

# **COMP2310/COMP6310**

## **Systems, Networks, & Concurrency**

Convener: Prof John Taylor

# Course Update

- **Checkpoint 2 – Marking out**
- **Quiz 2 – Marks out end of the week**
- **Assignment 2 – Released**
  - Due 2<sup>nd</sup> November 11:59pm
  - Recommend that you start early!
- **Final Exam – Closed Book**
  - Wednesday 12/11/2025 2-5:15pm
  - Melville Hall
- **SELT Survey available**

# Today

- **Automating the Build Process**
  - make
  - cmake
- **Strings and concurrency**
- **The Future**
- **Final exam review**

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## **Automating the build process**

# Automate the build Process: Make

**Make is a build automation tool that uses Makefiles to define build rules.**

- **Configuration:** Requires manually written Makefiles.
- **Build Process:**
  - **Compilation:** Defines rules to compile source files into object files.
  - **Linking:** Specifies how to link object files into executables or libraries.
- **Pros:**
  - Simple and straightforward for small projects
  - Widely used and well-documented
  - Rebuilds only what is needed
- **Cons:**
  - Manual Makefile maintenance can be error-prone.
  - Less suitable for large, complex projects.

# Automate the build Process: cmake

`cmake` is a cross-platform build system generator that produces build files for various tools (e.g., Make, Ninja, Visual Studio)

- **Uses CMakeLists.txt files to define project structure and build rules**
- **Build Process:**
  - **Compilation:** Automatically generates Makefiles or other build scripts.
  - **Linking:** Simplifies linking with `target_link_libraries` and other commands
- **Pros:**
  - Automates build configuration, reducing manual effort
  - Supports complex projects and multiple platforms
  - Easier integration with external libraries
- **Cons:**
  - Learning curve for beginners
  - Requires `cmake` installation

# CMakeLists.txt file for a simple C project

```
# Specify the minimum version of CMake required
cmake_minimum_required(VERSION 3.10)

# Define the project name and the programming language
project(MyProject C)

# Add an executable target
add_executable(MyExecutable main.c)

# Specify include directories to search for header file
include_directories(${PROJECT_SOURCE_DIR}/include)

# Link libraries (if any)
target_link_libraries(MyExecutable m)    # Example: linking
                                         the math library

# Set C standard
set(CMAKE_C_STANDARD 99)
set(CMAKE_C_STANDARD_REQUIRED True)
```

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## **Strings and concurrency**

# Combining Linked Lists and Threads

- Multiple threads can operate on different parts of a linked list concurrently
- You can use mutexes to protect the linked list during insertions, deletions, and updates
- You can select which region of the list to lock
  - *Whole List Locking*: Lock the entire list for any operation - simpler but less efficient
  - *Segment Locking*: Divide the list into segments, each protected by a separate mutex - more efficient if access is close to uniform
  - *Fine-Grained Locking*: Lock individual nodes or small groups of nodes – the most efficient but complex
- Proper synchronization can improve performance by allowing more parallelism while avoiding race conditions

# Update the list with a single lock

```
void* update_whole_list(void* arg) {  
    int new_availability = *(int*)arg;  
    pthread_mutex_lock(&list_mutex);  
    Node* current = head;  
    while (current != NULL) {  
        current->availability = new_availability;  
        current = current->next;  
    }  
    pthread_mutex_unlock(&list_mutex);  
    return NULL;  
}
```

# Each thread updates a single element

```
void update_list_individual_elements(int num_threads, int
new_availability) {
    pthread_t threads[num_threads];
    Element elements[num_threads];
    Node* current = head;
    for (int i = 0; i < num_threads && current != NULL; i++) {
        elements[i].node = current;
        elements[i].new_availability = new_availability;
        pthread_create(&threads[i], NULL, update_element,
&elements[i]);
        current = current->next;
    }
    for (int i = 0; i < num_threads; i++) {
        pthread_join(threads[i], NULL);
    }
}
```

