

Lab 07

4-bit UpDown Counter

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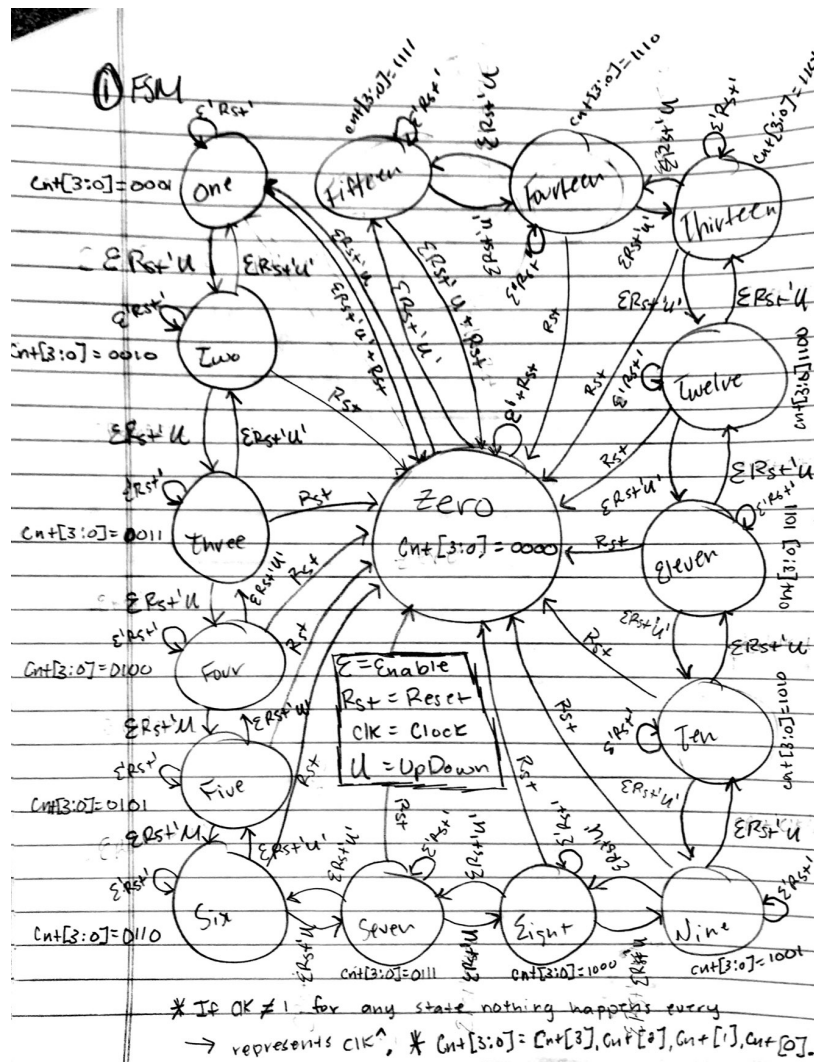
Lab Purpose

The purpose of this lab is to implement a behavioral 4-bit up-down counter and interface it with the seven segment LED display using binary coded decimal, using knowledge from Lab03. The counter will count at 1 Hz, using the clock divider that we learned how to implement in the last lab. The counter has the ability to count up and down from 0 to 15. It wraps when it hits either boundary, and can be reset and paused with buttons on the board that we map using a module and .ucf.

