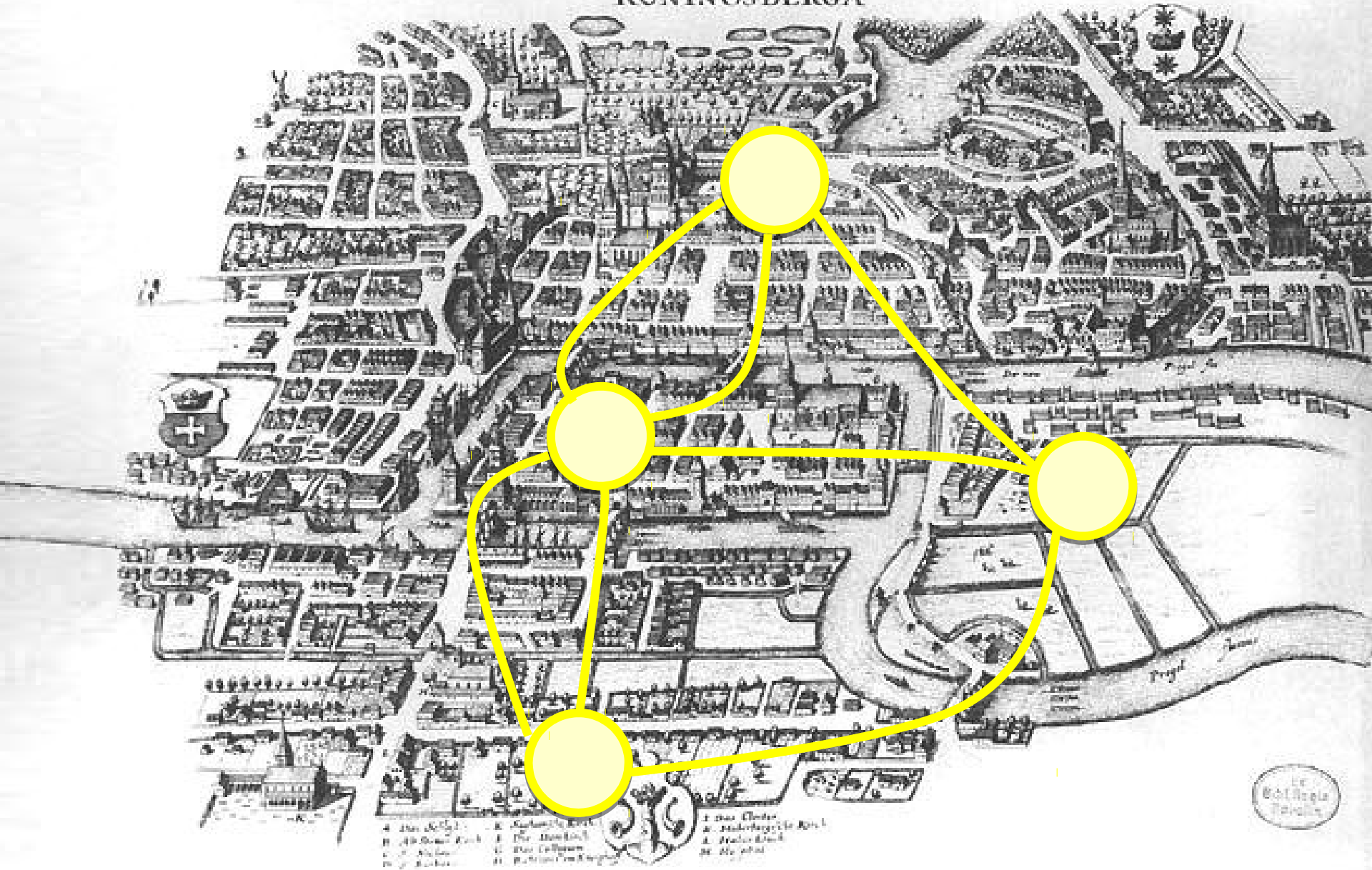


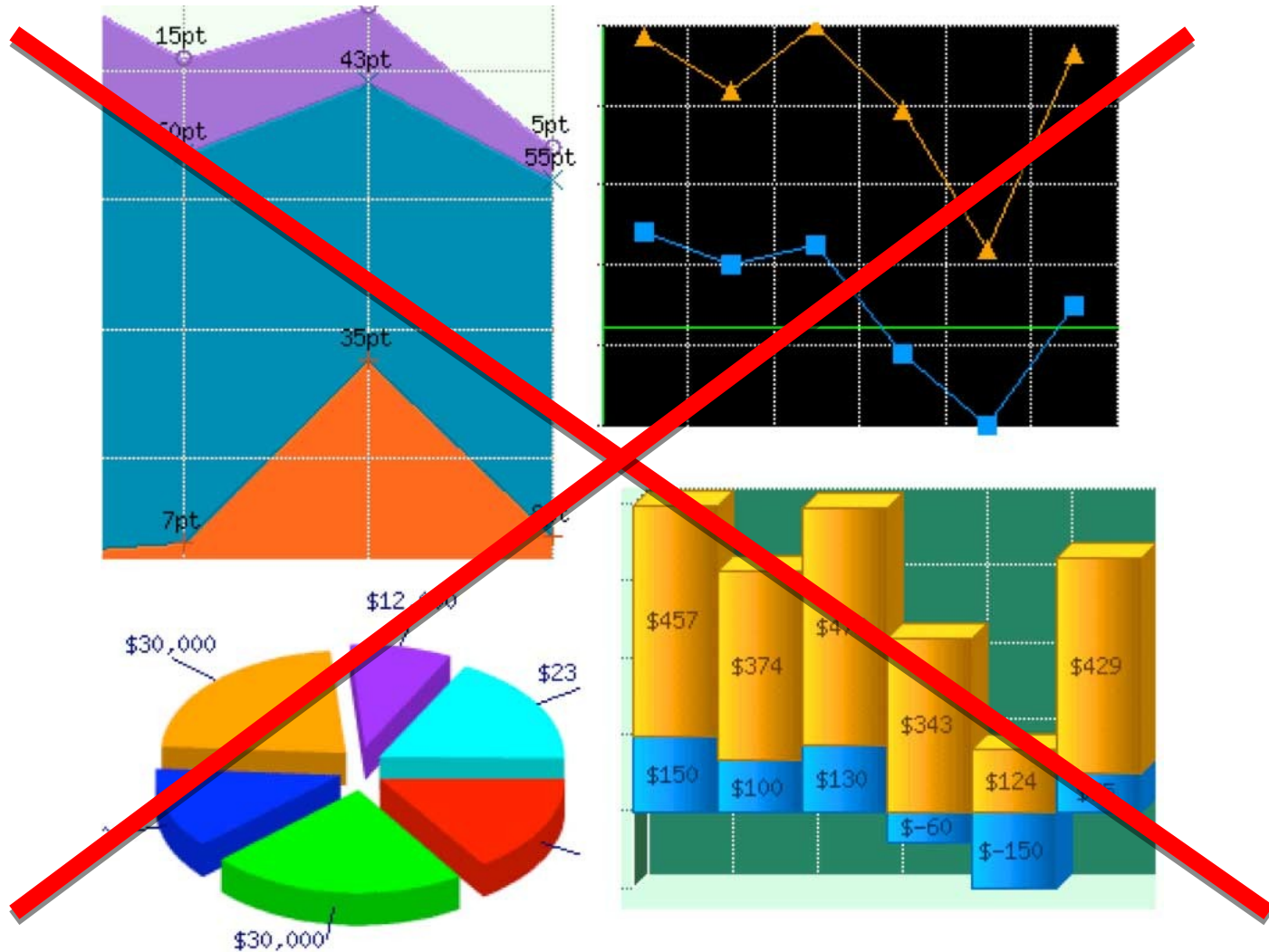
KONINGSBERGA



GRAPH

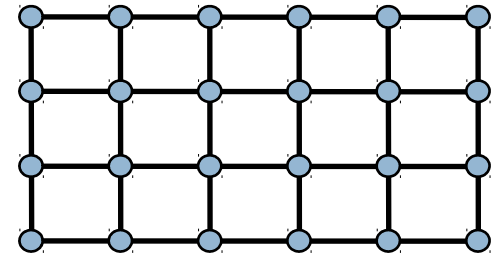
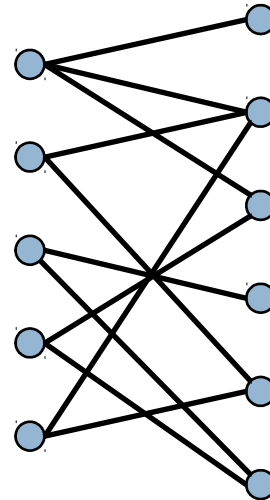
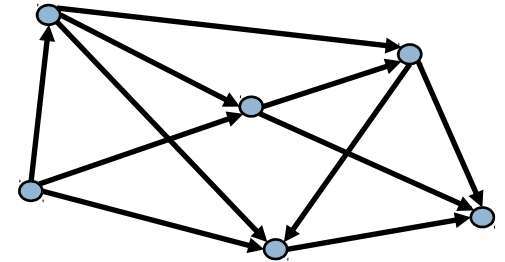
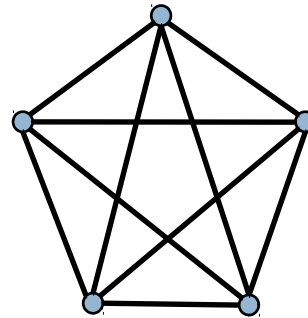
Lecture 16
CS2110 Fall 2017

