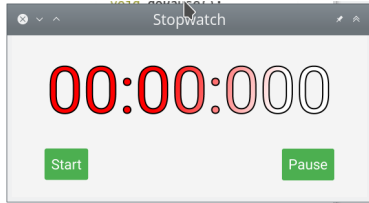


interface:
in event leftButton
in event rightButton
out event start
out event stop
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out event pause
out event resume

- doReset() : void
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- doStop() : void
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Stopwatch

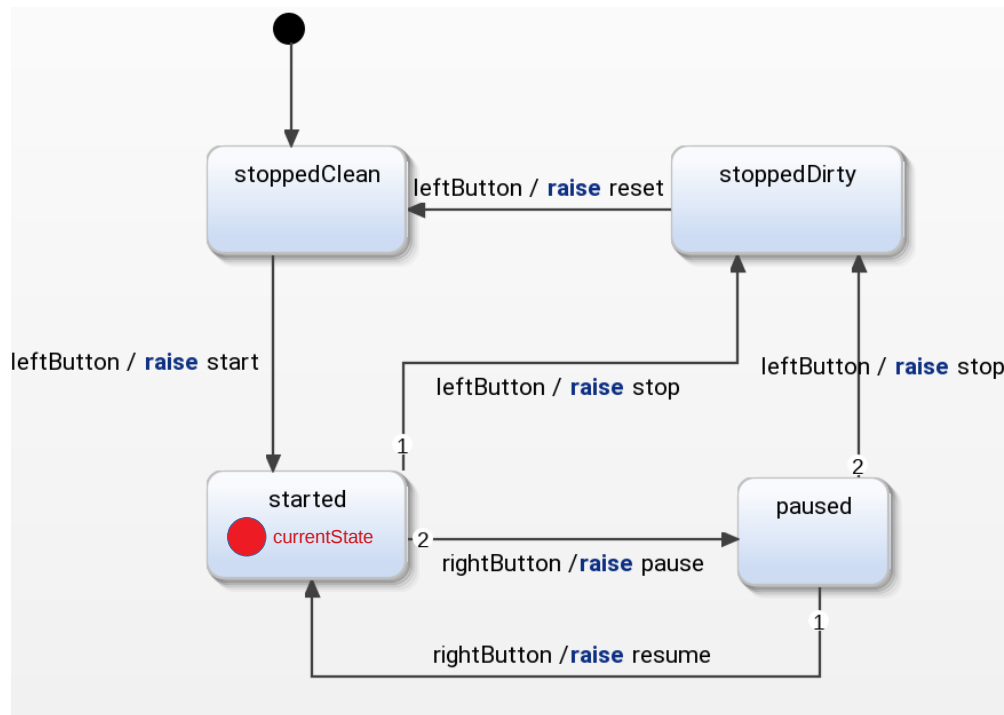


interface:
in event leftButton
in event rightButton
out event start
out event stop
out event reset
out event pause
out event resume

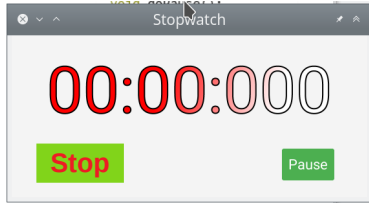
- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void

```
protected void doStart() {
    msTimer.start();
    updateTimer.start();
    leftButton.setText("stop");
    rightButton.setText("pause");
}
```

Consume the
event and call
the method

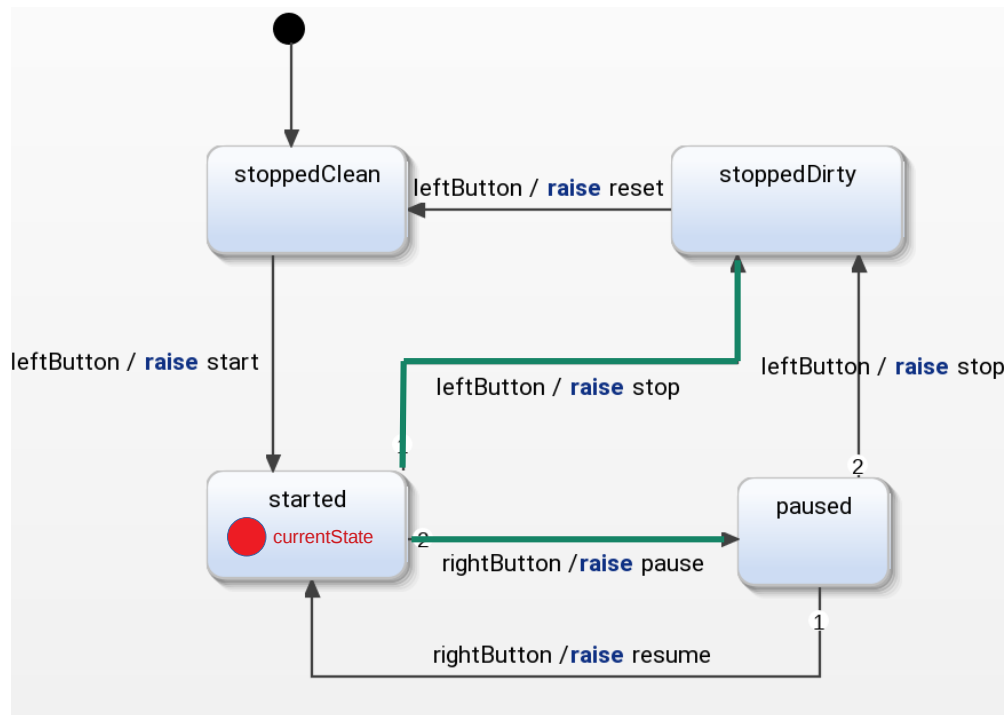


Stopwatch

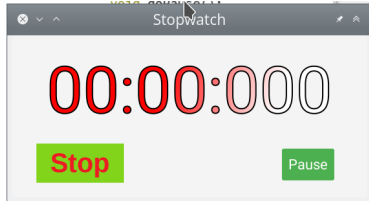


interface:
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out event pause
out event resume

- doReset() : void
- doResume() : void
- doPause() : void
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Stopwatch

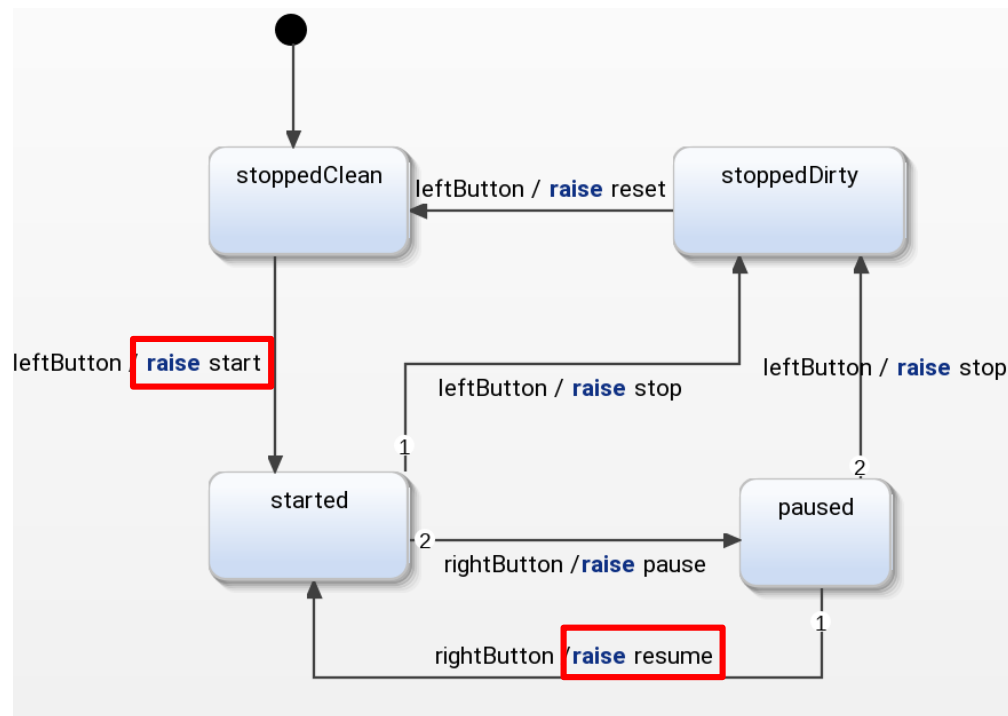


interface:
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- doReset() : void
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- doStop() : void
- doStart() : void

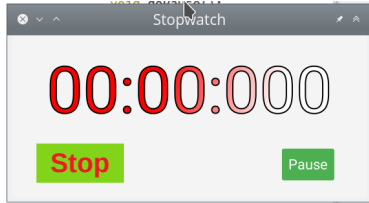
```
protected void doStart() {
    msTimer.start();
    updateTimer.start();
    leftButton.setText("stop");
    rightButton.setText("pause");
}
```

```
protected void doResume() {
    updateTimer.start();
    rightButton.setText("pause");
}
```



Mealy

Stopwatch

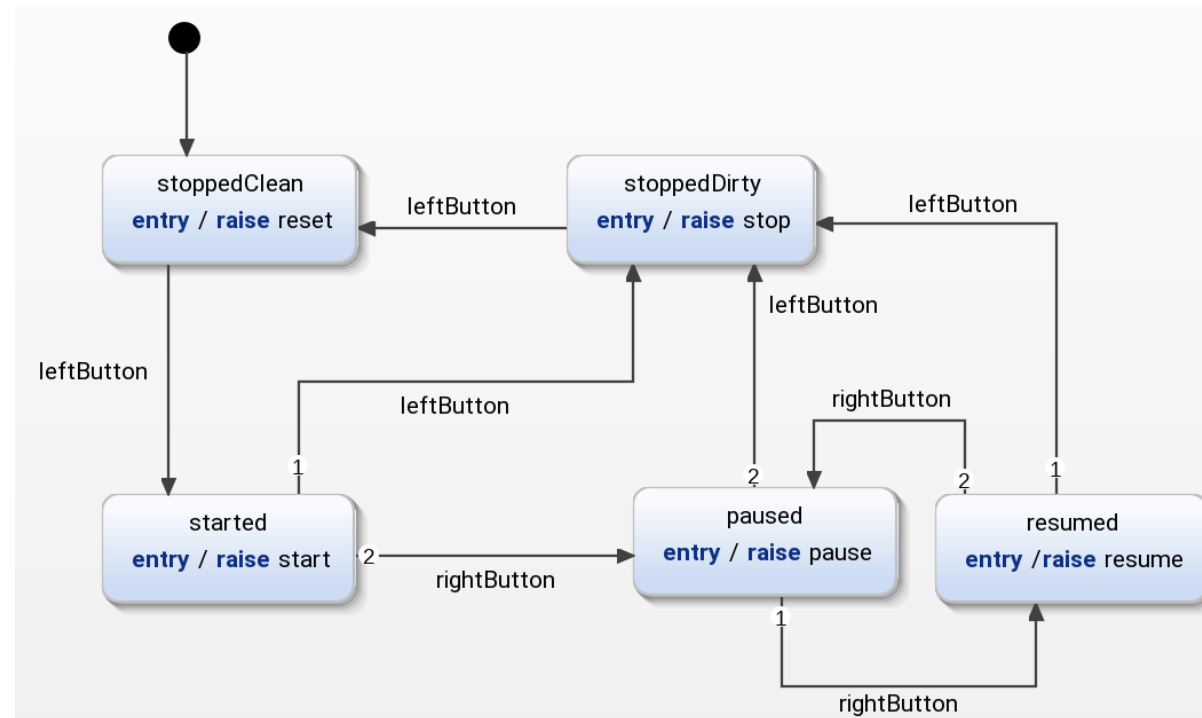


interface:
in event leftButton
in event rightButton
out event start
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out event reset
out event pause
out event resume

