

Electronic Companion for Risk-Averse Multi-Stage Stochastic CCUS-ED

EC.1 Problem Formulation

EC.1.1 Objective Function

The overall operating costs $f_t(\mathbf{x}_t, \mathbf{y}_t)$ at each stage t comprise generation cost, the nodal imbalance penalty, and the carbon-emission-related costs, as shown in (EC.1). In the final stage $t = T$, the objective function additionally incorporates an imbalance penalty to ensure the storage levels of rich and lean solvent tanks return to their initial values. In (EC.1), τ represents the time duration of each stage; \mathcal{G} and \mathcal{B} represent the sets of generation units and buses in the transmission network, respectively; C_g^G and C^C denote the generation cost and carbon tax, corresponding to the gross generation output $P_{g,t}^G$ and net emissions $E_{g,t}^N$, where carbon-emission-related costs might arise from various emission-related policy alternatives, such as carbon tax and carbon cap-and-trade; C^P indicates the penalty coefficient; $\delta_{b,t}^+$ and $\delta_{b,t}^-$ represent nodal energy deficiency and energy surplus, respectively; $E_{g,t}^{R,\pm}$ and $E_{g,t}^{L,\pm}$ respectively represent the positive and negative imbalance values in rich and lean solvent tanks at T , which are enforced in the final-stage constraint (EC.6).

$$f_t(\mathbf{x}_t, \mathbf{y}_t) = \sum_{g \in \mathcal{G}} [C_g^G \cdot P_{g,t}^G + C^C \cdot E_{g,t}^N] \cdot \tau + \sum_{b \in \mathcal{B}} C^P \cdot [\delta_{b,t}^+ + \delta_{b,t}^-] \cdot \tau \\ + \begin{cases} \sum_{g \in \mathcal{G}} C^P \cdot [E_{g,t}^{R,+} + E_{g,t}^{R,-} + E_{g,t}^{L,+} + E_{g,t}^{L,-}], & \text{if } t = T \\ 0 & , \text{ otherwise} \end{cases} \quad (\text{EC.1})$$

EC.1.2 Constraints

Prevailing constraints including power balance requirements, power flow limits, power output constraints, and capacity constraints of the solvent tanks are detailed as follows.

EC.1.2.1 Nodal Power Balance Constraints

$$\sum_{g \in \mathcal{G}_b} P_{g,t}^N + \sum_{l \in to(b)} P_{l,t}^L - \sum_{l \in fr(b)} P_{l,t}^L + \delta_{b,t}^+ - \delta_{b,t}^- = D_{b,t} \quad \forall b, t \quad (\text{EC.2})$$

where $\mathcal{G}_b \subseteq \mathcal{G}$, $fr(b) \subseteq \mathcal{L}$, and $to(b) \subseteq \mathcal{L}$ are the set of units connected to b , the set of lines that flow out of and into bus $b \in \mathcal{B}$, respectively; $D_{b,t}$ represents the net load at bus b .

EC.1.2.2 Power Flow Constraints

$$-\overline{P}_l^L \leq P_{l,t}^L \leq \overline{P}_l^L \quad \forall l, t \quad (\text{EC.3a})$$

$$P_{l,t}^L = \frac{1}{X_l} (\theta_{fr(l),t} - \theta_{to(l),t}) \quad \forall l, t \quad (\text{EC.3b})$$

where \overline{P}_l^L denotes the power flow limit of transmission line $l \in \mathcal{L}$; X_l represents the reactance of line l ; $\theta_{b,t}$ is the phase angle of bus $b \in \mathcal{B}$; $fr(l)$ and $to(l) \in \mathcal{B}$ return the starting and ending buses of line l .

EC.1.2.3 Power Output Constraints

$$\underline{P}_g^G \cdot \hat{u}_{g,t} \leq P_{g,t}^G \leq \overline{P}_g^G \cdot \hat{u}_{g,t} \quad \forall g, t \quad (\text{EC.4a})$$

$$P_{g,t}^G - P_{g,t-1}^G \leq RU_g \cdot \hat{u}_{g,t-1} + SU_g \cdot (\hat{u}_{g,t} - \hat{u}_{g,t-1}) \quad \forall g, t \quad (\text{EC.4b})$$

$$P_{g,t-1}^G - P_{g,t}^G \leq RD_g \cdot \hat{u}_{g,t} + SD_g \cdot (\hat{u}_{g,t-1} - \hat{u}_{g,t}) \quad \forall g, t \quad (\text{EC.4c})$$

$$P_{g,t}^G = P_{g,t}^N + \kappa_g^F \cdot \overline{P}_g^G \cdot \hat{u}_{g,t} + P_{g,t}^C + \omega_g^I \cdot E_{g,t}^I \quad \forall g, t \quad (\text{EC.4d})$$

$$E_{g,t}^N = E_{g,t}^G - E_{g,t}^C = e_g^E \cdot P_{g,t}^G - P_{g,t}^C / \omega_g^C \quad \forall g, t \quad (\text{EC.4e})$$