These aren't the graphs we're looking for

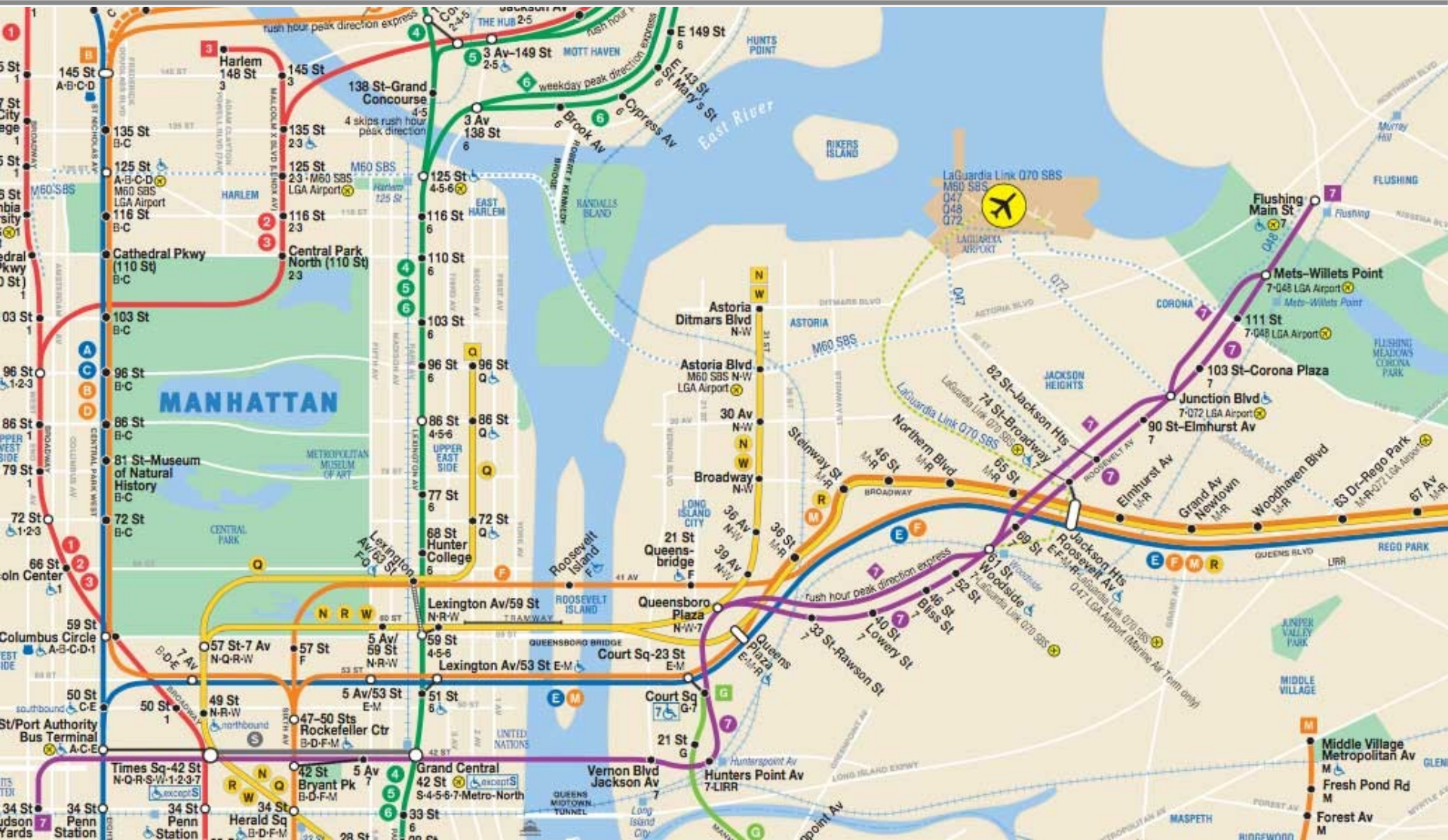


Graphs

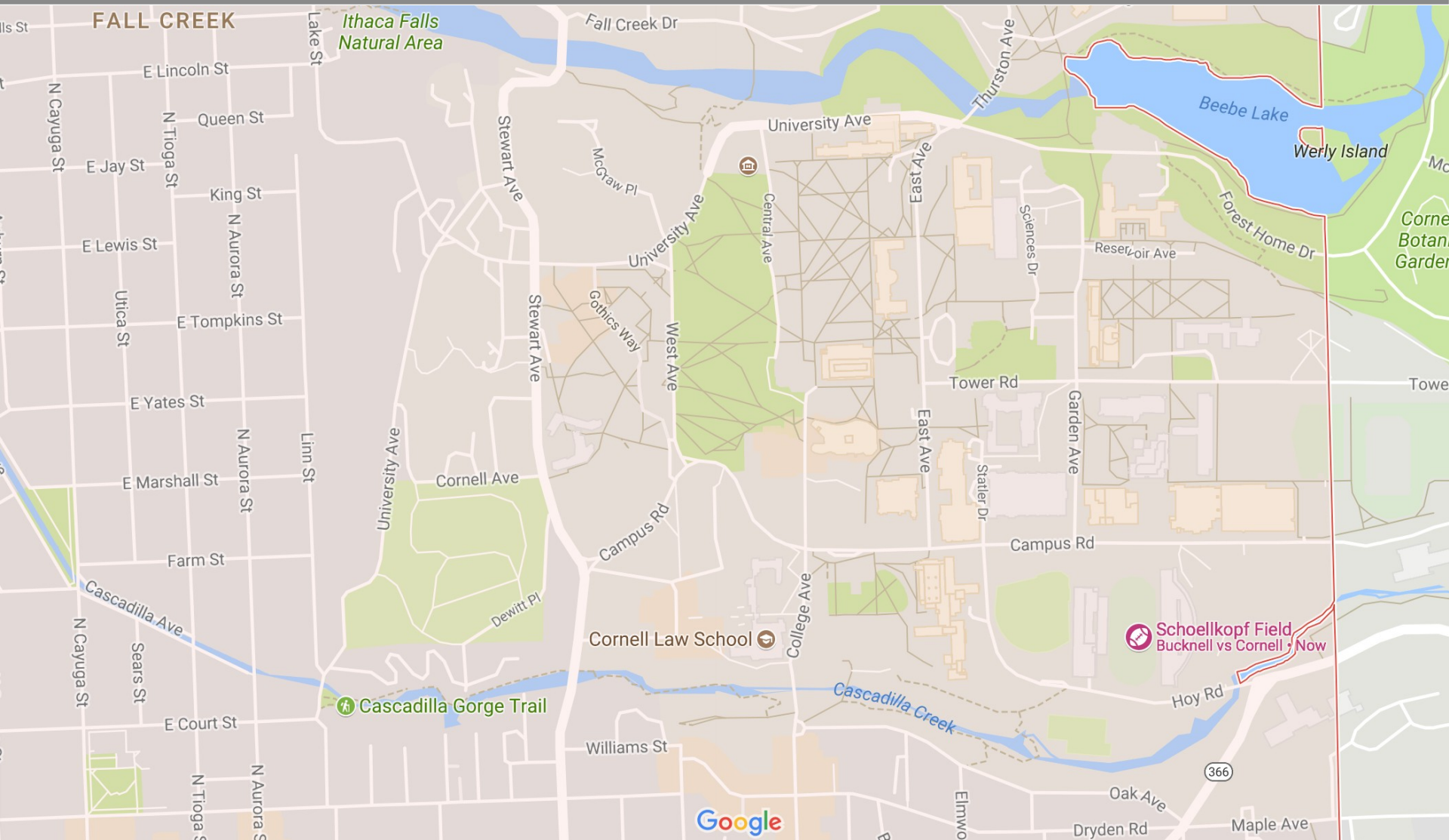
- A graph is a data structure
- A graph has
 - a set of vertices
 - a set of edges between vertices
- Graphs are a generalization of trees



