COMP2310/COMP6310 Systems, Networks, & Concurrency

Convener: Prof John Taylor

Course Update

- Checkpoint 1 (7.5%) This week in Labs
 - Make sure you have completed labs 1-3
 - Review the lectures
- Quiz 1 (5%) Week 6 in labs
 - Cover all material in lectures and labs weeks 1-5

Exceptional Control Flow: Signals

Acknowledgement of material: With changes suited to ANU needs, the slides are obtained from Carnegie Mellon University: https://www.cs.cmu.edu/~213/

ECF Exists at All Levels of a System

- Exceptions
 - Hardware and operating system kernel software
- Process Context Switch
 - Hardware timer and kernel software
- Signals
 - Kernel software and application software
- Nonlocal jumps
 - Application code

Previous Lecture

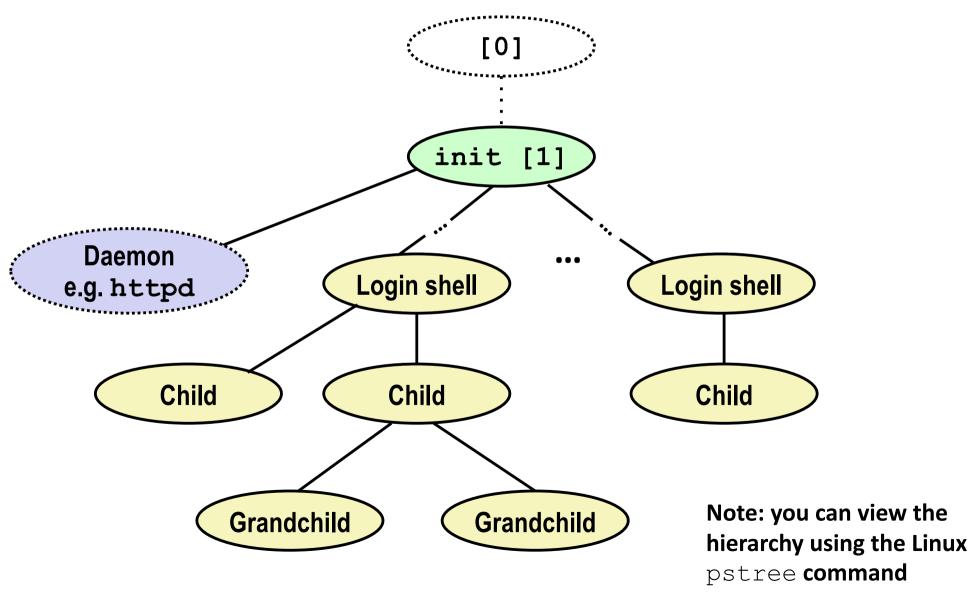
This Lecture

Textbook and supplemental slides

Today

- Shells
- Signals

Linux Process Hierarchy



Shell Programs

A shell is an application program that runs programs on behalf of the user.

```
    sh
    csh/tcsh
    bash
    Original Unix shell (Stephen Bourne, AT&T Bell Labs, 1977)
    BSD Unix C shell
    bash
    Bourne-Again" Shell (default Linux shell)
```

```
int main()
{
    char cmdline[MAXLINE]; /* command line */
    while (1) {
        /* read */
        printf("> ");
        Fgets(cmdline, MAXLINE, stdin);
        if (feof(stdin))
            exit(0);

        /* evaluate */
        eval(cmdline);
    }
}
```

