GIANT: Experiments

Experiment Environment

• Spark 2.1.1 + Scala 2.11.8





Experiment Environment

• Spark 2.1.1

+

Scala 2.11.8





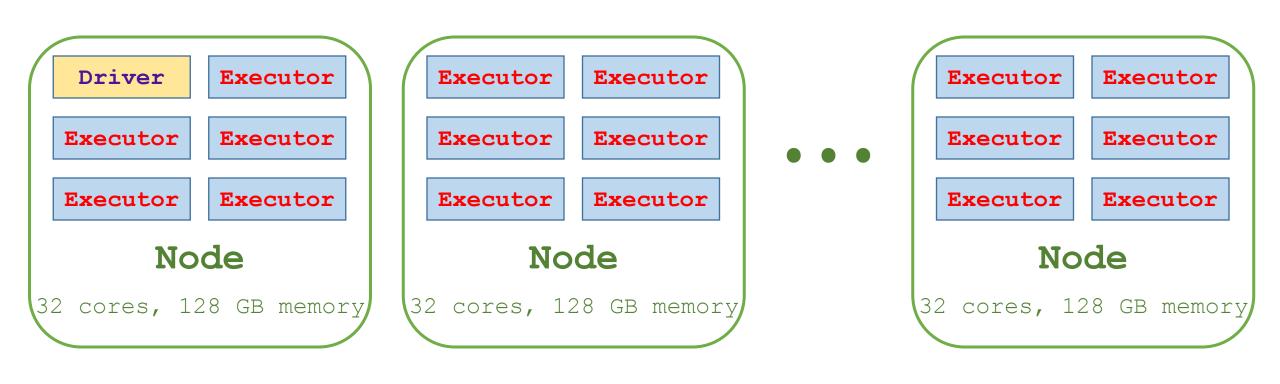
• Cori Supercomputer







Experiment Environment



10 nodes, 59 executors

Settings

• Solve the ℓ_2 -regularized logistic regression:

$$\min_{\mathbf{w} \in \mathbb{R}^d} \left\{ f(\mathbf{w}) \triangleq \frac{1}{n} \sum_{j=1}^n \log \left(1 + e^{-y_j \mathbf{x}_j^T \mathbf{w}} \right) + \frac{\gamma}{2} ||\mathbf{w}||_2^2 \right\}$$

- Split $\mathbf{X} \in \mathbb{R}^{n \times d}$ (by data) to m = 59 parts.
- Local sample size $s = \frac{n}{m}$

Settings

• Solve the ℓ_2 -regularized logistic regression:

$$\min_{\mathbf{w} \in \mathbb{R}^d} \left\{ f(\mathbf{w}) \triangleq \frac{1}{n} \sum_{j=1}^n \log \left(1 + e^{-y_j \mathbf{x}_j^T \mathbf{w}} \right) + \frac{\gamma}{2} ||\mathbf{w}||_2^2 \right\}$$

- Split $\mathbf{X} \in \mathbb{R}^{n \times d}$ (by data) to m = 59 parts.
- Local sample size $s = \frac{n}{m}$ \geq number of features d.

Settings

• Solve the ℓ_2 -regularized logistic regression:

$$\min_{\mathbf{w} \in \mathbb{R}^d} \left\{ f(\mathbf{w}) \triangleq \frac{1}{n} \sum_{j=1}^n \log \left(1 + e^{-y_j \mathbf{x}_j^T \mathbf{w}} \right) + \frac{\gamma}{2} ||\mathbf{w}||_2^2 \right\}$$

- Split $\mathbf{X} \in \mathbb{R}^{n \times d}$ (by data) to m = 59 parts.
- Local sample size $s = \frac{n}{m} \gtrsim \text{number of features } d$.
- We use dense X.

