



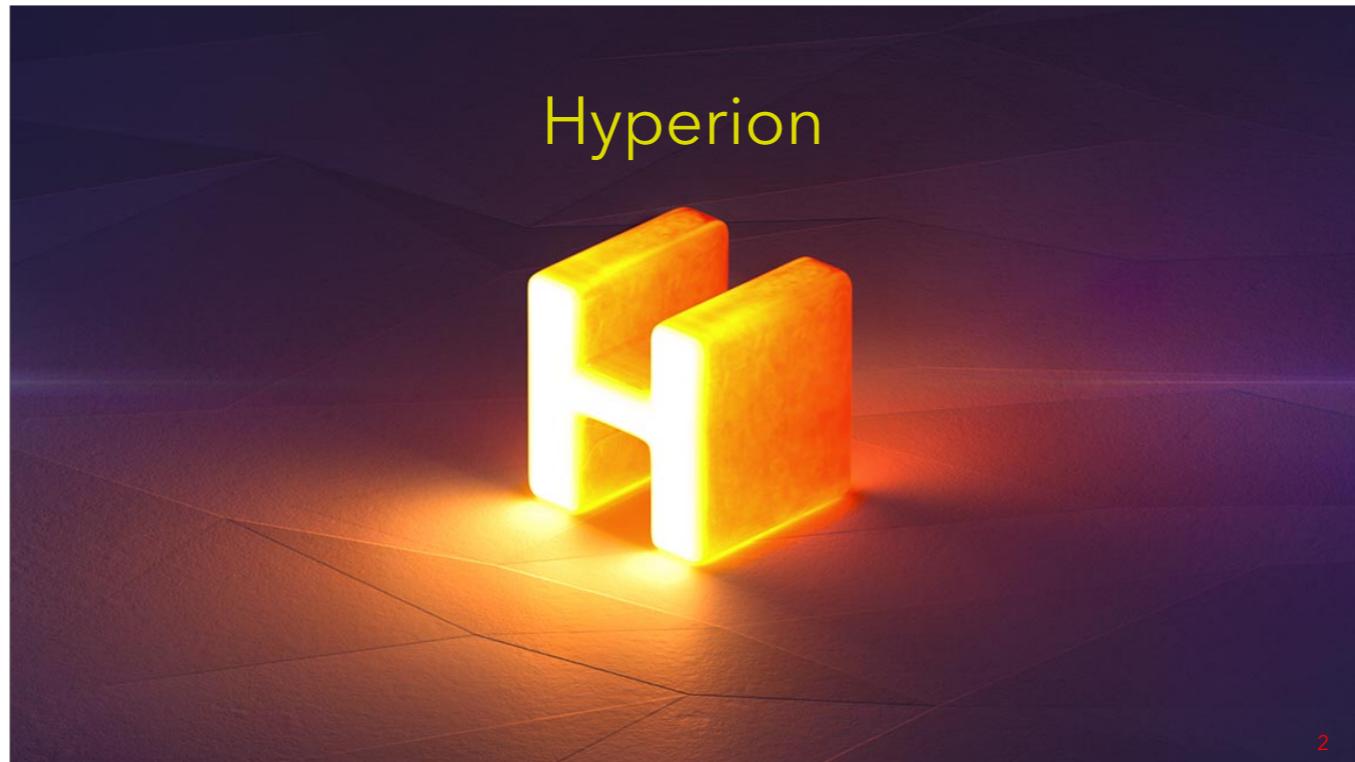
Progressive null-tracking for volumetric rendering

Zackary Misso¹ Yining Karl Li² Brent Burley² Daniel Teece² Wojciech Jarosz¹

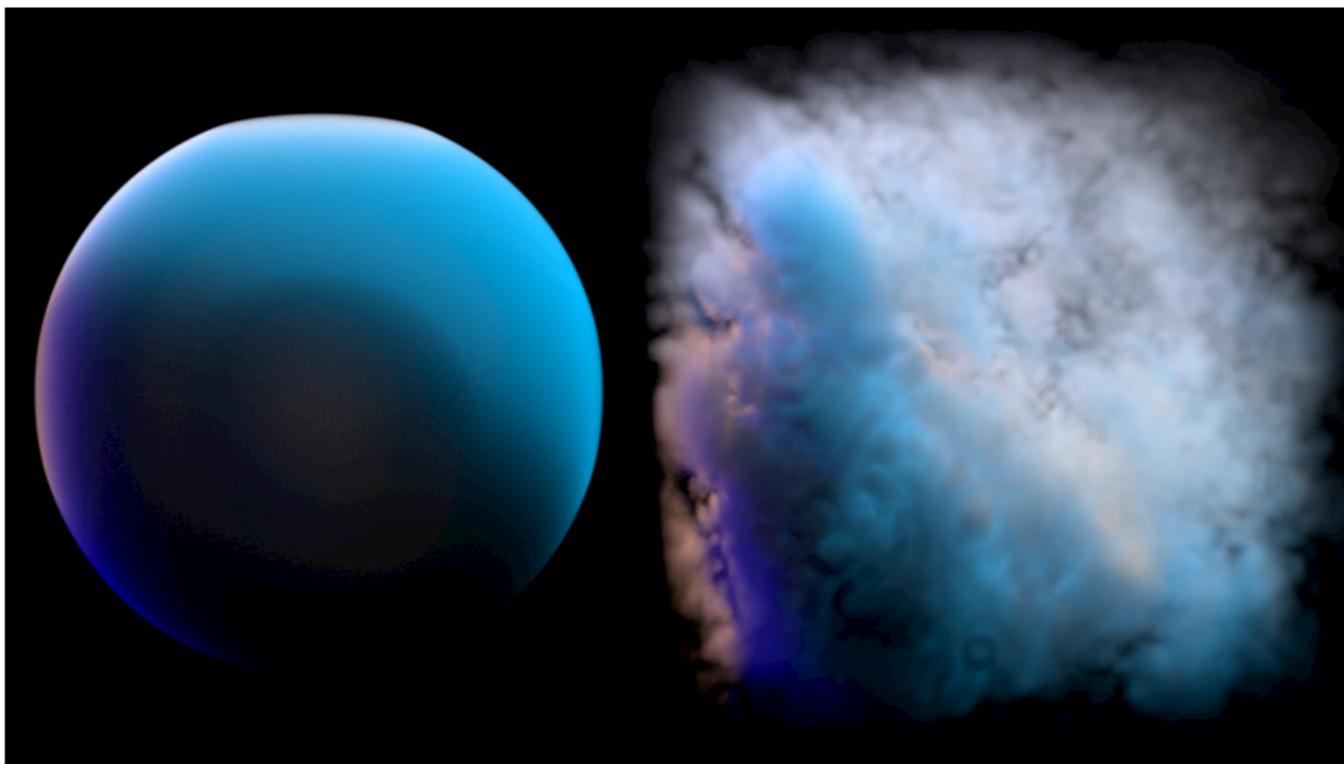
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1

Good afternoon everyone! This project began early last summer during an internship at Walt Disney Animation,



Where we initially met with a team of VFX artists see what features they wanted from the next generation of Disney's Hyperion rendering engine. One of the features which they requested



was for Hyperion to eventually support rendering general procedural media.



This would allow for supporting near infinite amounts of detail within the volumes used in their theatrical productions. However, due to algorithmic constraints this is not currently supported

From the SIGGRAPH Asia 2014 conference proceedings.

Residual Ratio Tracking for Estimating Attenuation in Participating Media

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¹Walt Disney Animation Studios ²Disney Research Zürich

Figure 1: A cloudscape rendered with a combination of our spectral and decomposition tracking techniques, which gracefully handle chromatic media and reduce collision coefficient evaluations. The insets on the right were computed in equal time, with our method yielding 3.5x lower MSE than delta tracking.

Abstract

Evaluating transmittance within participating media is a fundamental operation required by many light transport algorithms. We present **ratio tracking** and **residual ratio tracking**, two novel unbiased estimators that can be combined in an efficient, unbiased estimator for evaluating transmittance in complex heterogeneous media. In comparison to current approaches, our new estimator is unbiased, yields high efficiency, gracefully handles media with wavelength dependent extinction, and bridges the gap between closed form solutions and purely numerical methods. A key feature of ratio tracking is its ability to handle negative densities. This in turn enables us to separate the main part of the transmittance function, handle it analytically, and numerically estimate only the residual transmittance. In addition to proving the unbiasedness of our estimators, we perform an extensive empirical analysis to reveal parameters that lead to high efficiency. Finally, we describe how to integrate the ratio tracking estimator into a production pipeline.

1 Introduction

The world around us is filled with participating media that attenuates and scatters light as it travels from light sources, to surfaces, and finally to our eyes. To render this light in a heterogenous environment—such as smoke, clouds, rain, reactor housings, biological tissue, or other volumetric datasets—is important in many fields, ranging from neutron transport, to medical physics, scientific visualization, and film and visual effects production.