Execution is a sequence of read/evaluate steps

Simple Shell eval Function

```
void eval(char *cmdline)
     char *argv[MAXARGS]; /* Argument list execve() */
     char buf[MAXLINE];
int bg;
pid_t pid;
/* Holds modified command line */
/* Should the job run in bg or fg? */
/* Process id */
     int bg;
pid_t pid;
     strcpy(buf, cmdline);
     bg = parseline(buf, argv);
if (argv[0] == NULL)
          return; /* Ignore empty lines */
     if (!builtin_command(argv)) {
          if ((pid = Fork()) == 0) { /* Child runs user job */
   if (execve(argv[0], argv, environ) < 0) {
      printf("%s: Command not found.\n", argv[0]);</pre>
                     exit(0):
          /* Parent waits for foreground job to terminate */
          if (!ba) {
                int status:
                if (waitpid(pid, &status, 0) < 0)</pre>
                     unix_error("waitfg: waitpid error");
          else
                printf("%d %s", pid, cmdline);
     return;
                                                                                  shellex.c
```

Problem with Simple Shell Example

Our example shell correctly waits for and reaps foreground jobs

- But what about background jobs?
 - Will become zombies when they terminate
 - Will never be reaped because shell (typically) will not terminate
 - Will create a memory leak that could run the kernel out of memory

ECF to the Rescue!

- Solution: Exceptional control flow
 - The kernel will interrupt regular processing to alert us when a background process completes
 - In Unix, the alert mechanism is called a signal

Today

- Shells
- Signals
- Nonlocal jumps

Signals

- A signal is a small message that notifies a process that an event of some type has occurred in the system
 - Akin to exceptions and interrupts
 - Sent from the kernel (sometimes at the request of another process) to a process
 - Signal type is identified by small integer ID's (1-30)
 - Only information in a signal is its ID and the fact that it arrived

ID	Name	Default Action	Corresponding Event
2	SIGINT	Terminate	User typed ctrl-c
9	SIGKILL	Terminate	Kill program (cannot override or ignore)
11	SIGSEGV	Terminate	Segmentation violation
14	SIGALRM	Terminate	Timer signal
17	SIGCHLD	Ignore	Child stopped or terminated

Signal Concepts: Sending a Signal

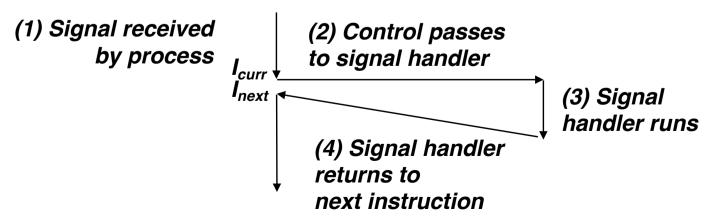
- Kernel sends (delivers) a signal to a destination process by updating some state in the context of the destination process
- Kernel sends a signal for one of the following reasons:
 - Kernel has detected a system event such as divide-by-zero (SIGFPE) or the termination of a child process (SIGCHLD)
 - Another process has invoked the kill system call to explicitly request the kernel to send a signal to the destination process

Signal Concepts: Receiving a Signal

A destination process receives a signal when it is forced by the kernel to react in some way to the delivery of the signal

Some possible ways to react:

- Ignore the signal (do nothing)
- Terminate the process (with optional core dump)
- Catch the signal by executing a user-level function called signal handler
 - Akin to a hardware exception handler being called in response to an asynchronous interrupt:



Signal Concepts: Pending and Blocked Signals

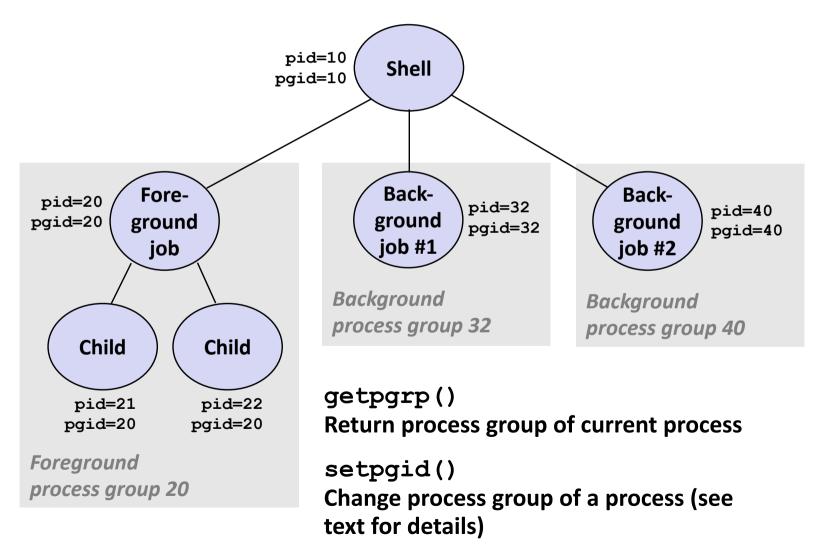
- A signal is pending if sent but not yet received
 - There can be at most one pending signal of any particular type
 - Important: Signals are not queued
 - If a process has a pending signal of type k, then subsequent signals of type k that are sent to that process are discarded
- A process can block the receipt of certain signals
 - Blocked signals can be delivered, but will not be received until the signal is unblocked
- A pending signal is received at most once

Signal Concepts: Pending/Blocked Bits

- Kernel maintains pending and blocked bit vectors in the context of each process
 - pending: represents the set of pending signals
 - Kernel sets bit k in pending when a signal of type k is delivered
 - Kernel clears bit k in **pending** when a signal of type k is received
 - blocked: represents the set of blocked signals
 - Can be set and cleared by using the sigprocmask function
 - Also referred to as the signal mask.

Sending Signals: Process Groups

Every process belongs to exactly one process group



Sending Signals with /bin/kill Program

/bin/kill program sends arbitrary signal to a process or process group

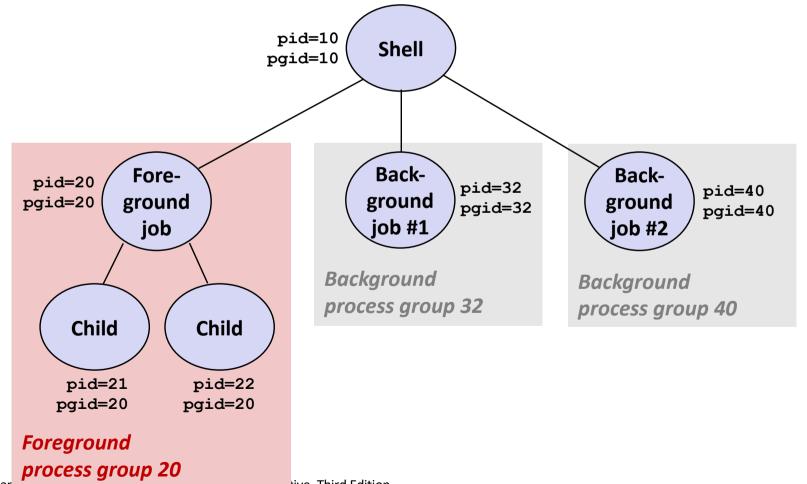
Examples

- bin/kill -9 24818 Send SIGKILL to process 24818
- /bin/kill -9 -24817
 Send SIGKILL to every process
 in process group 24817

```
linux> ./forks 16
Child1: pid=24818 pgrp=24817
Child2: pid=24819 pgrp=24817
linux> ps
  PID TTY
                   TIME CMD
24788 pts/2
               00:00:00 tcsh
24818 pts/2
               00:00:02 forks
24819 pts/2
               00:00:02 forks
24820 pts/2
               00:00:00 ps
linux> /bin/kill -9 -24817
linux> ps
  PID TTY
                   TIME CMD
24788 pts/2
               00:00:00 tcsh
24823 pts/2
               00:00:00 ps
linux>
```

Sending Signals from the Keyboard

- Typing ctrl-c (ctrl-z) causes the kernel to send a SIGINT (SIGTSTP) to every job in the foreground process group.
 - SIGINT default action is to terminate each process
 - SIGTSTP default action is to stop (suspend) each process