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void

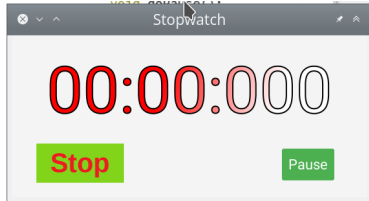
```
protected void doStart() {
    msTimer.start();
    updateTimer.start();
    leftButton.setText("stop");
    rightButton.setText("pause");
}
```

```
protected void doResume() {
    updateTimer.start();
    rightButton.setText("pause");
}
```



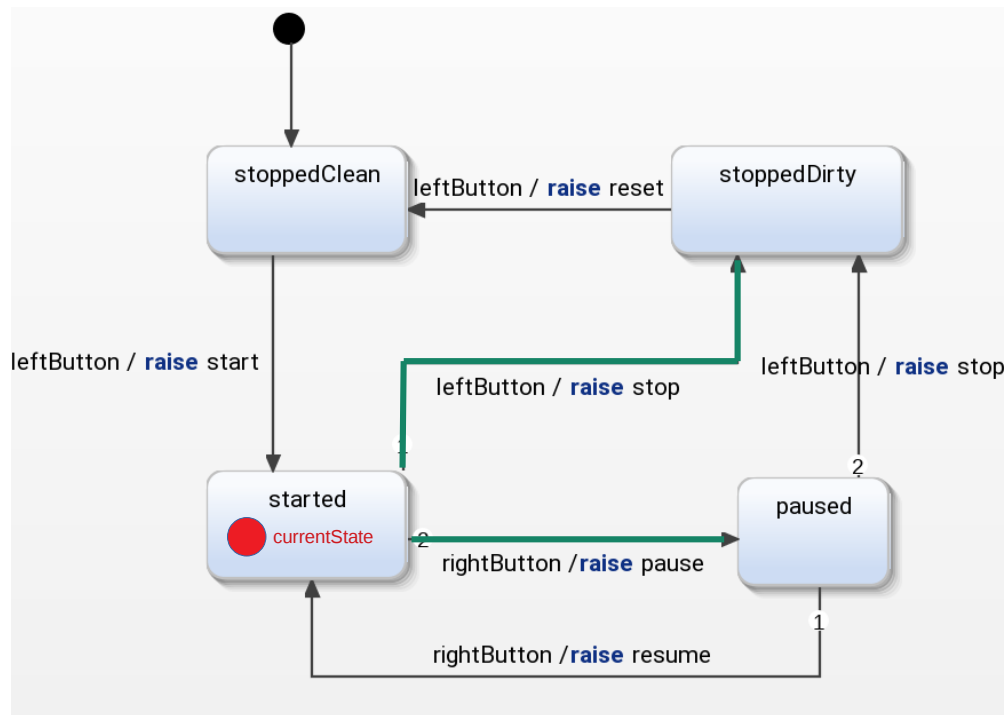
Moore

Stopwatch

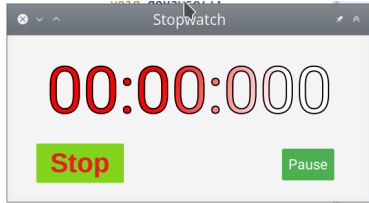


interface:
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- doReset() : void
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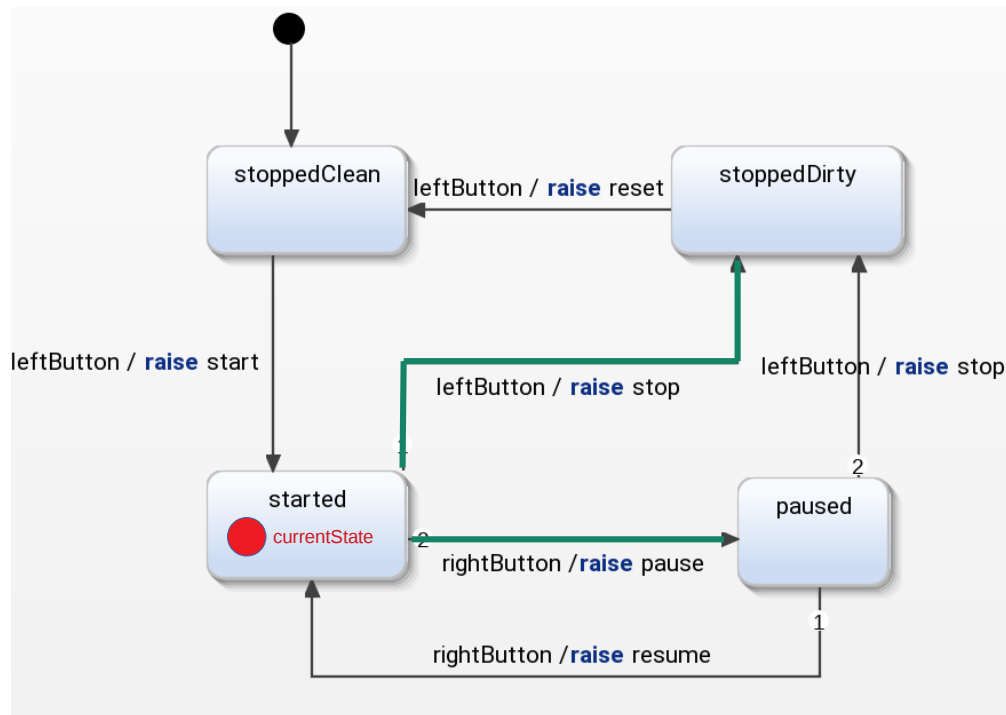


Stopwatch

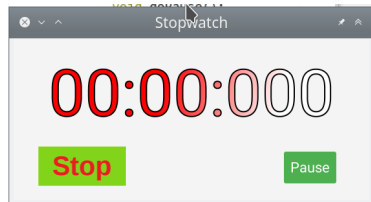


interface:
in event leftButton
in event rightButton
out event start
out event stop
out event reset
out event pause
out event resume

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void
- updateText() : void

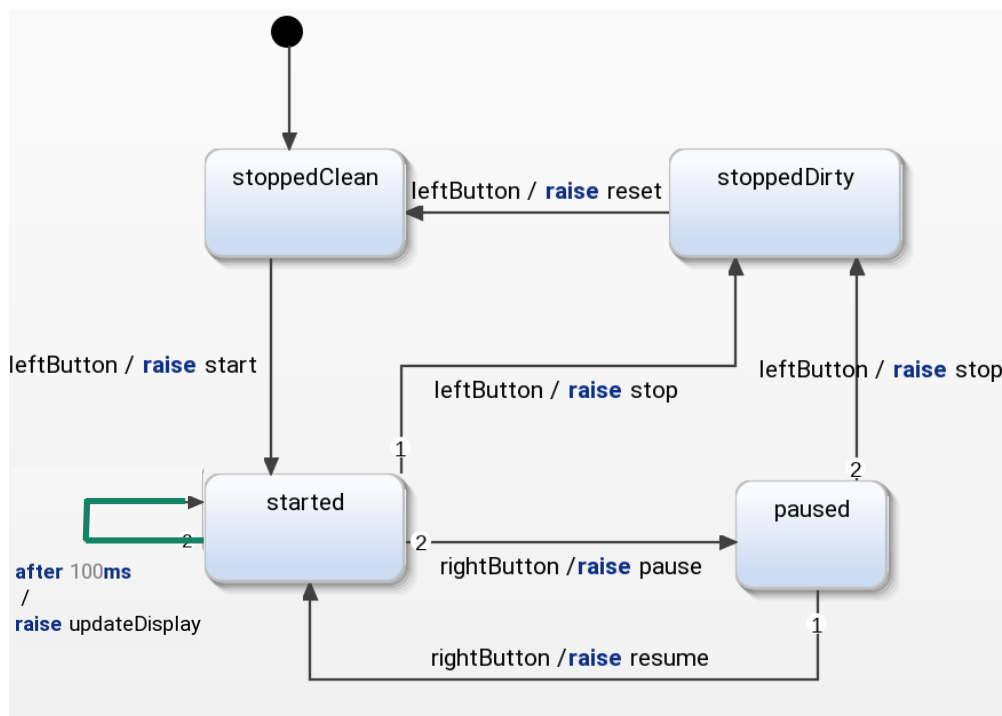


Stopwatch



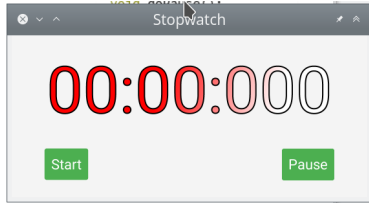
interface:
in event leftButton
in event rightButton
out event start
out event stop
out event reset
out event pause
out event resume
out event updateDisplay

- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void
- updateText() : void



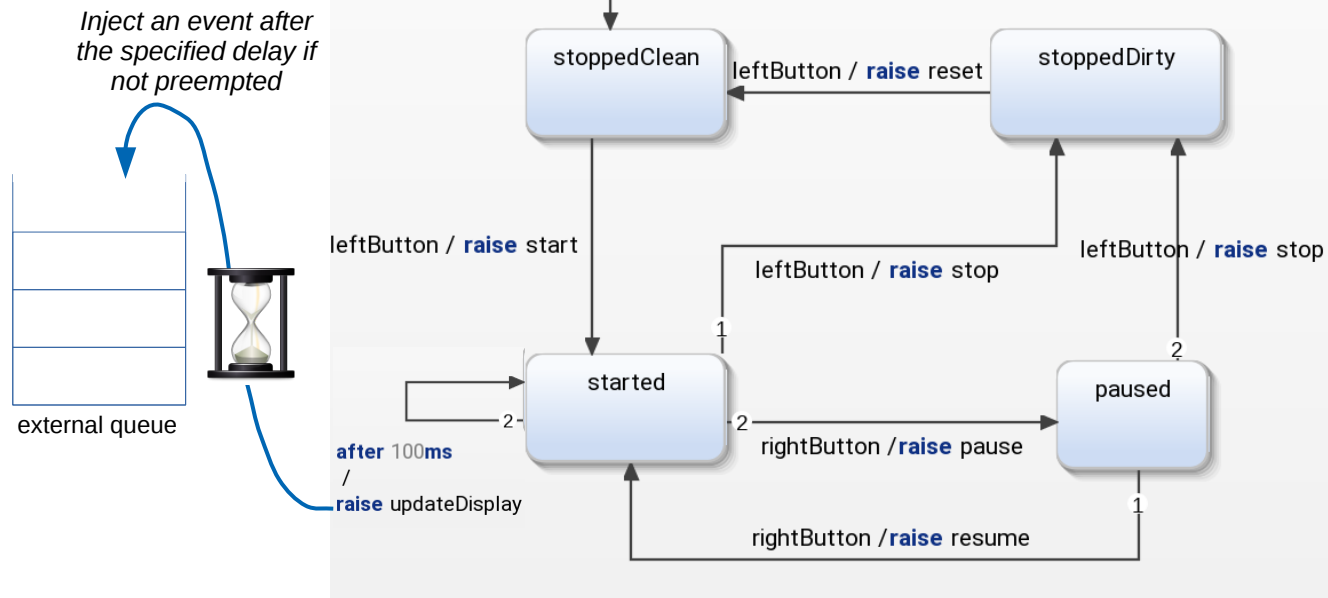
Timed Automata

Stopwatch

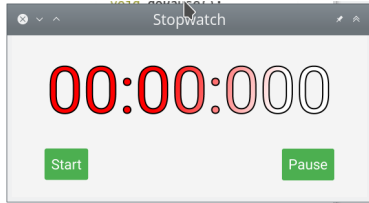


interface:
in event leftButton
in event rightButton
out event start
out event stop
out event reset
out event pause
out event resume
out event updateDisplay