Monte Carlo (MC) path sampling approaches, including variants of path tracing [Kajiya 1986], bidirectional path tracing [Lafortune and Willems 1993; Veach and Guibas 1994; Pauly et al. 2000], or many-light methods [Keller 1997; Dachschafer et al. 2013], have proved to be practical approaches for accurately simulating this light transport. As they rely on estimating random paths between the light(s) and the sensor, and there has been extensive research on importance sampling such paths to obtain low-noise images [Raab

We present two novel unbiased techniques for sampling free paths in heterogeneous participating media. Our **decomposition tracking** accelerates free-path construction by splitting the medium into a control component and a residual component and sampling each of them separately. To minimize expensive evaluations of spatially varying collision costs, we defer the control component to the rendering of paths in closed form. The residual heterogeneous component is then homogenized by adding a fictitious medium and handled using weighted delta tracking, which removes the need for computing strict bounds of the extinction function. Our second contribution, **spectral tracking**, enables efficient light transport simulation in chromatic media by adapting the sampling to account for the fluctuation of path throughput and thereby reduces the estimation variance. To demonstrate the correctness of our algorithms, we derive them directly from the radiative transfer equation by extending the integral formulation of null-collision algorithms recently developed in reactor physics. This mathematical framework, which we thoroughly review, encompasses existing trackers and postulates an entire family of new estimators for solving trans-

CCS Concepts: • Computing methodologies → Rendering, Ray tracing; Additional Key Words and Phrases: participating media, volume rendering, free-path sampling, transmittance, delta tracking, ratio tracking, color

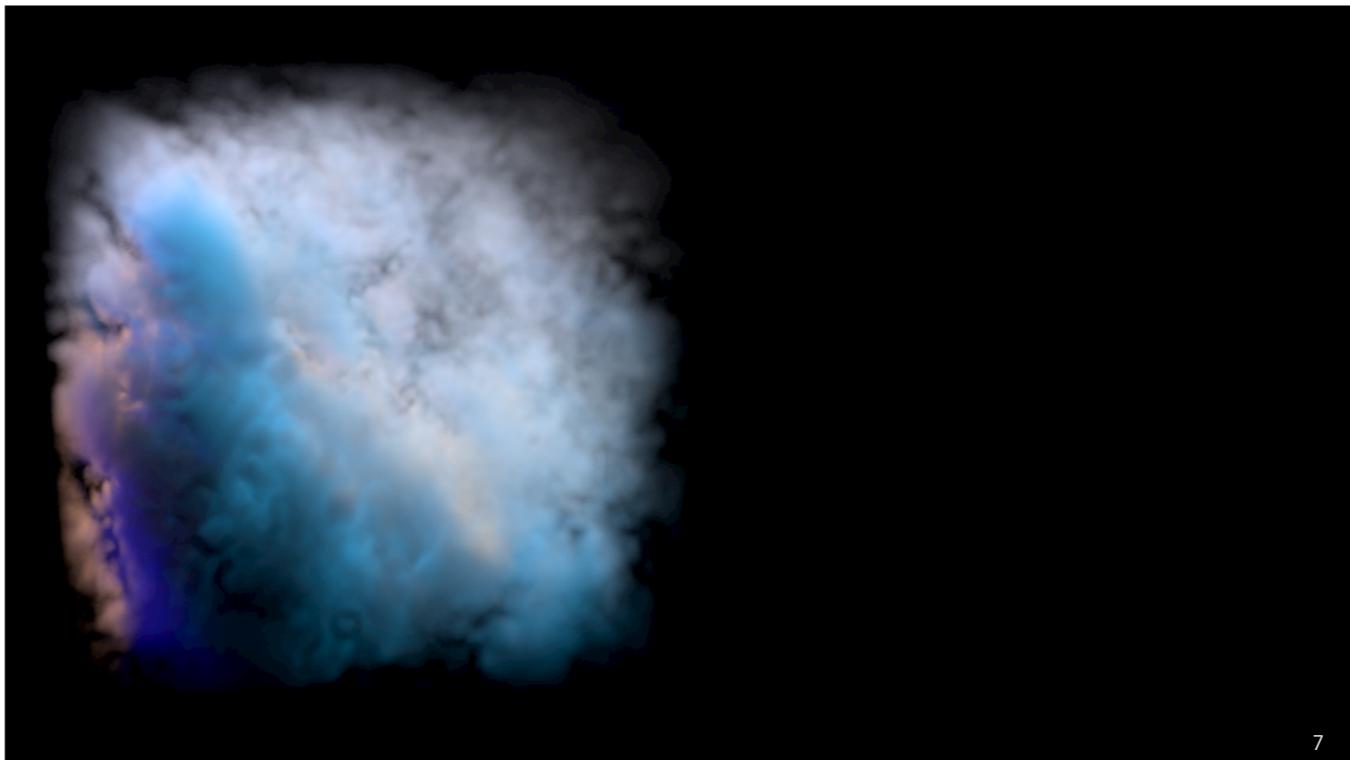
ACM Reference format:
Peter Kutz, Ralf Habel, Yining Karl Li, and Jan Novák. 2017. Spectral and Decomposition Tracking for Rendering Heterogeneous Volumes. *ACM Trans. Graph.* 36, 4, Article 111 (July 2017), 16 pages.
DOI: <http://dx.doi.org/10.1145/3072959.3073665>

5

To render their productions, Hyperion currently relies on techniques based on the null-scattering paradigm,

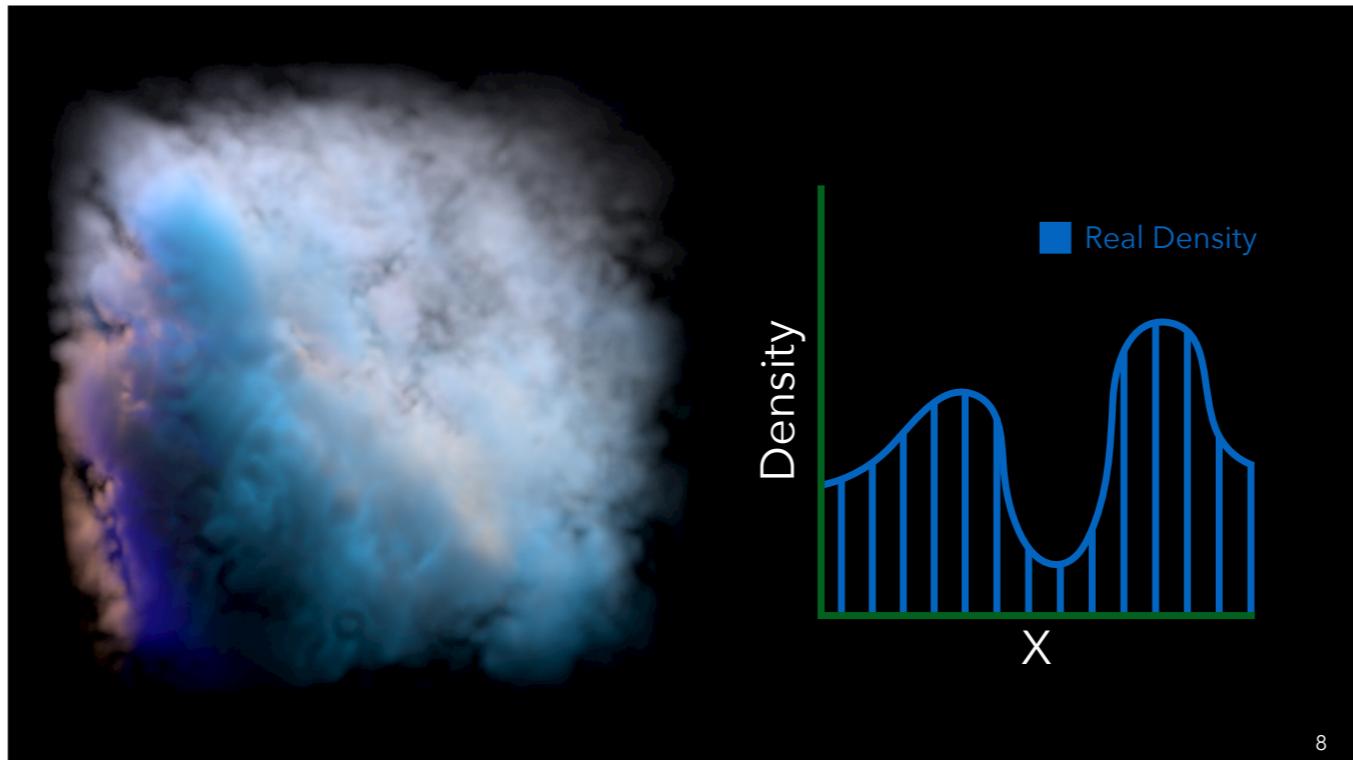


Which requires that we first homogenize all volumes.



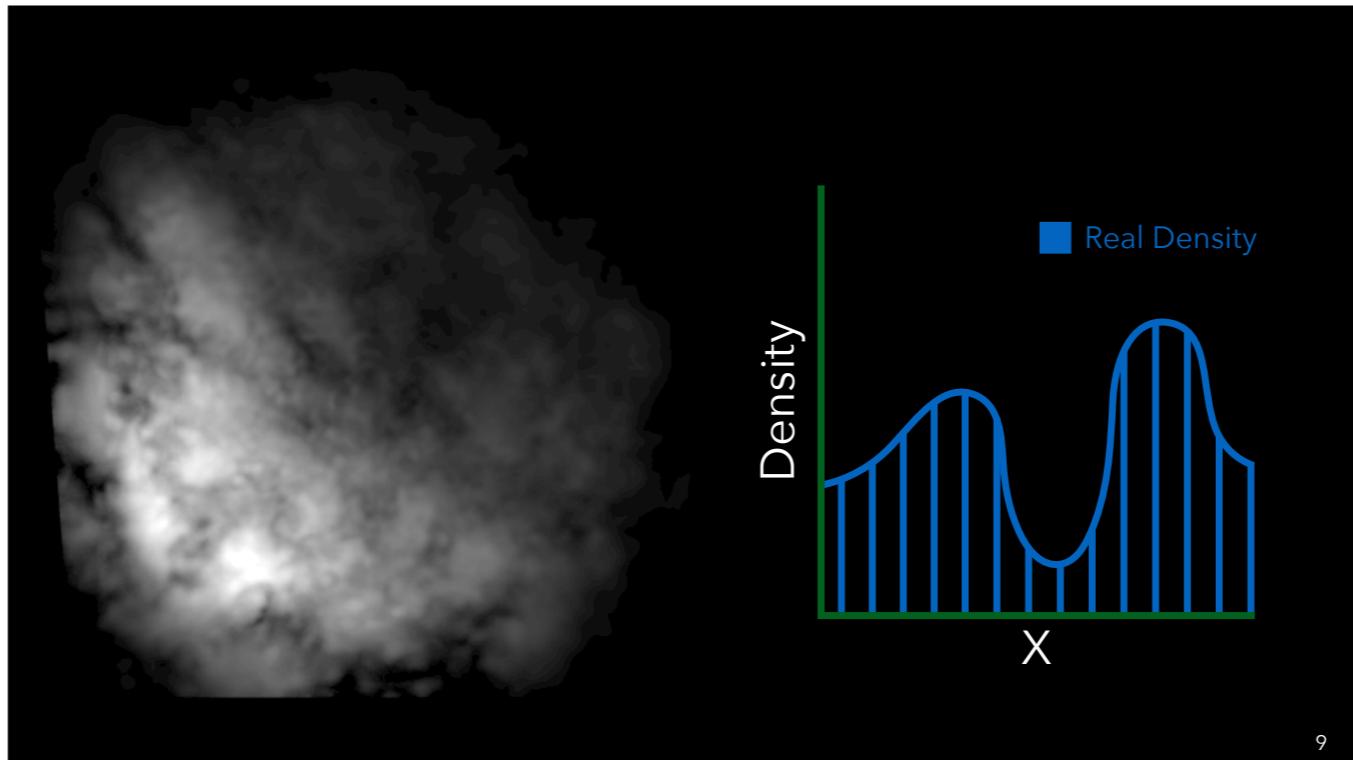
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Take for example this heterogeneous volume,