Example of ctrl-c and ctrl-z

```
bluefish> ./forks 17
Child: pid=28108 pgrp=28107
Parent: pid=28107 pgrp=28107
<types ctrl-z>
Suspended
bluefish> ps w
 PID TTY
             STAT
                    TIME COMMAND
27699 pts/8 Ss 0:00 -tcsh
28107 pts/8
          T 0:01 ./forks 17
28108 pts/8
          T 0:01 ./forks 17
28109 pts/8
             R+ 0:00 ps w
bluefish> fq
./forks 17
<types ctrl-c>
bluefish> ps w
 PID TTY
             STAT
                    TIME COMMAND
27699 pts/8 Ss 0:00 -tcsh
28110 pts/8 R+
                    0:00 ps w
```

STAT (process state) Legend:

First letter:

S: sleeping

T: stopped

R: running

Second letter:

s: session leader

+: foreground proc group

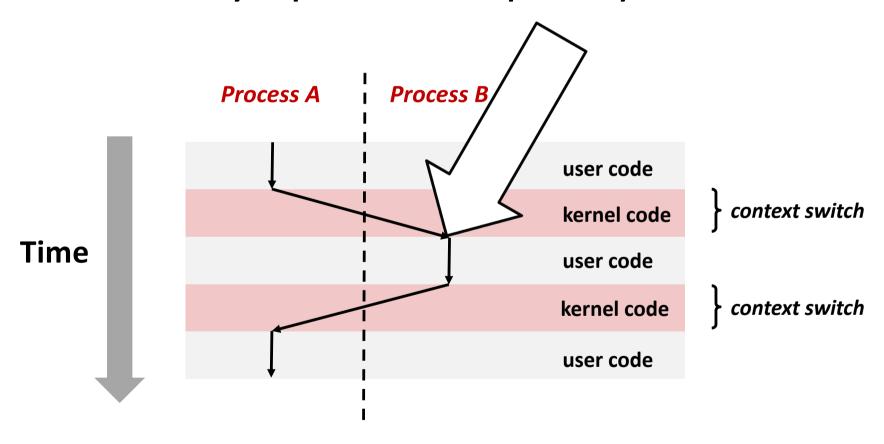
See "man ps" for more details

Sending Signals with kill Function

```
void fork12()
    pid_t pid[N];
    int i:
    int child status;
    for (i = 0; i < N; i++)
       if ((pid[i] = fork()) == 0) {
           /* Child: Infinite Loop */
           while(1)
    for (i = 0; i < N; i++) {
       printf("Killing process %d\n", pid[i]);
        kill(pid[i], SIGINT);
    for (i = 0; i < N; i++) {
        pid_t wpid = wait(&child_status);
       if (WIFEXITED(child_status))
           printf("Child %d terminated with exit status %d\n",
                  wpid, WEXITSTATUS(child status));
       else
           printf("Child %d terminated abnormally\n", wpid);
                                                            forks.c
```

Receiving Signals

 Suppose kernel is returning from an exception handler and is ready to pass control to process p



Receiving Signals

- Suppose kernel is returning from an exception handler and is ready to pass control to process p
- Kernel computes pnb = pending & ~blocked
 - The set of pending nonblocked signals for process p
- If (pnb == 0)
 - Pass control to next instruction in the logical flow for p
- Else
 - Choose least nonzero bit k in pnb and force process p to receive signal k
 - The receipt of the signal triggers some action by p
 - Repeat for all nonzero k in pnb
 - Pass control to next instruction in logical flow for p

Default Actions

- Each signal type has a predefined default action, which is one of:
 - The process terminates
 - The process stops until restarted by a SIGCONT signal
 - The process ignores the signal

Installing Signal Handlers

- The signal function modifies the default action associated with the receipt of signal signum:
 - handler_t *signal(int signum, handler_t *handler)