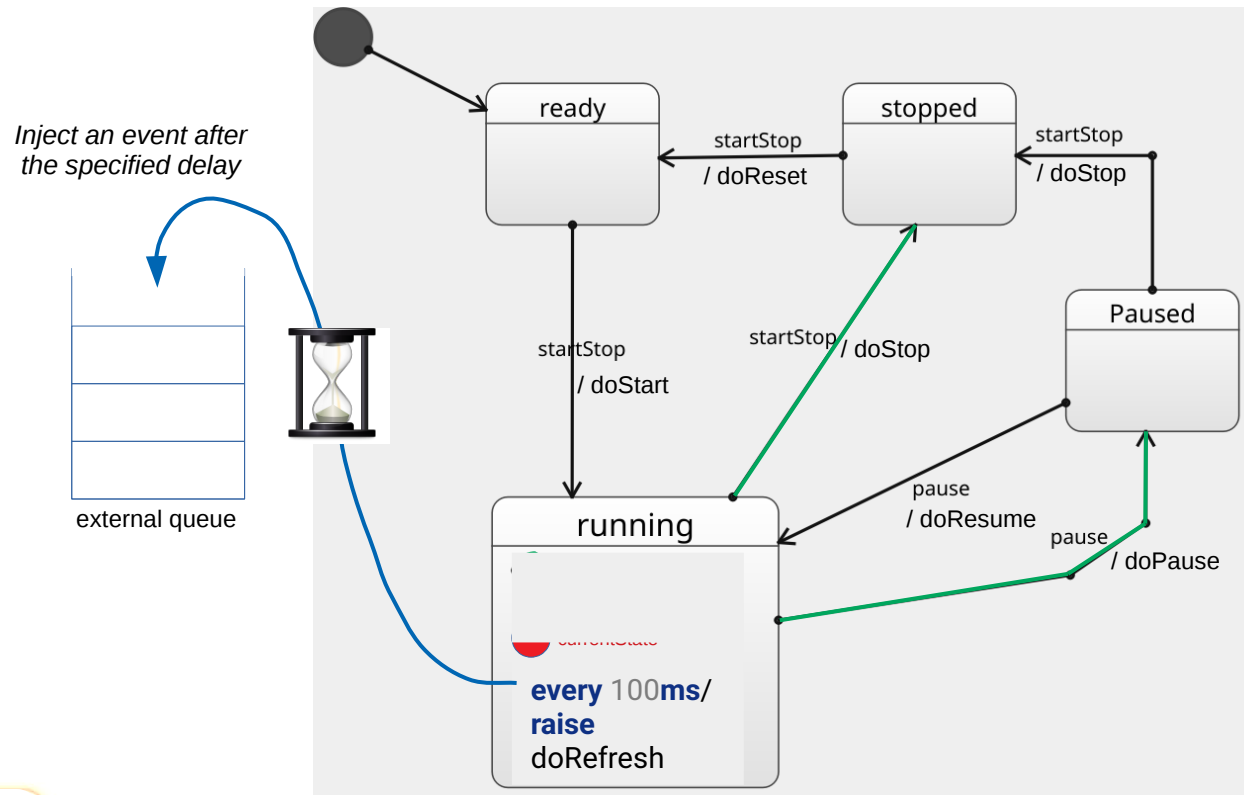
- doReset() : void
- doResume() : void
- doPause() : void
- doStop() : void
- doStart() : void
- updateText() : void



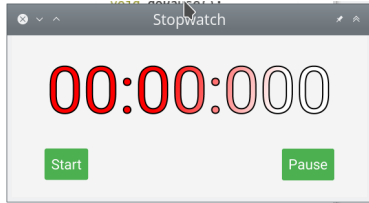
Stopwatch



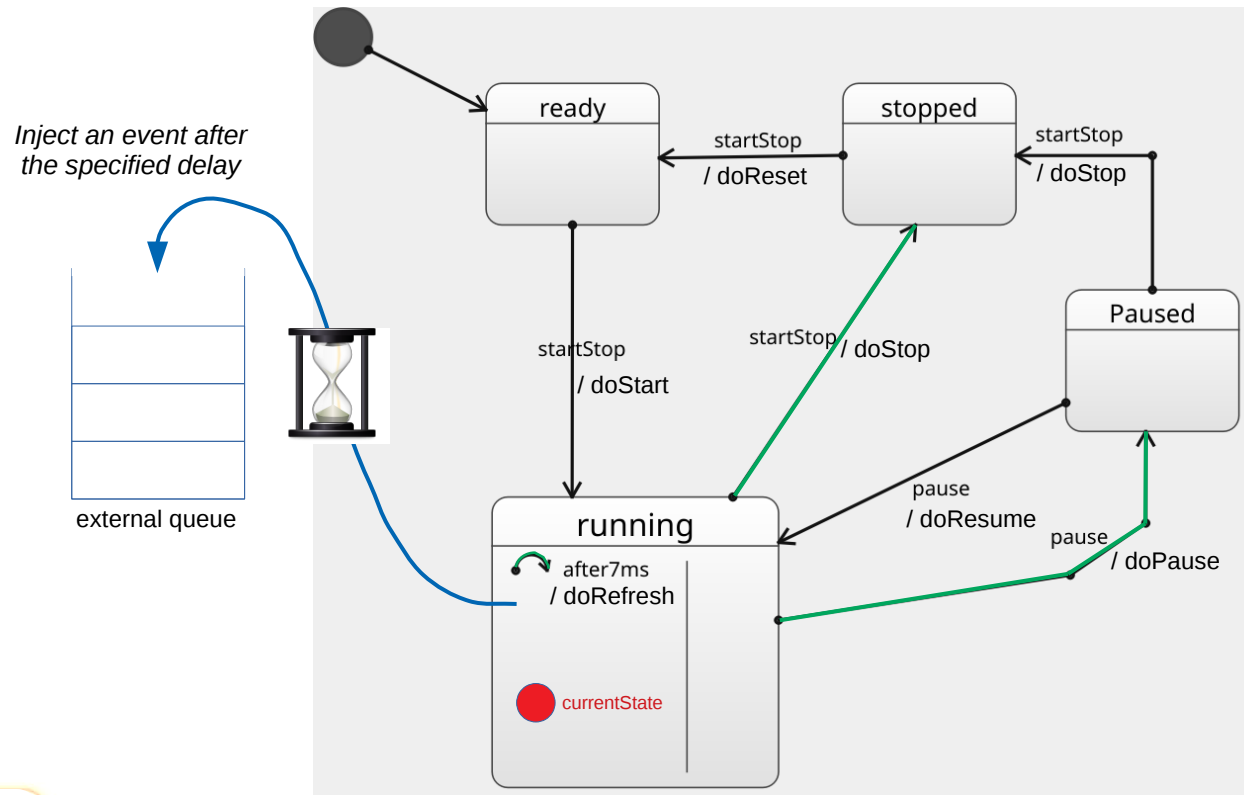
```
void doReset();
void doStart();
void doResume();
void doStop();
void doPause();
void doRefreshDisplay();
```



Stopwatch



```
void doReset();  
void doStart();  
void doResume();  
void doStop();  
void doPause();  
void doRefreshDisplay();
```



SCXML

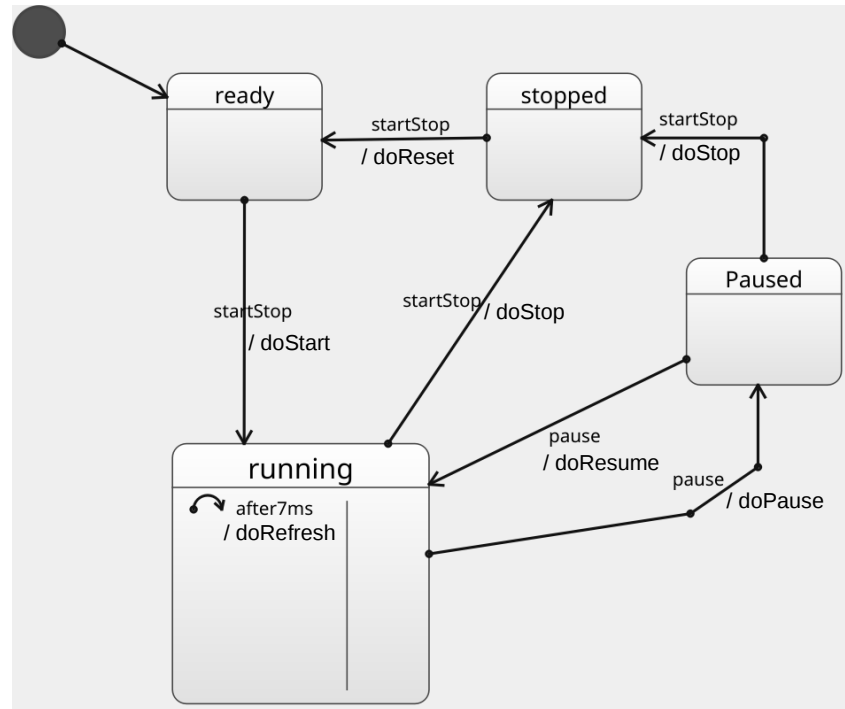
State Chart XML

statecharts = state-diagrams + depth
+ orthogonality + broadcast-communication.

Stopwatch

statecharts = state-diagrams + depth

+ orthogonality + broadcast-communication.



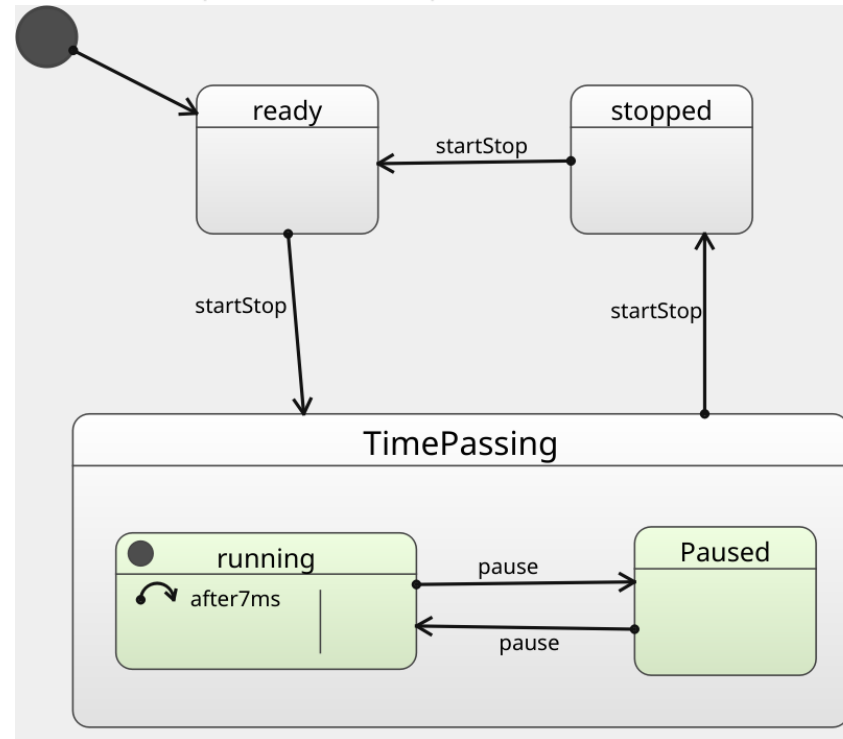
- A simple state is one which has no substructure.