- Accelerated gradient descent (AGD)
 - choose *step size* from {0.1, 1, 10, 100}
 - choose *momentum* from {0.5, 0.9, 0.95, 0.99, 0.999}

- Accelerated gradient descent (AGD)
- Limited memory BFGS (a quasi-Newton method)
 - choose *number of history* from {30, 100, 300}
 - line search is used

- Accelerated gradient descent (AGD)
- Limited memory BFGS
- DANE (another Newton-type method) [Shamir et al. 2014]
 - local solver: SVRG
 - choose *step size of SVRG* from {0.1, 1, 10, 100}
 - choose max iteration of SVRG from {30, 100, 300}

Reference:

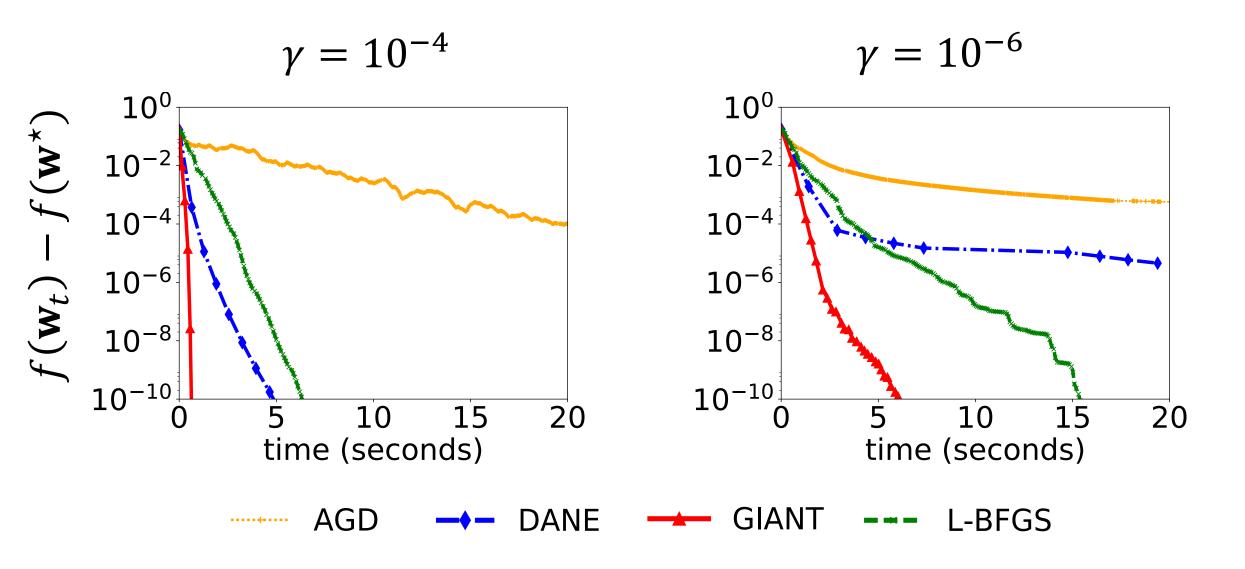
Shamir, Srebro, & Zhang. Communication Efficient Distributed Optimization using an Approximate Newton-type Method. In ICML, 2014.

- Accelerated gradient descent (AGD)
- Limited memory BFGS
- DANE (another Newton-type method)
- GIANT
 - local solver: conjugate gradient (CG)
 - choose *max iteration of CG* from {30, 100, 300}