Different values for handler:

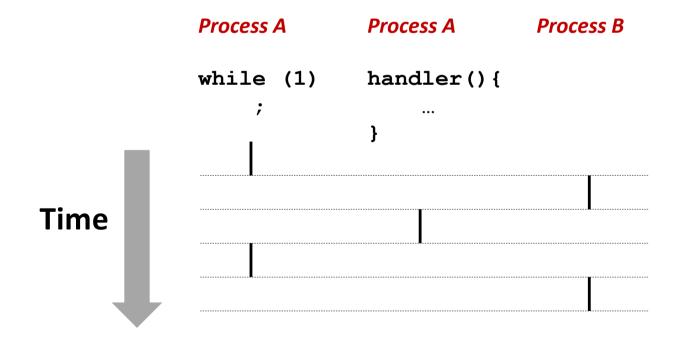
- SIG_IGN: ignore signals of type signum
- SIG_DFL: revert to the default action on receipt of signals of type signum
- Otherwise, handler is the address of a user-level signal handler
 - Called when process receives signal of type signum
 - Referred to as "installing" the handler
 - Executing handler is called "catching" or "handling" the signal
 - When the handler executes its return statement, control passes back to instruction in the control flow of the process that was interrupted by receipt of the signal

Signal Handling Example

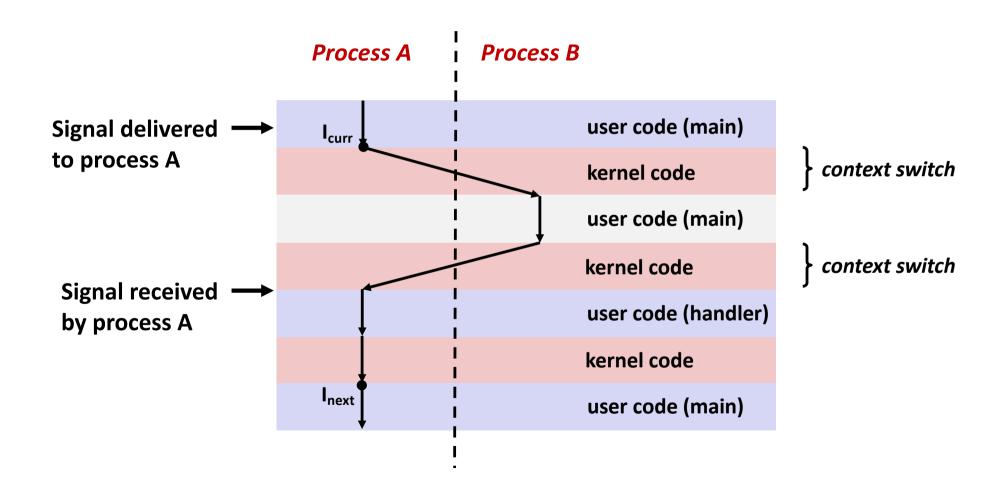
```
void sigint_handler(int sig) /* SIGINT handler */
   printf("So you think you can stop the bomb with ctrl-c, do
you?\n");
   sleep(2);
   printf("Well...");
   fflush(stdout);
   sleep(1);
   printf("OK. :-)\n");
   exit(0);
int main()
   /* Install the SIGINT handler */
    if (signal(SIGINT, sigint_handler) == SIG_ERR)
       unix_error("signal error");
   /* Wait for the receipt of a signal */
   pause();
    return 0:
```

Signals Handlers as Concurrent Flows

 A signal handler is a separate logical flow (not a process) that runs concurrently with the main program