Taken, modified, and completed from http://sce.uhcl.edu/helm/rationalunifiedprocess/process/modguide/md_stadm.htm

Stopwatch

statecharts = state-diagrams + depth

+ orthogonality + broadcast-communication.



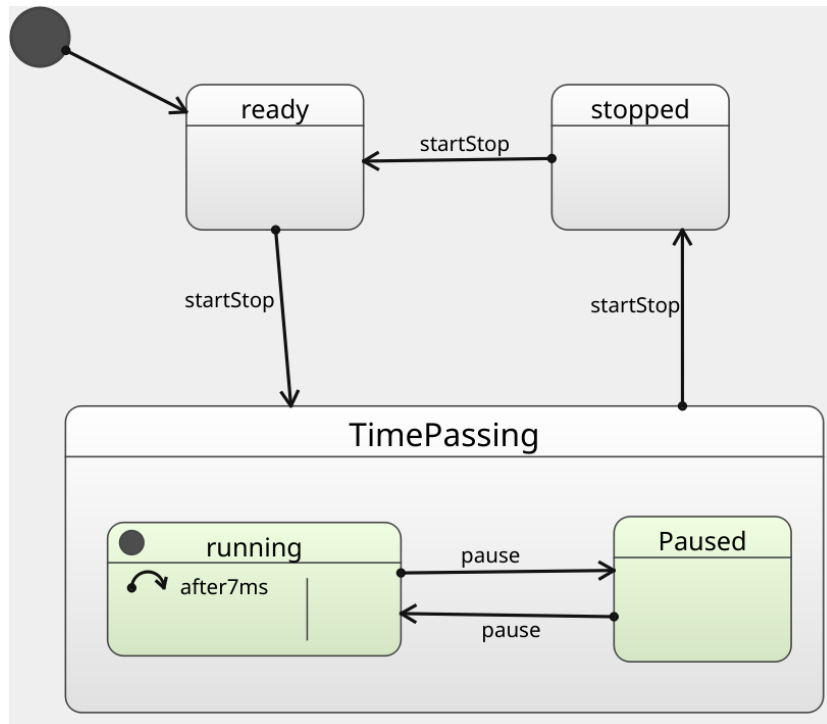
- A simple state is one which has no substructure.
- A state which has substates (nested states) is called a composite state (or compound state).
- Substates may be nested to any level. A nested state machine may have at most one initial state.
- **Substates are used to simplify complex flat state machines by showing that some states are only possible/accessible within a particular context (the enclosing state).**
- **A composite state factorizes the possible exits from all (most of) the states**

Taken and modified from http://sce.uhcl.edu/helm/rationalunifiedprocess/process/modguide/md_stadm.htm

Stopwatch

statecharts = state-diagrams + depth

+ orthogonality + broadcast-communication.



```

scxml.statemachine: "" : "controller: enter TimePassing"
scxml.statemachine: "" : "controller: enter Running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"

```

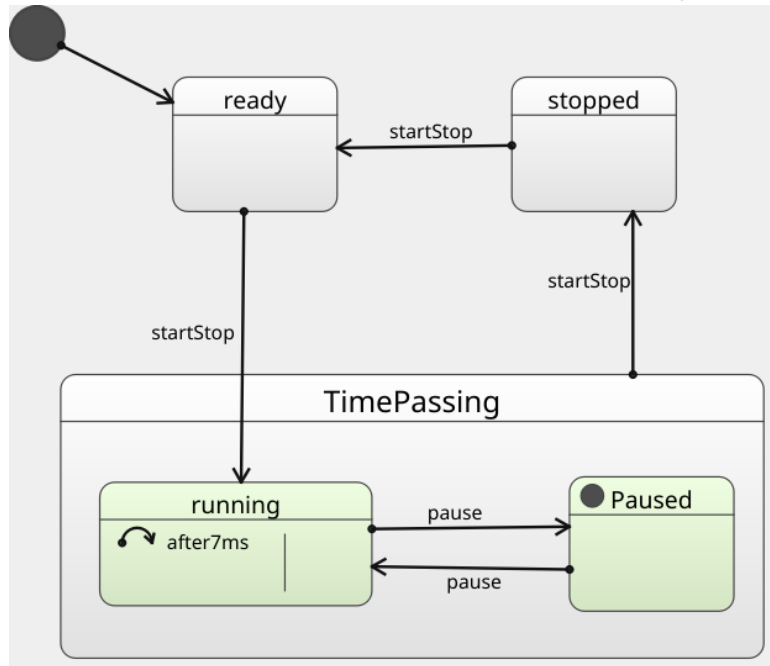
- A simple state is one which has no substructure.
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- Substates may be nested to any level. A nested state machine may have at most one initial state and one final state.
- **Substates are used to simplify complex flat state machines by showing that some states are only possible within a particular context (the enclosing state).**
- **A composite state factorizes the possible exits from all (most of) the states**

Taken and modified from http://sce.uhcl.edu/helm/rationalunifiedprocess/process/modguide/md_stadm.htm

Stopwatch

statecharts = state-diagrams + depth

+ orthogonality + broadcast-communication.



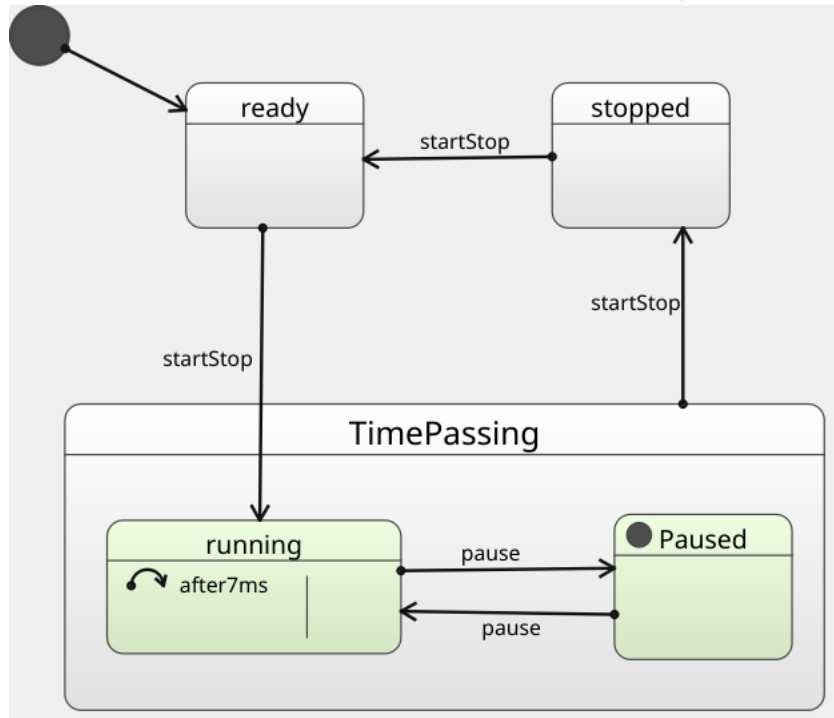
- A simple state is one which has no substructure.
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- Substates may be nested to any level. A nested state machine may have at most one initial state and one final state.
- **Substates are used to simplify complex flat state machines by showing that some states are only possible within a particular context (the enclosing state).**
- **A composite state factorizes the possible exits from all (most of) the states**

Taken and modified from http://sce.uhcl.edu/helm/rationalunifiedprocess/process/modguide/md_stadm.htm

Stopwatch

statecharts = state-diagrams + depth

+ orthogonality + broadcast-communication.



```

scxml.statemachine: "" : "controller: enter Running"
scxml.statemachine: "" : "controller: enter TimePassing"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"
scxml.statemachine: "" : "controller: is running"

```

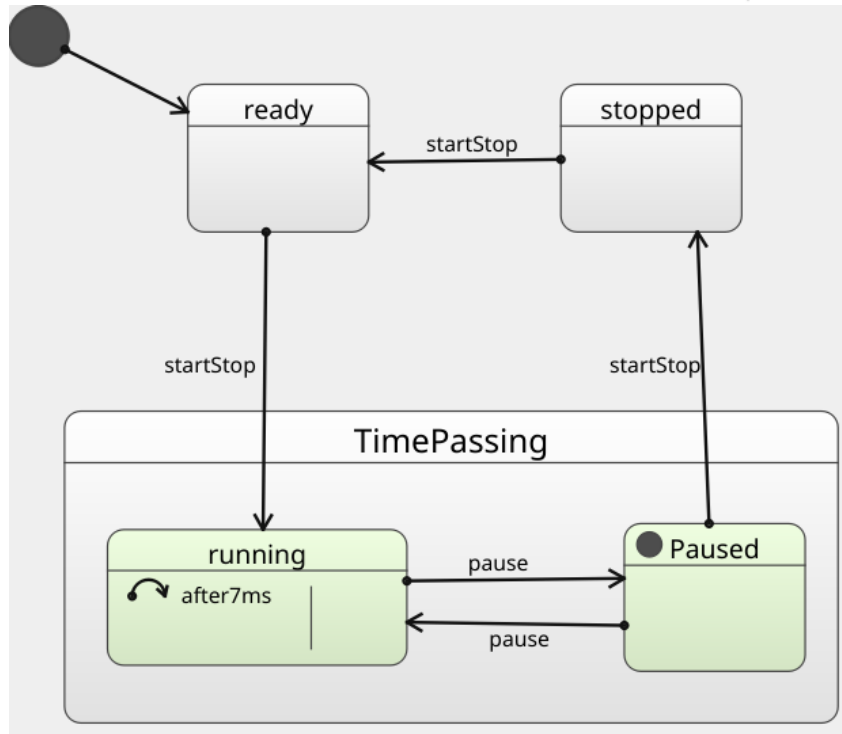
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Stopwatch

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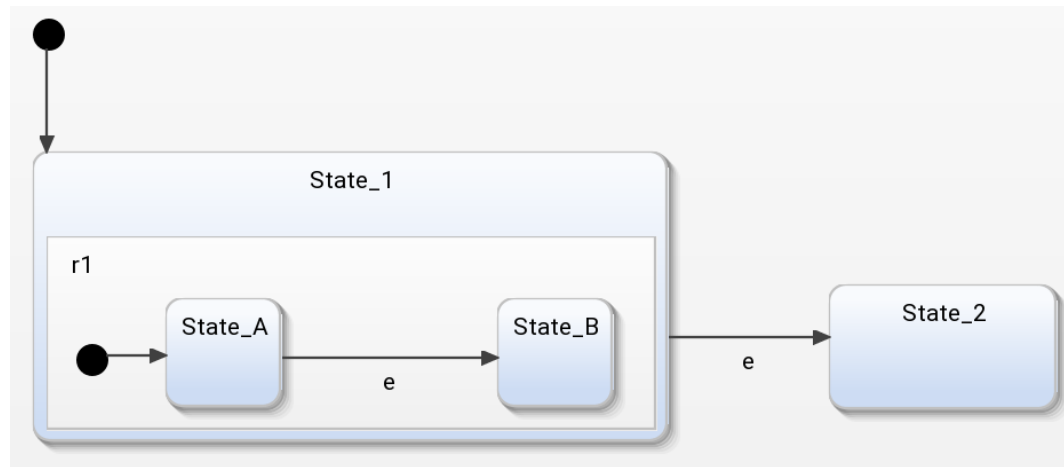


Syntactically correct but the **behavior** is not the expected one

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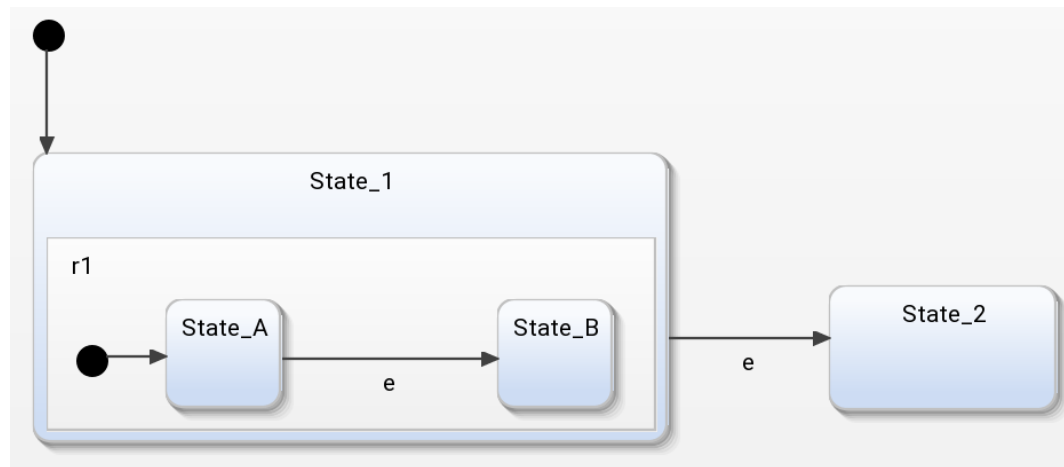
Taken and modified from http://sce.uhcl.edu/helm/rationalunifiedprocess/process/modguide/md_stadm.htm

Composite State



After initialization, 'e' is injected. What happens and why ?