Implementation Details

Pre-Lab Design

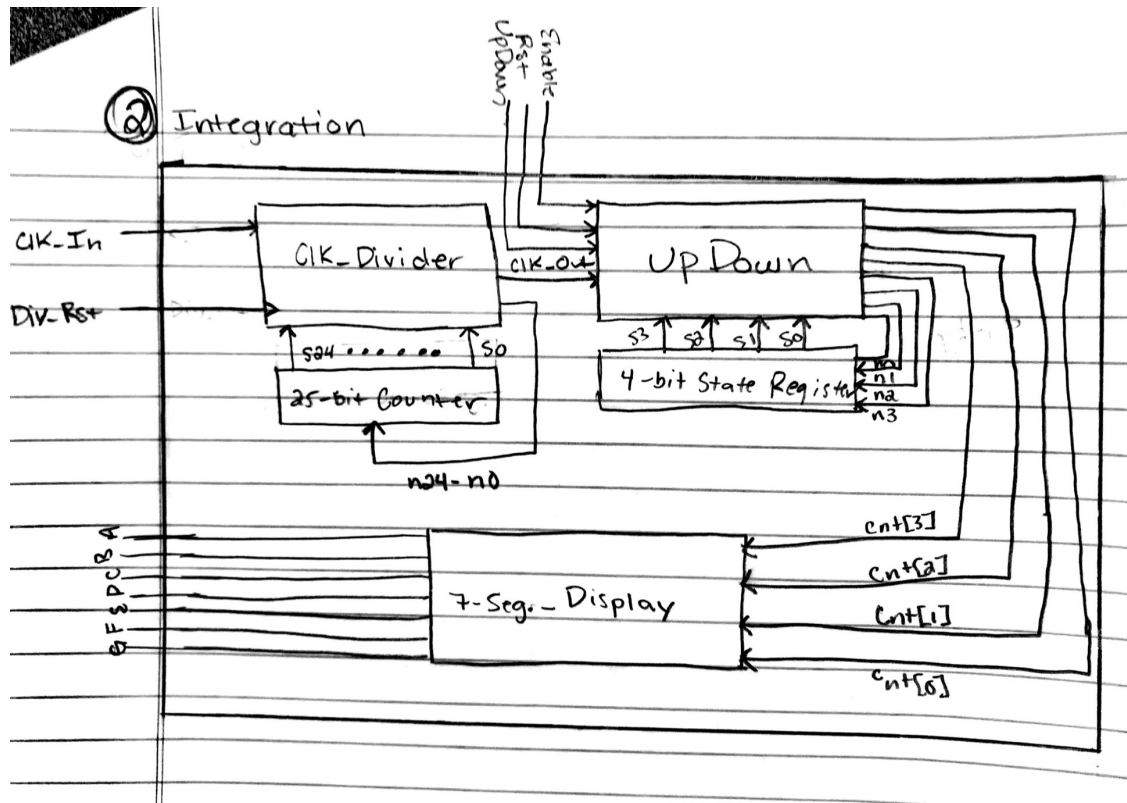
Finite-State-Machine



This FSM shows our intended design for the following project. If Enable is high and Rst is low then it counts up or down depending on the state of the UpDown switch. If Rst is high

in any state it returns to Zero. If Enable is low and Rst is low then it remains in whatever states it was in. The positive clock edge is assumed to be true for ever equation.

Controller Design



If we compare this controller design to the previous lab, we can see that it is mostly the same design, with the addition of the 7 segment display. The large difference is connecting the 4 state register of UpDown to the input of seven segment display.

UpDown

Behavioral Module Code

```
'timescale 1ns / 1ps
/////////////////////////////////////////////////////////////////
// Engineer:      Zachary Davis & Ryan Cruz
//
// Create Date:    11:24:41 10/13/2017
// Design Name:    UpDown_tb
// Module Name:    UpDown
// Description:    Uses switches to control the seven segment display by
//                  counting up or down on the rising edge of a clock cycle.
//
/////////////////////////////////////////////////////////////////
module UpDown(Clk_Out, Rst, Enable, UpDown, Count);
    input Clk_Out, Rst, Enable, UpDown;
    output reg [3:0] Count = 4'b0000;

    always @ (posedge Clk_Out)
    begin
        if (Rst == 4'b0001)
            Count <= 4'b0000;
        else if (Enable == 4'b0000)
            Count <= Count;
        else
            begin
                if (UpDown == 4'b0001)
                    begin
                        if (Count == 4'b1111)
                            Count <= 4'b0000;
                        else
                            Count <= Count + 4'b0001;
                        end
                else
                    begin
                        if (Count == 4'b0000)
                            Count <= 4'b1111;
                        else
                            Count <= Count - 4'b0001;
                        end
                    end
            end
    end
endmodule
```

This is the code that stems from the FSM in the prelab. No matter what is Rst is high go to the Zero state, etc. It follows the logic explained above.