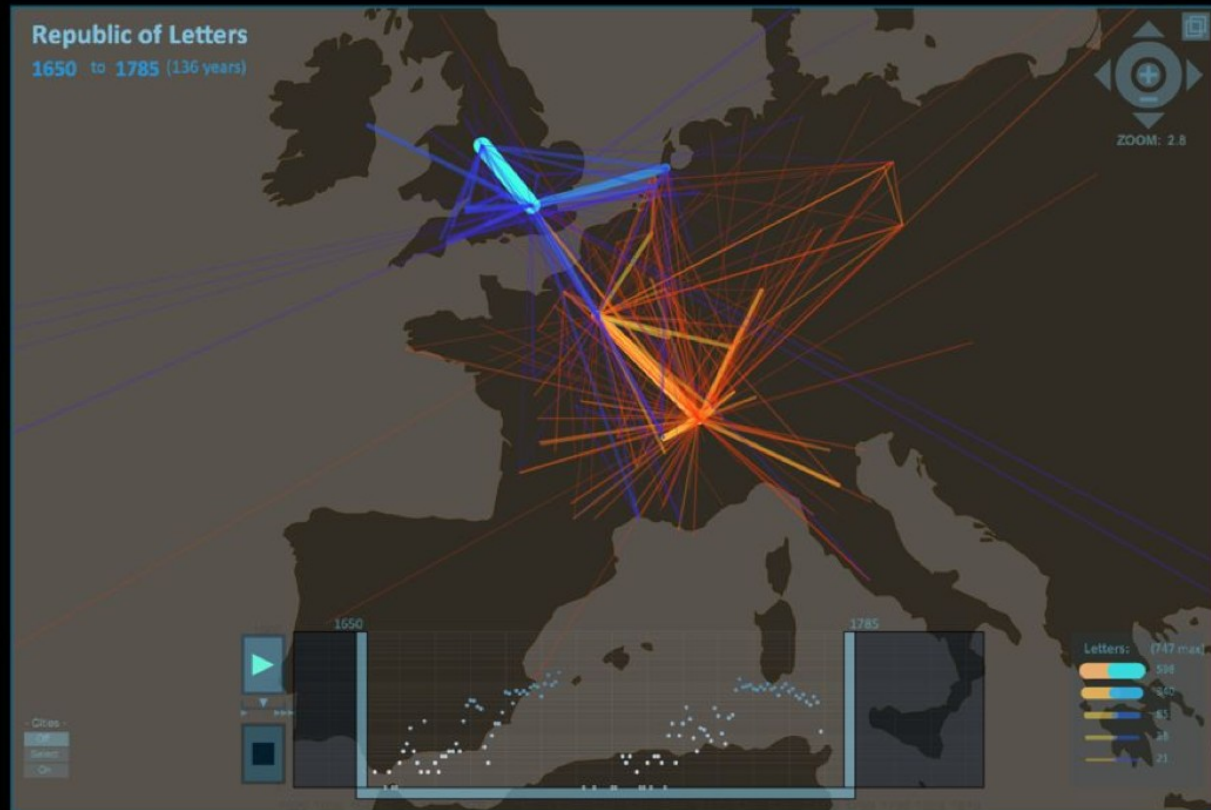
This is a graph



Another transport graph

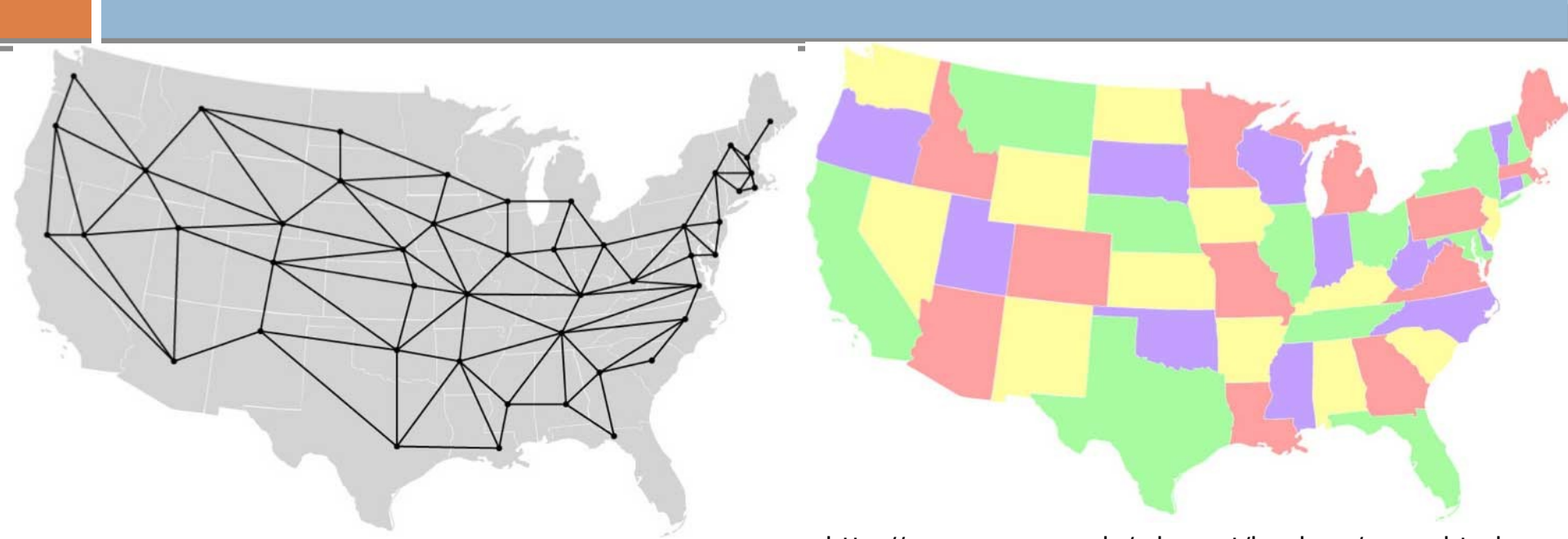


A Social Network Graph



Locke's (blue) and Voltaire's (yellow) correspondence.
Only letters for which complete location information is available are shown.
Data courtesy the Electronic Enlightenment Project, University of Oxford.

Viewing the map of states as a graph

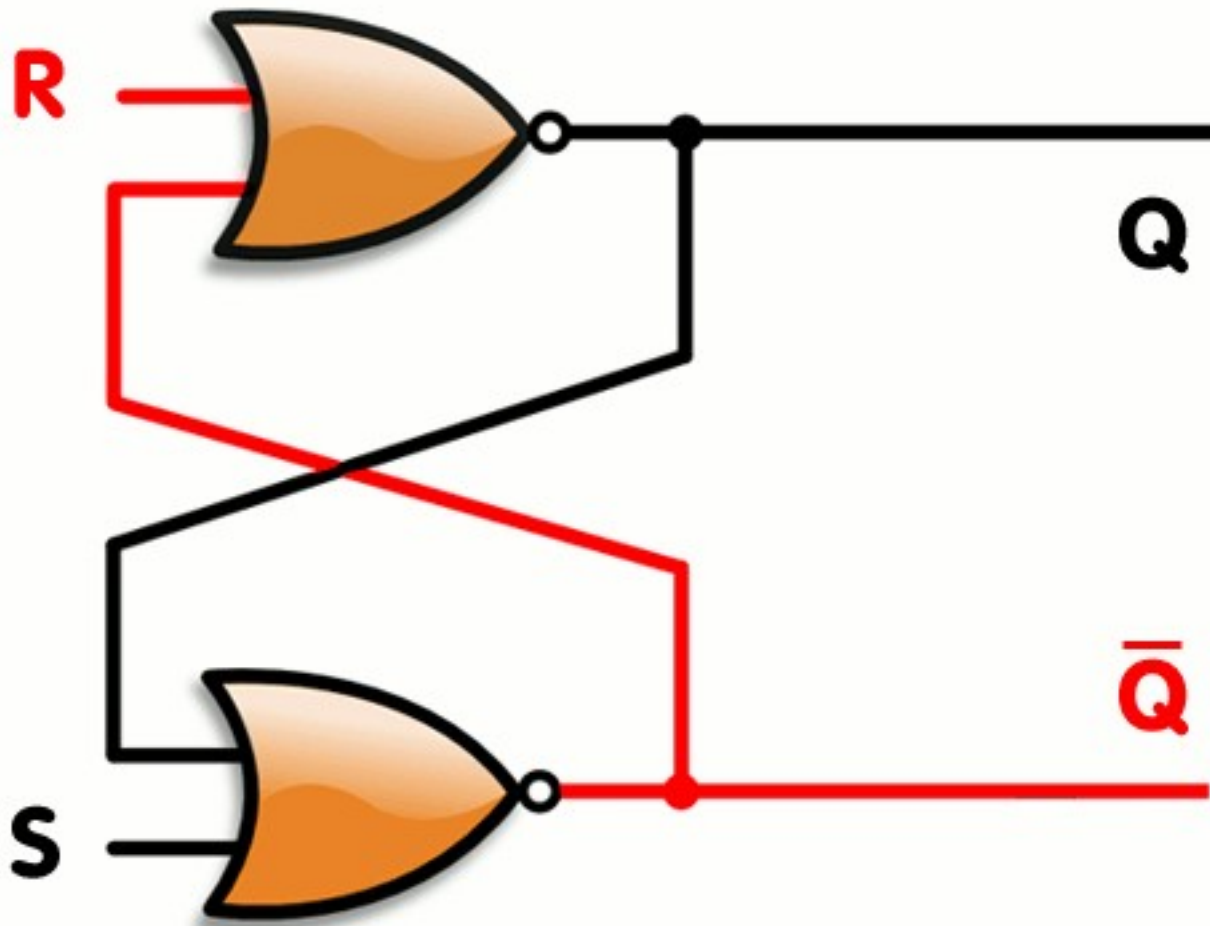


<http://www.cs.cmu.edu/~bryant/boolean/maps.html>

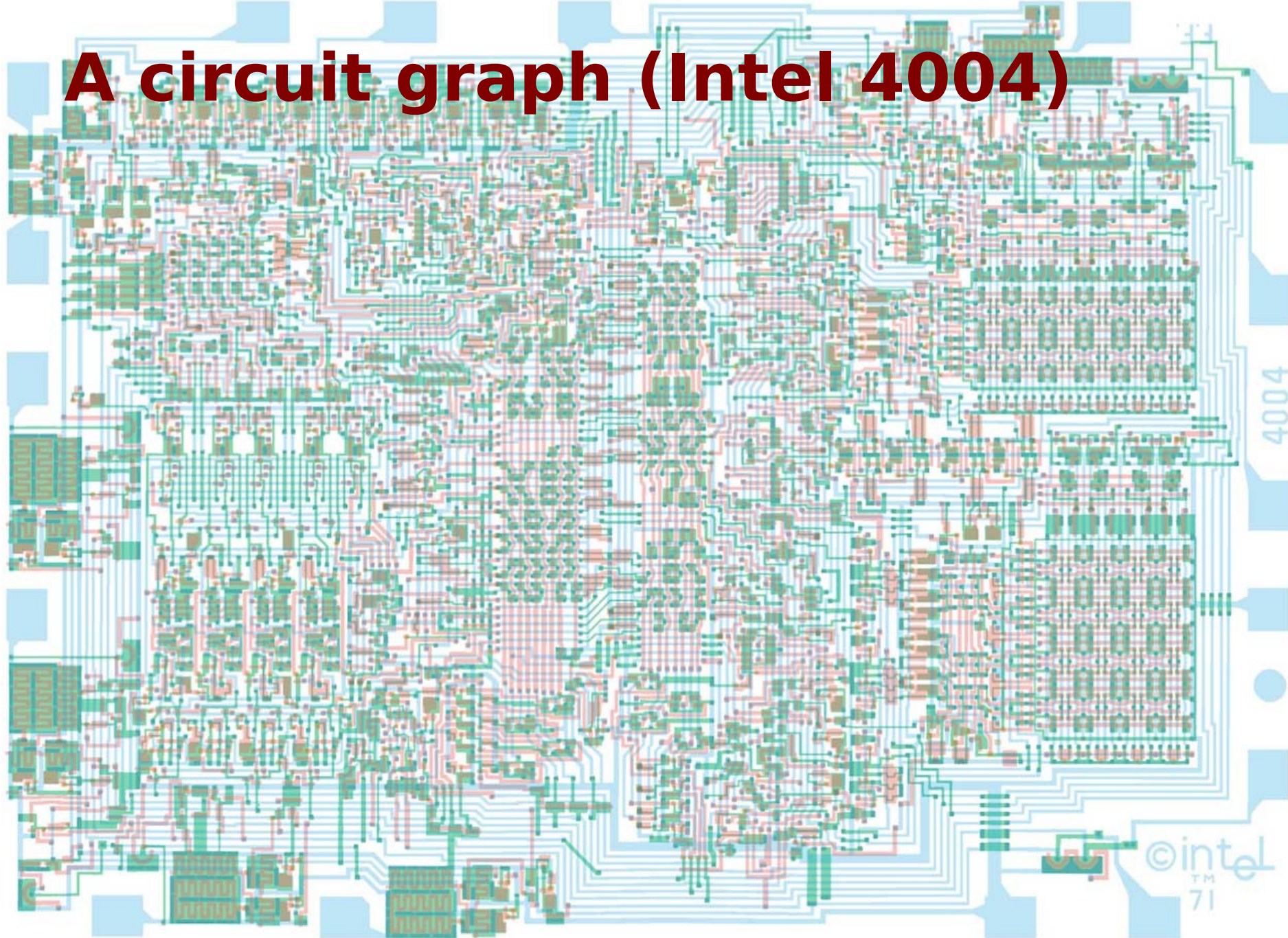
Each state is a point on the graph, and neighboring states are connected by an edge.

