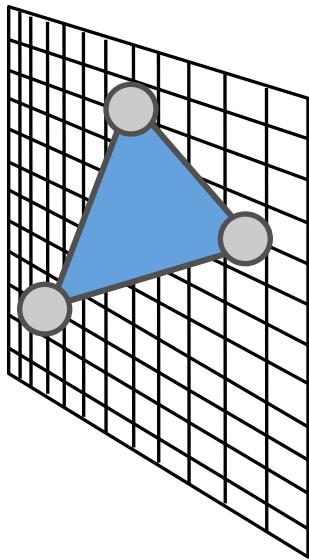
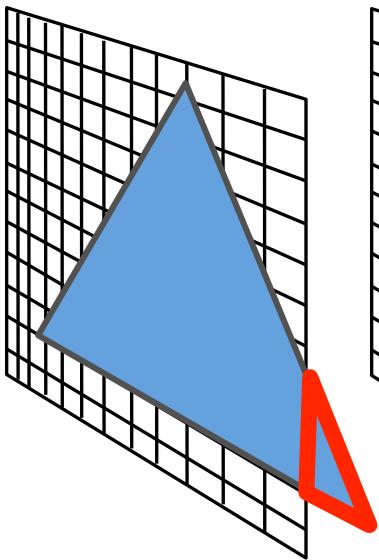