Test Bench Code

```
'timescale 1ns / 1ps
/////////////////////////////////////////////////////////////////
// Engineer:      Zachary Davis & Ryan Cruz
//
// Create Date:    11:24:41 10/13/2017
// Design Name:    UpDown_tb
// Module Name:    UpDown
// Description:    Uses switches to control the seven segment display by
//                  counting up or down on the rising edge of a clock cycle.
//
/////////////////////////////////////////////////////////////////
module UpDown_tb();
    reg Clk_Out_t, Rst_t, UpDown_t, Enable_t;
    wire [3:0] Count_t;

    UpDown UpDown_1(Clk_Out_t, Rst_t, Enable_t, UpDown_t, Count_t);

    initial
        Clk_Out_t <= 0;

    always
        #10 Clk_Out_t <= ~Clk_Out_t;

    initial begin
        UpDown_t <= 0; Rst_t <= 0; Enable_t <= 0;
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        UpDown_t <= 1; Rst_t <= 0; Enable_t <= 1;
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        UpDown_t <= 0; Rst_t <= 0; Enable_t <= 1;
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        Enable_t <= 0;
        @(posedge Clk_Out_t);
```

```

        @(posedge Clk_Out_t);
        Enable_t <= 1;
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        @(posedge Clk_Out_t);
        Rst_t <= 1;
    end
endmodule

```

We used the test bench to test many, but not all the use cases from the UpDown.v. What we are doing is explained more in depth below with its wave form.

SevenSegmentDisplay

Behavioral Module Code

```

`timescale 1ns / 1ps
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// Engineer:      Zachary Davis & Ryan Cruz
//
// Create Date:    11:24:41 10/13/2017
// Design Name:    Seven_Segment_Display
// Module Name:    Seven_Segment_Display
// Description:    Displays the numbers 0-15 in hexidecimal on and LED display
//
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
module Seven_Segment_Display(In, A, B, C, D, E, F, G);
    input [3:0] In;
    output A, B, C, D, E, F, G;
    reg A, B, C, D, E, F, G;

    always @ (In[3], In[2], In[1], In[0])
    begin
        if (In[3] == 0 && In[2] == 0 && In[1] == 0 && In[0] == 0)
        begin
            A <= 1;
            B <= 1;
            C <= 1;
            D <= 1;
            E <= 1;
            F <= 1;
            G <= 0;
        end
        else if (In[3] == 0 && In[2] == 0 && In[1] == 0 && In[0] == 1)
        begin
            A <= 0;
            B <= 1;

```

```

C <= 1;
D <= 0;
E <= 0;
F <= 0;
G <= 0;
end
else if (In[3] == 0 && In[2] == 0 && In[1] == 1 && In[0] == 0)
begin
A <= 1;
B <= 1;
C <= 0;
D <= 1;
E <= 1;
F <= 0;
G <= 1;
end
else if (In[3] == 0 && In[2] == 0 && In[1] == 1 && In[0] == 1)
begin
A <= 1;
B <= 1;
C <= 1;
D <= 1;
E <= 0;
F <= 0;
G <= 1;
end
else if (In[3] == 0 && In[2] == 1 && In[1] == 0 && In[0] == 0)
begin
A <= 0;
B <= 1;
C <= 1;
D <= 0;
E <= 0;
F <= 1;
G <= 1;
end
else if (In[3] == 0 && In[2] == 1 && In[1] == 0 && In[0] == 1)
begin
A <= 1;
B <= 0;
C <= 1;
D <= 1;
E <= 0;
F <= 1;
G <= 1;
end
else if (In[3] == 0 && In[2] == 1 && In[1] == 1 && In[0] == 0)

```

```

begin
A <= 1;
B <= 0;
C <= 1;
D <= 1;
E <= 1;
F <= 1;
G <= 1;
end
else if (In[3] == 0 && In[2] == 1 && In[1] == 1 && In[0] == 1)
begin
A <= 1;
B <= 1;
C <= 1;
D <= 0;
E <= 0;
F <= 0;
G <= 0;
end
else if (In[3] == 1 && In[2] == 0 && In[1] == 0 && In[0] == 0)
begin
A <= 1;
B <= 1;
C <= 1;
D <= 1;
E <= 1;
F <= 1;
G <= 1;
end
else if (In[3] == 1 && In[2] == 0 && In[1] == 0 && In[0] == 1)
begin
A <= 1;
B <= 1;
C <= 1;
D <= 1;
E <= 0;
F <= 1;
G <= 1;
end
else if (In[3] == 1 && In[2] == 0 && In[1] == 1 && In[0] == 0)
begin
A <= 1;
B <= 1;
C <= 1;
D <= 0;
E <= 1;
F <= 1;