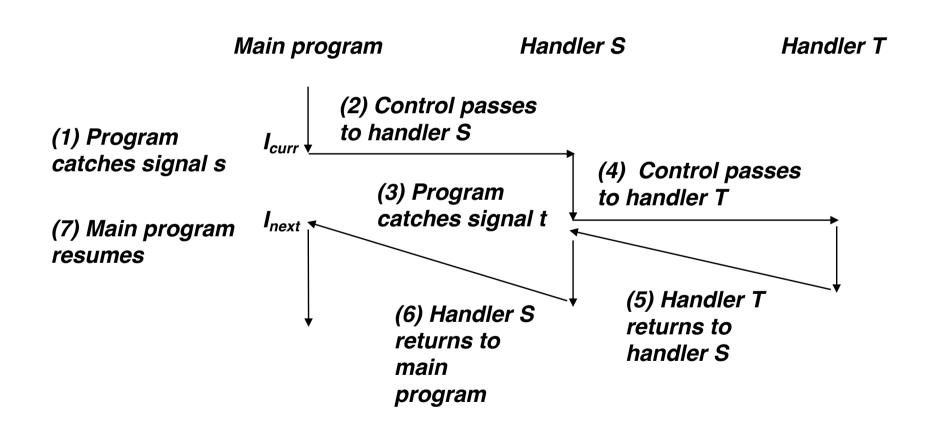


Another View of Signal Handlers as Concurrent Flows



Nested Signal Handlers

Handlers can be interrupted by other handlers



Blocking and Unblocking Signals

Implicit blocking mechanism

- Kernel blocks any pending signals of type currently being handled.
- E.g., A SIGINT handler can't be interrupted by another SIGINT

Explicit blocking and unblocking mechanism

sigprocmask function

Supporting functions

- sigemptyset Create empty set
- sigfillset Add every signal number to set
- sigaddset Add signal number to set
- sigdelset Delete signal number from set

Temporarily Blocking Signals

```
sigset_t mask, prev_mask;
Sigemptyset(&mask);
Sigaddset(&mask, SIGINT);

/* Block SIGINT and save previous blocked set */
Sigprocmask(SIG_BLOCK, &mask, &prev_mask);

/* Code region that will not be interrupted by SIGINT

*/

/* Restore previous blocked set, unblocking SIGINT */
Sigprocmask(SIG_SETMASK, &prev_mask, NULL);
```

Safe Signal Handling

- Handlers are tricky because they are concurrent with main program and share the same global data structures.
 - Shared data structures can become corrupted.
- We'll explore concurrency issues later.
- For now here are some guidelines to help you avoid trouble.

Guidelines for Writing Safe Handlers

- G0: Keep your handlers as simple as possible
 - e.g., Set a global flag and return
- G1: Call only async-signal-safe functions in your handlers
 - printf, sprintf, malloc, and exit are not safe!
- G2: Save and restore errno on entry and exit
 - So that other handlers don't overwrite your value of errno
- G3: Protect accesses to shared data structures by temporarily blocking all signals.
 - To prevent possible corruption
- G4: Declare global variables as volatile
 - To prevent compiler from storing them in a register
- G5: Declare global flags as volatile sig_atomic_t
 - flag: variable that is only read or written (e.g. flag = 1, not flag++)
 - Flag declared this way does not need to be protected like other globals

Async-Signal-Safety

- Function is async-signal-safe if either reentrant (e.g., all variables stored on stack frame, CS:APP3e 12.7.2) or non-interruptible by signals.
- Posix guarantees 117 functions to be async-signal-safe
 - Source: "man 7 signal"
 - Popular functions on the list:
 - _ exit, write, wait, waitpid, sleep, kill
 - Popular functions that are not on the list:
 - printf, sprintf, malloc, exit
 - Unfortunate fact: write is the only async-signal-safe output function