# Each thread updates a single element

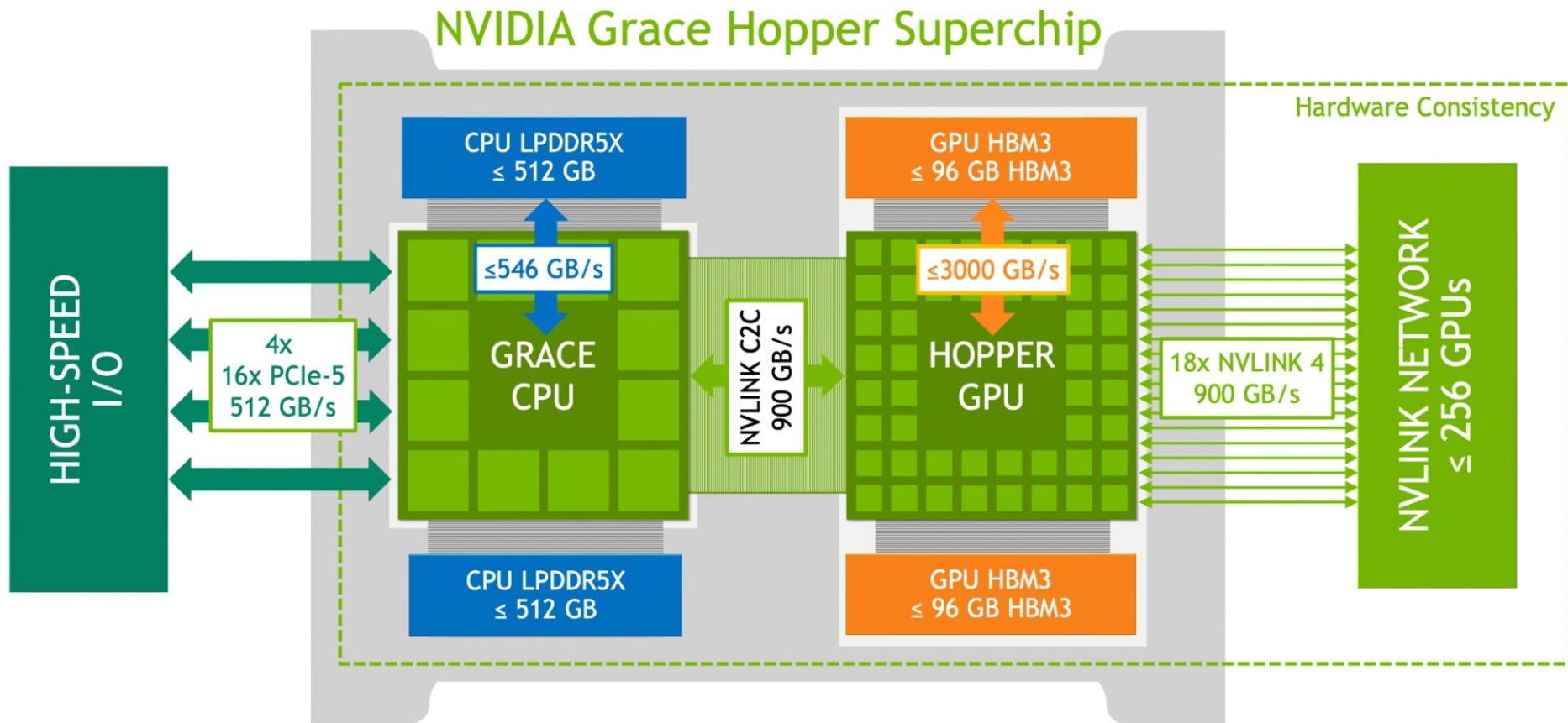
```
typedef struct {
    Node* node;
    int new_availability;
} Element;

void* update_element(void* arg) {
    Element* element = (Element*)arg;
    pthread_mutex_lock(&list_mutex);
    element->node->availability = element->new_availability;
    pthread_mutex_unlock(&list_mutex);
    return NULL;
}
```