# $z$ -Buffering & Interpolation

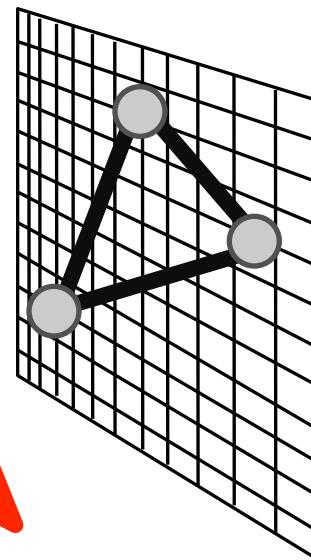
# Challenges



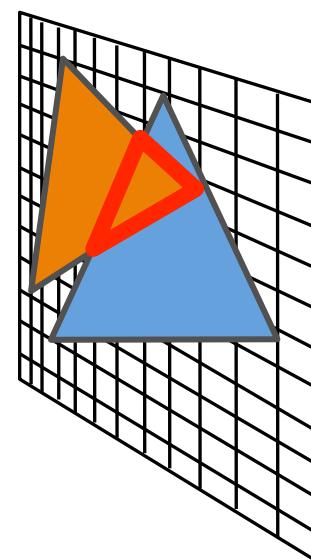
Projection



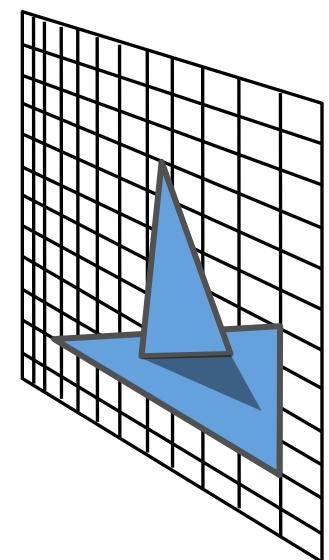
Clipping



Rasterization

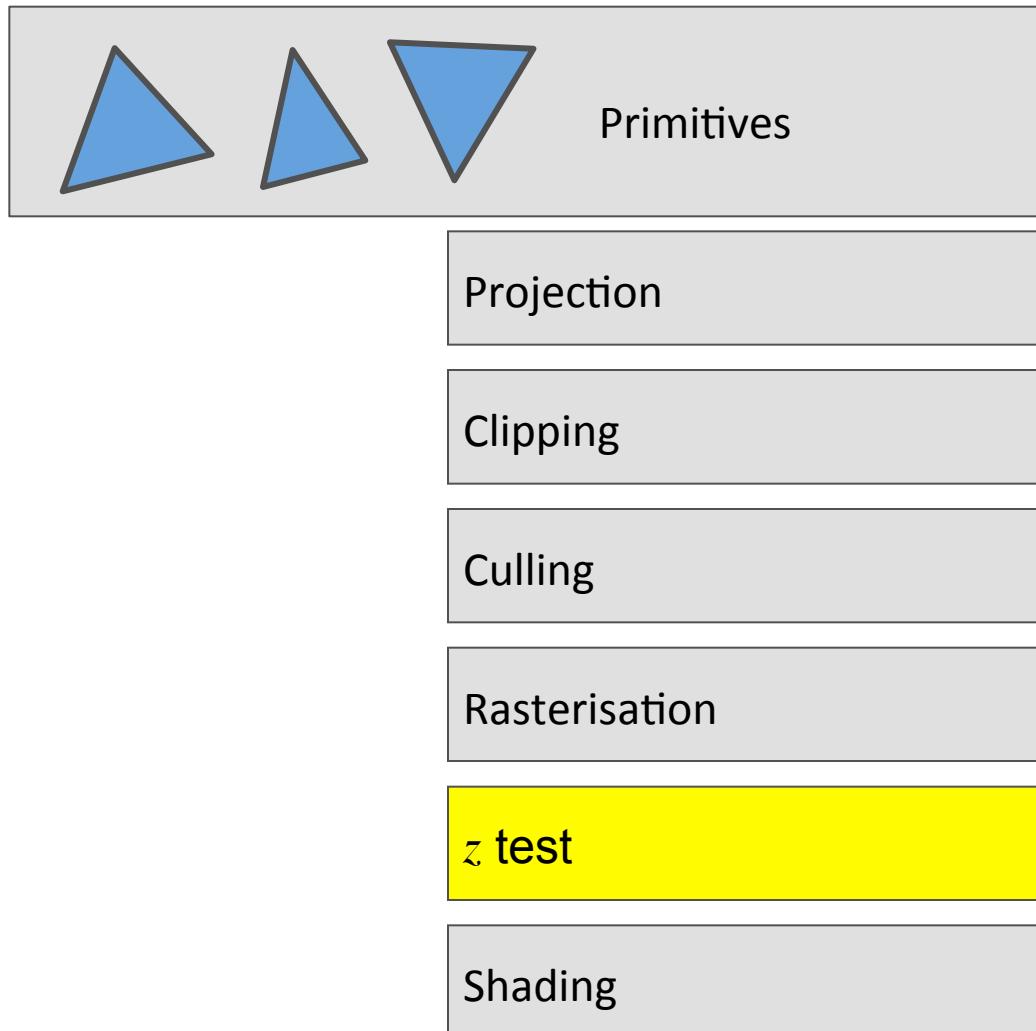


Visibility

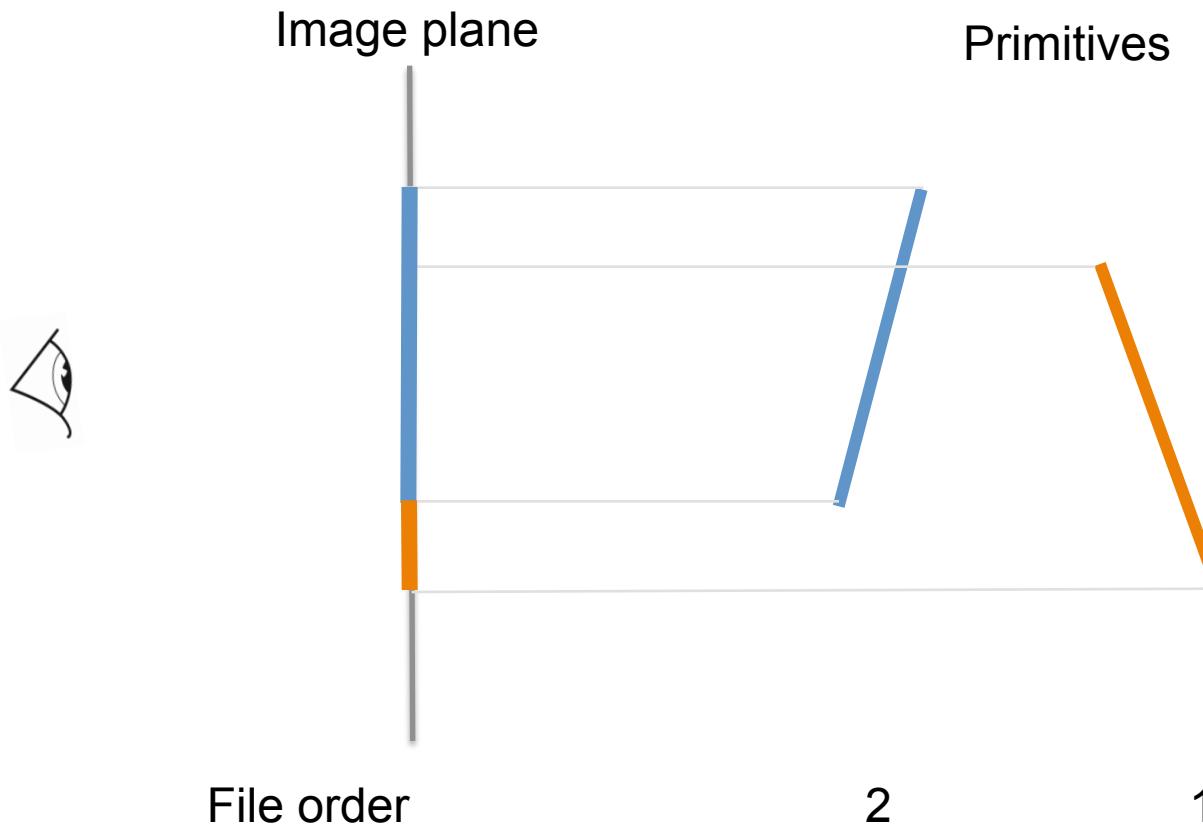


Shading

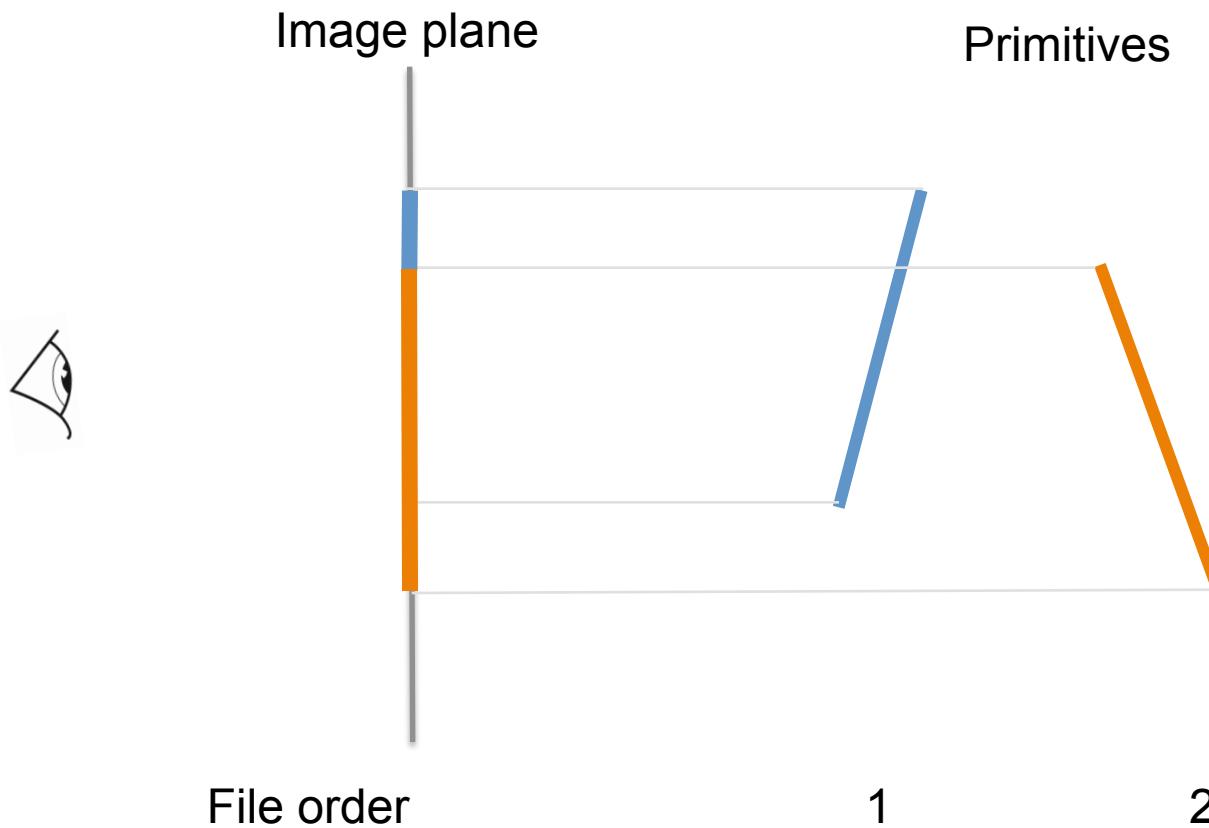
# Pipeline



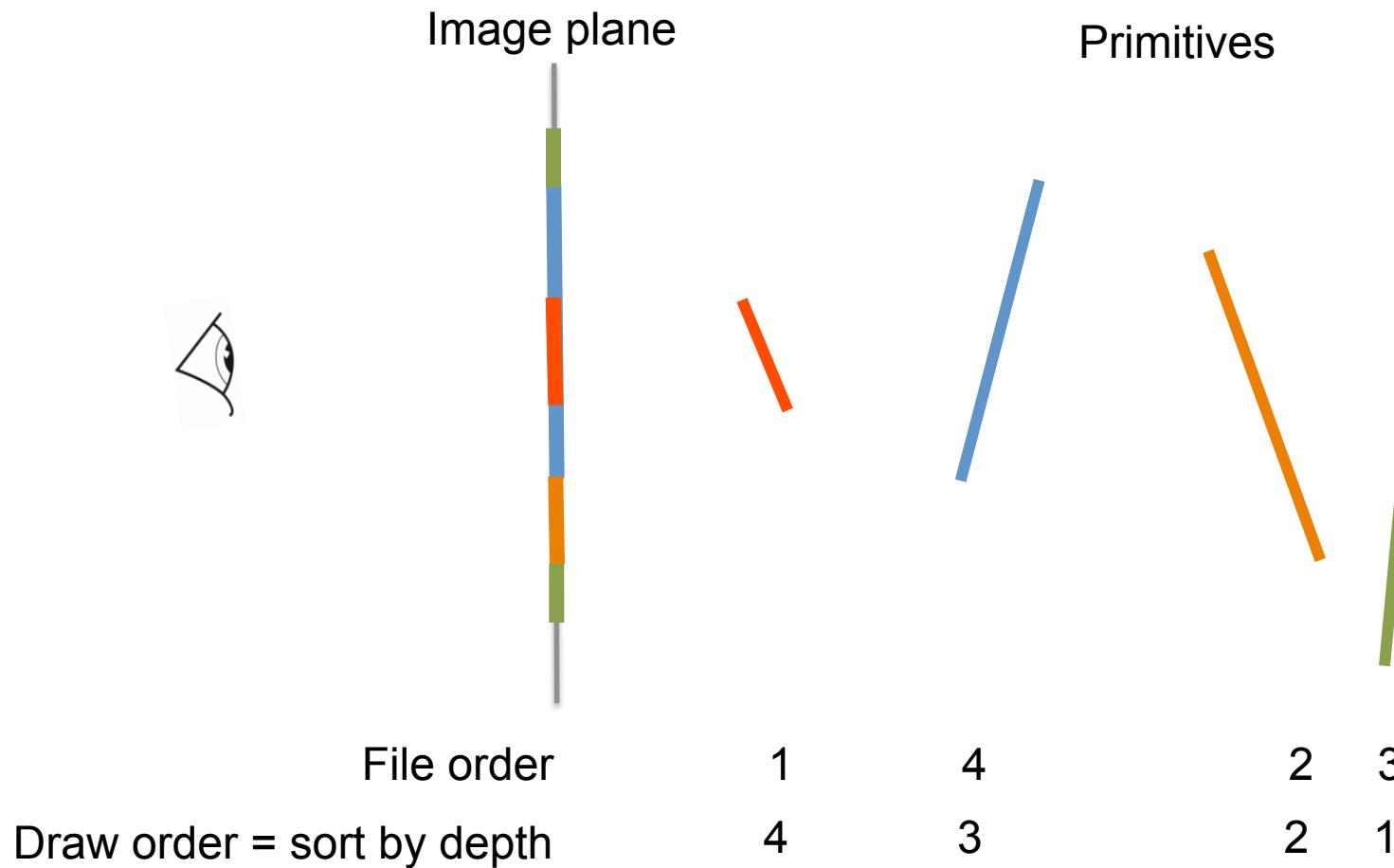
# Doing nothing (with some luck)