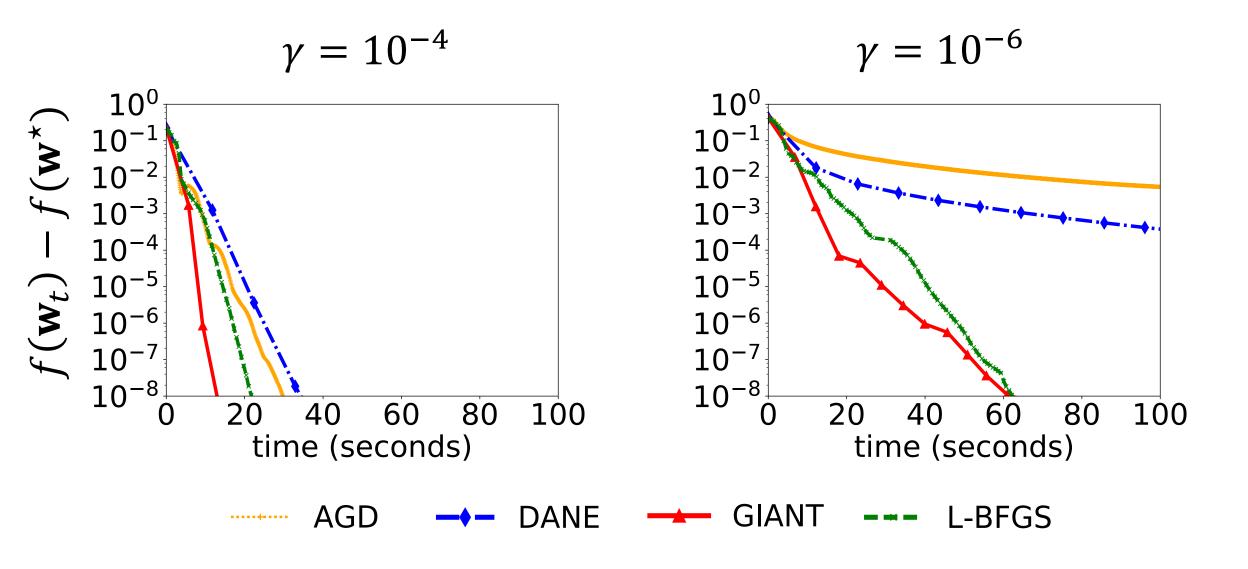
- Accelerated gradient descent (AGD)
- Limited memory BFGS
- DANE (another Newton-type method)
- GIANT

- 2 Tuning Parameters
- 1 Tuning Parameter
- 2 Tuning Parameters
- 1 Tuning Parameter

Covtype (n=581K, d=54)



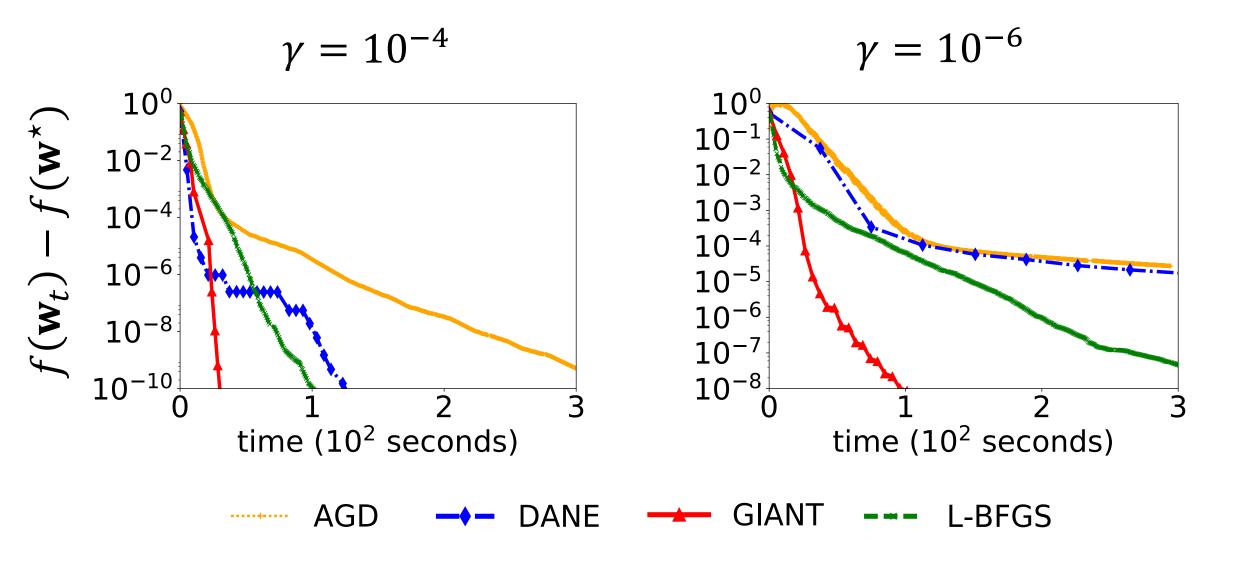
Epsilon (n=400K, d=2K)



MNIST8M (n=1.6M, d=784)

• Digits "4" versus "9": 1.6M samples out of the total 8M samples

MNIST8M (n=1.6M, d=784)



How about Larger d?