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## **The Future**

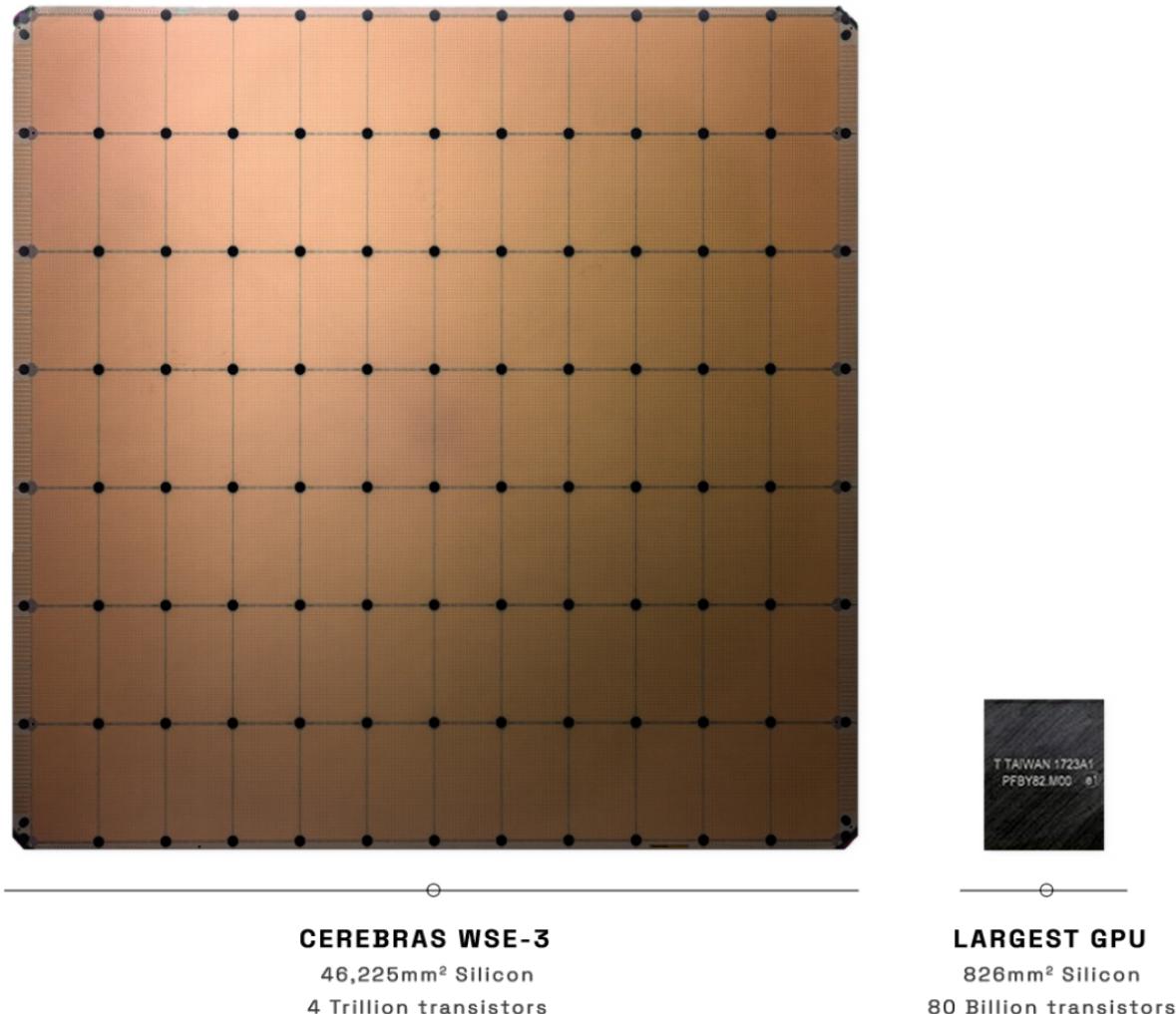
# Heterogenous Computing: Another step change



# CEREBRAS WSE-3

## The WSE-3

- 900,000 AI cores onto a single processor
- Each core on the WSE is independently programmable
- 44GB on-chip SRAM (21PB/s)
- Optimized for the tensor-based, sparse linear algebra operations that underpin neural network training and inference for deep learning
- LLM Sparse Llama: 70% Smaller, 3x Faster, Full Accuracy



# Transformative Impact of AI

- **OS-level AI features** for automation, predictive maintenance, and adaptive resource management are emerging.
- **Self-healing networks** using AI/ML for predictive analytics, anomaly detection, and traffic optimization.
- **Heterogeneous Computing** combining CPUs, GPUs, and accelerators for AI and HPC workloads.

# **COMP2310/6310**

## **Final Exam Review**

# Final Exam

## ➤ Everything!

everything : [Overview](#) [Similar and opposite words](#) [Usage examples](#)

### Dictionary

Definitions from Oxford Languages · [Learn more](#)

 **everything**  
pronoun

1. all things.  
"they did everything together"

Similar: [each item](#) [each thing](#) [every article](#) [every single thing](#) [the lot](#) [▼](#)

2. the current situation; life in general.  
"how's everything?"

Translate to [Choose language](#) ▾

## ➤ Inclusive of week 12

## ➤ Every lab

## ➤ Every slide - covering CS:APP Textbook Chapters

# Course Topics

- C to x86\_64
- Processes and Signals
- Locality and Cache Memories
- Disk storage
- Linking
- Virtual Memory
- I/O
- Networking
- Concurrent programming
- Scientific debugging

# Final Exam

- **What to study?**
  - Chapters posted on the course website
- **How to Study?**
  - Read each chapter many times, work practice problems in the book and do problems from course website.
  - The Practice problems allow you to get a feel for the questions on the exam

# Topics for Today

- C to x86\_64
- Virtual Memory
- I/O Redirection
- Threading
- Processes and Signals
- Deadlock
- Hyperthreading
- Sequential consistency
  
- Note: other topics will appear on the final exam!