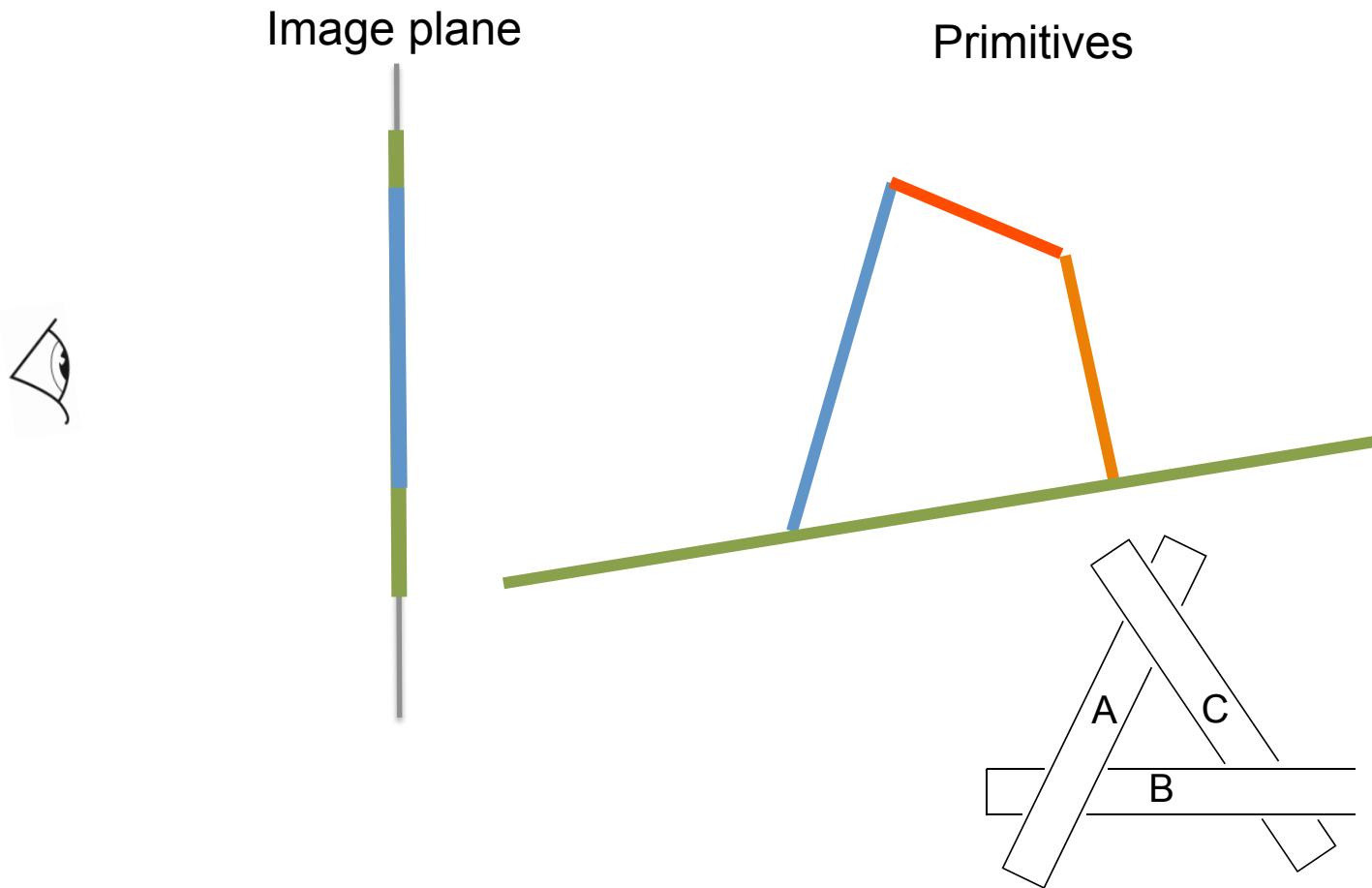
# Doing nothing (with no luck)



# Painters algorithm

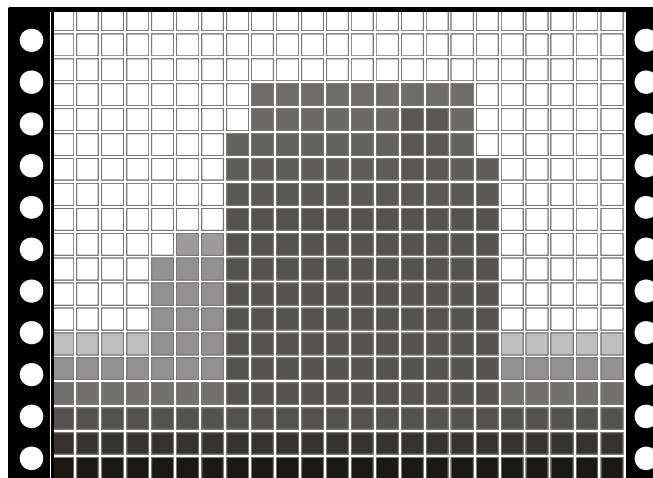


# Painters algorithm

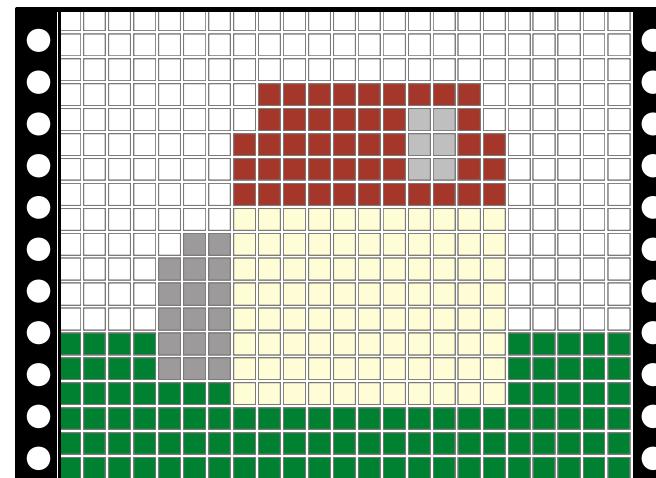


# $z$ -Buffer

- In addition to color buffer
- Depth buffer ( $z$  of view space coordinate)



Depth buffer



Color buffer

# Basic Idea

- Initialise the  $z$ -Buffer array  
`zbuffer[width*height]` to  $z_{\max}$
- Consider a point at  $(x, y, z)$ , projected to pixel  $(x_s, y_s)$  with colour  $c$
- If  $z < \text{zbuf}[x_s][y_s]$ 
  - set `colorBufer[x_s][y_s] = c, zBuffer[x_s][y_s] = z`
  - or else, do nothing

# Rasterization code with $z$ test

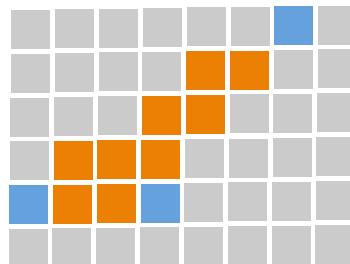
```
For every triangle
    ComputeProjection
    Compute bbox, clip bbox to screen limits
    Compute line equations
    For all pixels in bbox
        If all line equations > 0
            If z < depthBuffer[x, y]
                framebuffer[x, y] = color;
                depthBuffer[x, y] = depth;
    }
```