Do the same thing for a map of the world showing countries

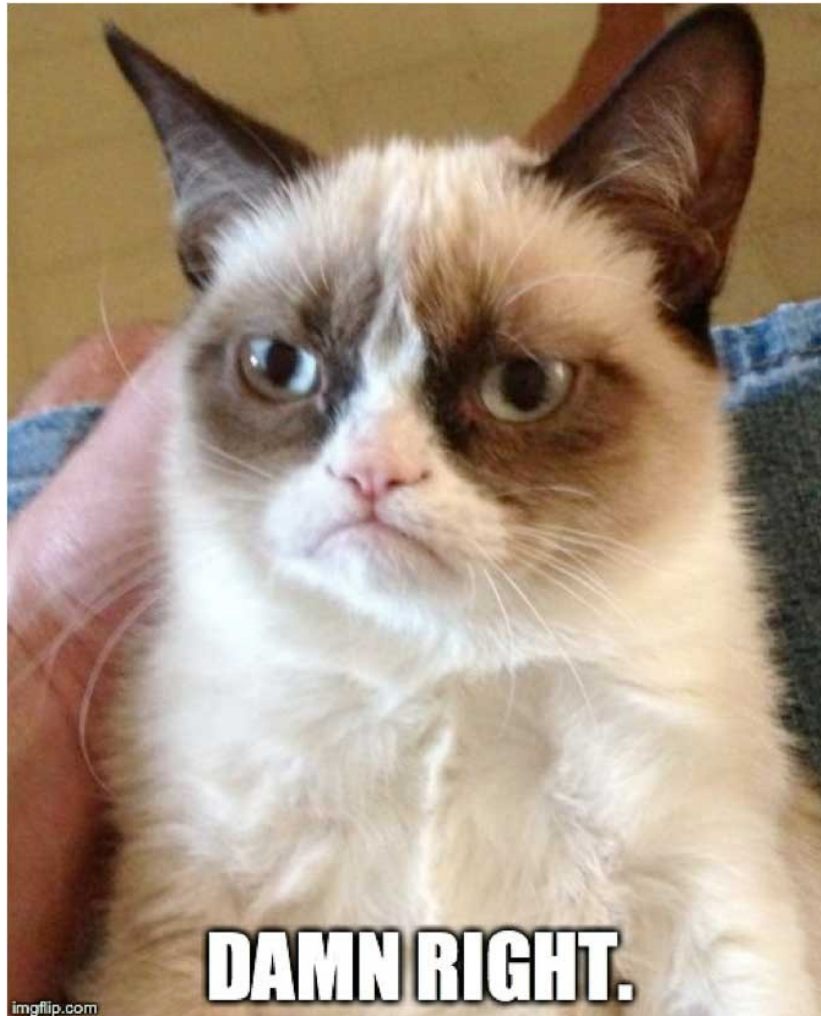
A circuit graph (flip-flop)



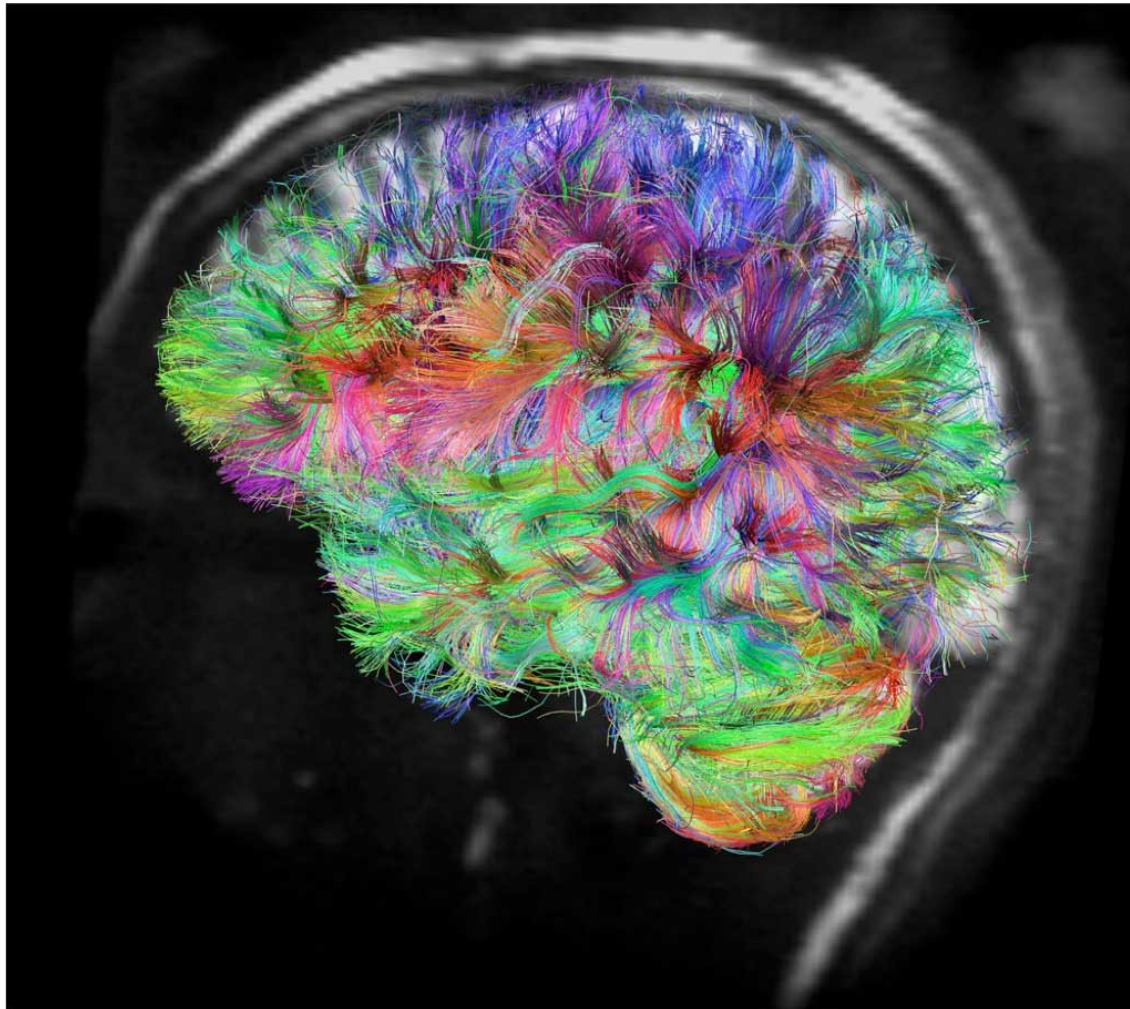
A circuit graph (Intel 4004)