Safely Generating Formatted Output

 Use the reentrant SIO (Safe I/O library) from csapp.c in your handlers.

```
ssize_t sio_puts(char s[]) /* Put string */
ssize_t sio_putl(long v) /* Put long */
void sio error(char s[]) /* Put msg & exit */
```

```
void sigint_handler(int sig) /* Safe SIGINT handler */
{
    Sio_puts("So you think you can stop the bomb with
ctrl-c, do you?\n");
    sleep(2);
    Sio_puts("Well...");
    sleep(1);
    Sio_puts("OK. :-)\n");
    _exit(0);
}
```

int ccount = 0; void child_handler(int sig) { int olderrno = errno: pid t pid; if ((pid = wait(NULL)) < 0)</pre> Sio_error("wait error"); ccount--; Sio puts("Handler reaped child "); Sio_putl((long)pid); Sio_puts(" \n"); sleep(1); errno = olderrno; } void fork14() { pid_t pid[N]; int i: ccount = N;Signal(SIGCHLD, child_handler); for (i = 0; i < N; i++) { if ((pid[i] = Fork()) == 0) { Sleep(1); exit(0); /* Child exits */ while (ccount > 0) /* Parent spins */

Correct Signal Handling

- Pending signals are not queued
 - For each signal type, one bit indicates whether or not signal is pending...
 - ...thus at most one pending signal of any particular type.
- You can't use signals to count events, such as children terminating.

whaleshark> ./forks 14
Handler reaped child 23240
Handler reaped child 23241

forks.c

Correct Signal Handling

- Must wait for all terminated child processes
 - Put wait in a loop to reap all terminated children

```
void child_handler2(int sig)
    int olderrno = errno;
    white ((pid = wait(NULL)) > 0) {
         Sio_puts("Handler reaped child ");
        Sio_putl((long)pid);
Sio_puts(" \n");
        (errno != ECHILD)
Sio_error("wait error");
    errno = olderrno;
                                  whaleshark> ./forks 15
                                  Handler reaped child 23246
                                  Handler reaped child 23247
                                  Handler reaped child 23248
                                  Handler reaped child 23249
                                  Handler reaped child 23250
                                  whaleshark>
```

Portable Signal Handling

- Ugh! Different versions of Unix can have different signal handling semantics
 - Some older systems restore action to default after catching signal
 - Some interrupted system calls can return with errno == EINTR
 - Some systems don't block signals of the type being handled
- Solution: sigaction

```
handler_t *Signal(int signum, handler_t *handler)
{
    struct sigaction action, old_action;

    action.sa_handler = handler;
    sigemptyset(&action.sa_mask); /* Block sigs of type being handled */
    action.sa_flags = SA_RESTART; /* Restart syscalls if possible */

    if (sigaction(signum, &action, &old_action) < 0)
        unix_error("Signal error");
    return (old_action.sa_handler);
}</pre>
```

Synchronizing Flows to Avoid Races

Simple shell with a subtle synchronization error because it assumes parent runs before child.

```
int main(int argc, char **argv)
{
   int pid;
   sigset_t mask_all, prev_all;
   Sigfillset(&mask all);
   Signal(SIGCHLD, handler);
   initjobs(); /* Initialize the job list */
   while (1) {
       if ((pid = Fork()) == 0) { /* Child */
           Execve("/bin/date", argv, NULL);
       Sigprocmask(SIG_BLOCK, &mask_all, &prev_all); /* Parent */
       addjob(pid); /* Add the child to the job list */
       Sigprocmask(SIG_SETMASK, &prev_all, NULL);
   exit(0);
                                                        procmask1.c
```

Synchronizing Flows to Avoid Races

SIGCHLD handler for a simple shell

```
void handler(int sig)
{
   int olderrno = errno;
   sigset_t mask_all, prev_all;
   pid t pid;
   Sigfillset(&mask_all);
   while ((pid = waitpid(-1, NULL, 0)) > 0) { /* Reap child */
       Sigprocmask(SIG_BLOCK, &mask_all, &prev_all);
       deletejob(pid); /* Delete the child from the job list */
       Sigprocmask(SIG_SETMASK, &prev_all, NULL);
      (errno != ECHILD)
       Sio_error("waitpid error");
   errno = olderrno;
                                                      procmask1.c
```