# Problems

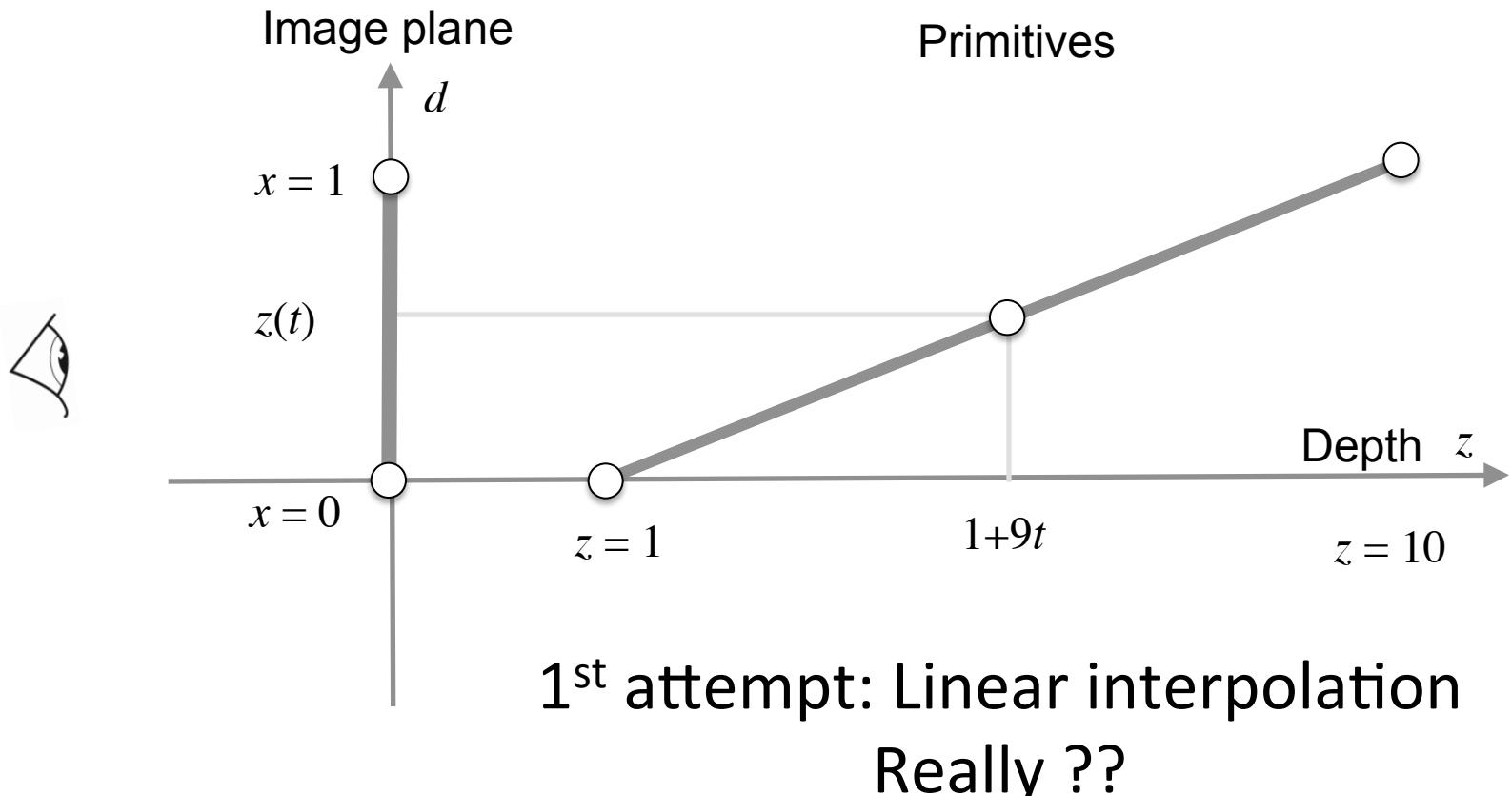
- Aliasing on depth ( $z$ -buffer tearing)
- Which  $z$  value?
- How to compute  $z$  value at each pixel?

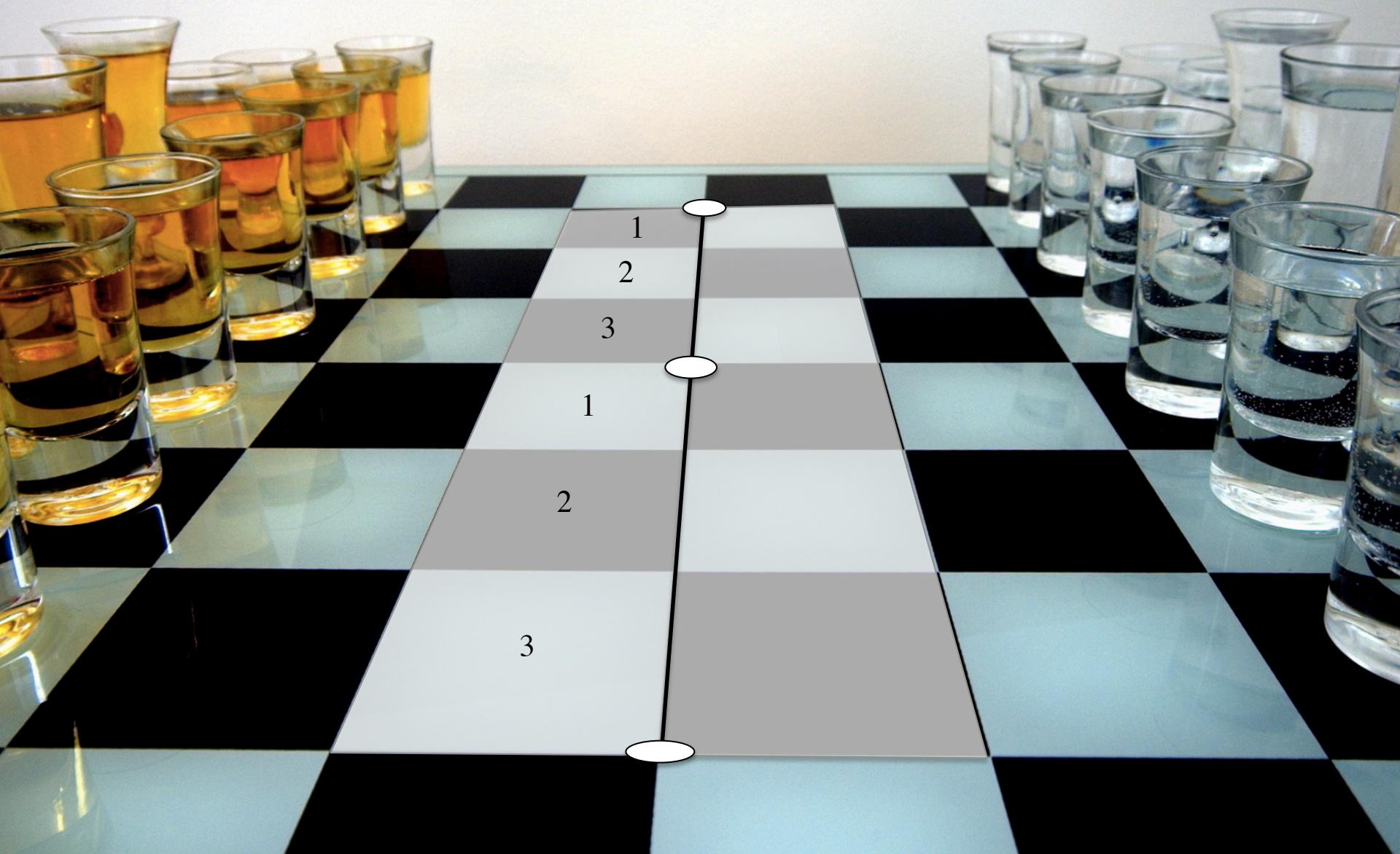
# Per-vertex and per-color depth

- Now we have to write a  $z$  value for each **pixel**
- Problem: We only know it at the **vertices**
- Solution: **Interpolate**
  - We will look at this in more detail!
  - The same interpolation will also give us per-pixel colors, normals, texture coords, etc