```



```

G <= 1;
end
else if (In[3] == 1 && In[2] == 0 && In[1] == 1 && In[0] == 1)
begin
A <= 0;
B <= 0;
C <= 1;
D <= 1;
E <= 1;
F <= 1;
G <= 1;
end
else if (In[3] == 1 && In[2] == 1 && In[1] == 0 && In[0] == 0)
begin
A <= 1;
B <= 0;
C <= 0;
D <= 1;
E <= 1;
F <= 1;
G <= 0;
end
else if (In[3] == 1 && In[2] == 1 && In[1] == 0 && In[0] == 1)
begin
A <= 0;
B <= 1;
C <= 1;
D <= 1;
E <= 1;
F <= 0;
G <= 1;
end
else if (In[3] == 1 && In[2] == 1 && In[1] == 1 && In[0] == 0)
begin
A <= 1;
B <= 0;
C <= 0;
D <= 1;
E <= 1;
F <= 1;
G <= 1;
end
else
begin
A <= 1;
B <= 0;
C <= 0;

```

```

        D <= 0;
        E <= 1;
        F <= 1;
        G <= 1;
        end
    end
endmodule

```

This is the logic from lab 3 earlier this semester. However, we chose back then not to use condition logic and we really paid the price this week. Rather than bandaid it all together we entirely rewrote this file from what we turned in in lab 3. Functionally it works exactly the same it is just far more readable and more compatible with a state register input.

Test Bench Code

```

`timescale 1ns / 1ps
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// Engineer:      Zachary Davis, Ryan Cruz
//
// Create Date:    12:28:46 09/22/2017
// Module Name:    Seven_Segment_Display
// Project Name:
// Target Devices: Spartan 3E
// Description:    Displays the numbers 0-15 in hexadecimal on and LED display
//
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
module Seven_Segment_Display_tb();

    reg [3:0] In;
    wire A_t, B_t, C_t, D_t, E_t, F_t, G_t;

    Seven_Segment_Display Seven_Segment_Display_1
        (In, A_t, B_t, C_t, D_t, E_t, F_t, G_t);

    initial
    begin

        //Case 0
        In <= 4'b0000;
        #1 $display("");
        #1 $display("Case 0: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);
        #1 $display("D_t = %b", D_t);
        #1 $display("E_t = %b", E_t);

```

```

        #1 $display("F_t = %b", F_t);
        #1 $display("G_t = %b", G_t);

        //Case 1
In <= 4'b0001;
        #1 $display("");
        #1 $display("Case 1: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);
        #1 $display("D_t = %b", D_t);
        #1 $display("E_t = %b", E_t);
        #1 $display("F_t = %b", F_t);
        #1 $display("G_t = %b", G_t);

        //Case 2
In <= 4'b0010;
        #1 $display("");
        #1 $display("Case 2: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);
        #1 $display("D_t = %b", D_t);
        #1 $display("E_t = %b", E_t);
        #1 $display("F_t = %b", F_t);
        #1 $display("G_t = %b", G_t);

        //Case 3
In <= 4'b0011;
        #1 $display("");
        #1 $display("Case 3: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);
        #1 $display("D_t = %b", D_t);
        #1 $display("E_t = %b", E_t);
        #1 $display("F_t = %b", F_t);
        #1 $display("G_t = %b", G_t);

        //Case 4
In <= 4'b0100;
        #1 $display("");
        #1 $display("Case 4: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);
        #1 $display("D_t = %b", D_t);

```

```

        #1 $display("E_t = %b", E_t);
        #1 $display("F_t = %b", F_t);
        #1 $display("G_t = %b", G_t);

        //Case 5
In <= 4'b0101;
        #1 $display("");
        #1 $display("Case 5: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);
        #1 $display("D_t = %b", D_t);
        #1 $display("E_t = %b", E_t);
        #1 $display("F_t = %b", F_t);
        #1 $display("G_t = %b", G_t);

        //Case 6
In <= 4'b0110;
        #1 $display("");
        #1 $display("Case 6: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);
        #1 $display("D_t = %b", D_t);
        #1 $display("E_t = %b", E_t);
        #1 $display("F_t = %b", F_t);
        #1 $display("G_t = %b", G_t);

        //Case 7
In <= 4'b0111;
        #1 $display("");
        #1 $display("Case 7: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);
        #1 $display("D_t = %b", D_t);
        #1 $display("E_t = %b", E_t);
        #1 $display("F_t = %b", F_t);
        #1 $display("G_t = %b", G_t);

        //Case 8
In <= 4'b1000;
        #1 $display("");
        #1 $display("Case 8: ");
        #1 $display("A_t = %b", A_t);
        #1 $display("B_t = %b", B_t);
        #1 $display("C_t = %b", C_t);