Corrected Shell Program without Race

```
int main(int argc, char **argv)
   int pid:
    sigset_t mask_all, mask_one, prev_one;
   Sigfillset(&mask_all);
   Sigemptyset(&mask_one);
   Sigaddset(&mask_one, SIGCHLD);
   Signal(SIGCHLD, handler);
    initjobs(); /* Initialize the job list */
   while (1) {
       Sigprocmask(SIG_BLOCK, &mask_one, &prev_one); /* Block SIGCHLD */
       if ((pid = Fork()) == 0) { /* Child process */
           Sigprocmask(SIG_SETMASK, &prev_one, NULL); /* Unblock SIGCHLD */
           Execve("/bin/date", argv, NULL);
       Sigprocmask(SIG_BLOCK, &mask_all, NULL); /* Parent process */
       addjob(pid); /* Add the child to the job list */
       Sigprocmask(SIG_SETMASK, &prev_one, NULL); /* Unblock SIGCHLD */
   exit(0);
                                                                procmask2.c
```

Explicitly Waiting for Signals

Handlers for program explicitly waiting for SIGCHLD to arrive.

```
volatile sig_atomic_t pid;

void sigchld_handler(int s)
{
    int olderrno = errno;
    pid = Waitpid(-1, NULL, 0); /* Main is waiting for nonzero pid

*/
    errno = olderrno;
}

void sigint_handler(int s)
{
}

waitforsignal.c
```

Explicitly Waiting for Signals

```
Similar to a shell waiting
int main(int argc, char **argv) {
                                                  for a foreground job to
    sigset t mask, prev;
                                                 terminate.
   Signal(SIGCHLD, sigchld_handler);
   Signal(SIGINT, sigint_handler);
   Sigemptyset(&mask);
   Sigaddset(&mask, SIGCHLD);
   while (1) {
        Sigprocmask(SIG_BLOCK, &mask, &prev); /* Block SIGCHLD */
        if (Fork() == 0) /* Child */
            exit(0):
        /* Parent */
        pid = 0:
        Sigprocmask(SIG_SETMASK, &prev, NULL); /* Unblock SIGCHLD */
        /* Wait for SIGCHLD to be received (wasteful!) */
        while (!pid)
        /* Do some work after receiving SIGCHLD */
        printf(".");
   exit(0):
}
                                                         waitforsignal.c
```

Explicitly Waiting for Signals

- Program is correct, but very wasteful
- Other options:

```
while (!pid) /* Race! */
  pause();
```

```
while (!pid) /* Too slow! */
    sleep(1);
```

Solution: sigsuspend

Waiting for Signals with sigsuspend

- int sigsuspend(const sigset_t *mask)
- Equivalent to atomic (uninterruptable) version of:

```
sigprocmask(SIG_BLOCK, &mask, &prev);
pause();
sigprocmask(SIG_SETMASK, &prev, NULL);
```

Waiting for Signals with sigsuspend

```
int main(int argc, char **argv) {
    sigset t mask, prev;
   Signal(SIGCHLD, sigchld handler);
   Signal(SIGINT, sigint handler);
   Sigemptyset(&mask);
   Sigaddset(&mask, SIGCHLD);
   while (1) {
        Sigprocmask(SIG BLOCK, &mask, &prev); /* Block SIGCHLD */
        if (Fork() == 0) /* Child */
            exit(0);
       /* Wait for SIGCHLD to be received */
       pid = 0;
        while (!pid)
            Sigsuspend(&prev);
       /* Optionally unblock SIGCHLD */
        Sigprocmask(SIG SETMASK, &prev, NULL);
        /* Do some work after receiving SIGCHLD */
       printf(".");
   exit(0);
                                                                sigsuspend.c
```

Today

- Shells
- Signals

Summary

- Signals provide process-level exception handling
 - Can generate from user programs
 - Can define effect by declaring signal handler
 - Be very careful when writing signal handlers
 - ...concurrency