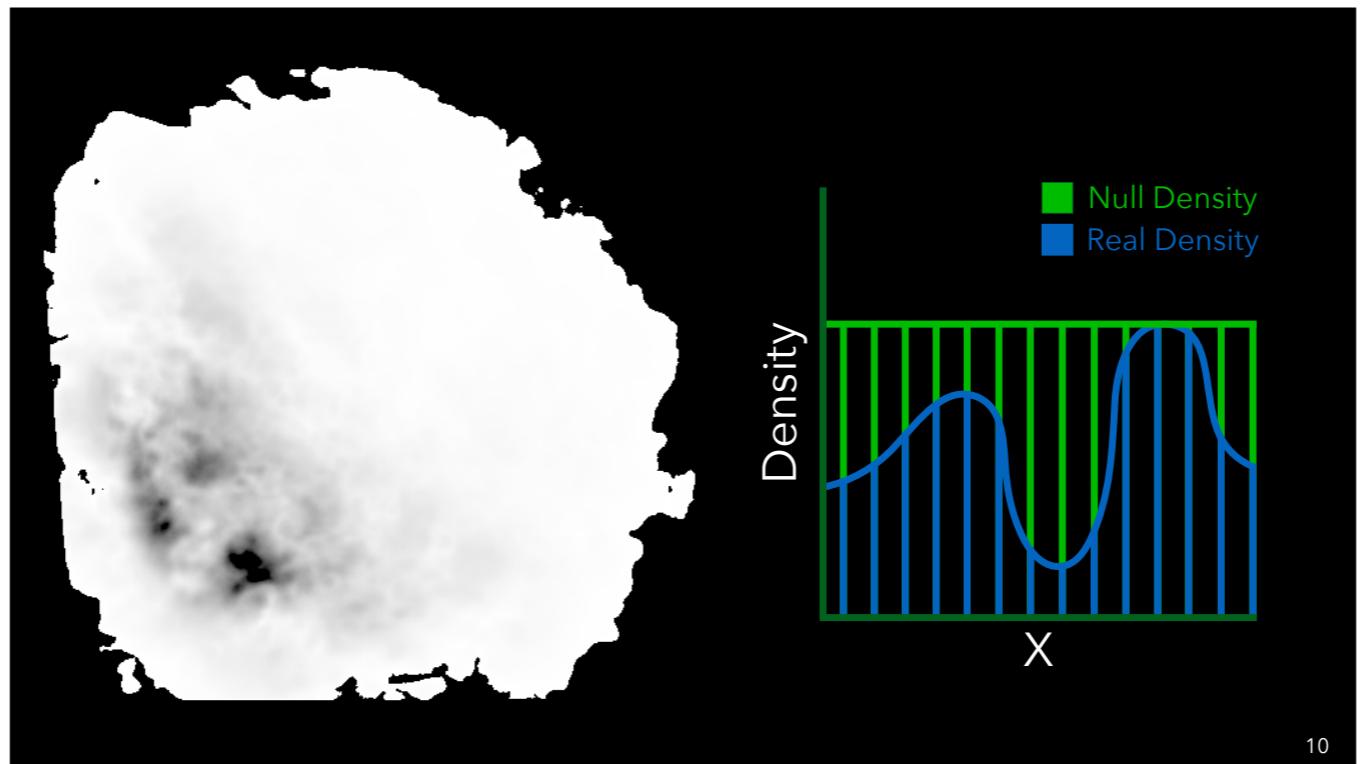
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Which has a spatially varying density function. For visualization purposes, I am going to replace the rendering of the volume,

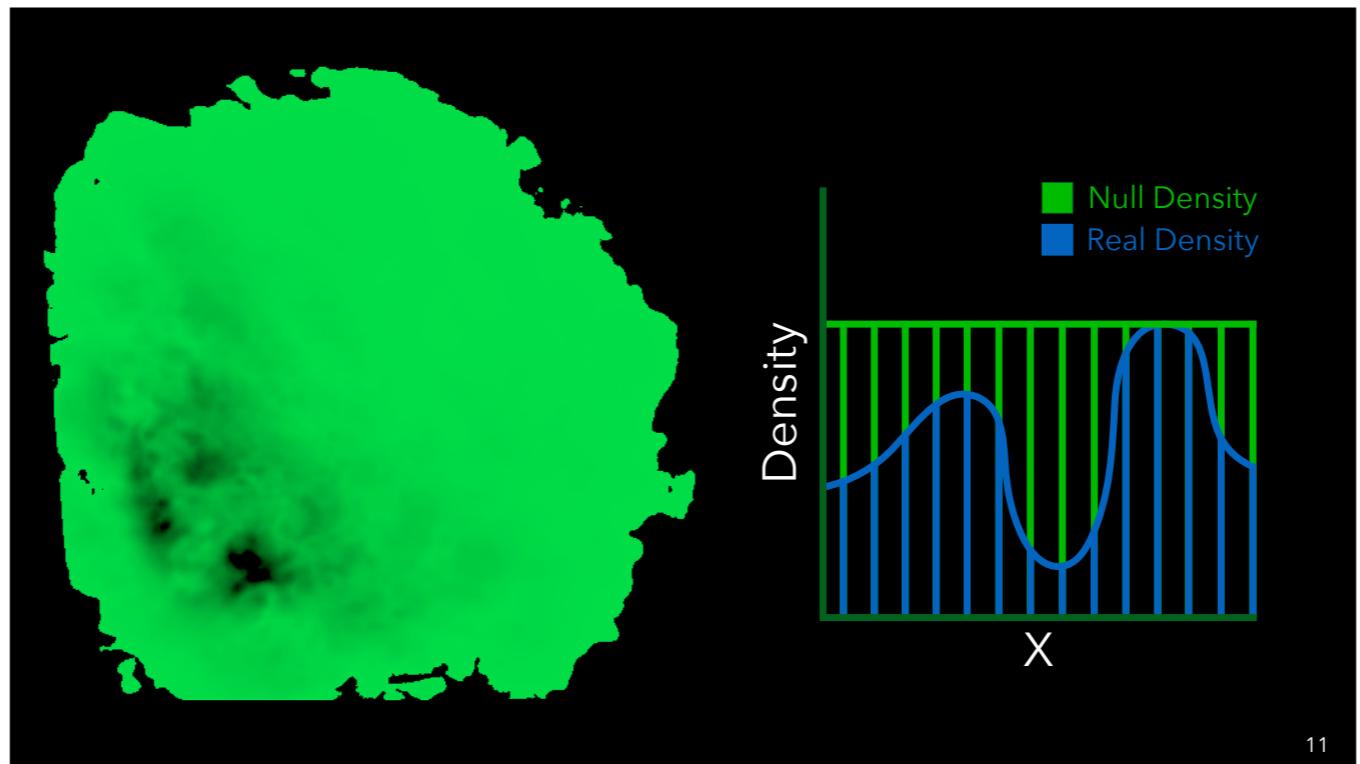


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With a visualization of the average density looking straight through the medium. Null-scattering techniques require us