- Split $\mathbf{X} \in \mathbb{R}^{n \times d}$ (by data) to m = 59 parts.
- Previously, local sample size $s = \frac{n}{m} \gg \text{number of features } d$.
- Does GIANT work if $s \approx d$?

Random Feature Maps (RFM)

• Generate 10K random Fourier features [Rahimi & Recht, 07] of the RBF kernel

$$k(\mathbf{x}_i, \mathbf{x}_j) = \exp\left(-\frac{1}{2\sigma} \|\mathbf{x}_i - \mathbf{x}_j\|_2^2\right)$$

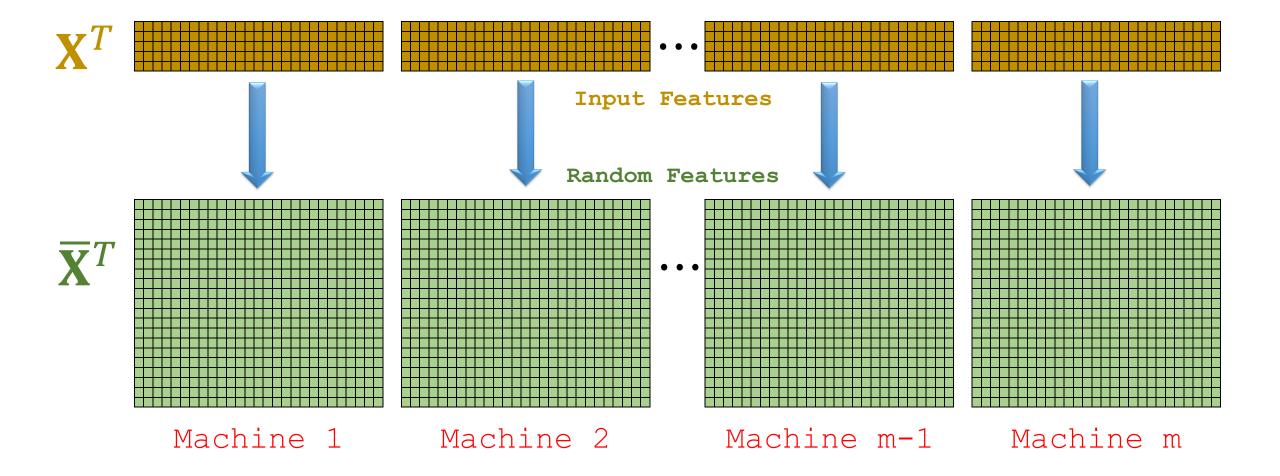
• Setting of RBF *kernel width parameter* σ :

$$\sigma = \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n \|\mathbf{x}_i - \mathbf{x}_j\|_2^2$$