This is not a graph, this is a cat



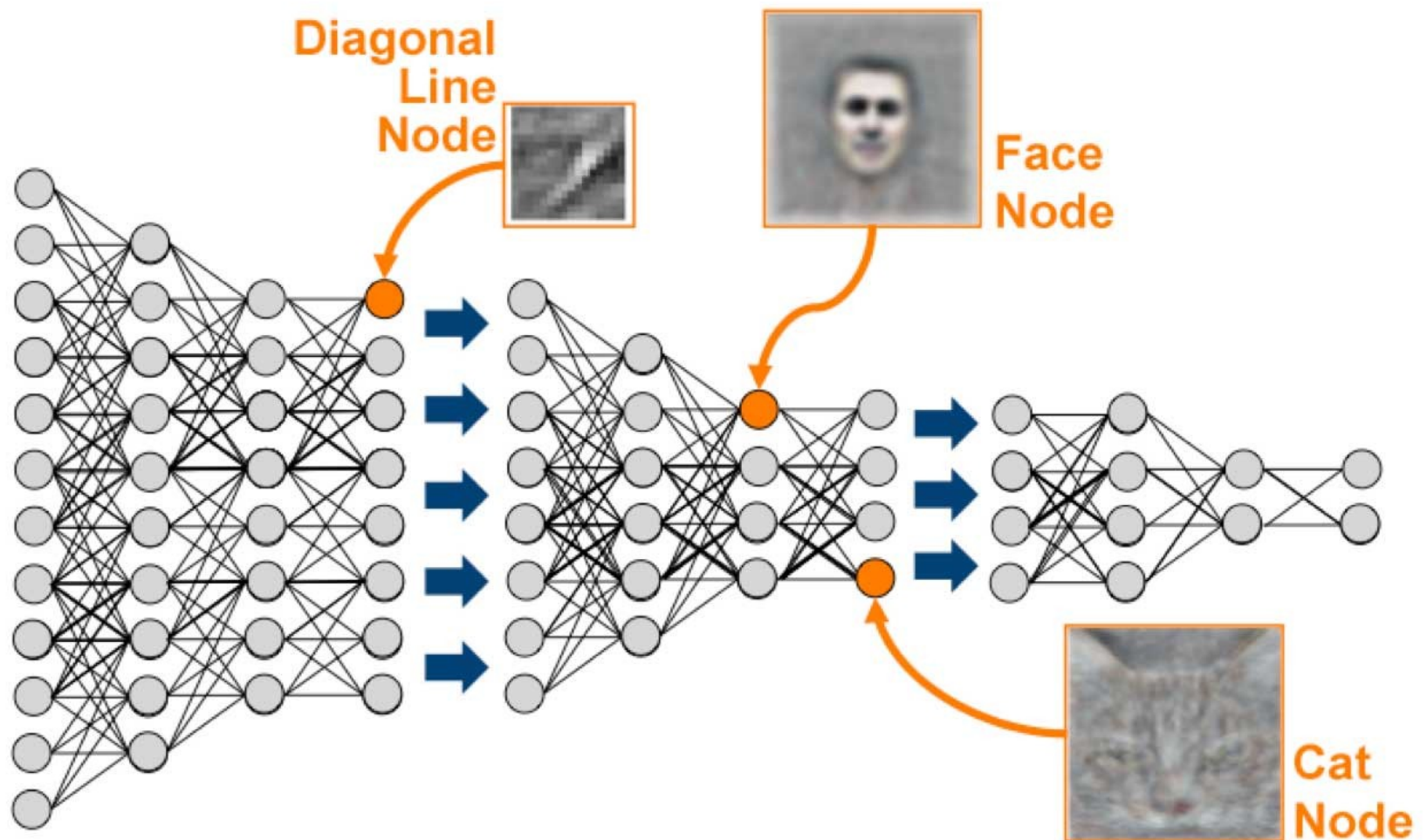
This is a graph



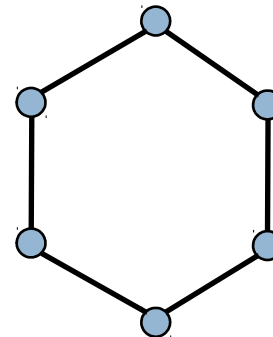
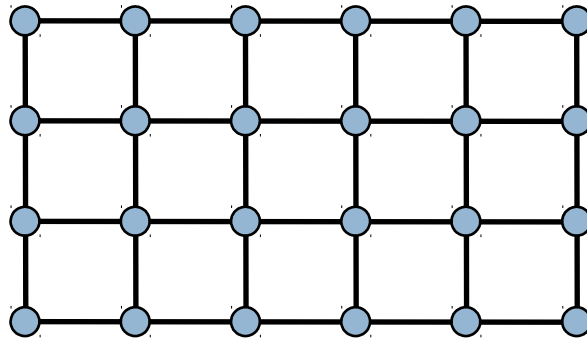
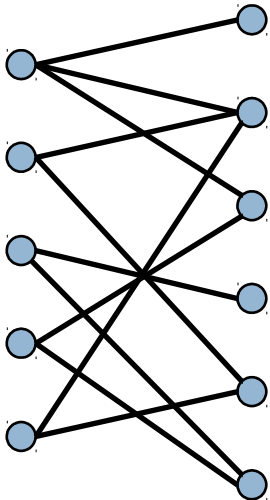
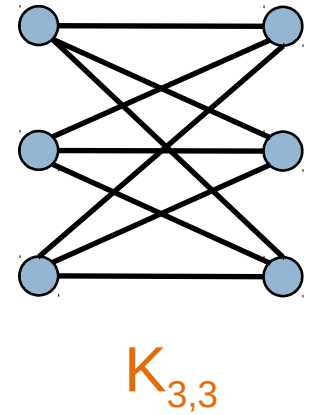
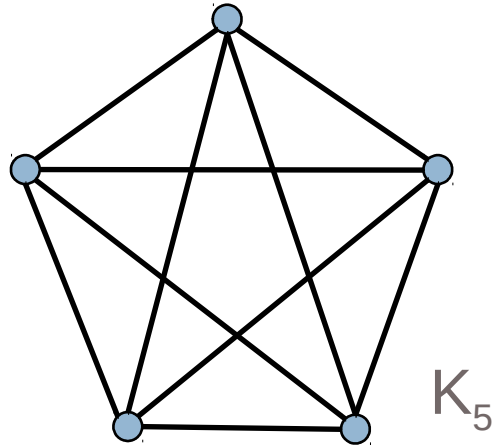
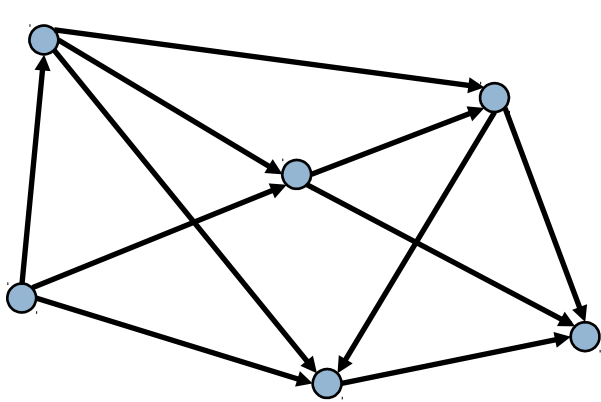
V.J. Wedeen and L.L. Wald, Martinos Center for Biomedical Imaging at

MGH

This is a graph(ical model) that has learned to recognize cats

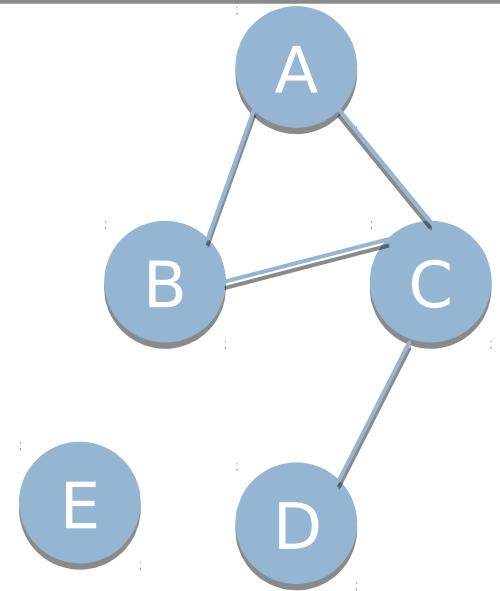


Graphs



Undirect graphs

- A **undirected graph** is a pair (V, E) where
 - V is a (finite) set
 - E is a set of pairs (u, v) where $u, v \in V$
 - Often require $u \neq v$ (i.e. no self-loops)
- Element of V is called a **vertex** or **node**
- Element of E is called an **edge** or **arc**
- $|V|$ = size of V , often denoted by n
- $|E|$ = size of E , often denoted by m



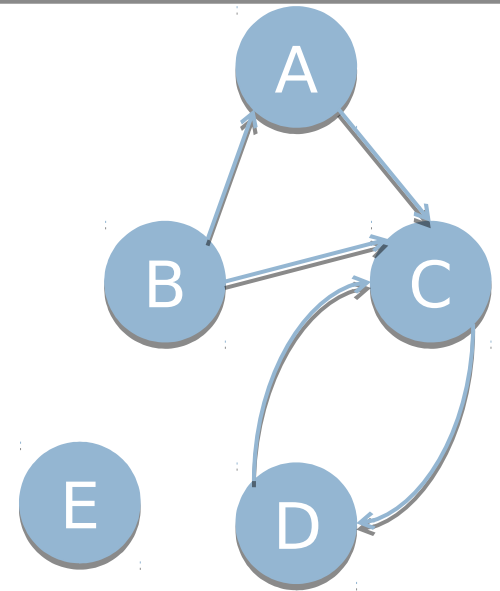
$$V = \{A, B, C, D, E\}$$
$$E = \{(A, B), (A, C), (B, C), (C, D)\}$$

$$|V| = 5$$

$$|E| = 4$$

Directed graphs

- A **directed graph** (**digraph**) is a lot like an undirected graph
 - V is a (finite) set
 - E is a set of **ordered** pairs (u, v) where $u, v \in V$
- Every undirected graph can be easily converted to an equivalent directed graph via a simple transformation:
 - Replace every undirected edge with two directed edges in opposite directions
- ... but not vice versa



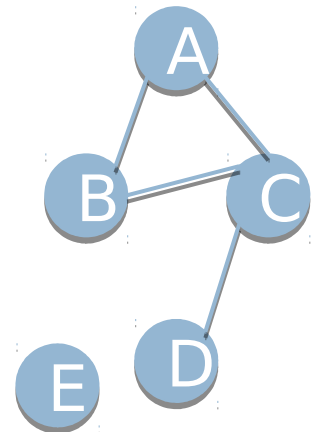
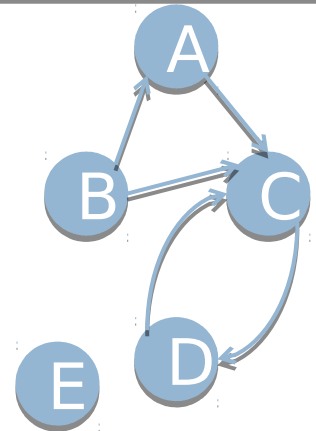
$$\begin{aligned} V &= \{A, B, C, D, E\} \\ E &= \{(A, C), (B, A), \\ &\quad (B, C), (C, D), \\ &\quad (D, C)\} \end{aligned}$$

$$|V| = 5$$

$$|E| = 5$$

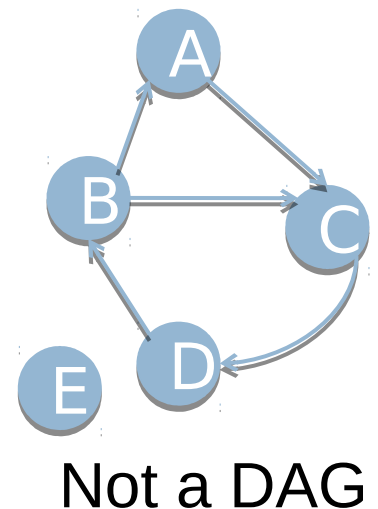
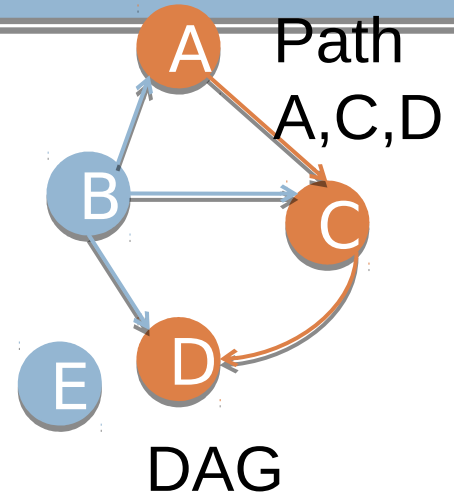
Graph terminology

- Vertices u and v are called
 - the **source** and **sink** of the directed edge (u, v) , respectively
 - the **endpoints** of (u, v) or $\{u, v\}$
- Two vertices are **adjacent** if they are connected by an edge
- The **outdegree** of a vertex u in a directed graph is the number of edges for which u is the source
- The **indegree** of a vertex v in a directed graph is the number of edges for which v is the sink
- The **degree** of a vertex u in an undirected graph is the number of edges of which u is an endpoint

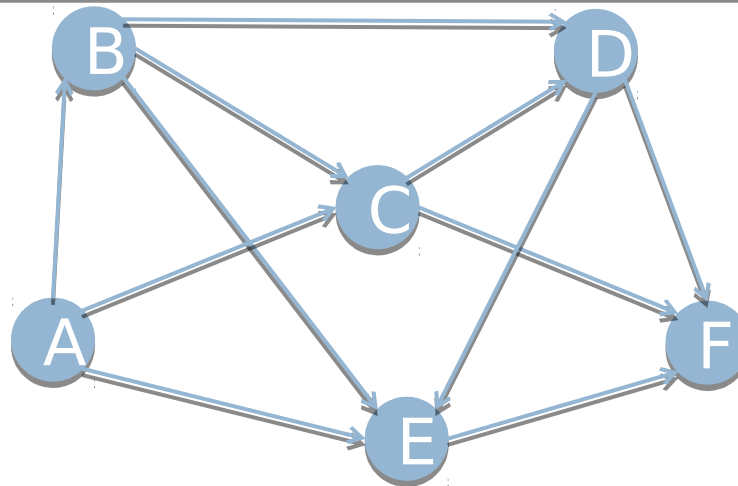


More graph terminology

- A **path** is a sequence $v_0, v_1, v_2, \dots, v_p$ of vertices such that for $0 \leq i < p$,
 - $(v_i, v_{i+1}) \in E$ if the graph is directed
 - $\{v_i, v_{i+1}\} \in E$ if the graph is undirected
- The **length of a path** is its number of edges
- A path is **simple** if it doesn't repeat any vertices
- A **cycle** is a path $v_0, v_1, v_2, \dots, v_p$ such that $v_0 = v_p$
- A cycle is **simple** if it does not repeat any vertices except the first and last
- A graph is **acyclic** if it has no cycles
- A **directed acyclic graph** is called a **DAG**



Is this a DAG?