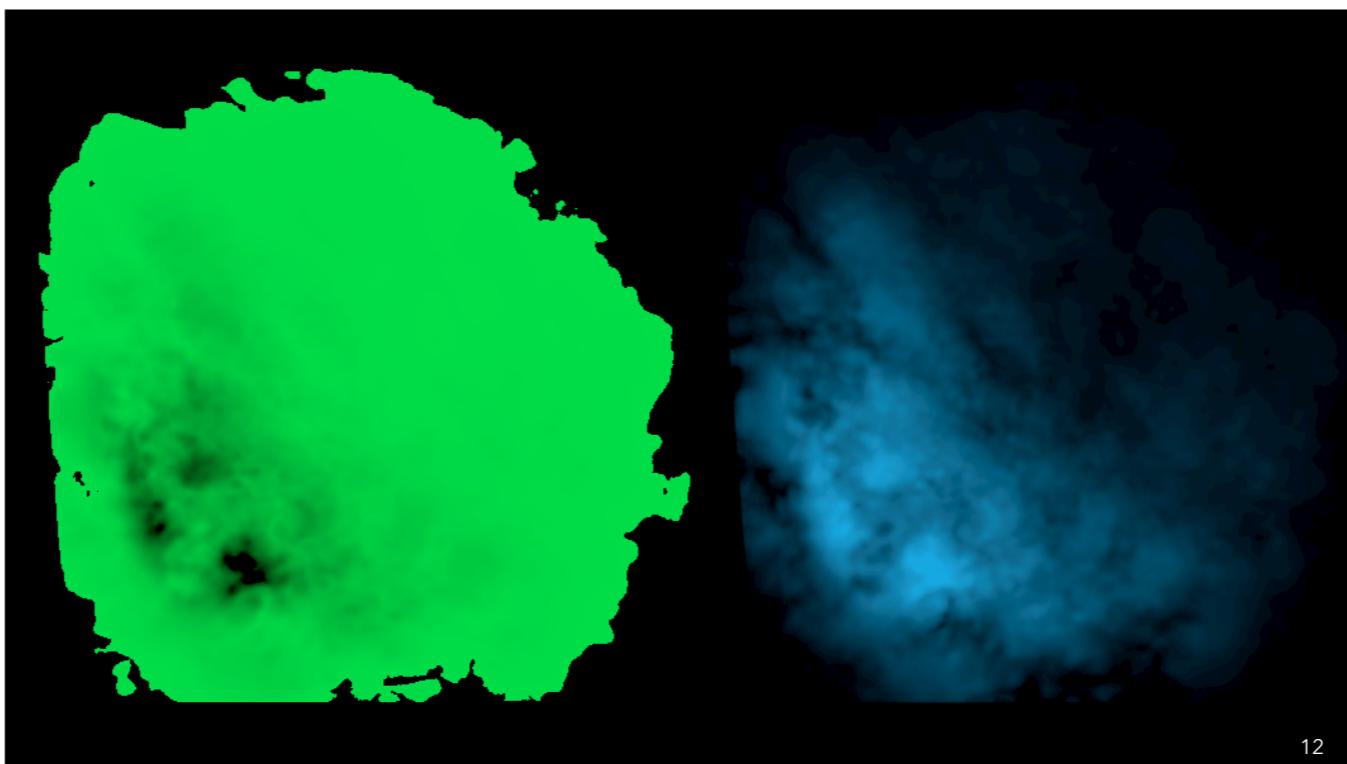


to inject fictitious, or null density into the medium, such that if we took



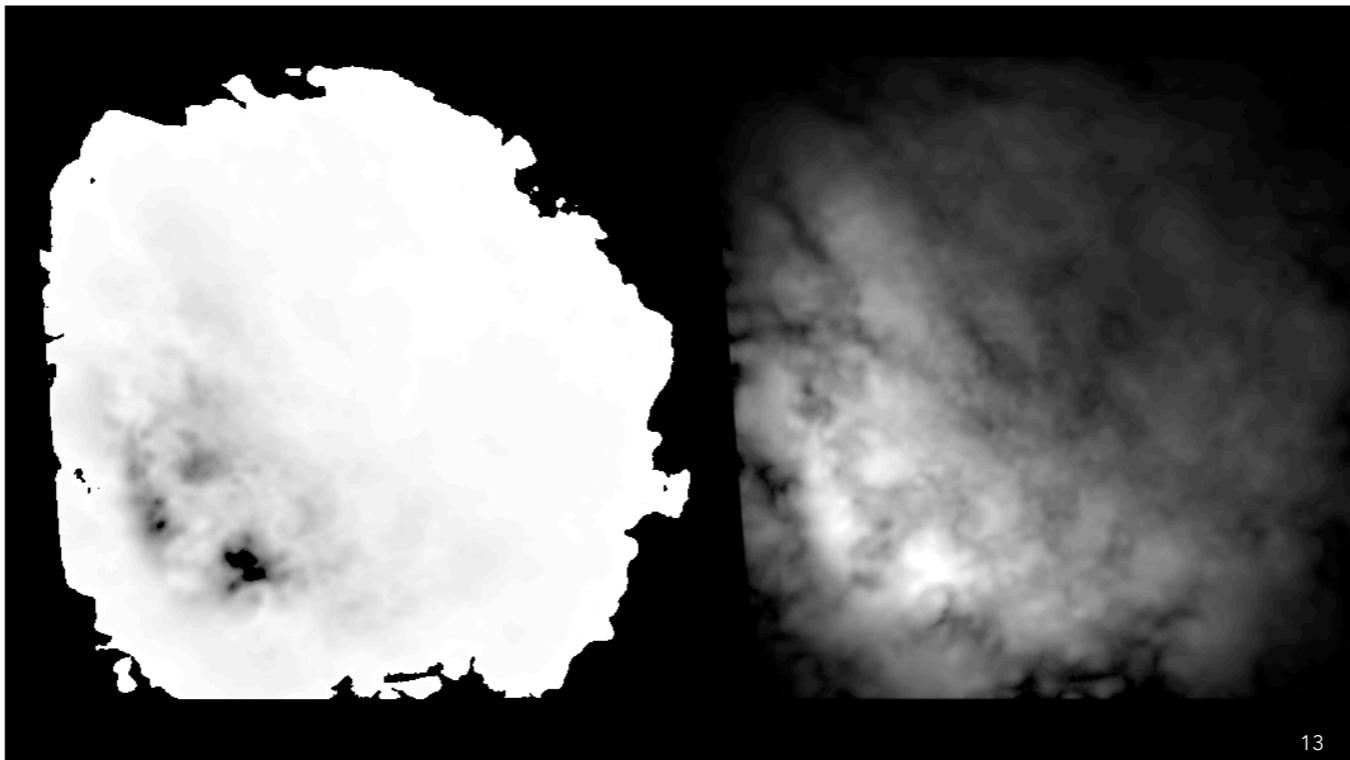
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the null density,



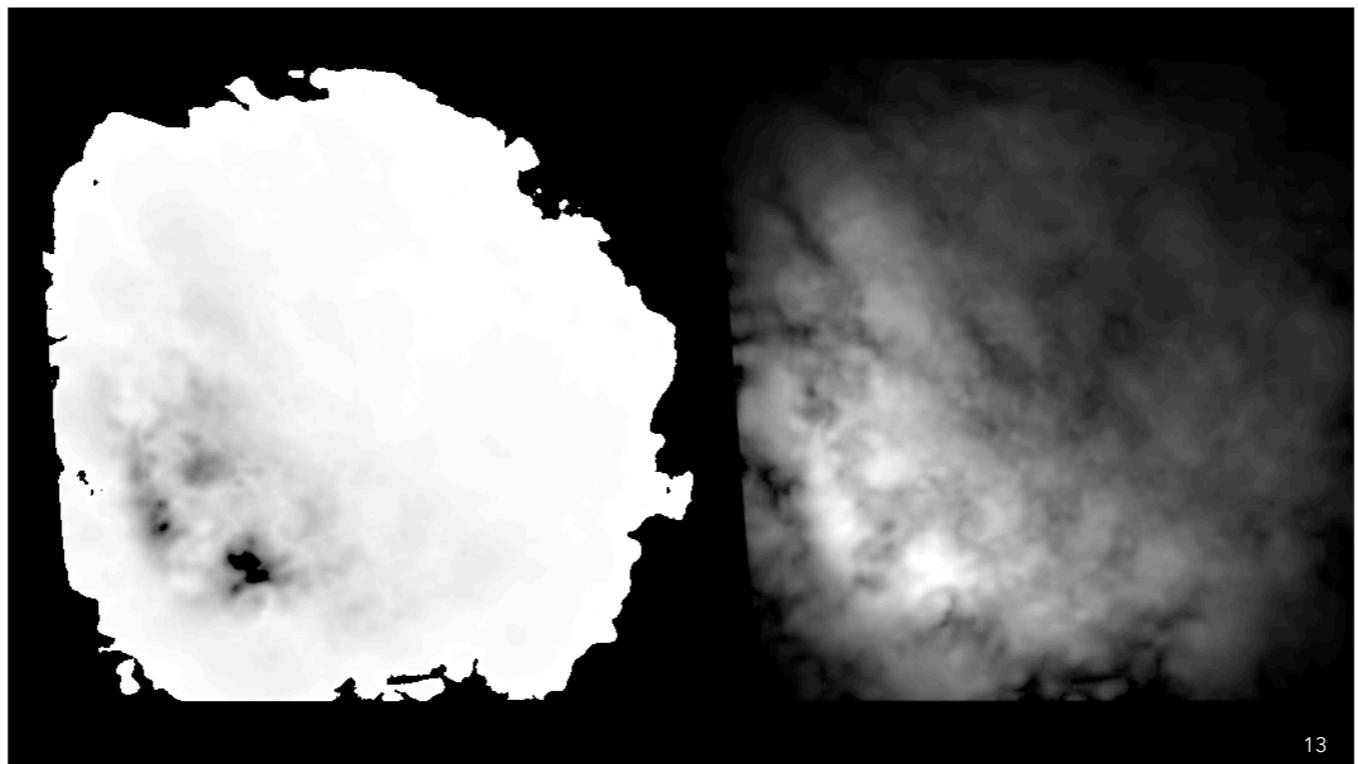
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and real density



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And then combined them by adding them together,