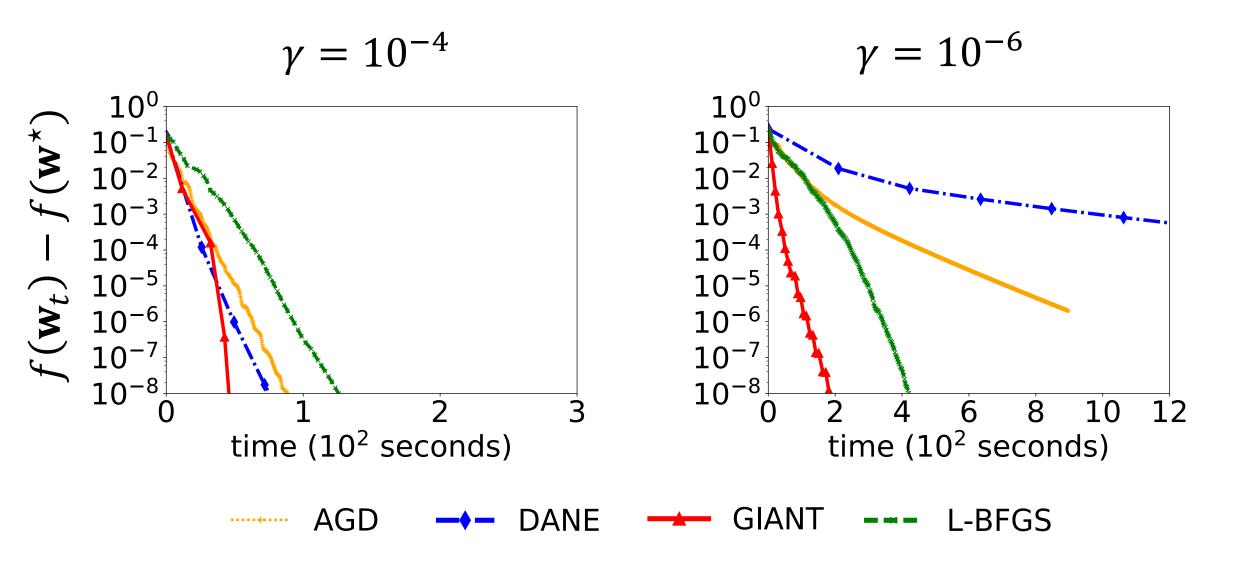
Replace the original features by the higher-dim random features.

Reference:

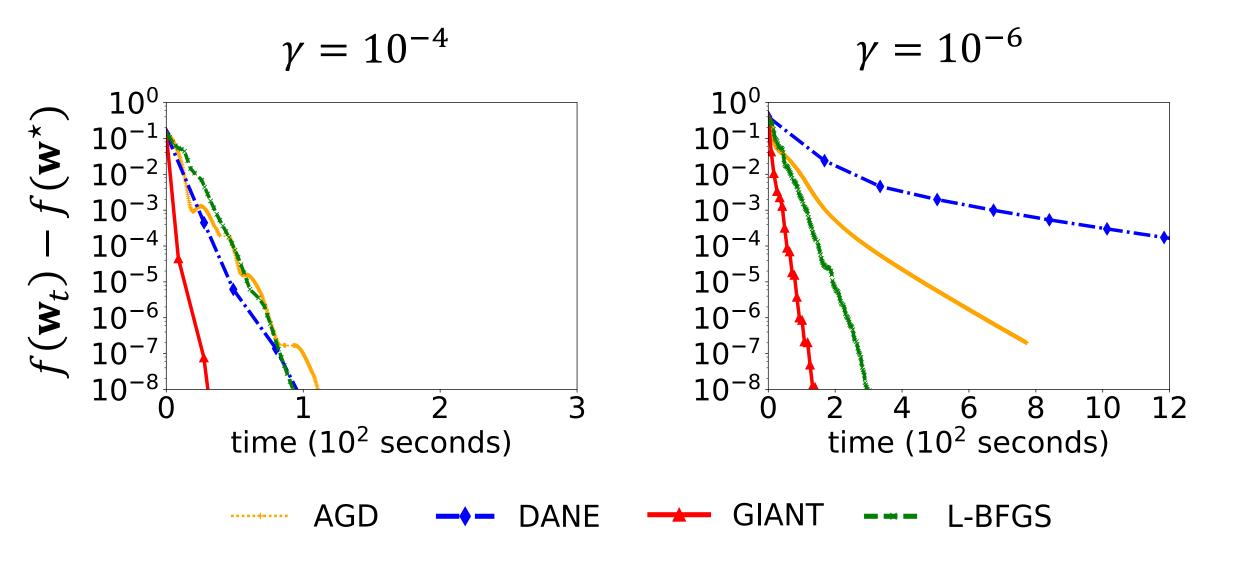
Random Feature Maps (RFM)



Covtype with RFM (n=581K, d=10K)



Epsilon with RFM (n=400K, d=10K)



MNIST8M with RFM (n=1.6M, d=10K)