```

```

#1 $display("D_t = %b", D_t);
#1 $display("E_t = %b", E_t);
#1 $display("F_t = %b", F_t);
#1 $display("G_t = %b", G_t);

//Case 9
In <= 4'b1001;
#1 $display("");
#1 $display("Case 9: ");
#1 $display("A_t = %b", A_t);
#1 $display("B_t = %b", B_t);
#1 $display("C_t = %b", C_t);
#1 $display("D_t = %b", D_t);
#1 $display("E_t = %b", E_t);
#1 $display("F_t = %b", F_t);
#1 $display("G_t = %b", G_t);

//Case 10
In <= 4'b1010;
#1 $display("");
#1 $display("Case 10: ");
#1 $display("A_t = %b", A_t);
#1 $display("B_t = %b", B_t);
#1 $display("C_t = %b", C_t);
#1 $display("D_t = %b", D_t);
#1 $display("E_t = %b", E_t);
#1 $display("F_t = %b", F_t);
#1 $display("G_t = %b", G_t);

//Case 11
In <= 4'b1011;
#1 $display("");
#1 $display("Case 11: ");
#1 $display("A_t = %b", A_t);
#1 $display("B_t = %b", B_t);
#1 $display("C_t = %b", C_t);
#1 $display("D_t = %b", D_t);
#1 $display("E_t = %b", E_t);
#1 $display("F_t = %b", F_t);
#1 $display("G_t = %b", G_t);

//Case 12
In <= 4'b1100;
#1 $display("");
#1 $display("Case 12: ");
#1 $display("A_t = %b", A_t);
#1 $display("B_t = %b", B_t);

```

```

#1 $display("C_t = %b", C_t);
#1 $display("D_t = %b", D_t);
#1 $display("E_t = %b", E_t);
#1 $display("F_t = %b", F_t);
#1 $display("G_t = %b", G_t);

//Case 13
In <= 4'b1101;
#1 $display("");
#1 $display("Case 13: ");
#1 $display("A_t = %b", A_t);
#1 $display("B_t = %b", B_t);
#1 $display("C_t = %b", C_t);
#1 $display("D_t = %b", D_t);
#1 $display("E_t = %b", E_t);
#1 $display("F_t = %b", F_t);
#1 $display("G_t = %b", G_t);

//Case 14
In <= 4'b1110;
#1 $display("");
#1 $display("Case 14: ");
#1 $display("A_t = %b", A_t);
#1 $display("B_t = %b", B_t);
#1 $display("C_t = %b", C_t);
#1 $display("D_t = %b", D_t);
#1 $display("E_t = %b", E_t);
#1 $display("F_t = %b", F_t);
#1 $display("G_t = %b", G_t);

//Case 15
In <= 4'b1111;
#1 $display("");
#1 $display("Case 15: ");
#1 $display("A_t = %b", A_t);
#1 $display("B_t = %b", B_t);
#1 $display("C_t = %b", C_t);
#1 $display("D_t = %b", D_t);
#1 $display("E_t = %b", E_t);
#1 $display("F_t = %b", F_t);
#1 $display("G_t = %b", G_t);

end
endmodule

```

This is our testbench for seven segment display. What exactly is happening here is explained below with its waveform.

Clock Divider

Behavioral Module Code

```
'timescale 1ns / 1ps
/////////////////////////////////////////////////////////////////
// Engineer:      Zachary Davis & Ryan Cruz
//
// Create Date:    11:24:41 10/13/2017
// Design Name:    Thunderbird Turn Signal
// Module Name:    Clock_Divider_tb
// Description:    A clock divider that divides 50 MHz into 1 Hz on the FPGA
//                  board. Simulator.
//
/////////////////////////////////////////////////////////////////
module Clock_Divider(Clk_In, Div_Rst, Clk_Out);
    input Clk_In, Div_Rst;
    output reg Clk_Out;
    reg [24:0] counter;

    always @(posedge Clk_In or posedge Div_Rst)
        begin
            if (Div_Rst == 1'b1)
                begin
                    counter <= 0;
                    Clk_Out <= 0;
                end
            else
                begin
                    counter <= counter + 1;
                    if (counter == 25_000_000) //25_000_000
                        begin
                            counter <= 0;
                            Clk_Out <= ~Clk_Out;
                        end
                end
            end
        end
endmodule
```

This is the exact same code from a previous lab and does the exact same thing. Its purpose is to divide the 50mHz clock speed of the Sparten3E to 1 lowly Hz.