## Cto x86\_64

- The following C code declares a structure. The declaration embeds one structure within another, just as arrays can be part of structures, and we can have arrays within arrays (e.g., two-dimensional arrays). The procedure on the left operates on the `comp2310` structure. We have intentionally omitted some expressions.

```
struct comp2310 {  
    short *p;  
    struct {  
        short x;  
        short y;  
    } s;  
    struct comp2310 *next;  
};
```

```
void init(struct comp2310 *cp) {  
    cp->s.y = ;  
    cp->p = ;  
    cp->next = ;  
}
```

- What are the offsets (in bytes) of the following fields?
  - p
  - s.x
  - s.y
  - next
- How many total bytes does the structure require?

## Cto x86\_64

- The compiler generates the following code for `init`

```
# void init(struct comp2310 *cp)
# cp in %rdi
1 init:
2     movl 8(%rdi), %eax
3     movl %eax, 10(%rdi)
4     leaq 10(%rdi), %rax
5     movq %rax, (%rdi)
6     movq %rdi, 12(%rdi)
7     ret
```

- Fill in the missing expressions in the C code for `init` based on this information.

# Assembly Loops

- Recognize common assembly instructions
- Know the uses of all registers in 64 bit systems
- Understand how different control flow is turned into assembly
  - For, while, do, if-else, switch, etc
- Be very comfortable with pointers and dereferencing
  - The use of parens in mov commands.
    - %rax vs. (%rax)
  - The options for memory addressing modes:
    - R(Rb, Ri, S)
    - lea vs. mov

# Array Access

- A suggested method for these problems:
  - Start with the C code
  - Then look at the assembly Work backwards!
  - Understand how in assembly, a logical 2D array is implemented as a 1D array, using the width of the array as a multiplier for access

[0][0] = [0]	[0][1] = [1]	[0][2] = [2]	[0][3] = [3]
[1][0] = [4]	[1][1] = [5]	[1][2] = [6]	[1][3] = [7]
[2][0] = [8]	[2][1] = [9]	[2][2] = [10]	[2][3] = [11]