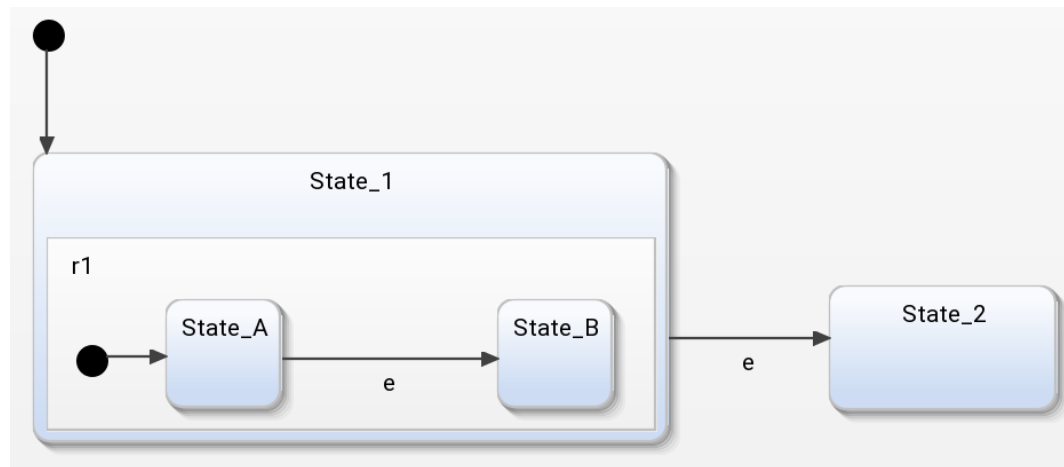
Composite State



After initialization, 'e' is injected. What happens and why ?

- **Compound States:** When looking for transitions, the state machine first looks in the most deeply nested active state(s), i.e., in the atomic state(s) that have no substates. If no transitions match in the atomic state, the state machine will look in its parent state, then in the parent's parent, etc. Thus transitions in ancestor states serve as defaults that will be taken if no transition matches in a descendant state. If no transition matches in any state, the event is discarded.

Composite State

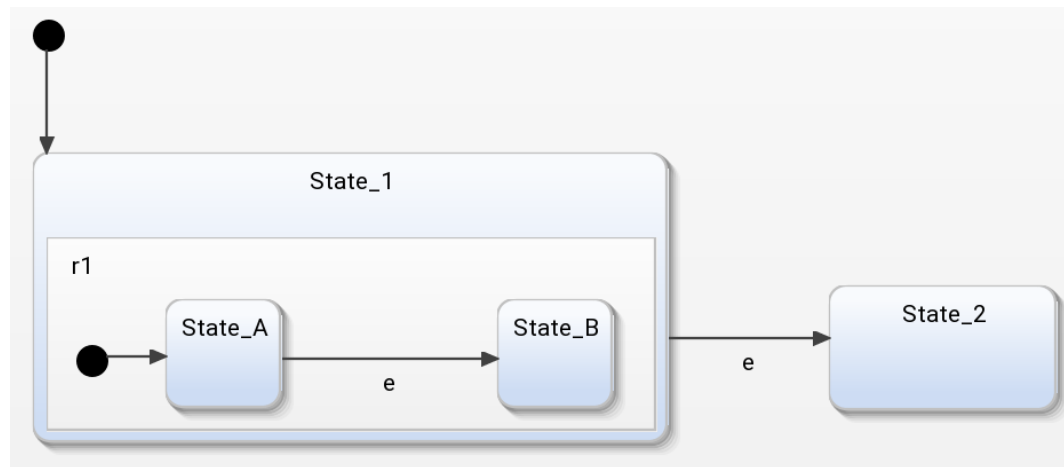


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```
enter State_1;  
enter State_A;  
Inject e  
exit State_A;  
enter State_B;
```

Composite State



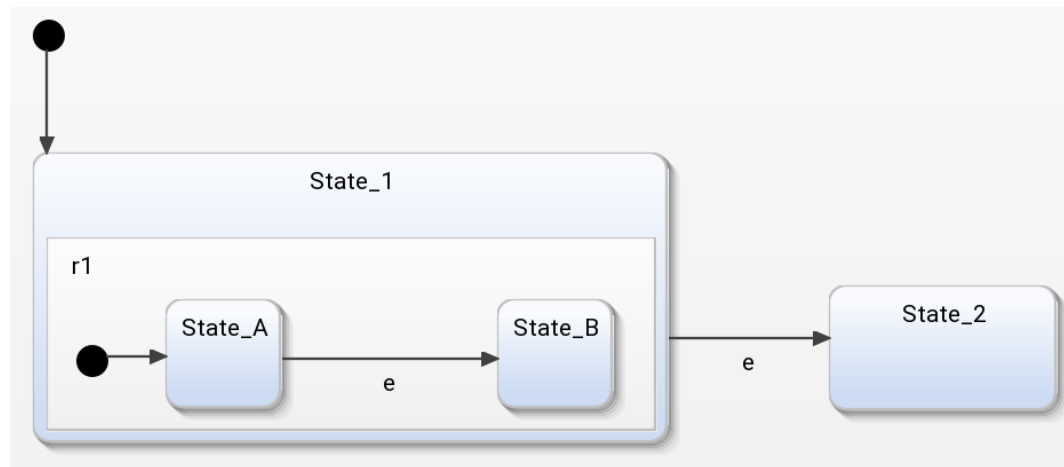
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```
enter State_1;
enter State_A;
Inject e;
exit State_A;
enter State_B;
```

```
Inject e;
exit State_B;
exit State_1;
enter State_2;
```

Composite State



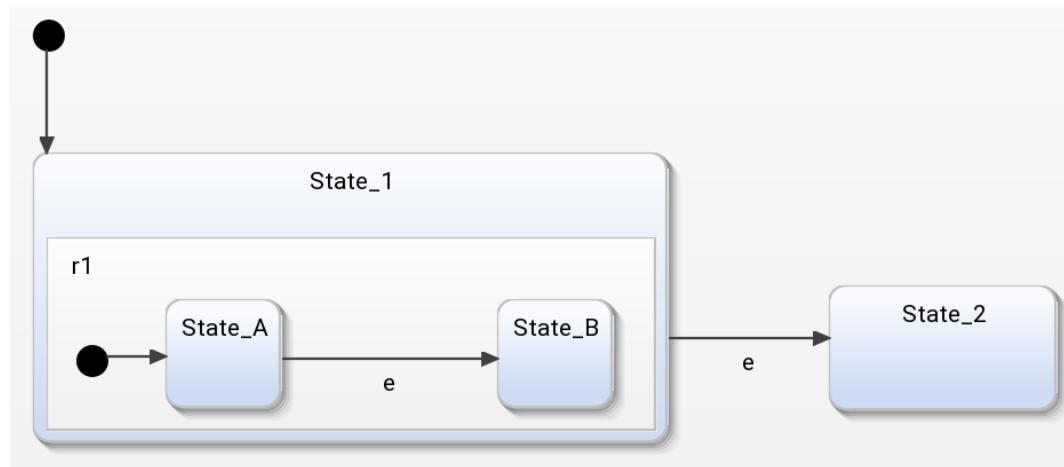
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```
enter State_1;
enter State_A;
Inject e;
exit State_A;
enter State_B;
```

```
Inject e;
exit State_B;
exit State_1;
enter State_2;
Inject e;
Inject e;
```

Composite State



After initialization, 'e' is injected. What happens and why ?

- Compound States: When looking for transitions, the state machine first looks in the most deeply nested active state(s), i.e., in the atomic state(s) that have no substates. If no transitions match in the atomic state, the state machine will look in its parent state, then in the parent's parent, etc. Thus transitions in ancestor states serve as defaults that will be taken if no transition matches in a descendant state. If no transition matches in any state, the event is discarded.

```
enter State_1;
enter State_A;
Inject e
exit State_A;
enter State_B;
```

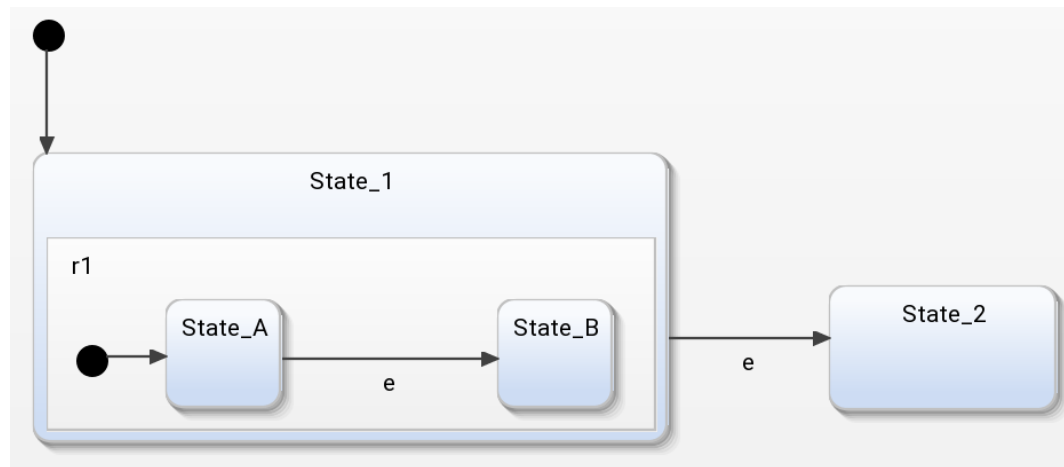


In Yakindu, this is a **semantic variation point**, i.e., a part of the semantics that can be adjusted by the user

@ChildFirstExecution → SCXML semantics

@ParentFirstExecution → Simulink Stateflow semantics

Composite State



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```
enter State_1;
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```

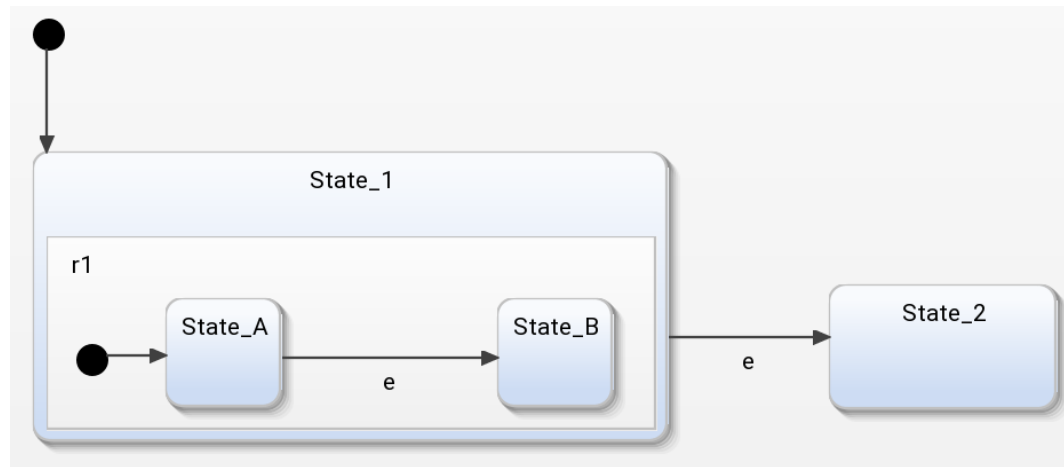


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```
enter State_1;
enter State_A;
Inject e
exit State_A;
Exit State_1;
enter State_2;
```