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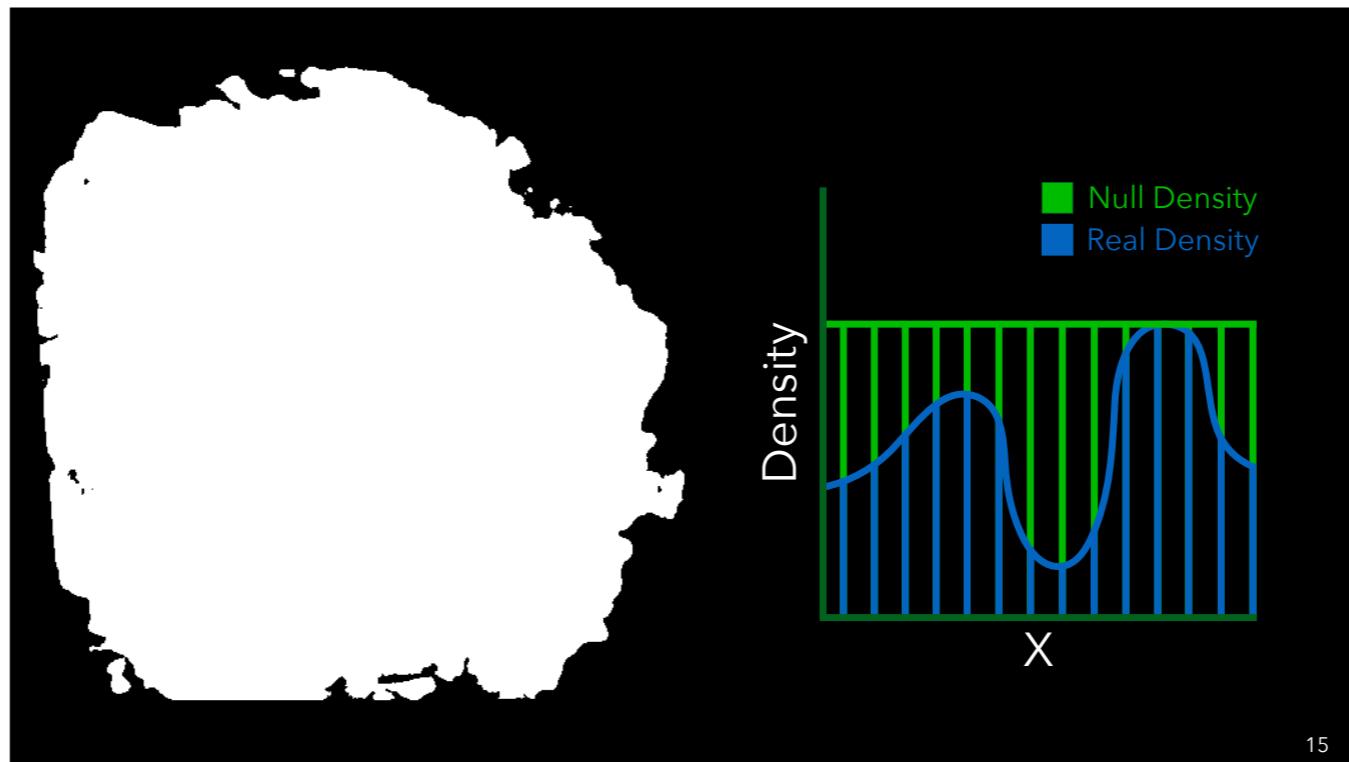


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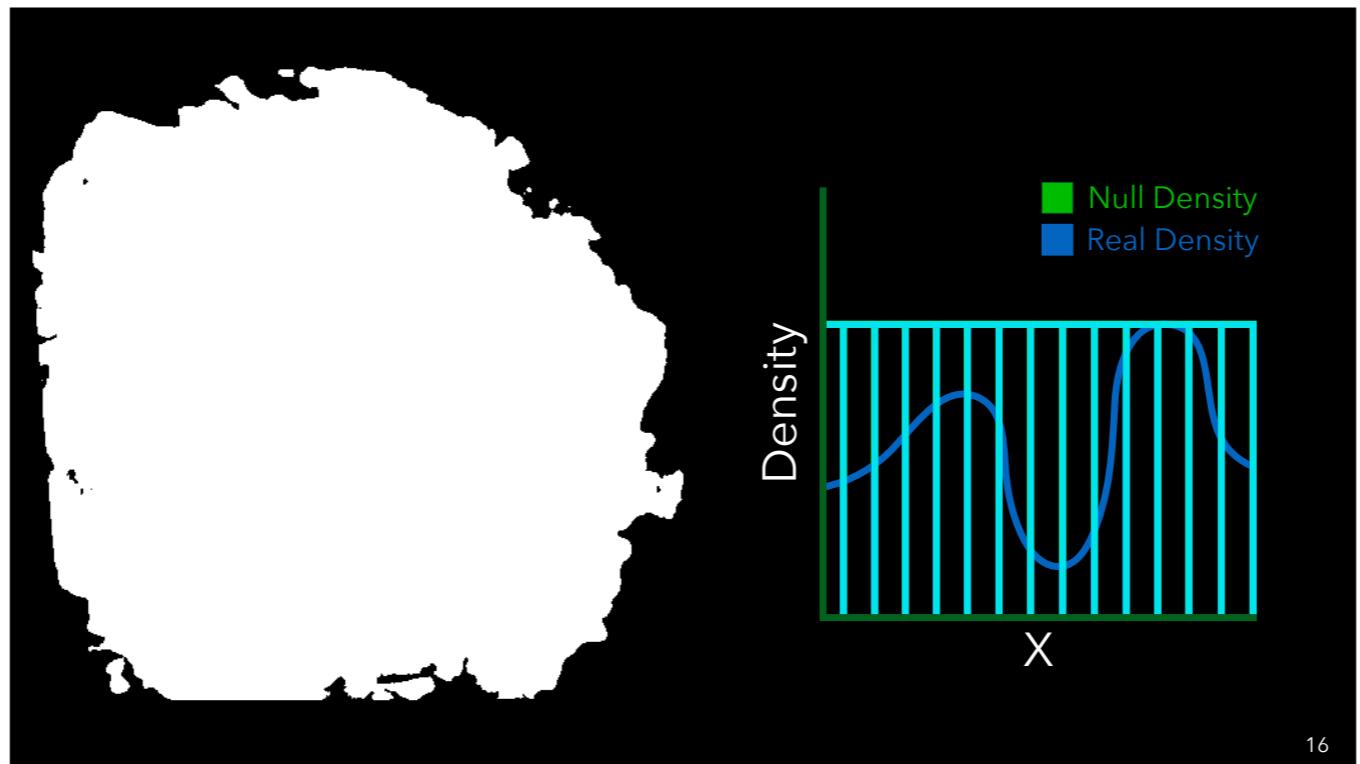
We would end up



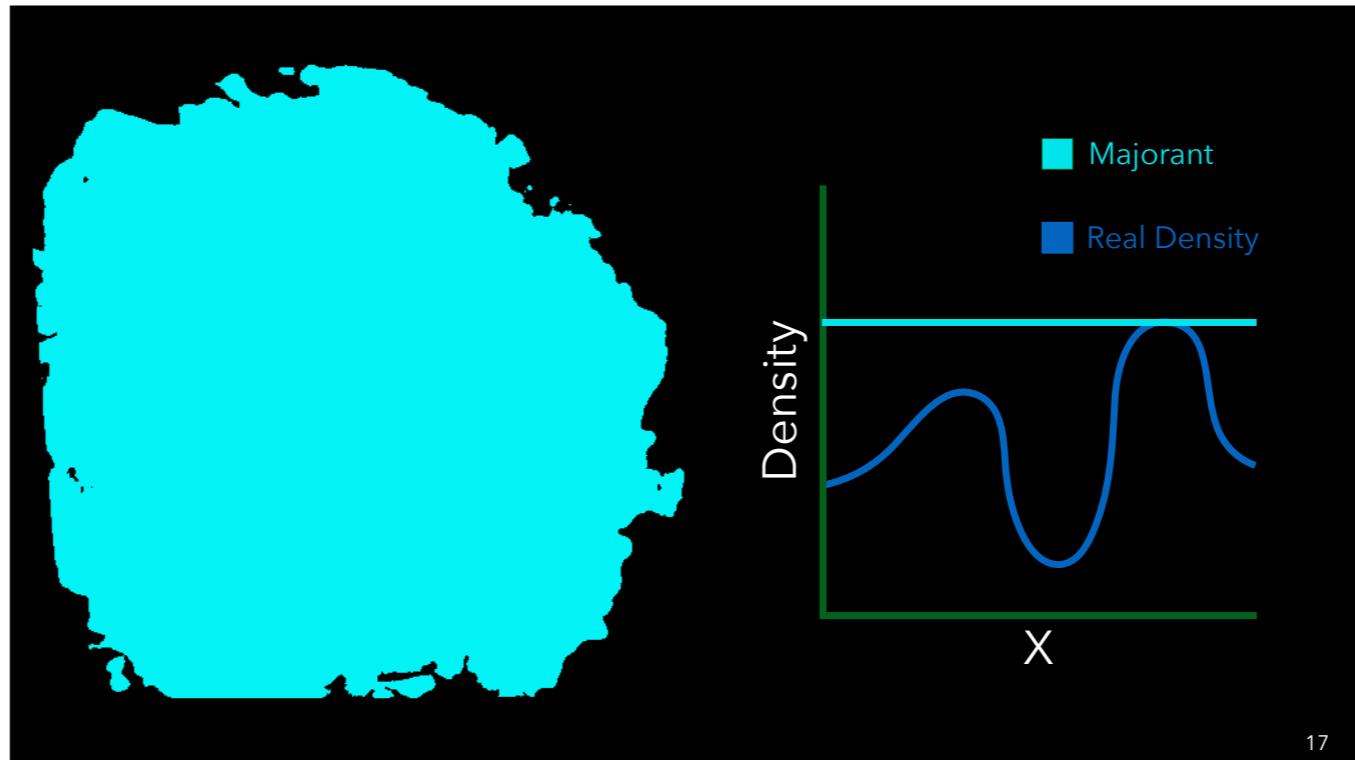
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With a constant density medium whose