Constraints (EC.4a)-(EC.4c) enforce limitations on the gross power output of the CCUS power plants based on their operational and ramping limits, while taking commitment decisions $\hat{u}_{g,t}$ from the day-ahead UC as parameters. RU_g , RD_g , SU_g , and SD_g represent the upward, downward, startup, and shutdown ramping capacities of CCUS unit g , respectively. \overline{P}_g^G and \underline{P}_g^G denote maximum and minimum generation limits, respectively.

As depicted in Fig. 1, constraint (EC.4d) specifies the power balance of the gross power output P_{gt}^G of the power plant integrated with CCUS. P_{gt}^G consists of several components, including: (i) the net power P_{gt}^C which is the actual electric energy delivered to the power grids of the plant; (ii) the fixed power consumption which is proportional to the fixed carbon capture energy coefficient κ_g^F ; (iii) the energy consumption P_{gt}^C which is associated with CO₂ absorption; and (iv) the desorption energy P_{gt}^I which is proportional to the absorbed emissions E_{gt}^I with coefficient ω_g^I .

Constraint (EC.4e) defines the net emission balance for each CCUS unit, where the gross emission E_{gt}^G is proportional to the gross power output, with e_g^E representing the CO₂ emission intensity factor. The captured emission E_{gt}^C is proportional to the absorption-related power consumption P_{gt}^C , with ω_g^C denoting the energy penalty coefficient.

EC.1.2.4 Capacity Constraints of the Solvent Tanks

$$E_{g,t}^R = E_{g,t-1}^R + (E_{g,t}^I - E_{g,t}^C) \cdot \tau \quad \forall g, t \quad (\text{EC.5a})$$

$$E_{g,t}^L = E_{g,t-1}^L + (E_{g,t}^C - E_{g,t}^I) \cdot \tau \quad \forall g, t \quad (\text{EC.5b})$$

$$0 \leq E_{g,t}^R, E_{g,t}^L \leq e_g^E \cdot \overline{P}_g^G \cdot T_g^S \quad \forall g, t \quad (\text{EC.5c})$$

$$0 \leq E_{gt}^I, E_{gt}^C \leq \alpha_g^C \cdot E_{gt}^N \quad \forall g, t \quad (\text{EC.5d})$$

where (EC.5a) indicates that the net flows of rich solvent $E_{g,t}^R - E_{g,t-1}^R$, pumped into the rich solvent storage tank from the absorber at stage t , could be expressed as the amount of rich solvent (in the form of contained CO₂) transferred from the absorber to the rich solvent tank $E_{g,t}^I$ minus that drained from the rich solvent tank to the stripper $E_{g,t}^C$. This expression can also be implemented for the net flow of the lean solvent $E_{g,t}^L - E_{g,t-1}^L$ drained from the lean solvent storage tank, as shown in (EC.5b). T_g^S is introduced in constraints (EC.5c) to describe the maximum capacity of the tanks, which is defined as the number of hours required to completely fill an empty rich/lean solvent tank under the condition $P_{g,t}^G = \overline{P}_g^G$. Constraint (EC.5d) indicates that the stripped amount E_{gt}^C and the absorbed amount E_{gt}^I depend on the maximum capturable emission, where α_g^C denotes the capture rate of CO₂ in the absorber.

Moreover, the final reservoir storage volumes in the final stage $t = T$ should return to their initial values. This is achieved by penalizing the gaps between the final stage storage levels and the initial stage values as evaluated in (EC.6).

$$E_{g,T}^R + E_{g,T}^{R+} - E_{g,T}^{R-} = E_{g,1}^R = \beta_g^R \cdot e_g^E \cdot \overline{P}_g^G \cdot T_g^S \quad \forall g \quad (\text{EC.6a})$$

$$E_{g,T}^L + E_{g,T}^{L+} - E_{g,T}^{L-} = E_{g,1}^L = \beta_g^L \cdot e_g^E \cdot \overline{P}_g^G \cdot T_g^S \quad \forall g \quad (\text{EC.6b})$$

where β_g^R and β_g^L indicate the initial volumes of solvent in the rich and lean solvent storage tanks.