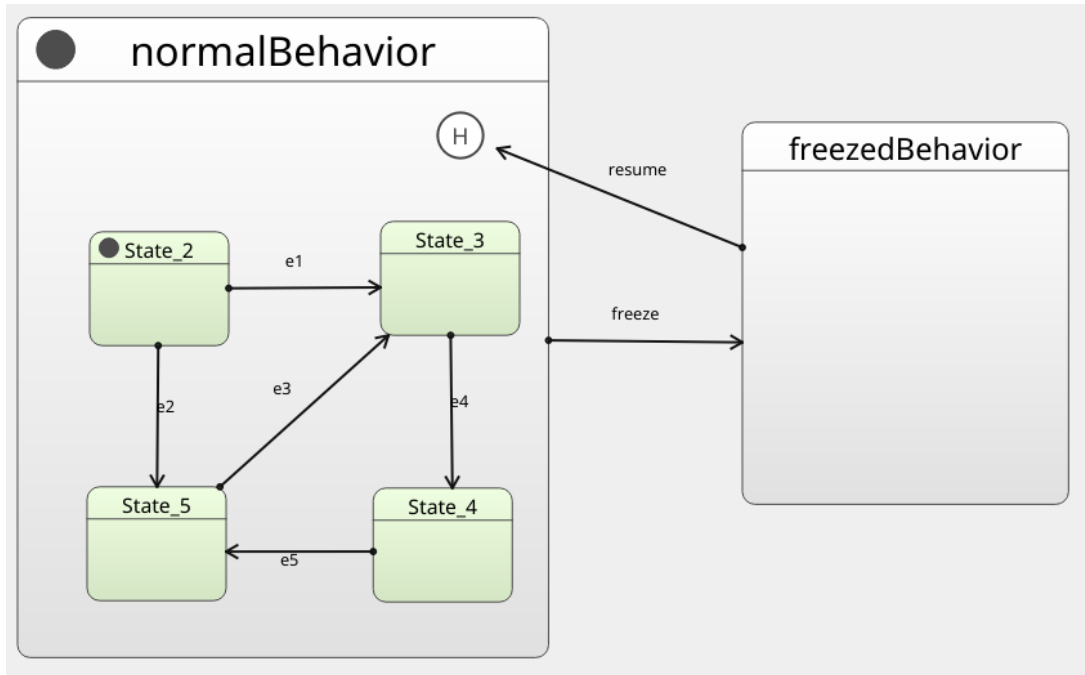


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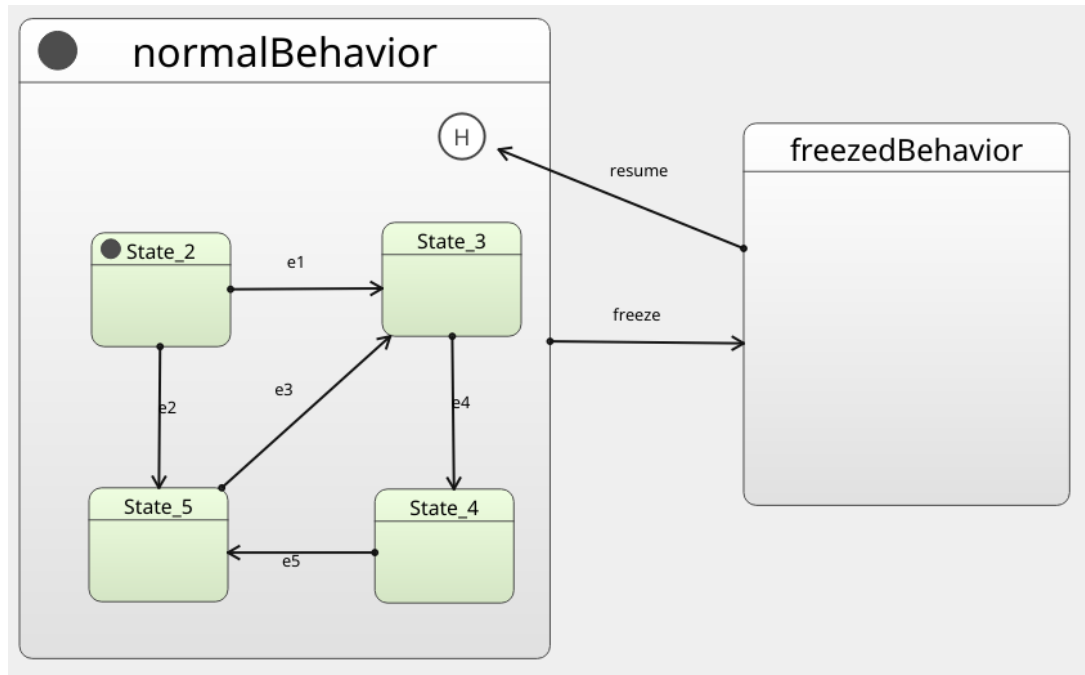
History state



Deep or shallow...

- <history> allows for pause and resume semantics in compound states. Before the state machine exits a compound state, it records the state's active descendants. If the 'type' attribute of the <history> state is set to "deep", the state machine saves the state's full active descendant configuration, down to the atomic descendant(s). If 'type' is set to "shallow", the state machine remembers only which immediate child was active. After that, if a transition takes a <history> child of the state as its target, the state machine re-enters not only the parent compound state but also the state(s) in the saved configuration. Thus a transition with a deep history state as its target returns to exactly where the state was when it was last exited, while a transition with a shallow history state as a target re-enters the previously active child state, but will enter the child's default initial state (if the child is itself compound.).

History state

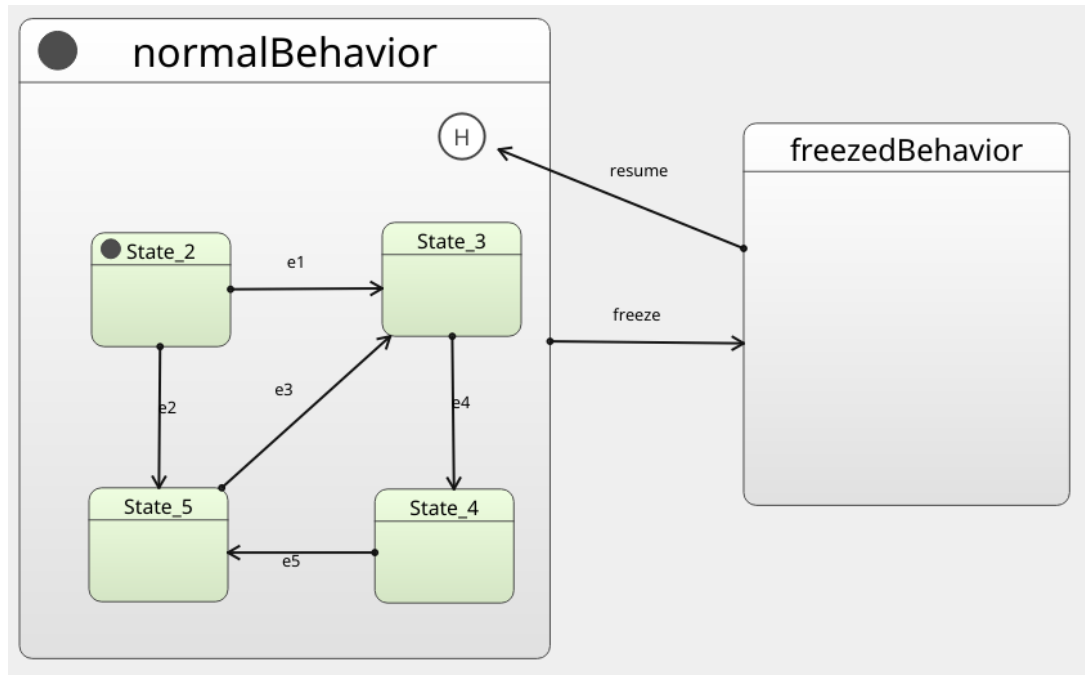


Deep or shallow...

```
h.start();  
this->h.submitEvent("e1");  
this->h.submitEvent("freeze");  
this->h.submitEvent("resume");
```

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History state



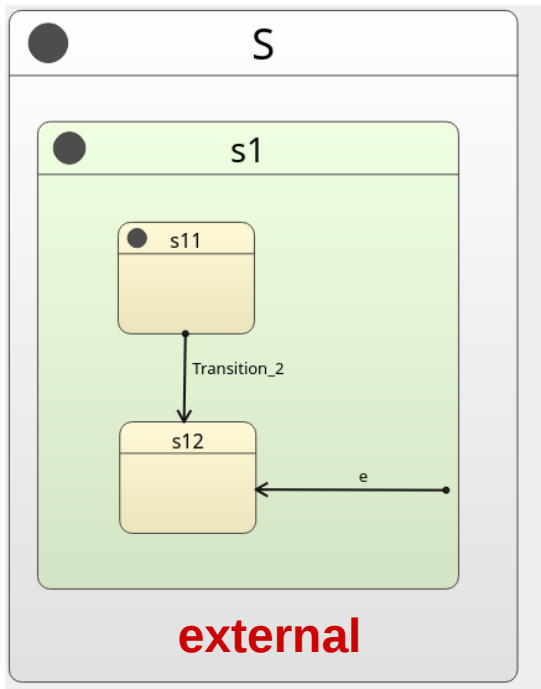
```
h.start();  
this->h.submitEvent("e1");  
this->h.submitEvent("freeze");  
this->h.submitEvent("resume");
```

```
scxml.statemachine: " " : "enter normalBehavior"  
scxml.statemachine: "" : "enter State_2"  
scxml.statemachine: "" : "enter State_3"  
scxml.statemachine: "" : "enter FreezedBehavior"  
scxml.statemachine: "" : "enter State_3"
```

partial trace...