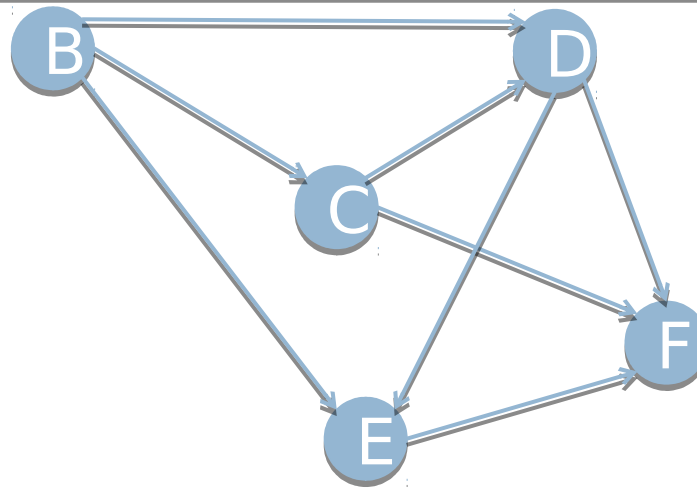
□ Intuition:

- If it's a DAG, there must be a vertex with indegree zero

□ This idea leads to an *algorithm*

- A digraph is a DAG if and only if we can iteratively delete indegree-0 vertices until the graph disappears

Is this a DAG?



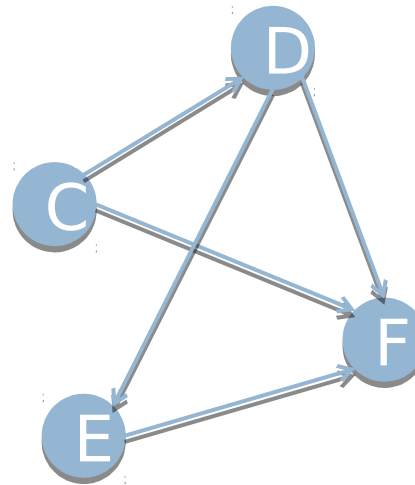
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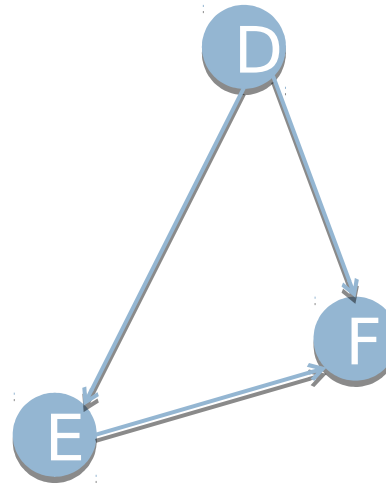
□ Intuition:

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Is this a DAG?



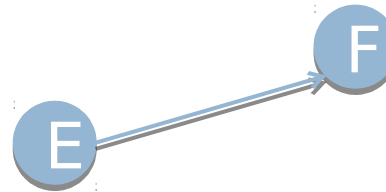
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Is this a DAG?



□ Intuition:

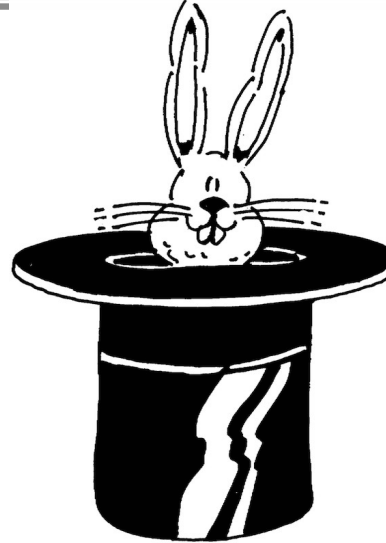
- If it's a DAG, there must be a vertex with indegree zero

□ This idea leads to an *algorithm*

- A digraph is a DAG if and only if we can iteratively delete indegree-0 vertices until the graph disappears

Is this a DAG?

YES!



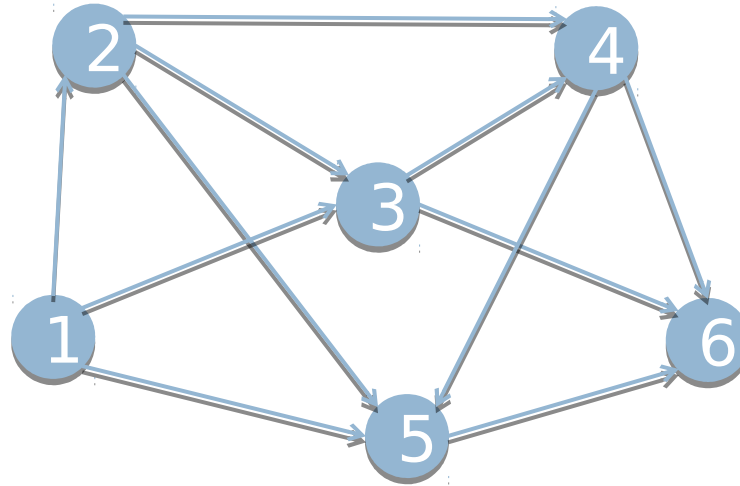
□ Intuition:

- If it's a DAG, there must be a vertex with indegree zero

□ This idea leads to an *algorithm*

- A digraph is a DAG if and only if we can iteratively delete indegree-0 vertices until the graph disappears

Topological sort



- We just computed a **topological sort** of the DAG
 - This is a numbering of the vertices such that all edges go from lower- to higher-numbered vertices
 - Useful in job scheduling with precedence constraints

Topological sort

k = 0;

// inv: k nodes have been given numbers in 1..k in such a way that
if $n_1 \leq n_2$, there is no edge from n_2 to n_1 .

while (there is a node of in-degree 0) {

Let n be a node of in-degree 0;

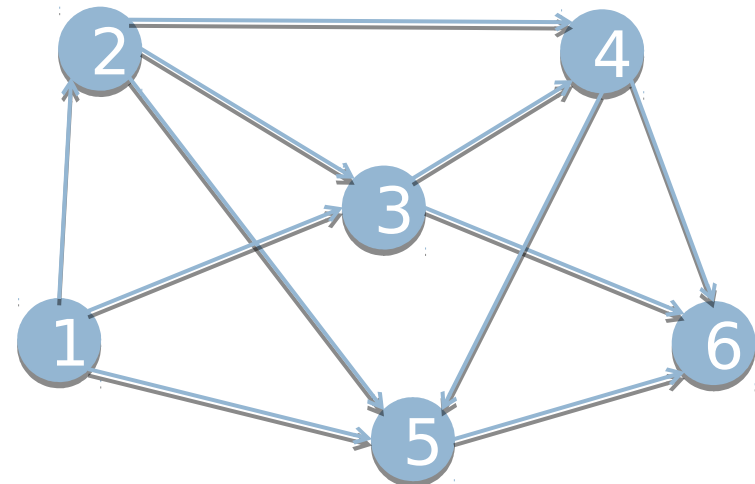
Give it number k;

Delete n and all edges leaving it from the graph.

k = k + 1;

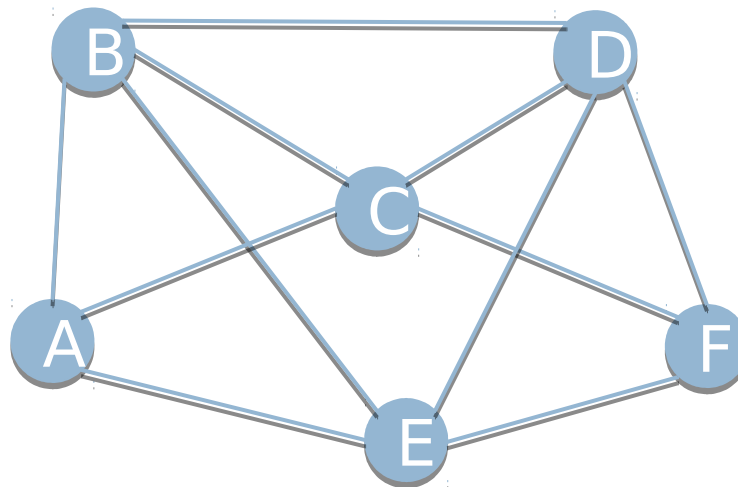
}

1. Abstract algorithm
2. Don't really want to change the graph.
3. Will have to invent data structures to make it efficient.



Graph coloring

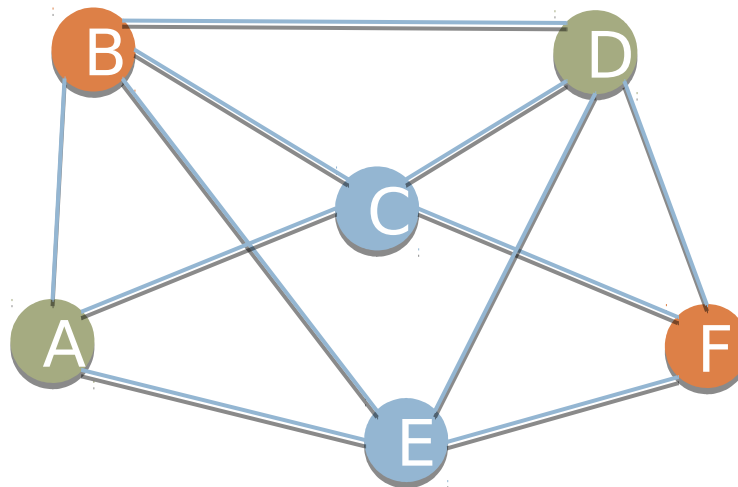
- A **coloring** of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



- How many colors are needed to color this graph?