# Interpolating $z$ along a line

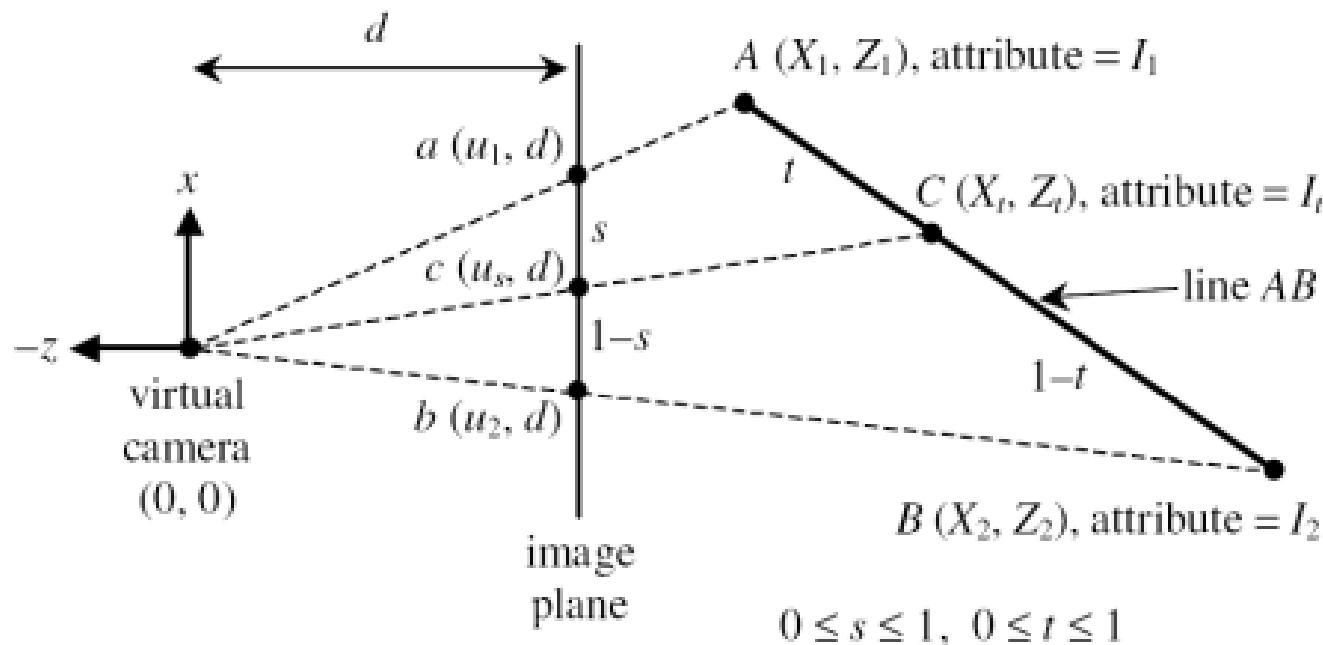




# Why is this incorrect?

- Interpolating  $z$  linearly along scan-line is **incorrect!**
- Why is that?
  - Projection of a point onto screen is done with non-linear projection matrix  
(Remember:  $w = (z + 1)$  factor)
  - **Must** take that into account

# Perspective Correct Depth Interpolation



Given this scenario, can write down equations and see that we need to linearly interpolate  $1/z$  (and not  $z$ )

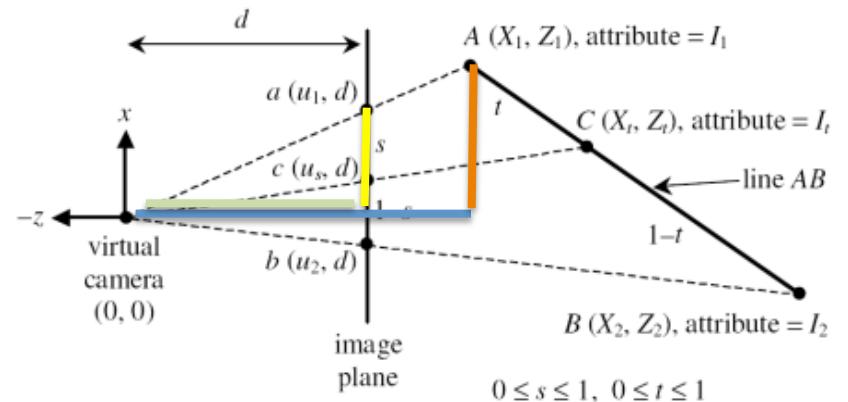
# Perspective Correct Depth Interpolation

By similar triangles we have:

$$\frac{X_1}{Z_1} = \frac{u_1}{d} \Rightarrow X_1 = \frac{u_1 Z_1}{d}, \quad (1)$$

$$\frac{X_2}{Z_2} = \frac{u_2}{d} \Rightarrow X_2 = \frac{u_2 Z_2}{d}, \quad (2)$$

$$\frac{X_t}{Z_t} = \frac{u_s}{d} \Rightarrow Z_t = \frac{d X_t}{u_s}. \quad (3)$$



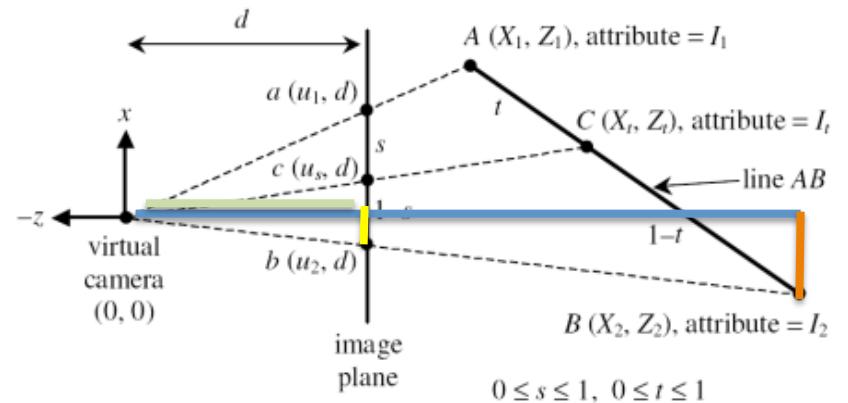
# Perspective Correct Depth Interpolation

By similar triangles we have:

$$\frac{X_1}{Z_1} = \frac{u_1}{d} \Rightarrow X_1 = \frac{u_1 Z_1}{d}, \quad (1)$$

$$\frac{X_2}{Z_2} = \frac{u_2}{d} \Rightarrow X_2 = \frac{u_2 Z_2}{d}, \quad (2)$$

$$\frac{X_t}{Z_t} = \frac{u_s}{d} \Rightarrow Z_t = \frac{d X_t}{u_s}. \quad (3)$$



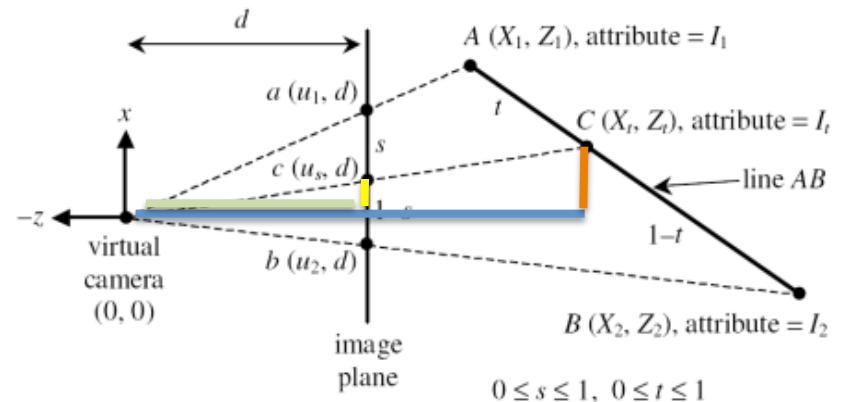
# Perspective Correct Depth Interpolation

By similar triangles we have:

$$\frac{X_1}{Z_1} = \frac{u_1}{d} \Rightarrow X_1 = \frac{u_1 Z_1}{d}, \quad (1)$$

$$\frac{X_2}{Z_2} = \frac{u_2}{d} \Rightarrow X_2 = \frac{u_2 Z_2}{d}, \quad (2)$$