Test Bench Code

```
'timescale 1ns / 1ps
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// Engineer:      Zachary Davis & Ryan Cruz
//
// Create Date:    11:24:41 10/13/2017
// Design Name:    Thunderbird Turn Signal
// Module Name:    Clock_Divider_tb
// Description:    A clock divider that divides 50 MHz into 1 Hz on the FPGA
//                  board.  Simulator.
//
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
module Clock_Divider_tb();
    reg Clk_In_t, Div_Rst_t;
    wire Clk_Out_t;

    Clock_Divider Clock_Divider_1(Clk_In_t, Div_Rst_t, Clk_Out_t);

    always
        begin
            Clk_In_t <= 1;
            #10;
            Clk_In_t <= 0;
            #10;
        end

    initial begin
        Div_Rst_t <= 0;
        #5;
        Div_Rst_t <= 1;
        #5;
        Div_Rst_t <= 0;
    end
end
endmodule
```

This is the testbench for the clock divider and it is altered for the simulation so that it is usable. This is explained further in the waveform below.

Top Module

Behavioral Module Code

```
'timescale 1ns / 1ps
/////////////////////////////////////////////////////////////////
// Engineer:      Zachary Davis & Ryan Cruz
//
// Create Date:    12:29:15 10/20/2017
// Design Name:    Seven Segment Display
// Module Name:    Top_Mod
// Description:    Call on clock divider, seven segment display, and up down
//                  to combine the whole project.
//
/////////////////////////////////////////////////////////////////
'timescale 1ns / 1ps

module Top_Mod(Clk_In, Rst, Enable, UpDown, A, B, C, D, E, F, G, Div_Rst);
    input Clk_In, Rst, Enable, UpDown, Div_Rst;
    output A, B, C, D, E, F, G;

    wire Clk_Out;
    wire [3:0] Count;

    Clock_Divider Clock_Divider_1 (Clk_In, Div_Rst, Clk_Out);
    UpDown UpDown_1 (Clk_Out, Rst, Enable, UpDown, Count);
    Seven_Segment_Display Seven_Segment_Display_1 (Count, A, B, C, D, E, F, G);
endmodule
```

This is the top module that calls all of the above as functions and connects them together as shown in part two of the prelab.

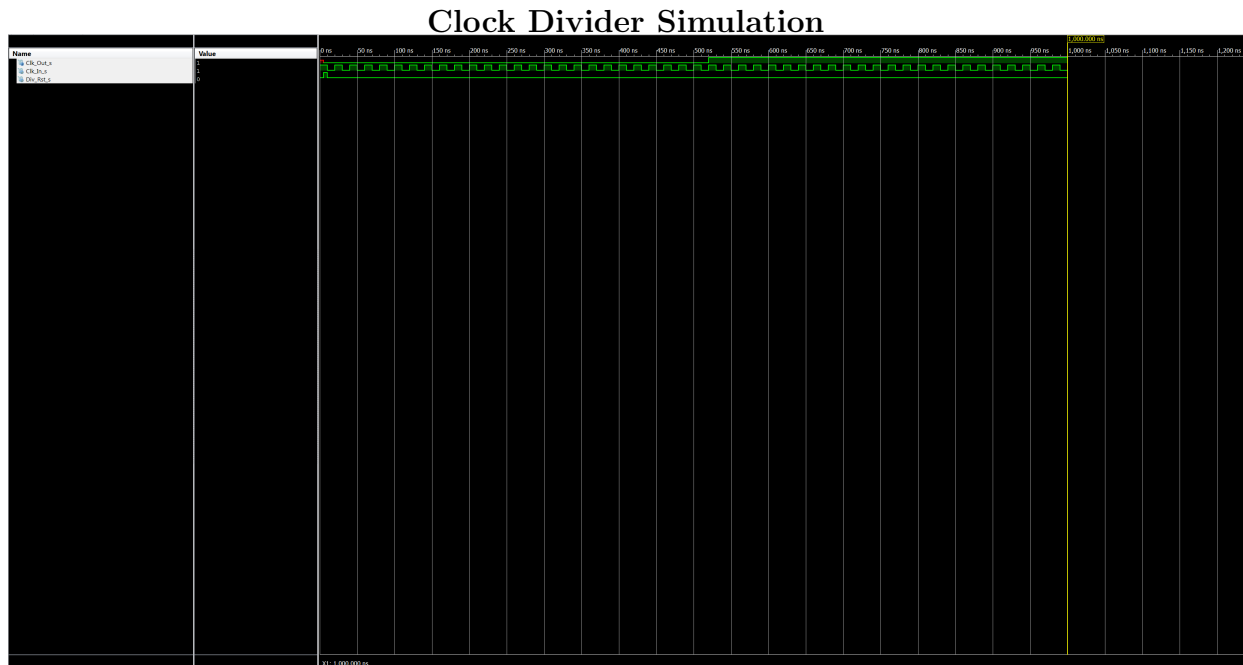
UCF

```
NET "Clk_In" LOC = "C9";
NET "Rst" LOC = "K17" | PULLDOWN;
NET "Div_Rst" LOC = "D18" | PULLDOWN;
NET "Enable" LOC = "N17";
NET "UpDown" LOC = "H18";
NET "A" LOC = B4;
NET "B" LOC = A4;
NET "C" LOC = D5;
NET "D" LOC = C5;
NET "E" LOC = A6;
NET "F" LOC = B6;
NET "G" LOC = E7;
```