Graph coloring

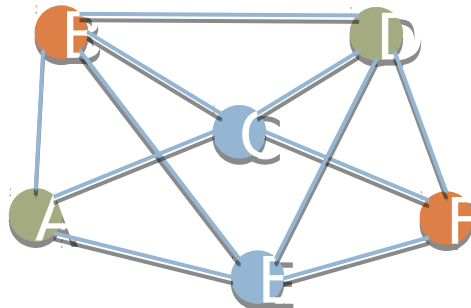
- A **coloring** of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



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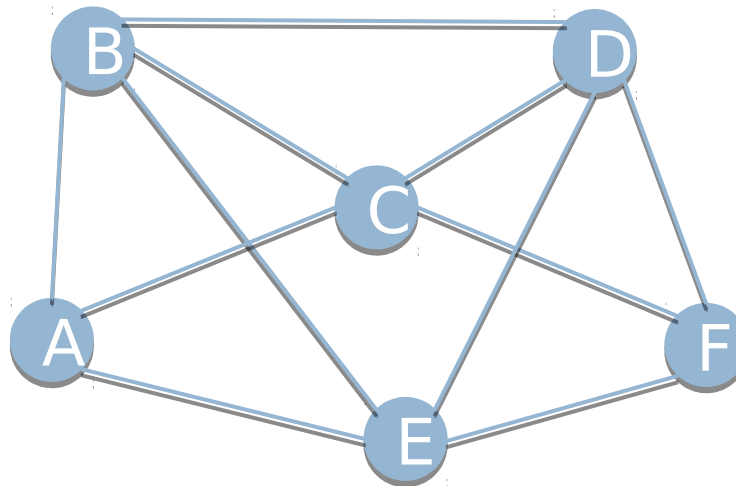
An application of coloring

- **Vertices** are **tasks**
- **Edge** (u, v) is present if tasks u and v each require access to the **same shared resource**, and thus cannot execute simultaneously
- **Colors** are **time slots** to schedule the tasks
- Minimum number of colors needed to color the graph = minimum number of time slots required



Planarity

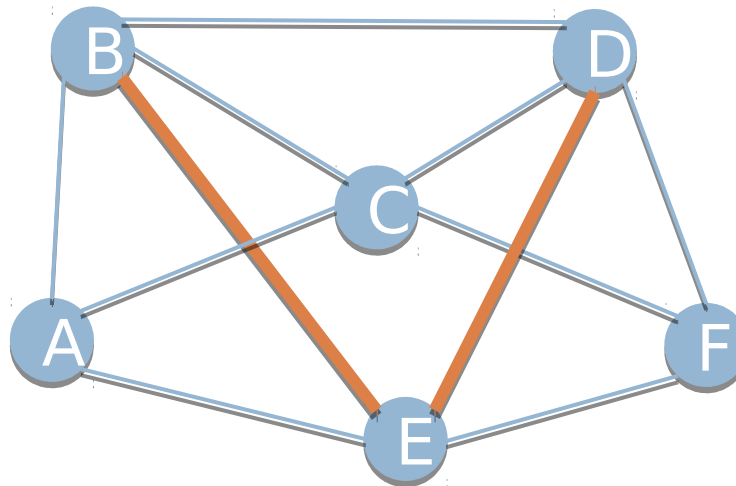
- A graph is planar if it can be drawn in the plane without any edges crossing



- Is this graph planar?

Planarity

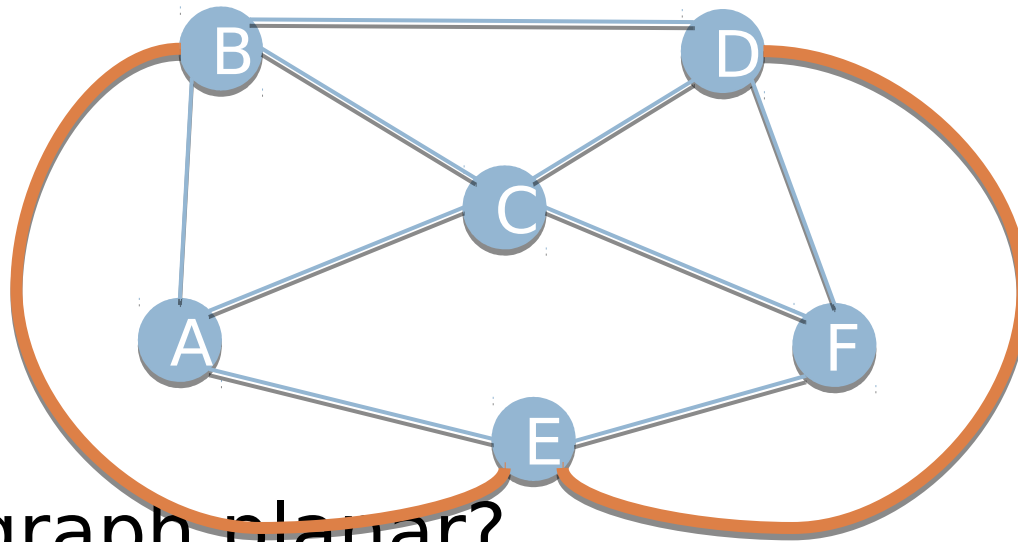
- A graph is planar if it can be drawn in the plane without any edges crossing



- Is this graph planar?
 - Yes!

Planarity

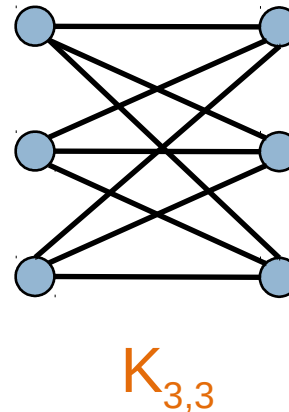
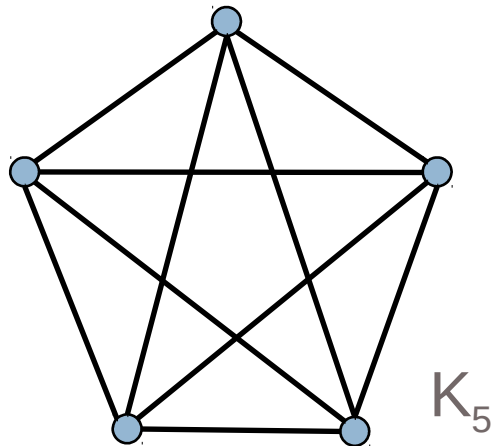
- A graph is planar if it can be drawn in the plane without any edges crossing



- Is this graph planar?
 - Yes!

Detecting Planarity

Kuratowski's Theorem:

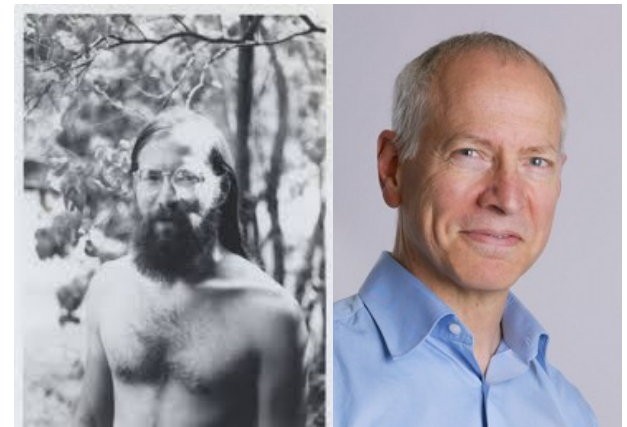


- A graph is planar if and only if it does not contain a copy of K_5 or $K_{3,3}$ (possibly with other nodes along the edges shown)

Detecting Planarity

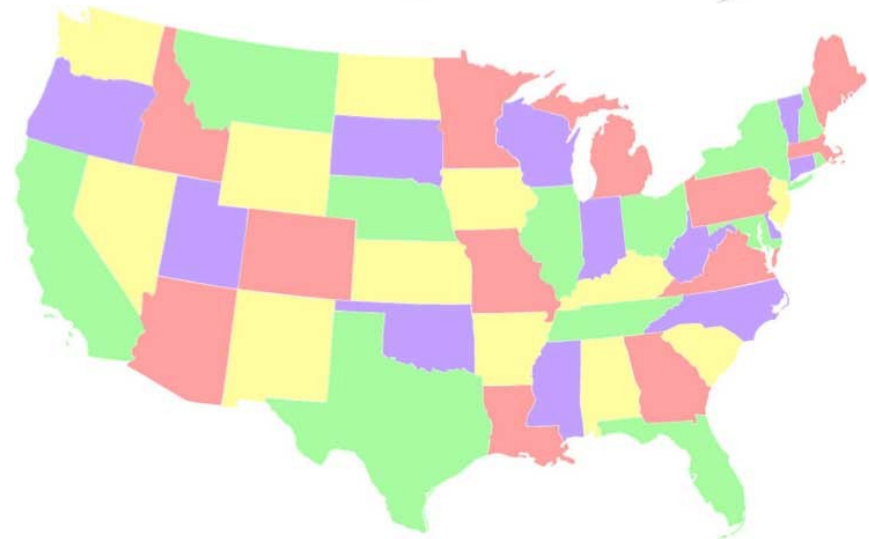
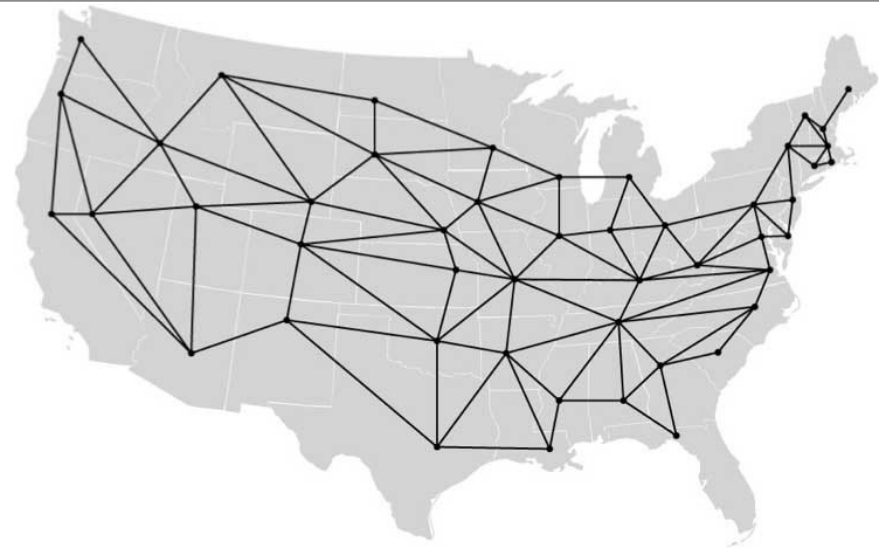
In the early 1970's, Cornell Prof **John Hopcroft** spent a sabbatical at Stanford and worked with PhD student **Bob Tarjan**. They developed the first linear-time algorithm for testing whether a graph was planar. They later received the ACM Turing Award for their work on algorithms.