$$[0][2] = 0 * 4 + 2 = 2$$

$$[1][3] = 1 * 4 + 3 = 7$$

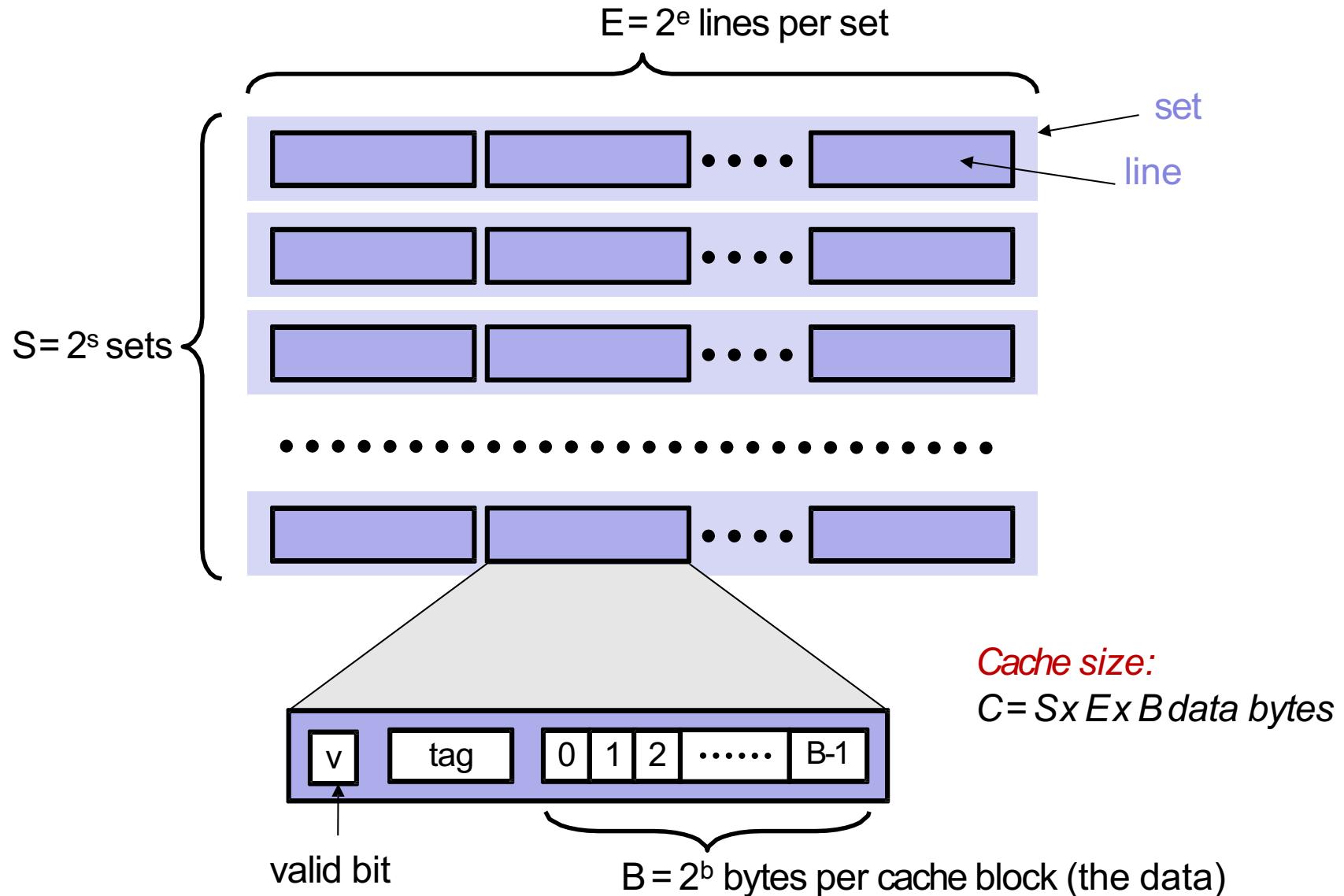
$$[2][1] = 2 * 4 + 1 = 9$$

$$[i][j] = i * \text{width of array} + j$$

# Caching Concepts

- **Dimensions: S, E, B**
  - S: Number of sets
  - E: Associativity – number of lines per set
  - B: Block size – number of bytes per block (1 block per line)
- **Given Values for S,E,B,m**
  - Find which address maps to which set
  - Is it a Hit/Miss? Is there an eviction?
  - Hit rate/Miss rate
- **Types of misses**
  - Which types can be avoided?
  - What cache parameters affect types/number of misses?
- **Understanding of Locality**

# General Cache Organization (S, E, B)



# Locality Example

**Question:** Can you permute the loops so that the function scans the 3-d array  $a$  with a stride-1 reference pattern (and thus has good spatial locality)?

```
int sum_array_3d(int a[M][N][N])
{
    int i, j, k, sum = 0;

    for (i = 0; i < N; i++)
        for (j = 0; j < N; j++)
            for (k = 0; k < M; k++)
                sum += a[k][i][j];
    return sum;
}
```

# Caching

The machine that you are working on has a 64KB direct mapped cache with 4 byte lines

A. What percentage of the writes in the following code will miss in the cache?

```
for (j=0; j < 640; j++) {  
    for (i=0; i < 480; i++){  
        buffer[i][j].r = 0;  
        buffer[i][j].g = 0;  
        buffer[i][j].b = 0;  
        buffer[i][j].a = 0;  
    }  
}
```

Miss rate for writes to **buffer**: \_\_\_\_\_ %

# Virtual Memory

## Problem 9. (12 points):

*Address translation.* This problem concerns the way virtual addresses are translated into physical addresses. Imagine a system has the following parameters:

- Virtual addresses are 20 bits wide.
- Physical addresses are 18 bits wide.
- The page size is 1024 bytes.
- The TLB is 2-way set associative with 16 total entries.

The contents of the TLB and the first 32 entries of the page table are shown as follows. All numbers are given in hexadecimal.

TLB			
Index	Tag	PPN	Valid
0	03	C3	1
	01	71	0
1	00	28	1
	01	35	1
2	02	68	1
	3A	F1	0
3	03	12	1
	02	30	1
4	7F	05	0
	01	A1	0
5	00	53	1
	03	4E	1
6	1B	34	0
	00	1F	1
7	03	38	1
	32	09	0

Page Table					
VPN	PPN	Valid	VPN	PPN	Valid
000	71	1	010	60	0
001	28	1	011	57	0
002	93	1	012	68	1
003	AB	0	013	30	1
004	D6	0	014	0D	0
005	53	1	015	2B	0
006	1F	1	016	9F	0
007	80	1	017	62	0
008	02	0	018	C3	1
009	35	1	019	04	0
00A	41	0	01A	F1	1
00B	86	1	01B	12	1
00C	A1	1	01C	30	0
00D	D5	1	01D	4E	1
00E	8E	0	01E	57	1
00F	D4	0	01F	38	1