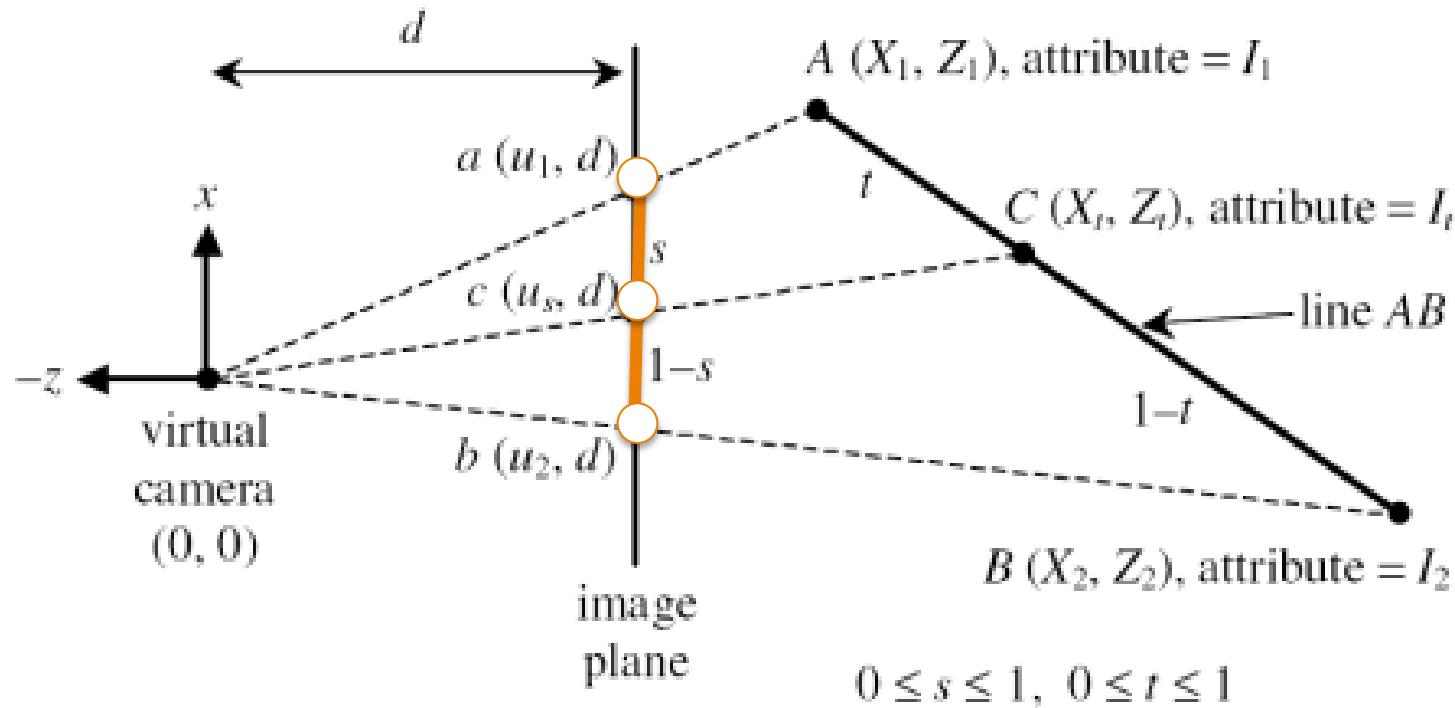
$$\frac{X_t}{Z_t} = \frac{u_s}{d} \Rightarrow Z_t = \frac{d X_t}{u_s}. \quad (3)$$



# Perspective Correct Depth Interpolation

By linearly interpolating in the image plane (or screen space), we have

$$u_s = u_1 + s(u_2 - u_1). \quad (4)$$

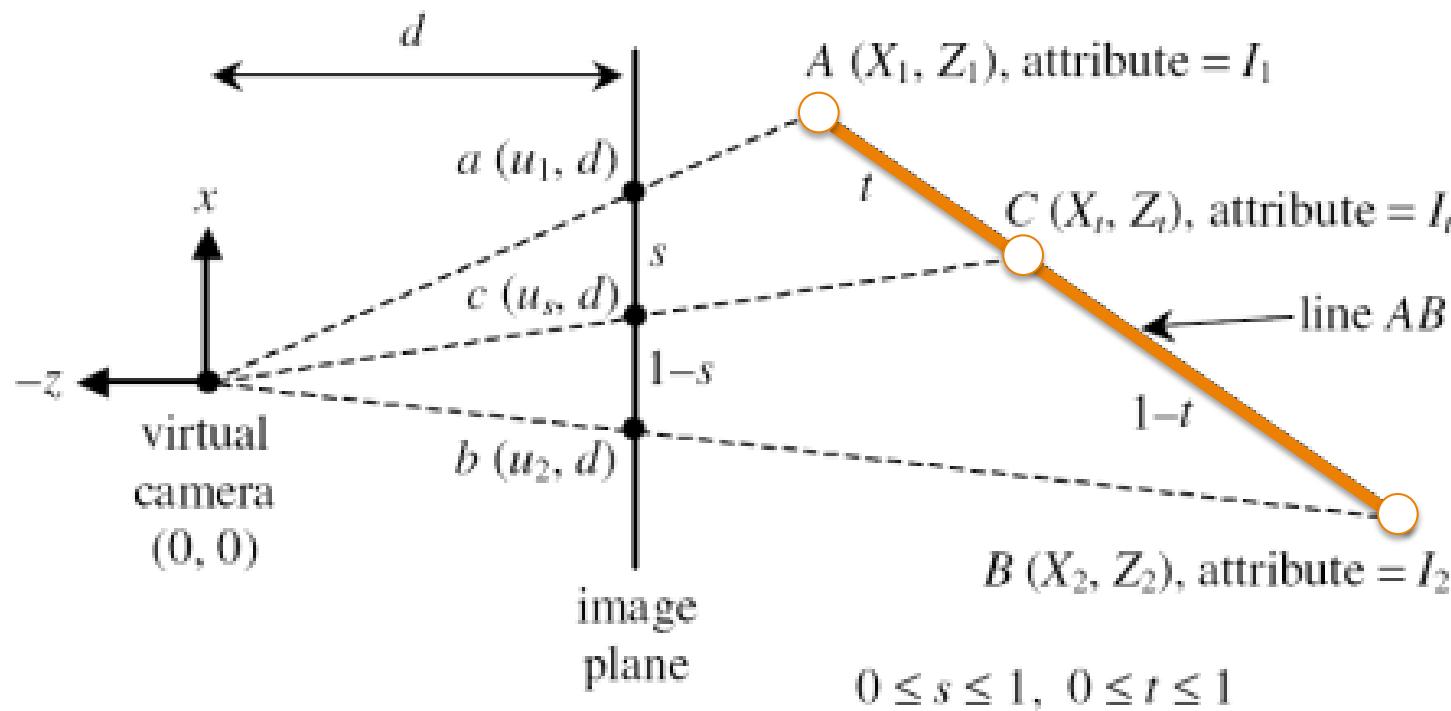


# Perspective Correct Depth Interpolation

By linearly interpolating across the primitive in the camera coordinate system, we have

$$X_t = X_1 + t(X_2 - X_1), \quad (5)$$

$$Z_t = Z_1 + t(Z_2 - Z_1), \quad (6)$$



# Perspective Correct Depth Interpolation

By linearly interpolating in the image plane (or screen space), we have

$$u_s = u_1 + s(u_2 - u_1). \quad (4)$$

By linearly interpolating across the primitive in the camera coordinate system, we have

$$X_t = X_1 + t(X_2 - X_1), \quad (5)$$

$$Z_t = Z_1 + t(Z_2 - Z_1), \quad (6)$$

Substituting (4) and (5) into (3),

$$Z_t = \frac{d(X_1 + t(X_2 - X_1))}{u_1 + s(u_2 - u_1)}. \quad (7)$$

# Perspective Correct Depth Interpolation

Substituting (1) and (2) into (7),

$$\begin{aligned} Z_t &= \frac{d \left( \frac{u_1 Z_1}{d} + t \left( \frac{u_2 Z_2}{d} - \frac{u_1 Z_1}{d} \right) \right)}{u_1 + s(u_2 - u_1)} \\ &= \frac{u_1 Z_1 + t(u_2 Z_2 - u_1 Z_1)}{u_1 + s(u_2 - u_1)}. \end{aligned} \quad (8)$$

Substituting (6) into (8),

$$Z_1 + t(Z_2 - Z_1) = \frac{u_1 Z_1 + t(u_2 Z_2 - u_1 Z_1)}{u_1 + s(u_2 - u_1)}, \quad (9)$$

# Perspective Correct Depth Interpolation

which can be simplified into

$$t = \frac{sZ_1}{sZ_1 + (1-s)Z_2}. \quad (10)$$

Substituting (10) into (6), we have

$$Z_t = Z_1 + \frac{sZ_1}{sZ_1 + (1-s)Z_2} (Z_2 - Z_1), \quad (11)$$

which can be simplified to

$$Z_t = \frac{1}{\frac{1}{Z_1} + s \left( \frac{1}{Z_2} - \frac{1}{Z_1} \right)}. \quad (12)$$