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Type d'une transition



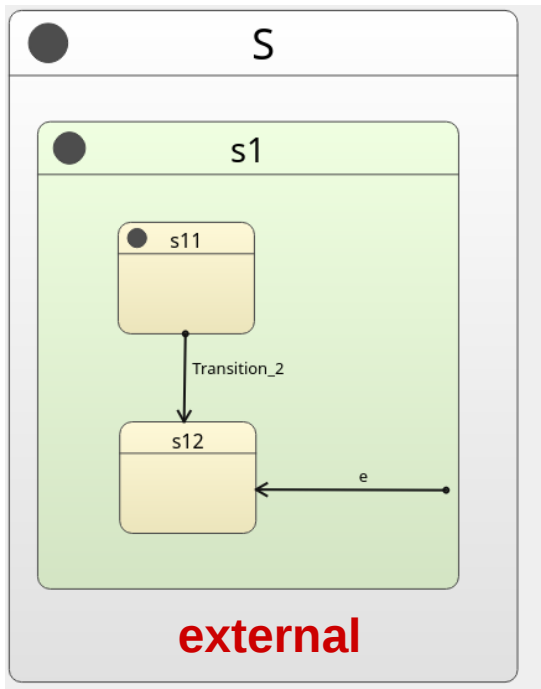
```
int_ext.start();
this->int_ext.submitEvent("e");
```

```
scxml.statemachine: "" : "entering S"
scxml.statemachine: "" : "entering s1"
scxml.statemachine: "" : "entering s11"
```

In the case of a transition located in a compound state, the 'type' attribute is significant. The behavior of a transition with 'type' of "external" (the default) is defined in terms of the transition's source state (which is the state that contains the transition), the transition's target state(or states), and the Least Common Compound Ancestor (LCCA) of the source and target states (which is the closest compound state that is an ancestor of all the source and target states). When a transition is taken, the state machine will exit all active states that are proper descendants of the LCCA, starting with the innermost one(s) and working up to the immediate descendant(s) of the LCCA. (A 'proper descendant' of a state is a child, or a child of a child, or a child of a child of a child, etc.) Then the state machine enters the target state(s), plus any states that are between it and the LCCA, starting with the outermost one (i.e., the immediate descendant of the LCCA) and working down to the target state(s). As states are exited, their <onexit> handlers are executed. Then the executable content in the transition is executed, followed by the <onentry> handlers of the states that are entered. If the target state(s) of the transition is not atomic, the state machine will enter their default initial states recursively until it reaches an atomic state(s).

The behavior of transitions with 'type' of "internal" is identical, except in the case of a transition whose source state is a compound state and whose target(s) is a descendant of the source. In such a case, an internal transition will not exit and re-enter its source state, while an external one will, [...]

Type d'une transition



```
int_ext.start();
this->int_ext.submitEvent("e");
```

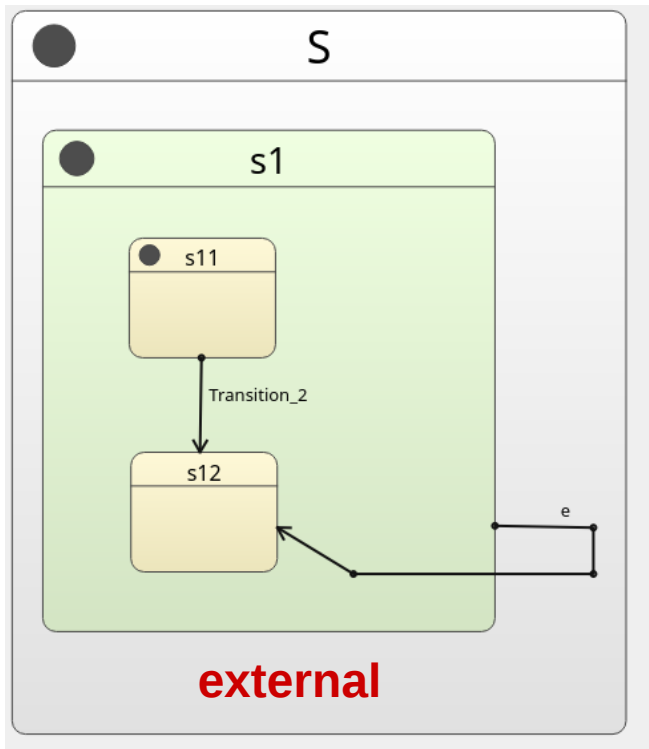
```
scxml.statemachine: "" : "entering S"
scxml.statemachine: "" : "entering s1"
scxml.statemachine: "" : "entering s11"
```

```
scxml.statemachine: "" : "leaving s11"
scxml.statemachine: "" : "leaving s1"
scxml.statemachine: "" : "executing transition"
scxml.statemachine: "" : "entering s1"
scxml.statemachine: "" : "entering s12"
```

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The behavior of transitions with 'type' of "internal" is identical, except in the case of a transition whose source state is a compound state and whose target(s) is a descendant of the source. In such a case, an internal transition will not exit and re-enter its source state, while an external one will, [...]

Type d'une transition



```
int_ext.start();
this->int_ext.submitEvent("e");
```

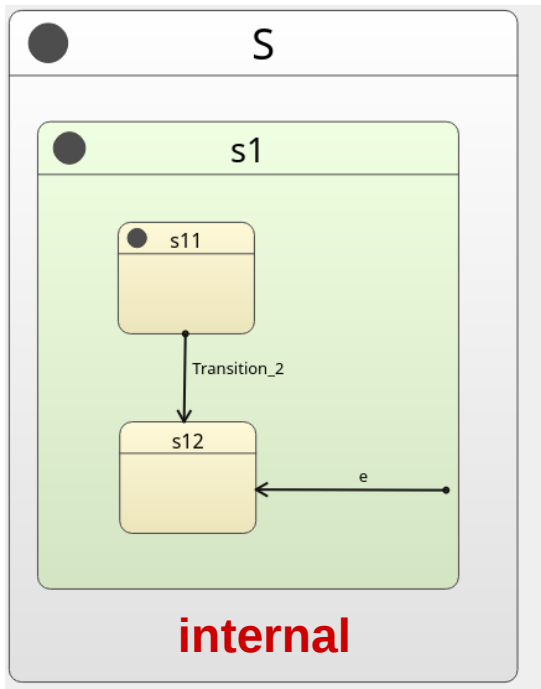
```
scxml.statemachine: "" : "entering S"
scxml.statemachine: "" : "entering s1"
scxml.statemachine: "" : "entering s11"
```

```
scxml.statemachine: "" : "leaving s11"
scxml.statemachine: "" : "leaving s1"
scxml.statemachine: "" : "executing transition"
scxml.statemachine: "" : "entering s1"
scxml.statemachine: "" : "entering s12"
```

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Type d'une transition



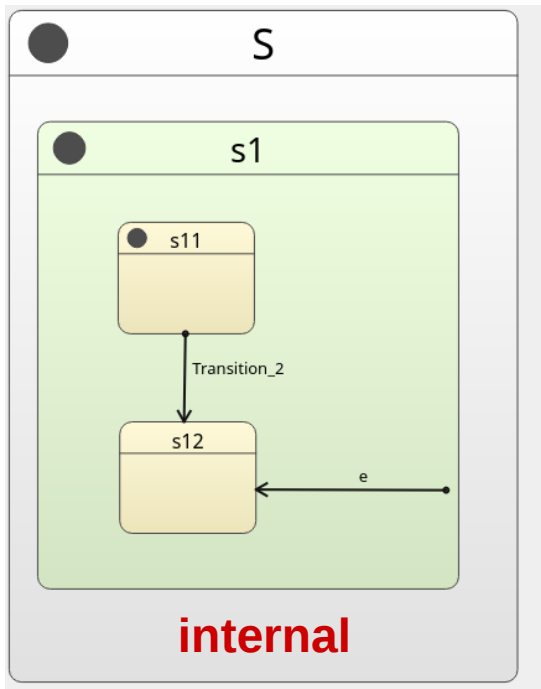
```
int_ext.start();
this->int_ext.submitEvent("e");
```

```
scxml.statemachine: "" : "entering S"
scxml.statemachine: "" : "entering s1"
scxml.statemachine: "" : "entering s11"
```

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Type d'une transition



```
int_ext.start();
this->int_ext.submitEvent("e");
```

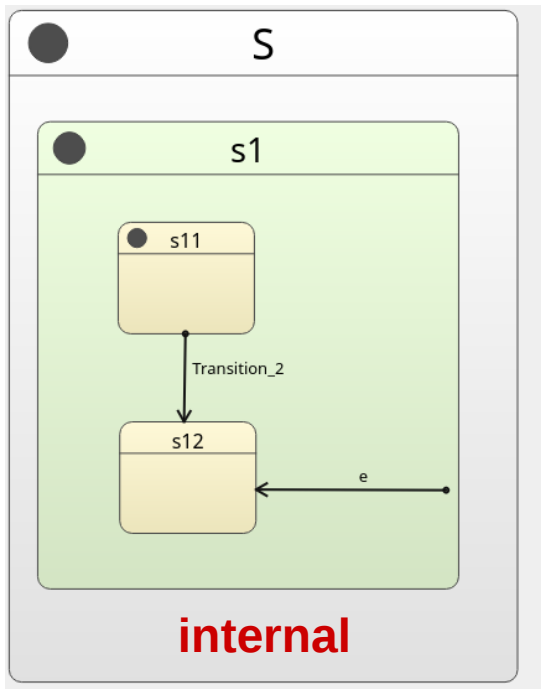
```
scxml.statemachine: "" : "entering S"
scxml.statemachine: "" : "entering s1"
scxml.statemachine: "" : "entering s11"
```

```
scxml.statemachine: "" : "leaving s11"
scxml.statemachine: "" : "executing transition"
scxml.statemachine: "" : "entering s12"
```

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Type d'une transition

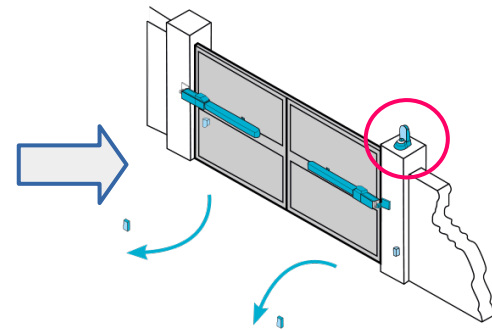
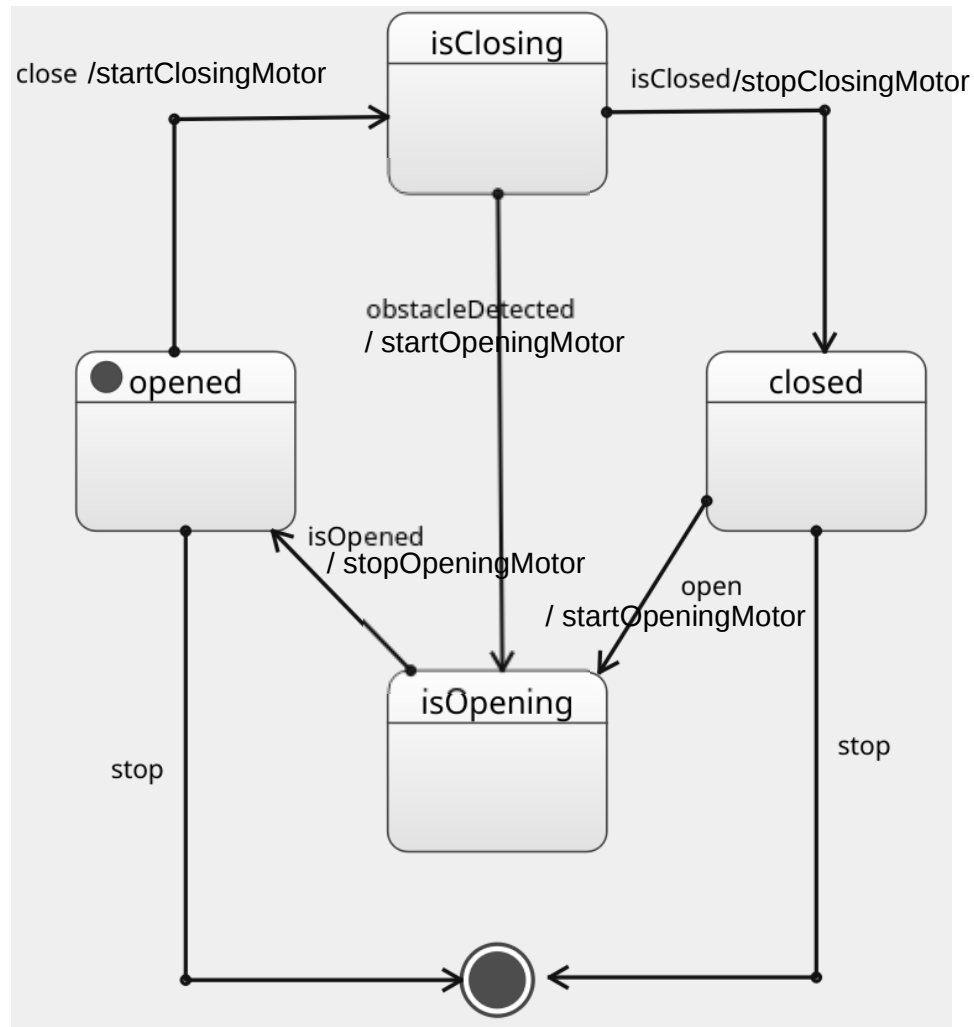