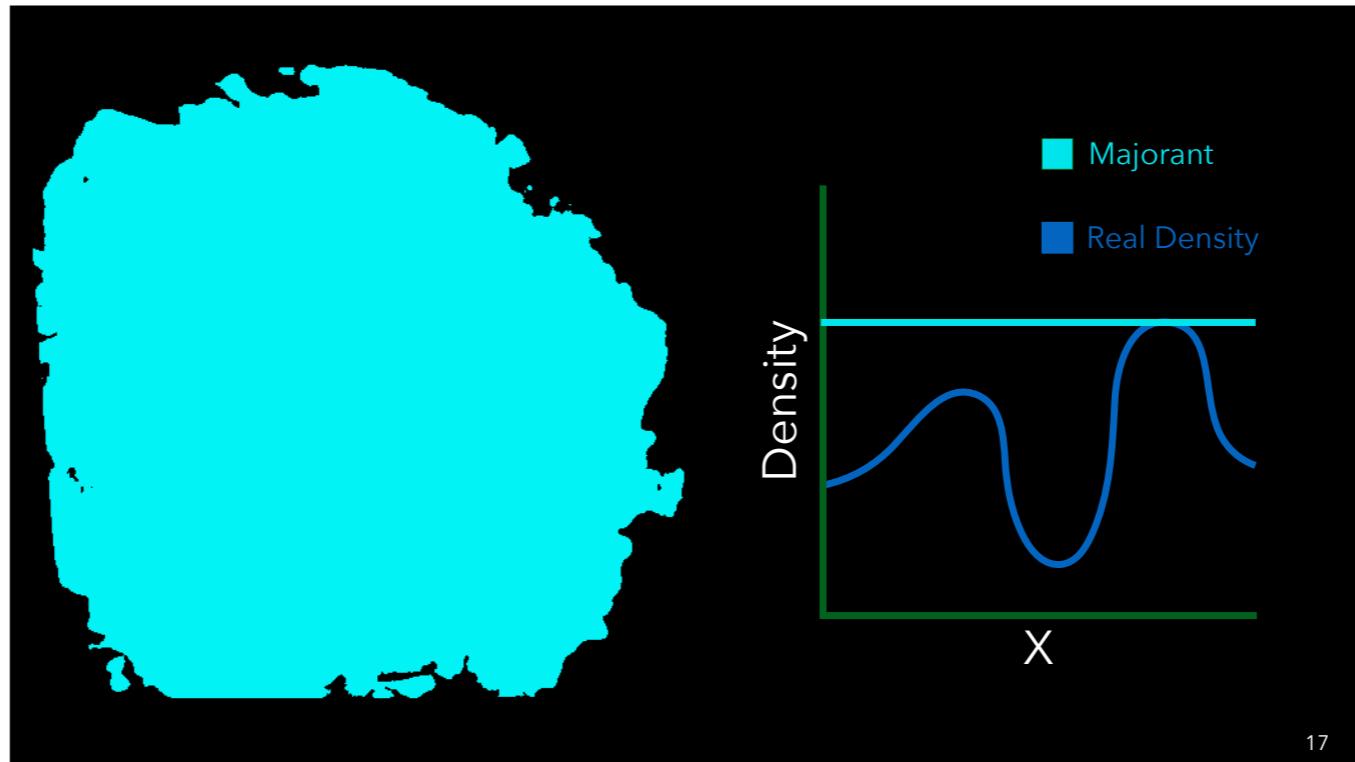


total combined density is often referred to

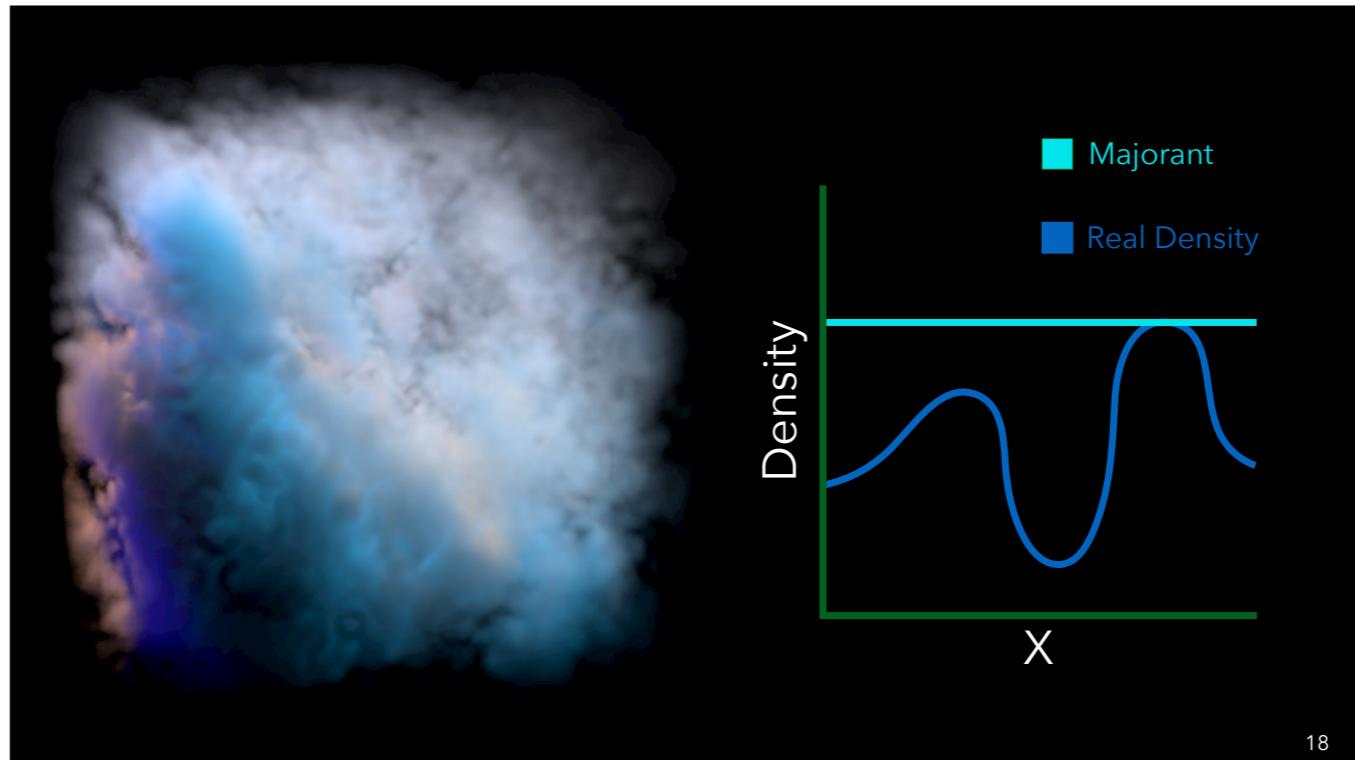


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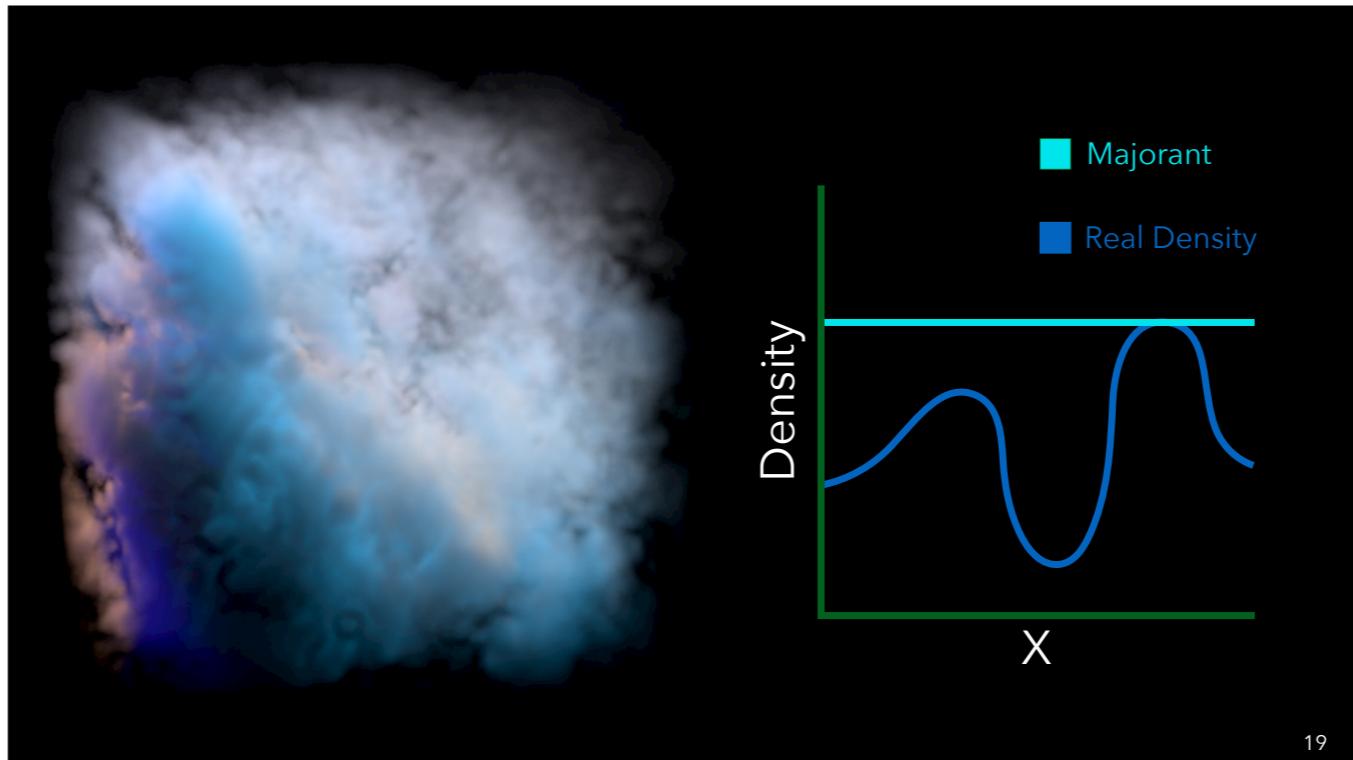
As the majorant. Now, most modern algorithms allow us to specify the majorant (click) as any non-zero positive value, and no matter what majorant we specify,