# “Can be simplified”

$$z_1 + t(z_2 - z_1) = (u_1 z_1 + t(u_2 z_2 - u_1 z_1)) / (u_1 + s(u_2 - u_1))$$

$$z_1 + tz_2 - tz_1 = (u_1 z_1 + t(u_2 z_2 - u_1 z_1)) / (u_1 + s(u_2 - u_1))$$

$$0 = (u_1 z_1 + t(u_2 z_2 - u_1 z_1)) / (u_1 + s(u_2 - u_1)) - z_1 - tz_2 + tz_1$$

$$0 = u_1 z_1 + t(u_2 z_2 - u_1 z_1) + (-z_1 - tz_2 + tz_1) * (u_1 + s(u_2 - u_1))$$

$$0 = u_1 z_1 + t(u_2 z_2 - u_1 z_1) + (-z_1(u_1 + s(u_2 - u_1)) - tz_2(u_1 + s(u_2 - u_1)) + tz_1(u_1 + s(u_2 - u_1)))$$

$$0 = u_1 z_1 + tu_2 z_2 - tu_1 z_1 - z_1 u_1 - z_1 s(u_2 - u_1) - tz_2 u_1 - tz_2 s(u_2 - u_1) + tz_1 u_1 + tz_1 s(u_2 - u_1)$$

$$0 = tu_2 z_2 - z_1 s(u_2 - u_1) - tz_2 u_1 - tz_2 s(u_2 - u_1) + tz_1 s(u_2 - u_1)$$

$$0 = tu_2 z_2 - z_1 s u_2 + z_1 s u_1 - tz_2 u_1 - tz_2 s u_2 + tz_2 s u_1 + tz_1 s u_2 - tz_1 s u_1$$

$$0 = -z_1 s u_2 + z_1 s u_1 + tu_2 z_2 - tz_2 u_1 - tz_2 s u_2 + tz_2 s u_1 + tz_1 s u_2 - tz_1 s u_1$$

$$0 = -z_1 s u_2 + z_1 s u_1 + t(u_2 z_2 - z_2 u_1 - z_2 s u_2 + z_2 s u_1 + z_1 s u_2 - z_1 s u_1)$$

$$t = z_1 s u_2 - z_1 s u_1 / (u_2 z_2 - z_2 u_1 - z_2 s u_2 + z_2 s u_1 + z_1 s u_2 - z_1 s u_1)$$

$$t = (z_1 s(u_2 - u_1)) / (u_2 z_2 - z_2 u_1 - z_2 s u_2 + z_2 s u_1 + z_1 s u_2 - z_1 s u_1)$$

$$t = (z_1 s(u_2 - u_1)) / ((u_2 - u_1)(z_2 - z_2 s + z_1 s))$$

$$t = z_1 s / (z_2 - z_2 s + z_1 s)$$

$$t = z_1 s / (z_2(1 - s) + z_1 s)$$

$$t = sz_1 / (z_1 s + (1 - s)z_2)$$

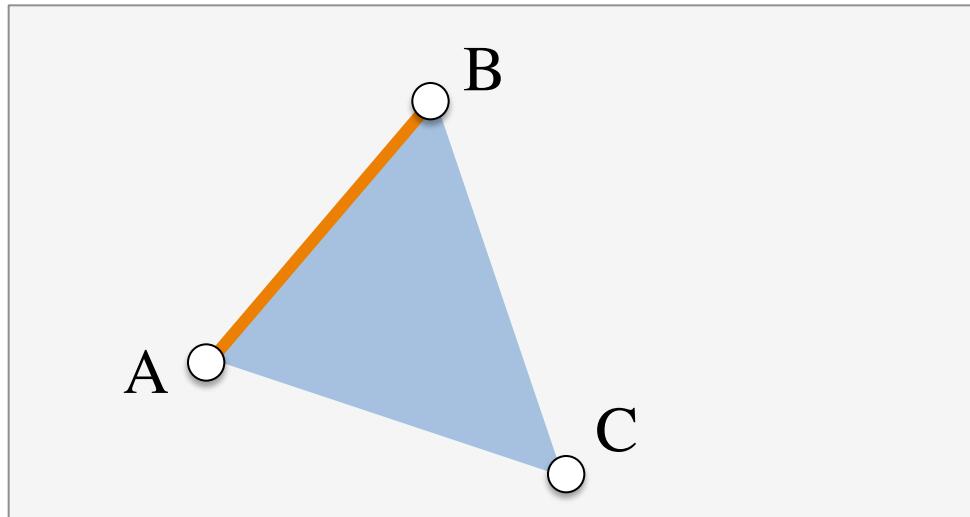
# Perspective Correct Depth Interpolation

Thus we only need to linearly interpolate  
between  $1/z$  values:

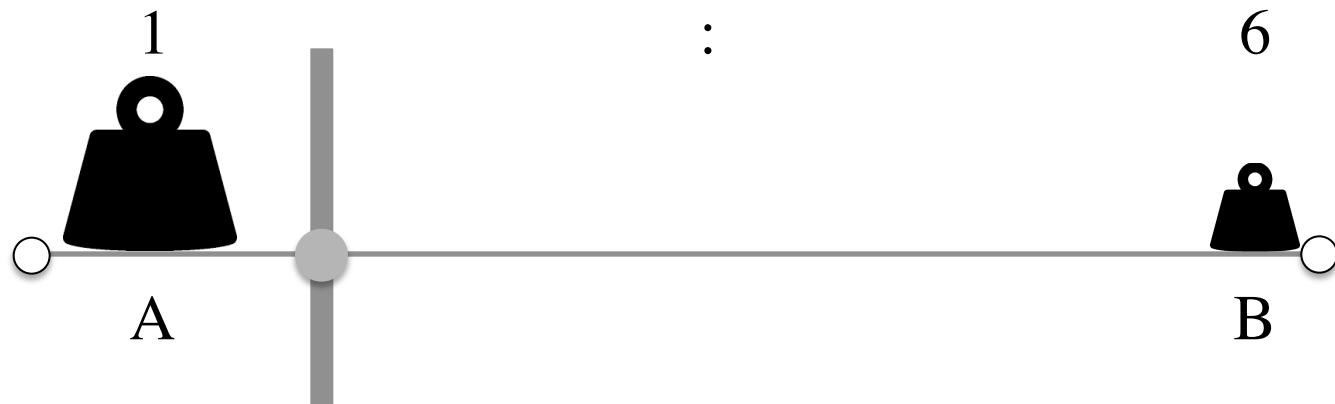
$$Z_t = \frac{1}{\frac{1}{Z_1} + s \left( \frac{1}{Z_2} - \frac{1}{Z_1} \right)} \quad (12)$$