**Part 1**

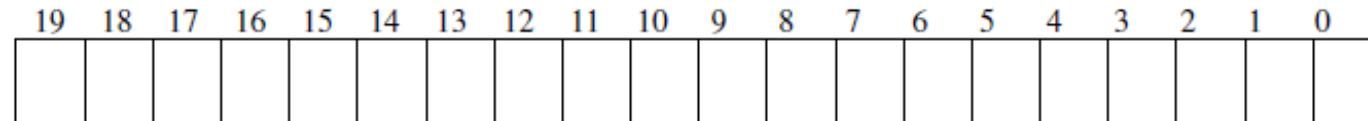
1. The diagram below shows the format of a virtual address. Please indicate the following fields by labeling the diagram:

*VPO* The virtual page offset

*VPN* The virtual page number

*TLBI* The TLB index

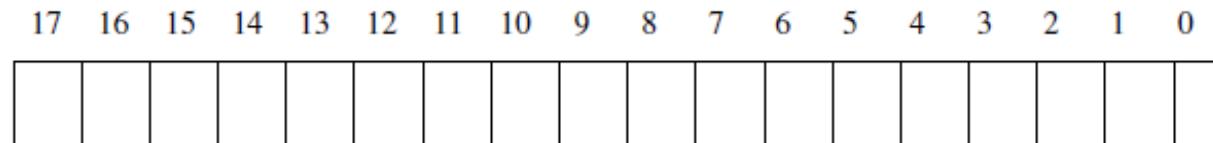
*TLBT* The TLB tag



2. The diagram below shows the format of a physical address. Please indicate the following fields by labeling the diagram:

*PPO* The physical page offset

*PPN* The physical page number



**Part 2**

For the given virtual addresses, please indicate the TLB entry accessed and the physical address. Indicate whether the TLB misses and whether a page fault occurs. If there is a page fault, enter “-” for “PPN” and leave the physical address blank.

**Virtual address:** 078E6

1. Virtual address (one bit per box)

19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
<input type="text"/>																			

2. Address translation

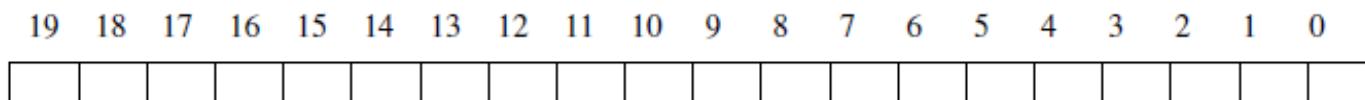
Parameter	Value	Parameter	Value
VPN	0x	TLB Hit? (Y/N)	
TLB Index	0x	Page Fault? (Y/N)	
TLB Tag	0x	PPN	0x

3. Physical address(one bit per box)

17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
<input type="text"/>																		

**Virtual address:** 04AA4

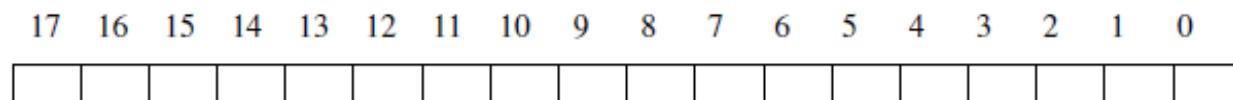
1. Virtual address (one bit per box)