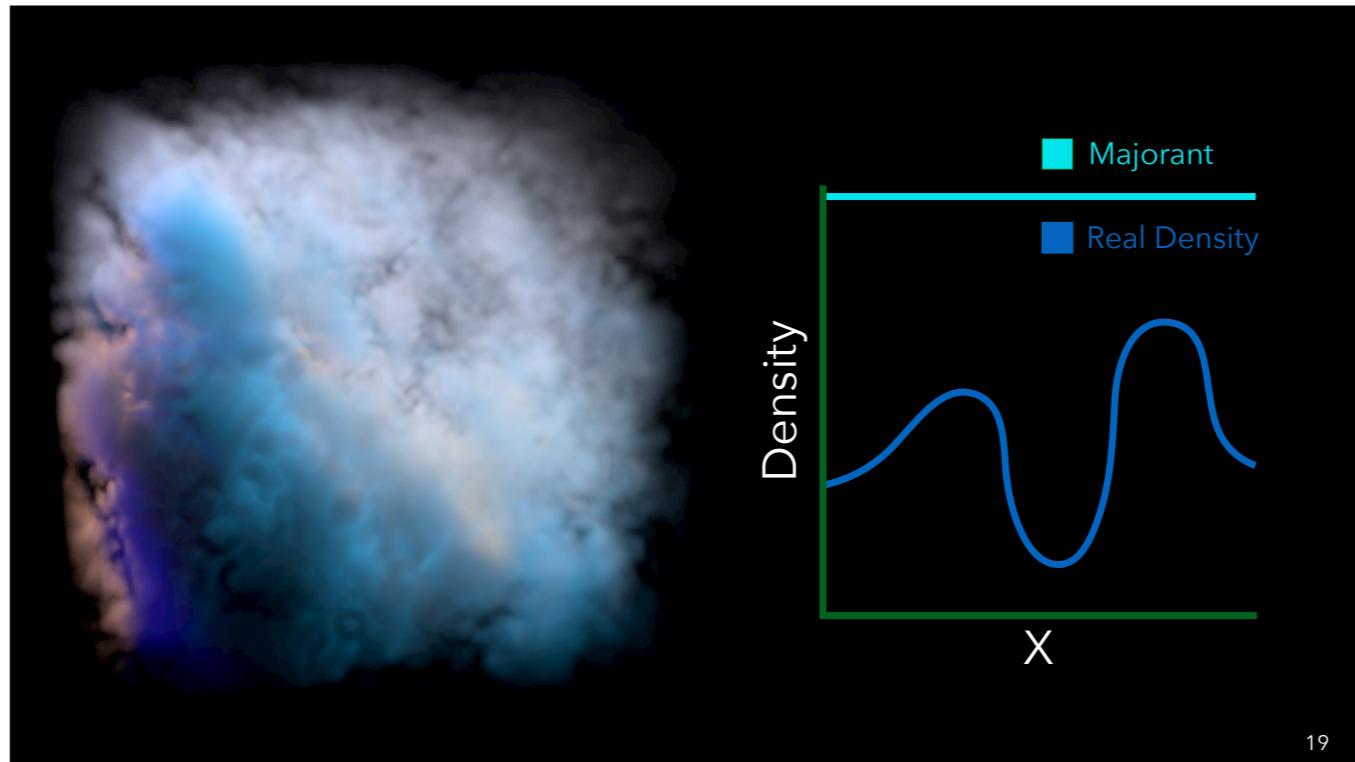
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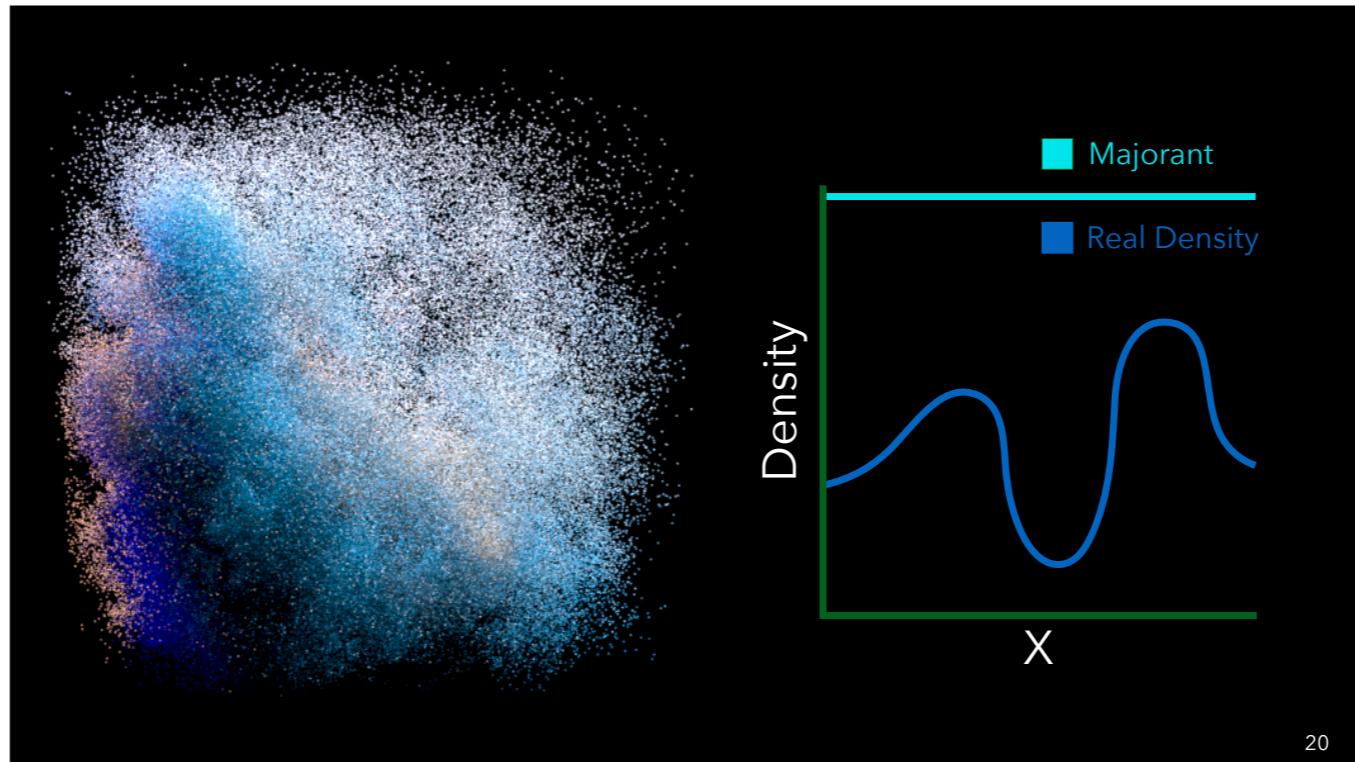
Modern null-scattering algorithms should still give us the correct expected result. However, the choice of the majorant directly impacts the performance of our renders.



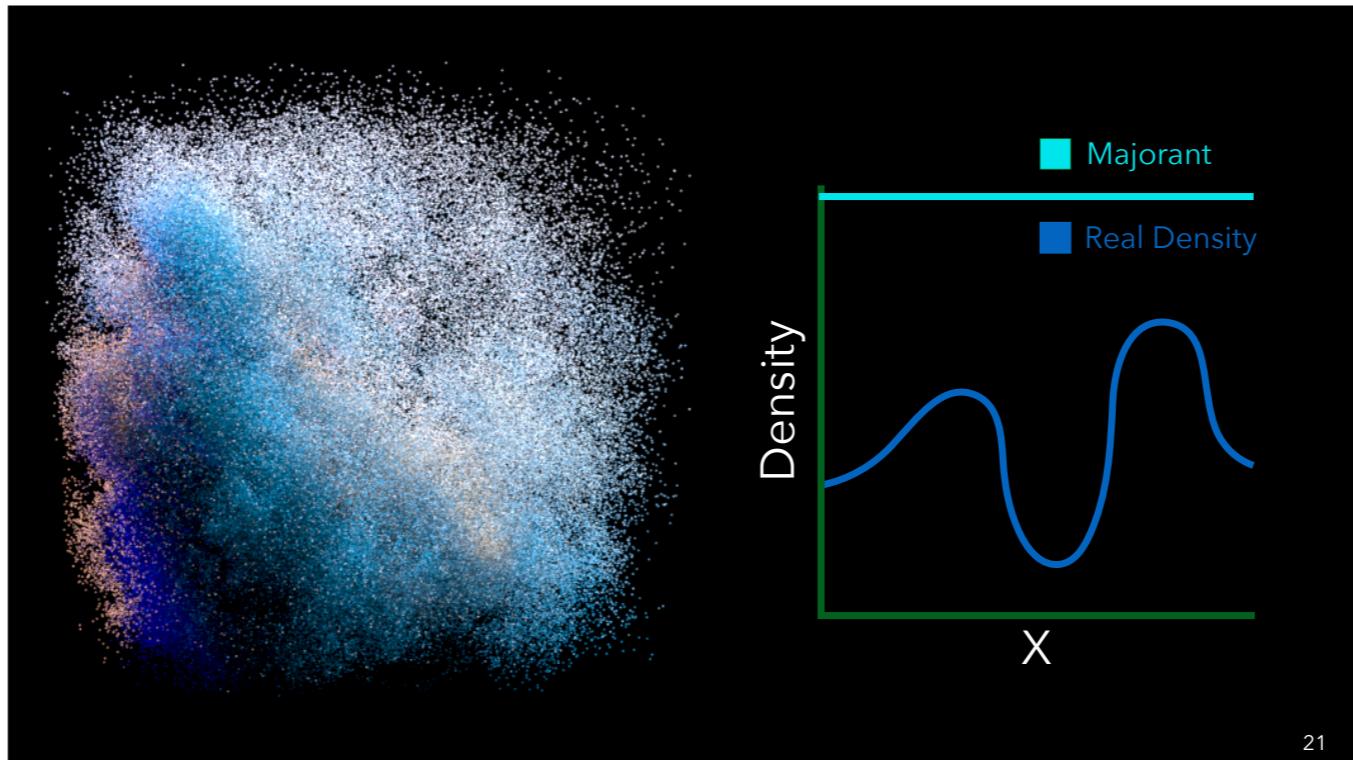
If the majorant is set too high (*click*),