Tarjan was hired at one point in the 1970's into our department, but the Ithaca weather was too depressing for him and he left for Princeton.



Coloring a graph

- How many colors are needed to color the states so that no two adjacent states have the same color?
- Asked since 1852
- 1879: Kemp publishes a proof that only 4 colors are needed!
- 1880: Julius Petersen finds a



Four Color Theorem

Every planar graph is 4-colorable [Appel & Haken, 1976]

The proof rested on checking that 1,936 special graphs had a certain property.

They used a computer to check that those 1, 936 graphs had that property!

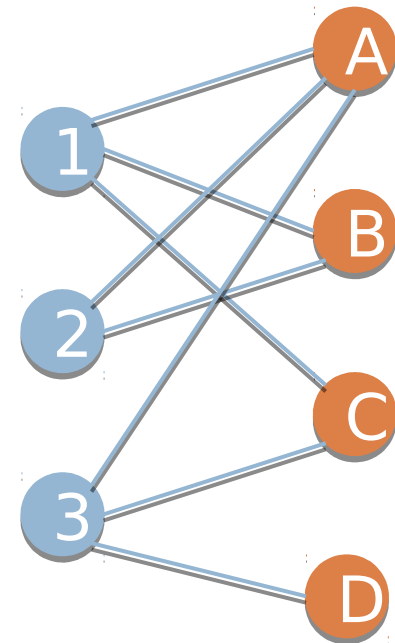
Basically the first time a computer was needed to check something. Caused a lot of controversy.

Gries looked at their computer program, a recursive program written in the assembly language of the IBM 7090 computer, and found an error, which was safe (it said something didn't have the property when it did) and could be fixed. Others did the same.

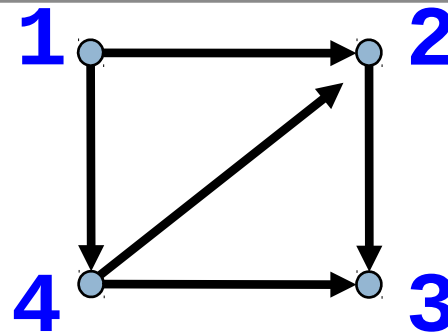
Since then, there have been improvements. And a formal proof

Bipartite graphs

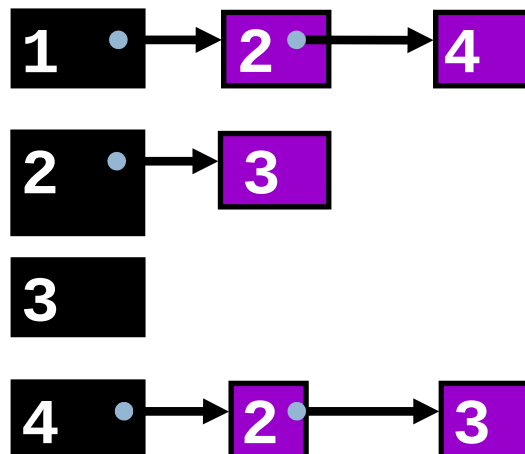
- A directed or undirected graph is **bipartite** if the vertices can be partitioned into two sets such that no edge connects two vertices in the same set
- The following are equivalent
 - G is bipartite
 - G is 2-colorable
 - G has no cycles of odd length



Representations of graphs



Adjacency List



Adjacency Matrix

	1	2	3	4
1	0	1	0	1
2	0	0	1	0
3	0	0	0	0
4	0	1	1	0

Adjacency matrix or adjacency List?

- n = number of vertices
- m = number of edges
- $d(u)$ = degree of u = no. of edges leaving u

	1	2	3	4
1	0	1	0	1
2	0	0	1	0
3	0	0	0	0
4	1	1	1	0

□ Adjacency Matrix

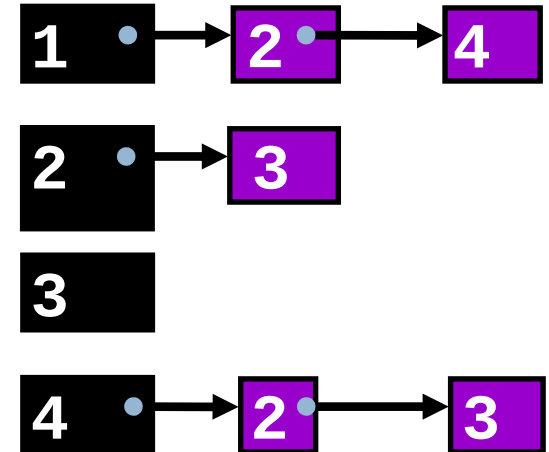
- Uses space $O(n^2)$
- Enumerate all edges in time $O(n^2)$
- Answer “Is there an edge from u to v ?” in $O(1)$ time
- Better for dense graphs (lots of edges)

Adjacency matrix or adjacency list?

- n = number of vertices
- e = number of edges
- $d(u)$ = degree of u = no. edges leaving u

□ Adjacency List

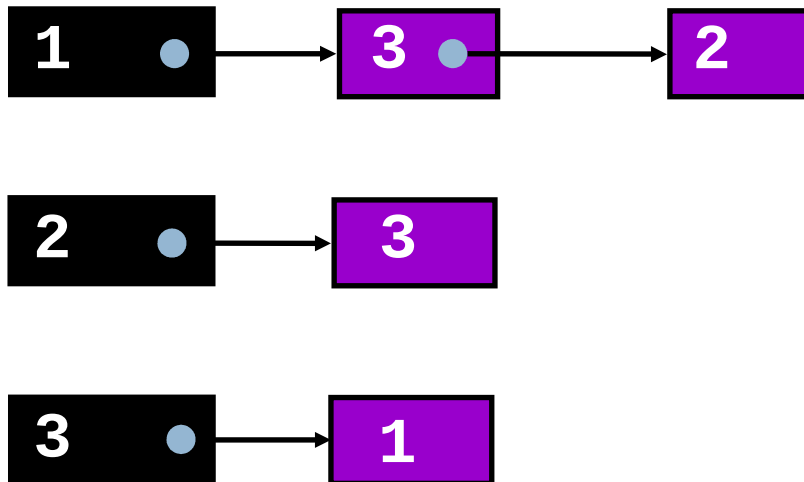
- Uses space $O(e + n)$
- Enumerate all edges in time $O(e + n)$
- Answer “Is there an edge from u to v ?” in $O(d(u))$ time
- Better for sparse graphs (fewer edges)



Breaking DAG

Which of the following two graphs are DAGs?
Directed **A**cyclic **G**raph

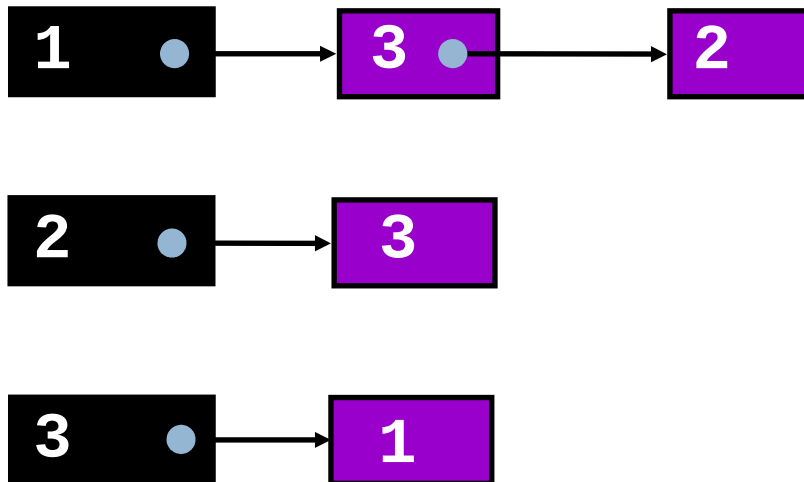
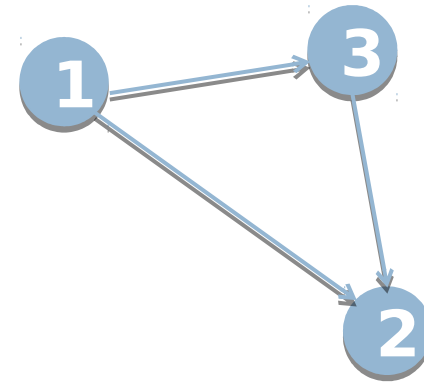
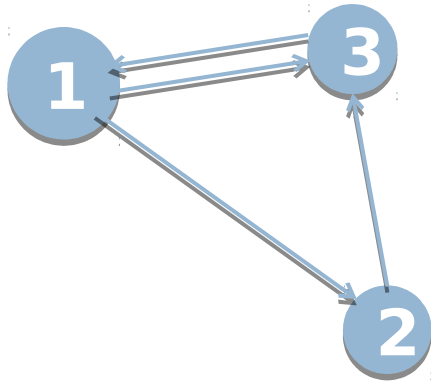
Graph 1:



Graph 2:

	1	2	3
1	0	1	1
2	0	0	0
3	0	1	0

Breaking DAG



	1	2	3
1	0	1	1
2	0	0	0
3	0	1	0

Graph algorithms

□ Search

- Depth-first search
- Breadth-first search

□ Shortest paths

- Dijkstra's algorithm

□ Minimum spanning trees

- Jarnik/Prim/Dijkstra algorithm
- Kruskal's algorithm