2. Address translation

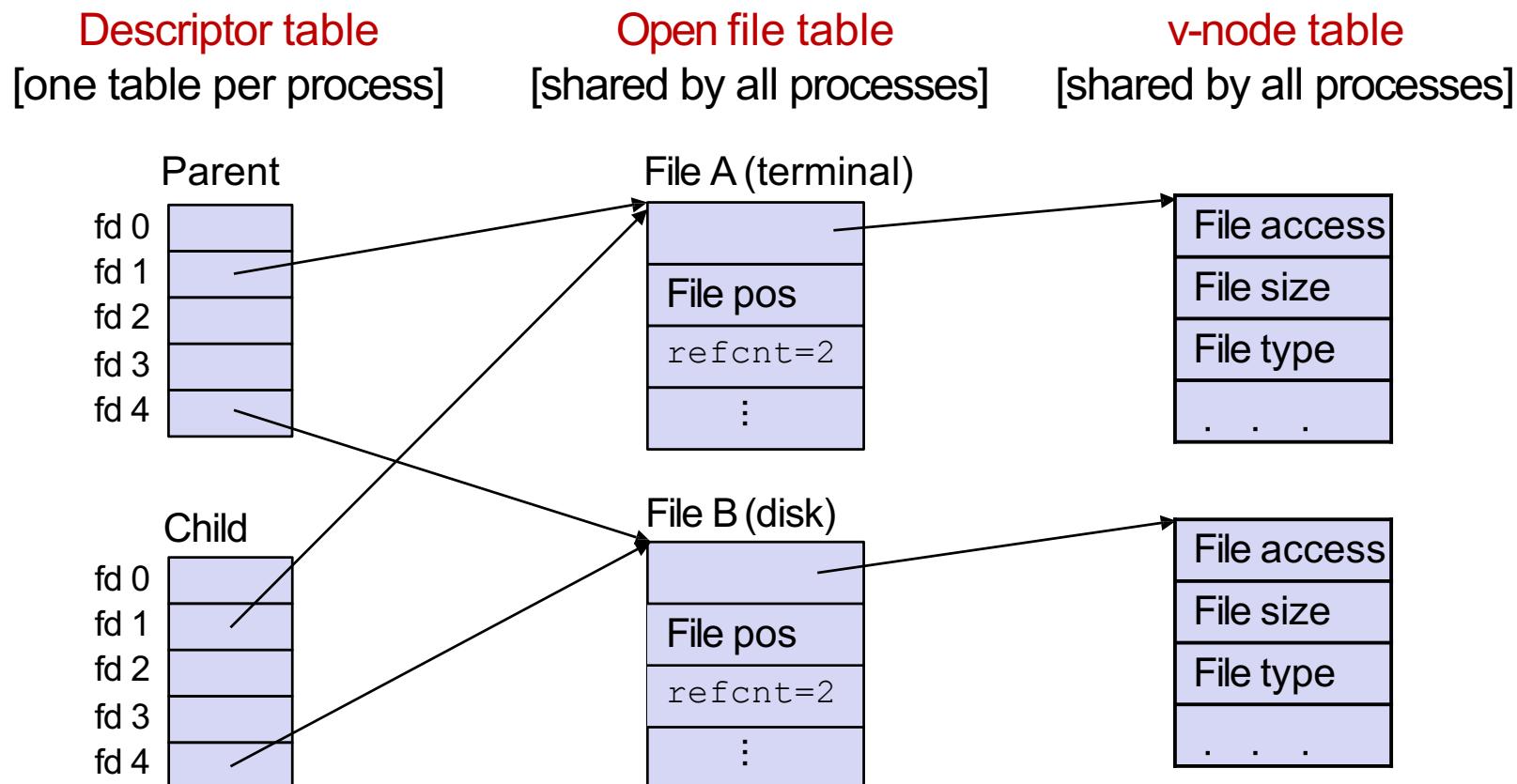
Parameter	Value	Parameter	Value
VPN	0x	TLB Hit? (Y/N)	
TLB Index	0x	Page Fault? (Y/N)	
TLB Tag	0x	PPN	0x

3. Physical address(one bit per box)



# How Processes Share Files: fork

- A child process inherits its parent's open files
- **After fork:**
  - Child's table same as parent's, and +1 to each refcnt



# I/O Redirection

- Question: How does a shell implement I/O redirection?

```
linux> ls > foo.txt
```

- Answer: By calling the `dup2 (oldfd, newfd)` function

- Copies (per-process) descriptor table entry `oldfd` to entry `newfd`

Descriptor table  
*before* `dup2 (4, 1)`

fd 0	
fd 1	a
fd 2	
fd 3	
fd 4	b



Descriptor table  
*after* `dup2 (4, 1)`

fd 0	
fd 1	b
fd 2	
fd 3	
fd 4	b

# I/O Redirection

## ■ Final Exam Question

### Problem 6. (10 points):

#### *File I/O*

The following problems refer to a file called `numbers.txt`, with contents the ASCII string 0123456789.

You may assume calls to `read()` are atomic with respect to each other. The following file, `read_and_print_one.h`, is compiled with each of the following code files.

```
#ifndef READ_AND_PRINT_ONE
#define READ_AND_PRINT_ONE
#include <stdio.h>
#include <unistd.h>

static inline void read_and_print_one(int fd) {
    char c;
    read(fd, &c, 1);
    printf("%c", c); fflush(stdout);
}
#endif
```

**■ A. List all outputs of the following code.**

```
#include "read_and_print_one.h"
#include <stdlib.h>
#include <fcntl.h>

int main() {
    int file1 = open("numbers.txt", O_RDONLY);
    int file2;
    int file3 = open("numbers.txt", O_RDONLY);
    file2 = dup2(file3, file2);

    read_and_print_one(file1);
    read_and_print_one(file2);
    read_and_print_one(file3);
    read_and_print_one(file2);
    read_and_print_one(file1);
    read_and_print_one(file3);

    return 0;
}
```