# Line vs. area interpolation

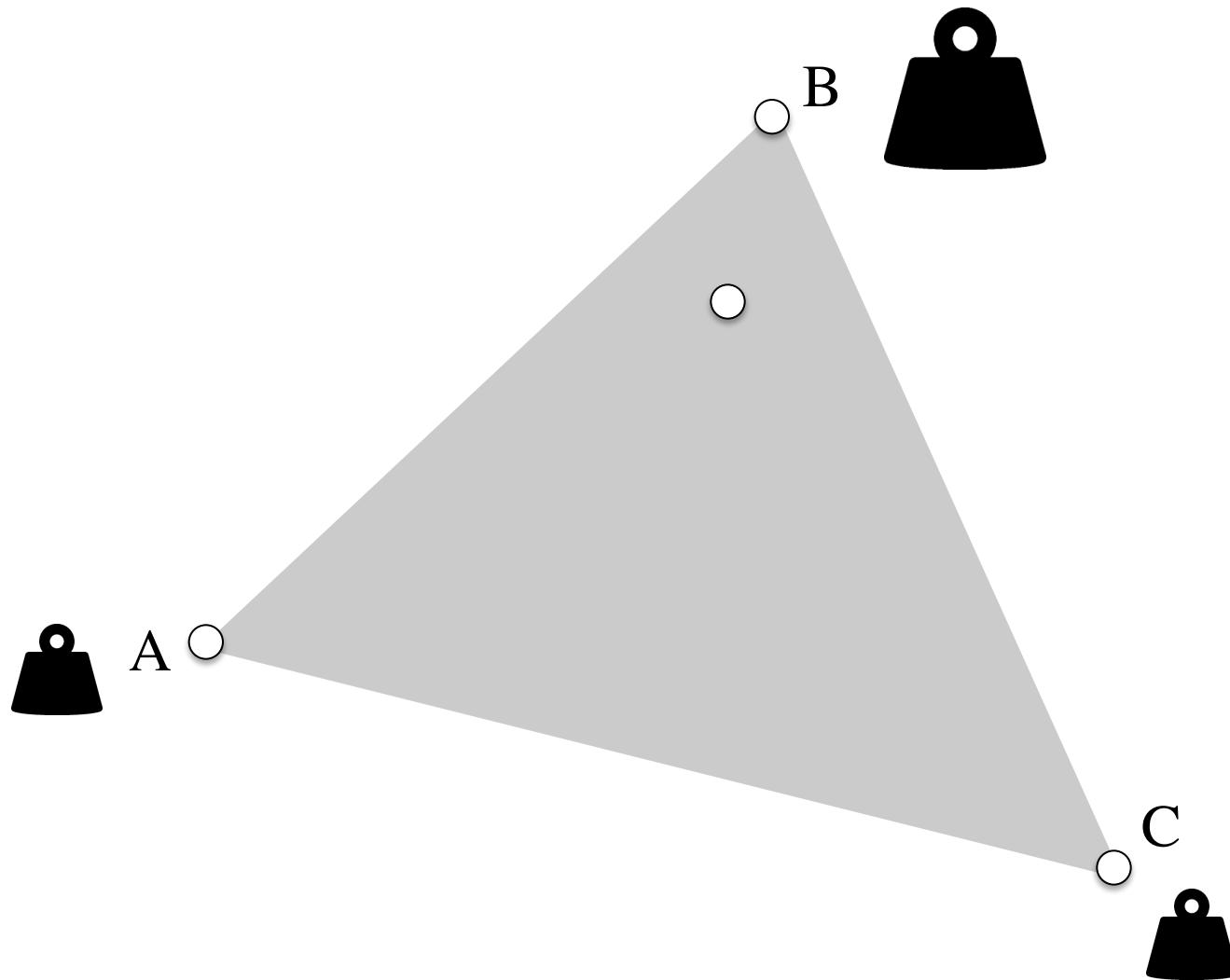
- We now **know** how to interpolate between **two** points A and B
- But triangle A, B, C has **three** points
- Solution: **Barycentric** interpolation



# Barycentric coordinates



# Barycentric coordinates

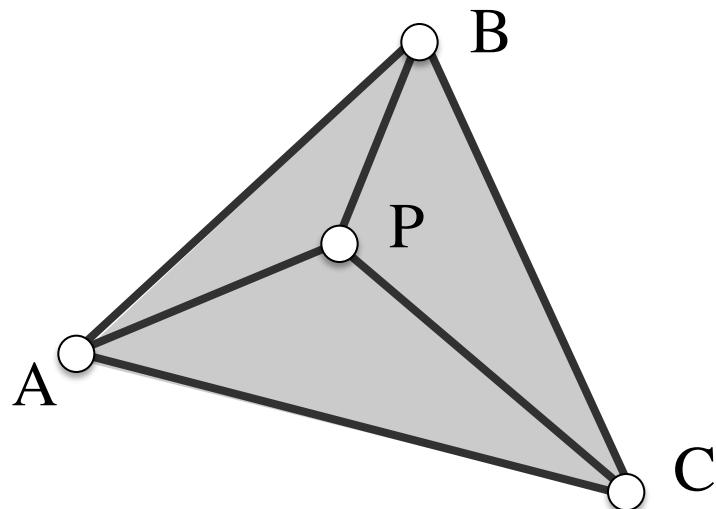


# Barycentric coordinates: Definition

$$w_A(P) = t(P, B, C) / t(A, B, C)$$

$$w_B(P) = t(P, C, A) / t(A, B, C)$$

$$w_C(P) = t(P, A, B) / t(A, B, C)$$



$t(A, B, C)$  is the triangle area

# Barycentric coordinates: Definition

$$w_A(P) = t(P, B, C) / t(A, B, C)$$

$$w_B(P) = t(P, C, A) / t(A, B, C)$$

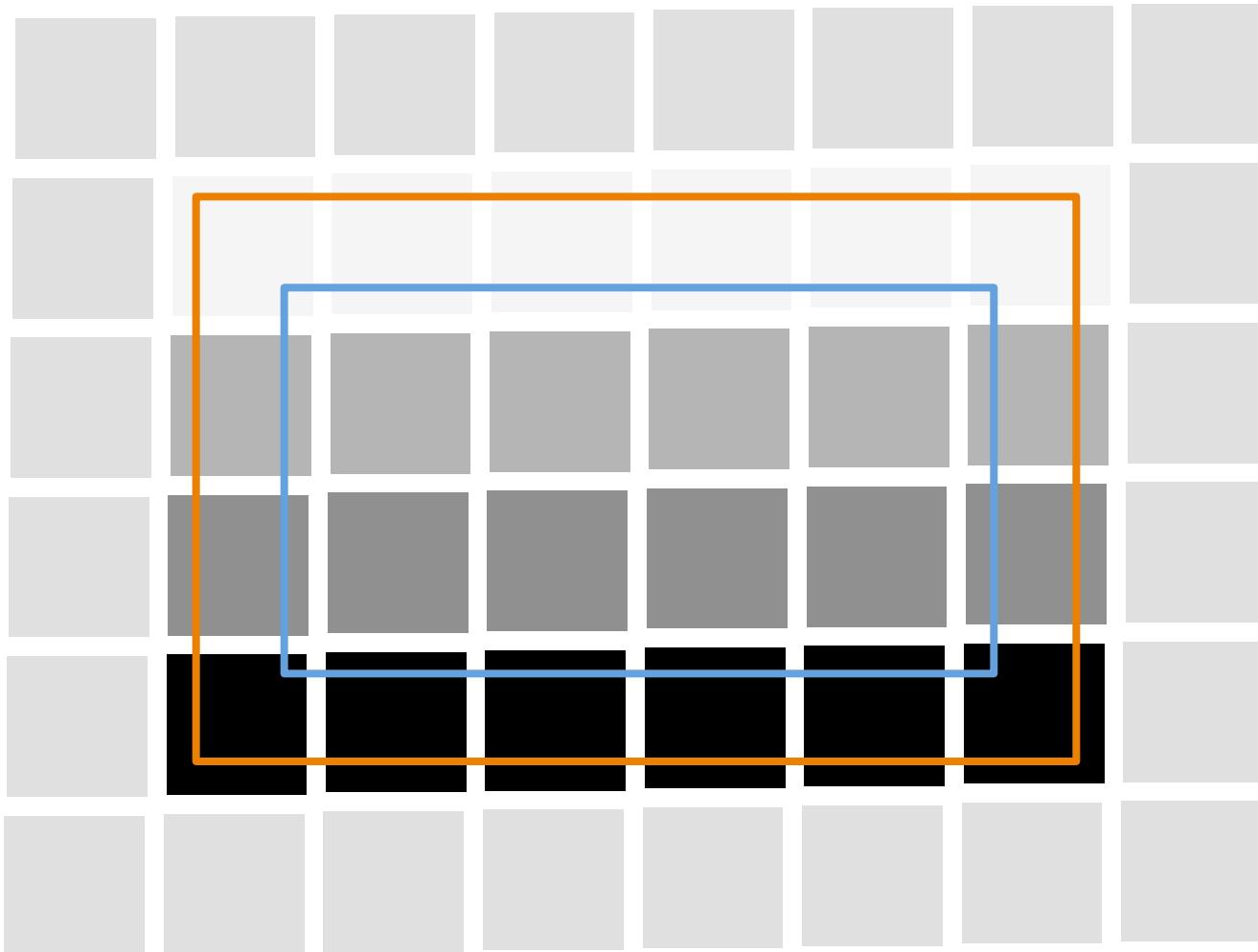
$$w_C(P) = t(P, A, B) / t(A, B, C)$$

Example:

$$\text{color}(P) = \text{color}_A w_A(P) + \text{color}_B w_B(P) + \text{color}_C w_C(P)$$



# Subpixel-correctness



# Trade-Offs

- Painter's algorithm:
  - Expensive
- z-Buffer can be inaccurate with few bits
  - Really simple to implement though!
- Z-Buffer good for small, sparse polygons
- Why doing both can be good?

# Recap: Rasterization

- Simple: Painter's method
- Used today:  $z$ -Buffer
- Need to interpolate  $z$  across triangles
- Need to do this perspective-correct