Assigning the four inputs to switches on the FPGA board as well as the clock. It also assigns the seven letters to a segment on the LED.

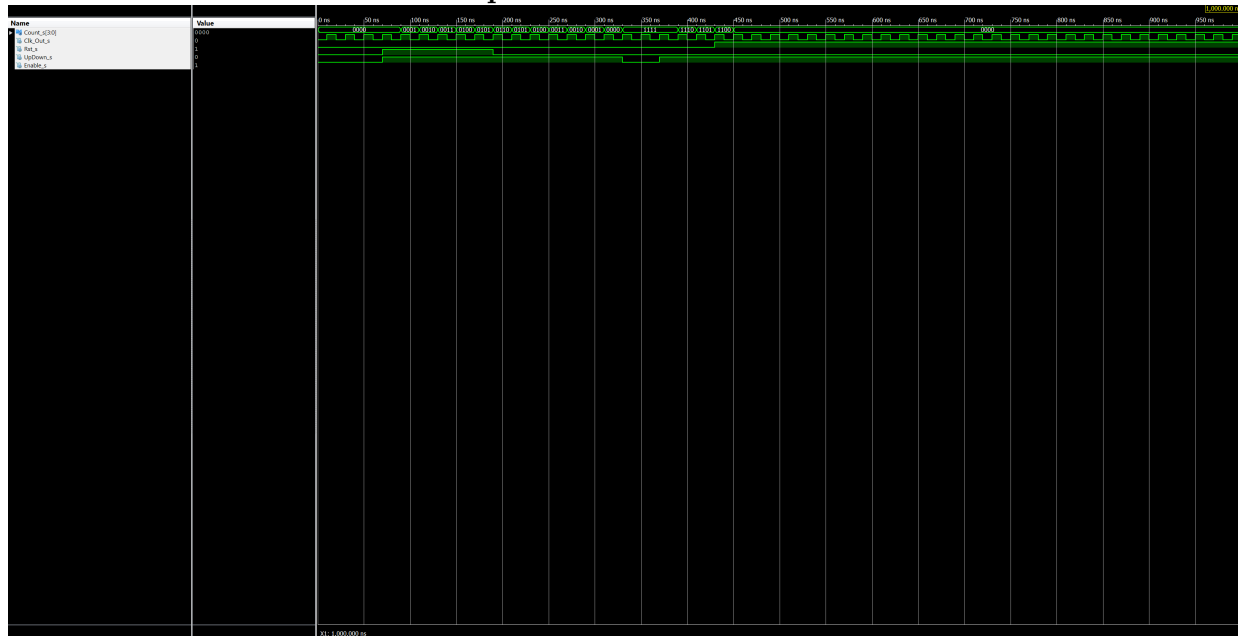
Experimental Results

Waveforms



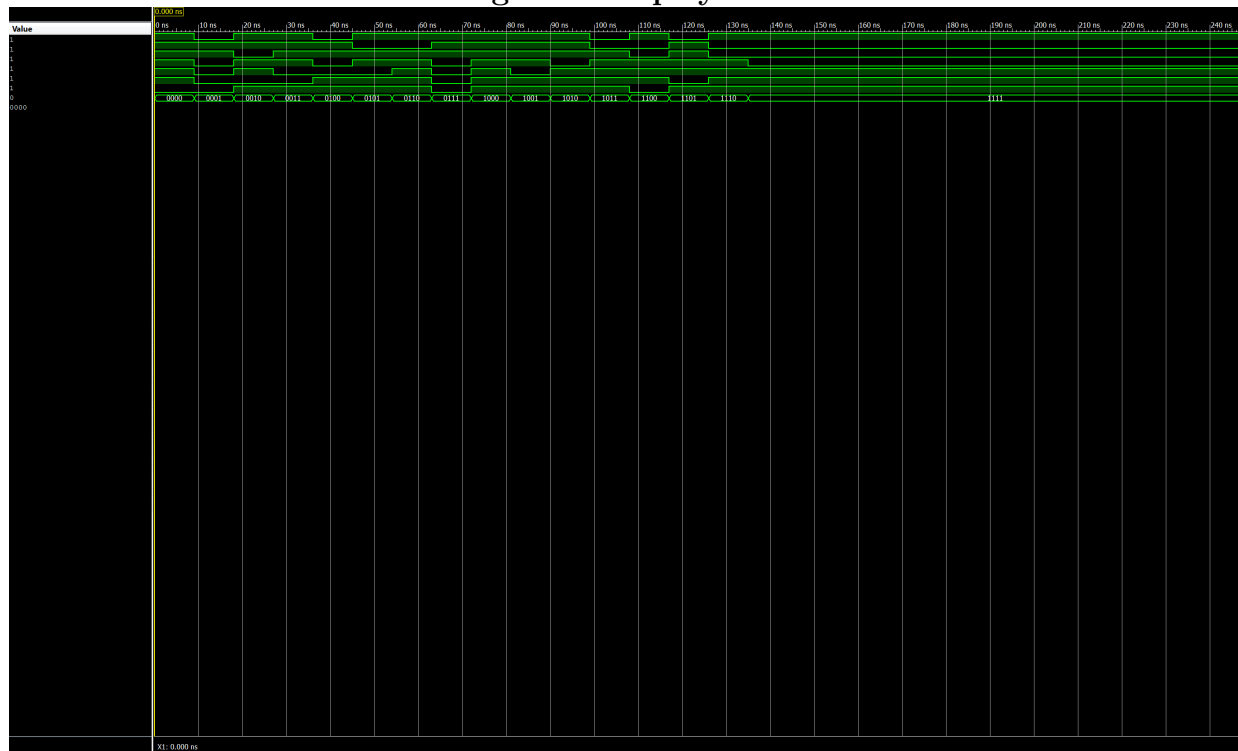
This code came straight from a previous lab. For the actual project we intended for clock divider to take the 50mHz clock and divide it into a 1Hz clock, but for the sake of the simulation we divided it into 1mHz clock so we could actually see the result.

UpDown Simulations



This simulation checks that UpDown counter acts as intended. To do this we checked all of the use cases we could come up with. Initially no switch is high and our default case is 0. From there UpDown and Enable are high which means the output should count up every clock cycle as it does. Then just before 200ns we turn UpDown low and the outputs begin counting down. Inbetween 300ns and 350ns you can see it wrap from 0000 to 1111. Also we turn Enable low which holds the output value at whatever it is. Finally we turn Enable high and Rst high to show that Rst returns it to 0000. Enable does not actually need to be high for this, which we did not show but we demonstrated in the demo.

Seven Segment Display Simulation



This simulation shows all fifteen possible cases for seven segment display. The simulation should look exactly the same as it did in lab three all though the way it is implemented was changed as explained above. Either way the state register is shown and the appropriate segments of the LED are high to form that digit.

Significance

This lab added another layer of complexity, introducing the concept of binary coded decimal and combining several topics from the previous labs, including clock division, displaying to the LED seven segment display, and binary/decimal/hex counting. It as we said above also stressed the value of behavioral logic as we had to change our previous design for seven segment display.

Comments/Suggestions

This lab is fine and builds up at a nice pace so that it does not feel to overwhelming, but if I had to change anything it would be a mention that we are able to simplify our FSM's in the prelab they are getting very complex and repeatitive logic is overcrowding the page like the RST switch.