**■ B. List all outputs of the following code.**

```
#include "read_and_print_one.h"
#include <stdlib.h>
#include <fcntl.h>
#include <sys/types.h>
#include <sys/wait.h>

int main() {
    int file1;
    int file2;
    int file3;
    int pid;

    file1 = open("numbers.txt", O_RDONLY);
    file3 = open("numbers.txt", O_RDONLY);

    file2 = dup2(file3, file2);

    read_and_print_one(file1);
    read_and_print_one(file2);

    pid = fork();

    if (!pid) {
        read_and_print_one(file3);
        close(file3);
        file3 = open("numbers.txt", O_RDONLY);
        read_and_print_one(file3);
    } else {
        wait(NULL);
        read_and_print_one(file3);
        read_and_print_one(file2);
        read_and_print_one(file1);
    }

    read_and_print_one(file3);

    return 0;
}
```

# Threading

## ■ Final Exam Question

### Problem 10. (10 points):

*Concurrency, races, and synchronization.* Consider a simple concurrent program with the following specification: The main thread creates two peer threads, passing each peer thread a unique integer *thread ID* (either 0 or 1), and then waits for each thread to terminate. Each peer thread prints its thread ID and then terminates.

Each of the following programs attempts to implement this specification. However, some are incorrect because they contain a race on the value of *my id* that makes it possible for one or more peer threads to print an incorrect thread ID. Except for the race, each program is otherwise correct.

You are to indicate whether or not each of the following programs contains such a race on the value of *my id*. You will be graded on each subproblem as follows:

A. Does the following program contain a race on the value of `myid`?      Yes      No

```
void *foo(void *vargp) {
    int myid;
    myid = *((int *)vargp);
    Free(vargp);
    printf("Thread %d\n", myid);
}

int main() {
    pthread_t tid[2];
    int i, *ptr;

    for (i = 0; i < 2; i++) {
        ptr = Malloc(sizeof(int));
        *ptr = i;
        Pthread_create(&tid[i], 0, foo, ptr);
    }
    Pthread_join(tid[0], 0);
    Pthread_join(tid[1], 0);
}
```

# Processes and Signals

## ■ Final Exam Question

### Problem 8. (10 points):

*Exceptional control flow.* Consider the following C program. (For space reasons, we are not checking error return codes, so assume that all functions return normally.)

```
int main()
{
    int val = 2;

    printf("%d", 0);
    fflush(stdout);

    if (fork() == 0) {
        val++;
        printf("%d", val);
        fflush(stdout);
    }
    else {
        val--;
        printf("%d", val);
        fflush(stdout);
        wait(NULL);
    }
    val++;
    printf("%d", val);
    fflush(stdout);
    exit(0);
}
```

For each of the following strings, circle whether (Y) or not (N) this string is a possible output of the program.  
You will be graded on each sub-problem as follows:

- If you circle no answer, you get 0 points.
- If you circle the right answer, you get 2 points.
- If you circle the wrong answer, you get –1 points (so don't just guess wildly).

A. 01432      Y      N

B. 01342      Y      N

C. 03142      Y      N

D. 01234      Y      N

E. 03412      Y      N

# Sequential Consistency

- Consider the execution of the following concurrent processes on two different processors, and A and B are originally cached by both processors with initial value of 0.

P1:            A = 0  
              . . . . .  
          A = 1;  
      if (B == 0) ...

P2:            B = 0  
              . . . . .  
          B = 1;  
      if (A == 0) ...

- Under sequential consistency which of the following outcomes are possible?

- (A)
- (B)
- (C)
- (D)

# Deadlock

## ■ Final Exam Question

### Problem 7. (14 points):

#### *Deadlocks and Deadlocks*

Two threads (X and Y) access shared variables A and B protected by mutex\_a and mutex\_b respectively.  
Assume all variable are declared and initialized correctly.

Thread X	Thread Y
P(&mutex_a);	P(&mutex_b);
A += 10;	B += 10;
P(&mutex_b);	P(&mutex_a);
B += 20;	A += 20;
V(&mutex_b);	V(&mutex_a);
A += 30;	B += 30;
V(&mutex_a);	V(&mutex_b);

- A. Show an execution of the threads resulting in a deadlock. Show the execution steps as follows

Thread X	Thread Y
<i>P(&amp;mutex_a)</i>	
<i>A+ = 10</i>	
<i>P(&amp;mutex_b)</i>	
	<i>P(&amp;mutex_b)</i>
...	
	...

Answer:

- B. There are different approaches to solve the deadlock problem. Modify the code above to show **two** approaches to prevent deadlocks. You can declare new mutex variables if required. Do not change the order or amount of the increments to A and B. Rather, change the locking behavior around them. The final values of A and B must still be guaranteed to be incremented by 60.

Answer:

# Thank you for participating in COMP2310 !

