



Multi-Agent Systems

Jordi Pascual – jordi.pascual@urv.cat

Presentation of the labs

MESIIA – Master's Degree in Computer Security Engineering and Artificial Intelligence MAI - Master's Degree in Artificial Intelligence

Outline

- 1. Course labs objective
- 2. URV Virtual Campus
- 3. Course timing and evaluation
- 4. Software requirements

1. Course labs objective

Design and develop a Multi-Agent System using the CrewAl framework

2. URV Virtual Campus

- All the material for the course will be available at the URV Virtual Campus (https://campusvirtual.urv.cat/)
- In the Practical part section, you will find all the materials related to the practical part of the course

3. Course timing and evaluation

| | | Lab/Practise | Comments |
|----|------------|--|----------|
| 1 | 25/09/2024 | Presentation of the lab sessions | 9 |
| 2 | 2/10/2024 | Defining agents and tasks | 18 |
| 3 | 9/10/2024 | Using tools | |
| 4 | 16/10/2024 | Creating custom tools | |
| 5 | 23/10/2024 | Leveraging tasks | |
| 6 | 30/10/2024 | Agent collaboration I | |
| 7 | 6/11/2024 | Task 1 presentations | 10% |
| 8 | 13/11/2024 | Agent collaboration II | |
| 9 | 20/11/2024 | Organising and training complex MAS projects | 3 |
| 10 | 27/11/2024 | Pipelines and routers | 18 |
| 11 | 4/12/2024 | Work session | |
| 12 | 11/12/2024 | Task 2 presentation | 10% |
| 13 | 18/12/2024 | Work session | 3 |
| 14 | 8/01/2025 | Work session | |
| 15 | 15/01/2025 | Practical work presentation | 35% |

4. Software requirements

You must install the following software:

- Python environment management: <u>conda</u> / <u>miniconda</u> / <u>mamba</u> / <u>virtualenv</u> / ...
- Ollama to execute AI models locally
- Visual Studio Code as the IDE
- Git as the source control system

- The use of a Python virtual environment / package management software is highly recommended
- You can choose any of them. The slides will show the examples using conda / mamba (conda and mamba commands are fully interchangeable)
- 1. Create a new <u>environment</u> with name **mas** (you can choose any other environment name) with **python 3.12**:

```
conda create -n mas python=3.12
```

Confirm changes: [Y/n] Y

jordi@jordi-Ubuntu:~\$ mamba create -n mas python=3.12

```
Summary:
```

Install: 25 packages

Total download: 37MB

Confirm changes: [Y/n] Y

2. Activate the new <u>environment</u> with name **mas** (or your chosen environment name). The environment must be activated each time you re-open the terminal:

conda activate mas

```
jordi@jordi-Ubuntu:~$ mamba activate mas
(mas) jordi@jordi-Ubuntu:~$
```

- 3. Install <u>CrewAl</u> version 0.61.0 with all the tools: pip install 'crewai[tools] == 0.61.0'
- 4. Install other required libraries:

 pip install ollama duckduckgo-search transformers torch
 poetry

conda install -c conda-forge osmnx

4. Install <u>Jupyter Lab</u>. The first labs will be provided as Notebooks. Although VS Code can also open Notebooks, there are some incompatibilities with human loops in CrewAl

```
conda install -c conda-forge jupyterlab
```

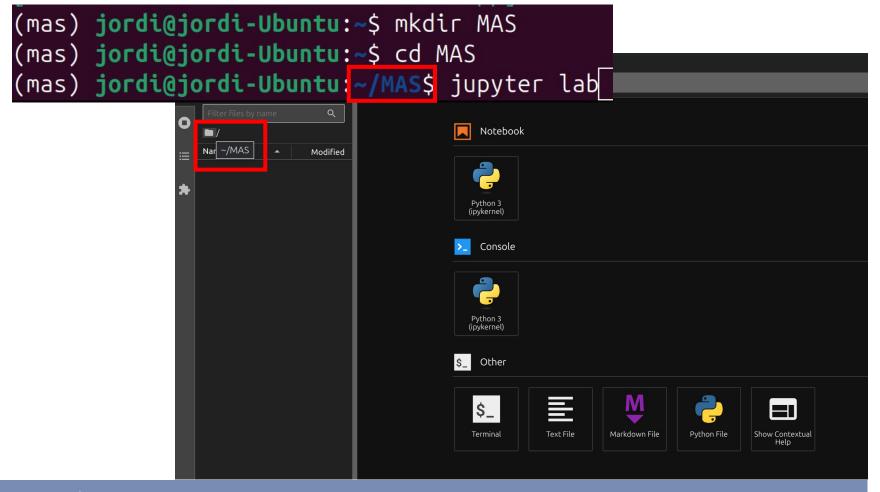
```
(mas) jordi@jordi-Ubuntu:~$ mamba install -c conda-forge jupyterlab
jupyter lab
```

```
(mas) jordi@jordi-Ubuntu:~$ jupyter lab
```

Ctrl+C & y to close Jupyter Lab

Shut down this Jupyter server (y/[n])? y

Jupyter Lab will open in the current working directory of the terminal



4.2. Ollama

- Download the LLM and embedding models. You are free to try different ones, local or API based (OpenAI, Google, etc.). We are going to use the following ones:
 - 1. <u>llama3.1</u> 8M: ollama pull llama3.1
 - 2. <u>mxbai-embed-large</u>: *ollama pull mxbai-embed-large*

```
jordi@jordi-Ubuntu:~$ ollama pull mxbai-embed-large
pulling manifest
pulling 819c2adf5ce6... 100% 669 MB
pulling c71d239df917... 100% 11 KB
pulling b837481ff855... 100% 16 B
pulling 38badd946f91... 100% 408 B
verifying sha256 digest
writing manifest
success
```

4.3. Notebooks

Labs 2 - 6 will be provided as Notebooks. You can open them using Jupyter Lab (or VS Code, PyCharm, etc.). Explanations, code and exercises are provided there