Such concept does not exist in Yakindu, even in the SCXML domain :'(

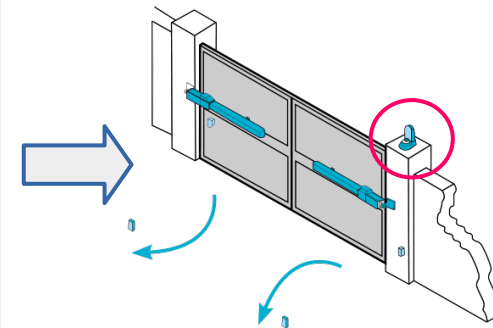
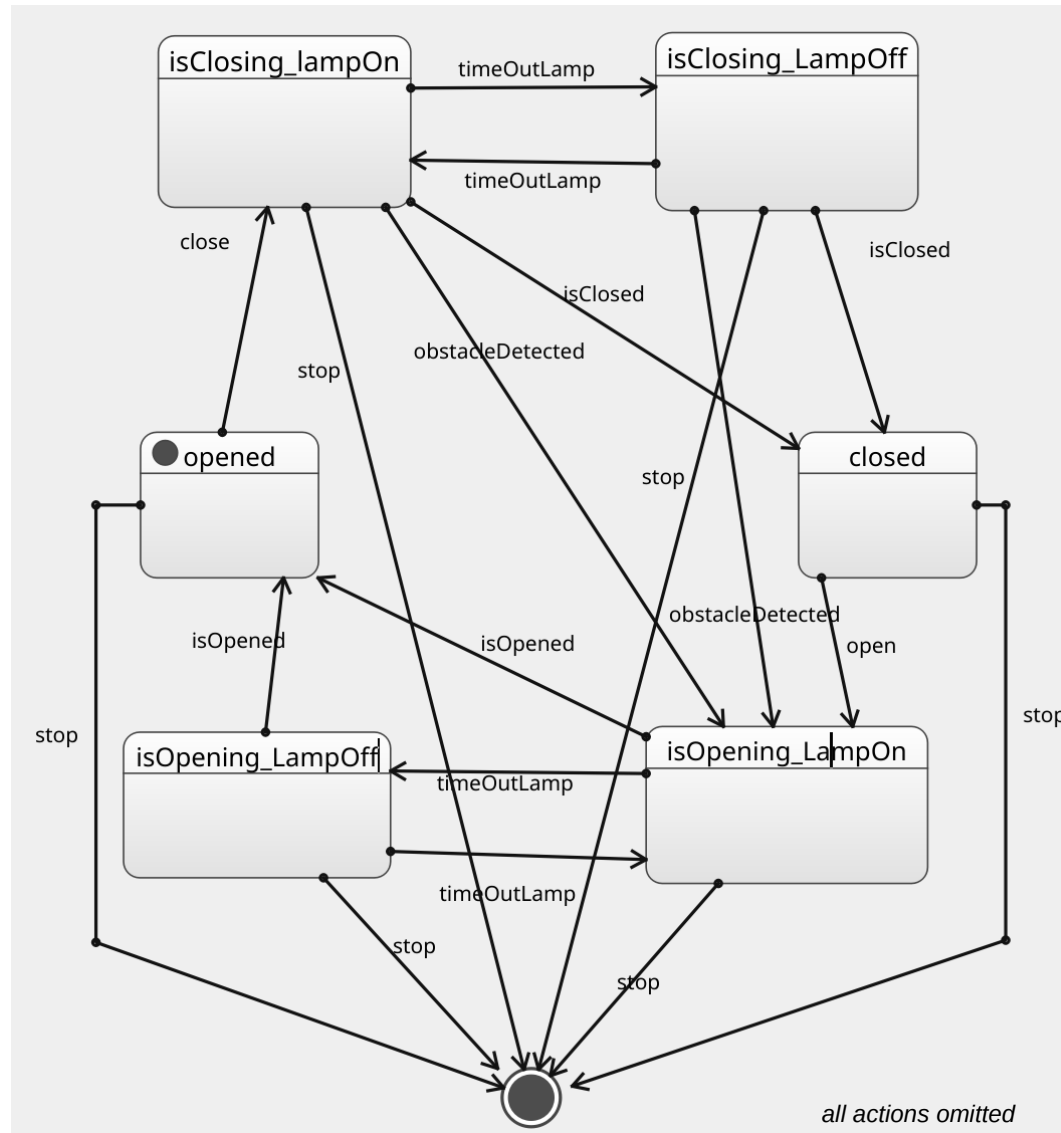
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Running Example

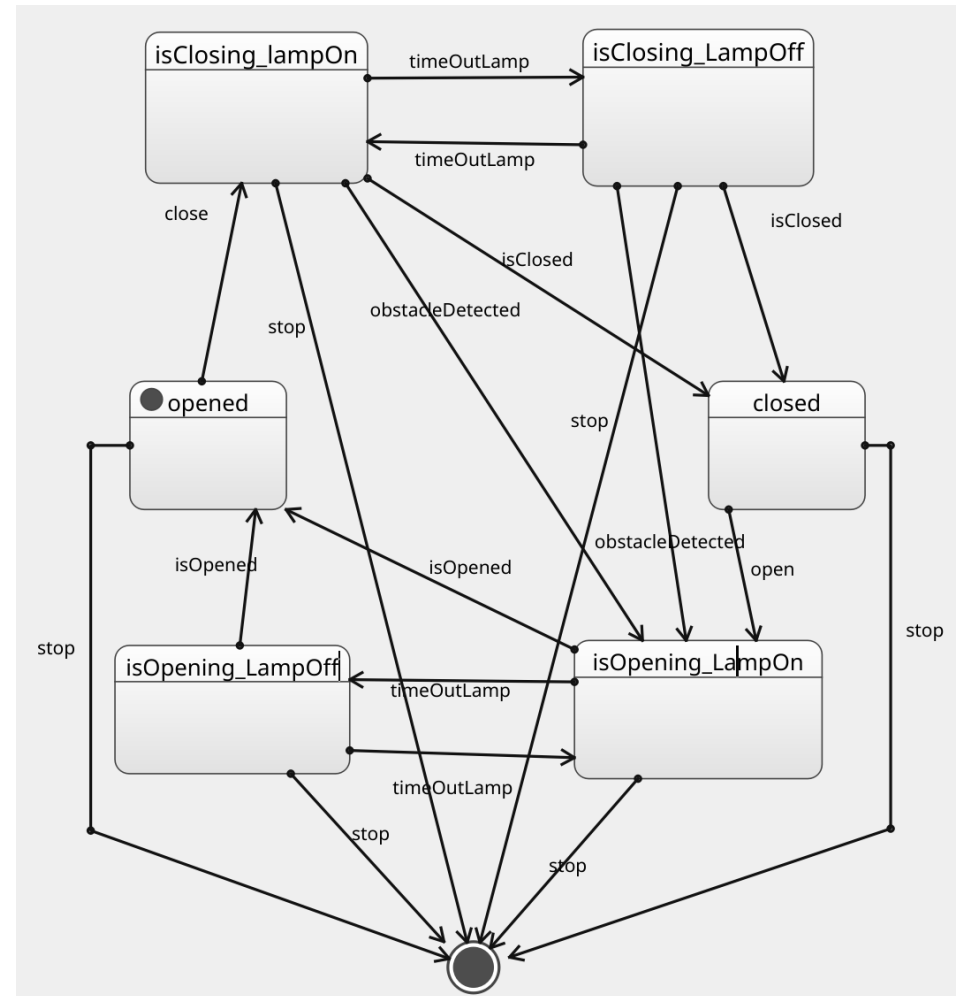
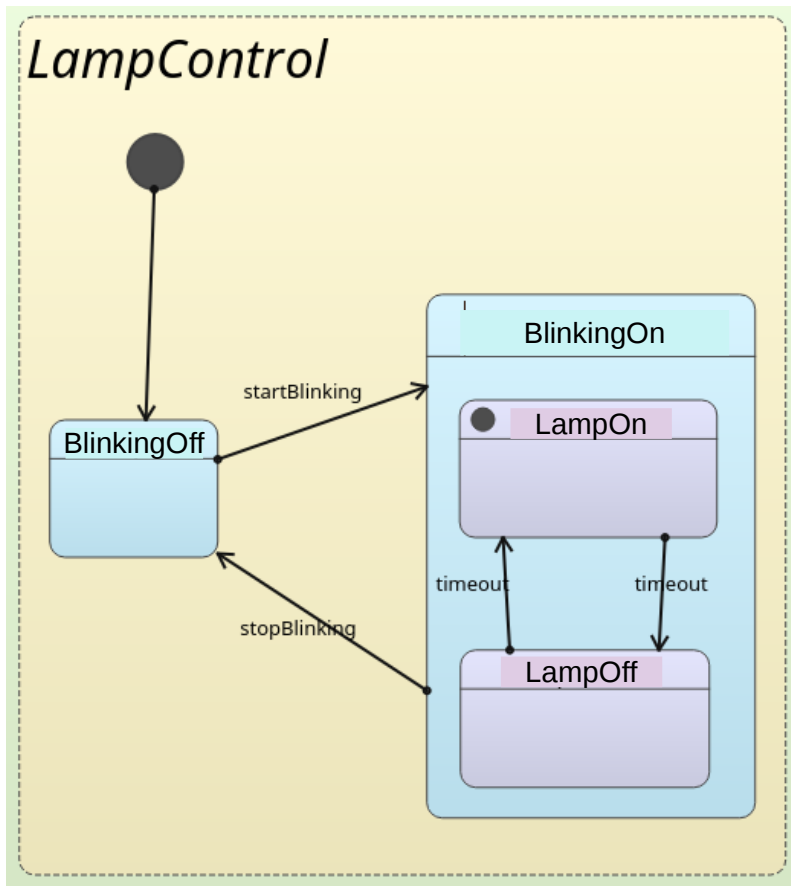


Running Example



wasn't it supposed to help ?

Composite State



- A simple state is one which has no substructure.
- A state which has substates (nested states) is called a composite state (or compound state).
- Substates may be nested to any level. A nested state machine may have at most one initial state and one final state.
- **Substates are used to simplify complex flat state machines by showing that some states are only possible within a particular context (the enclosing state).**
- **A composite state factorizes the possible exits from all (most of) the states**