19

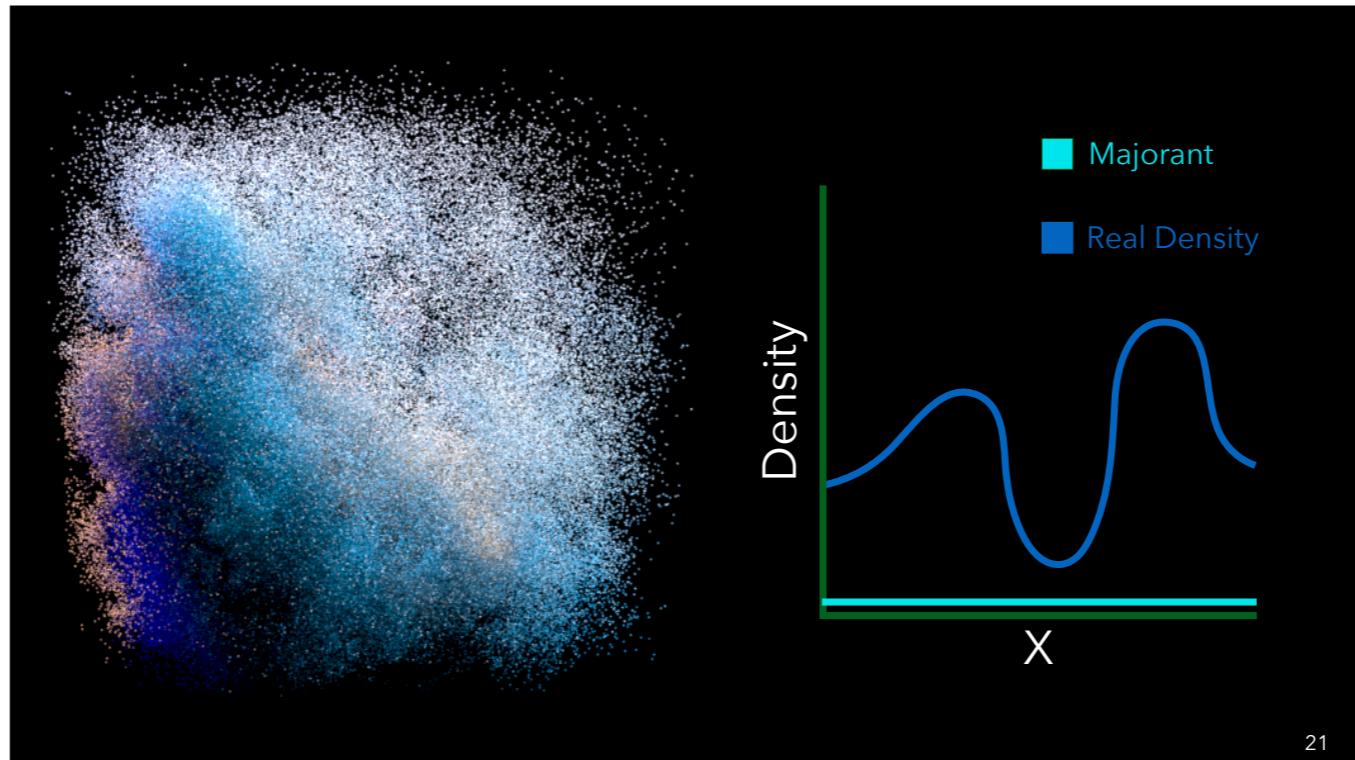


then the cost of our renders will increase, and may even become too costly to in production.

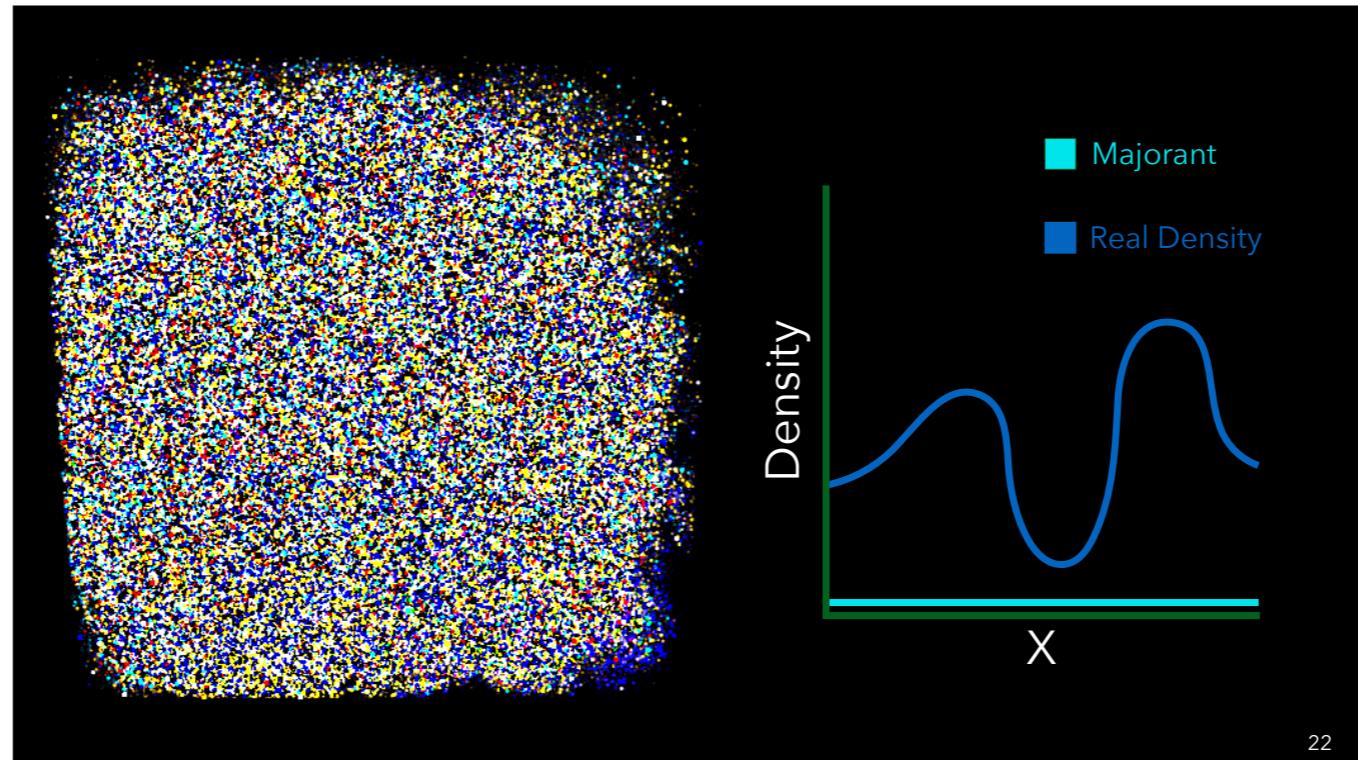


21

Alternatively, if the majorant is set too low (*click*) such that the majorant no longer bounds the density, the renders might become fast,

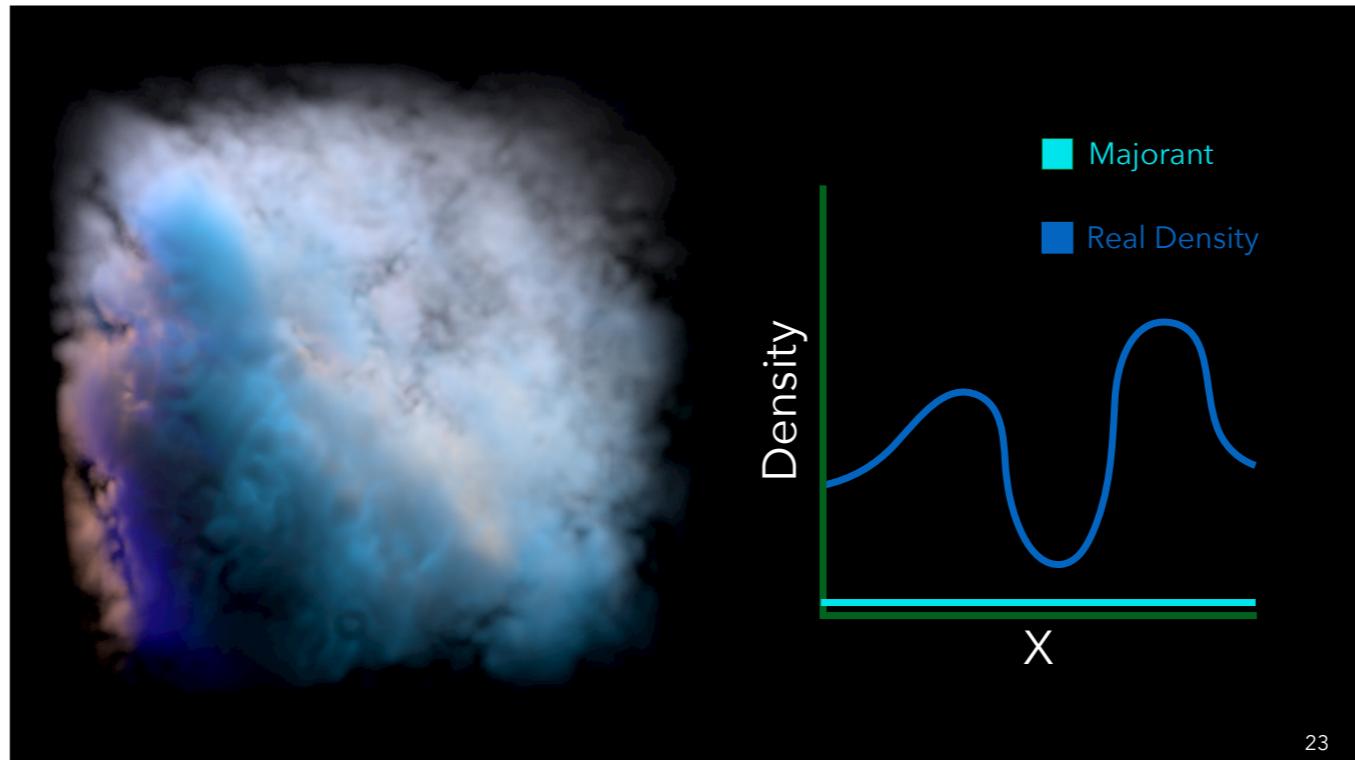


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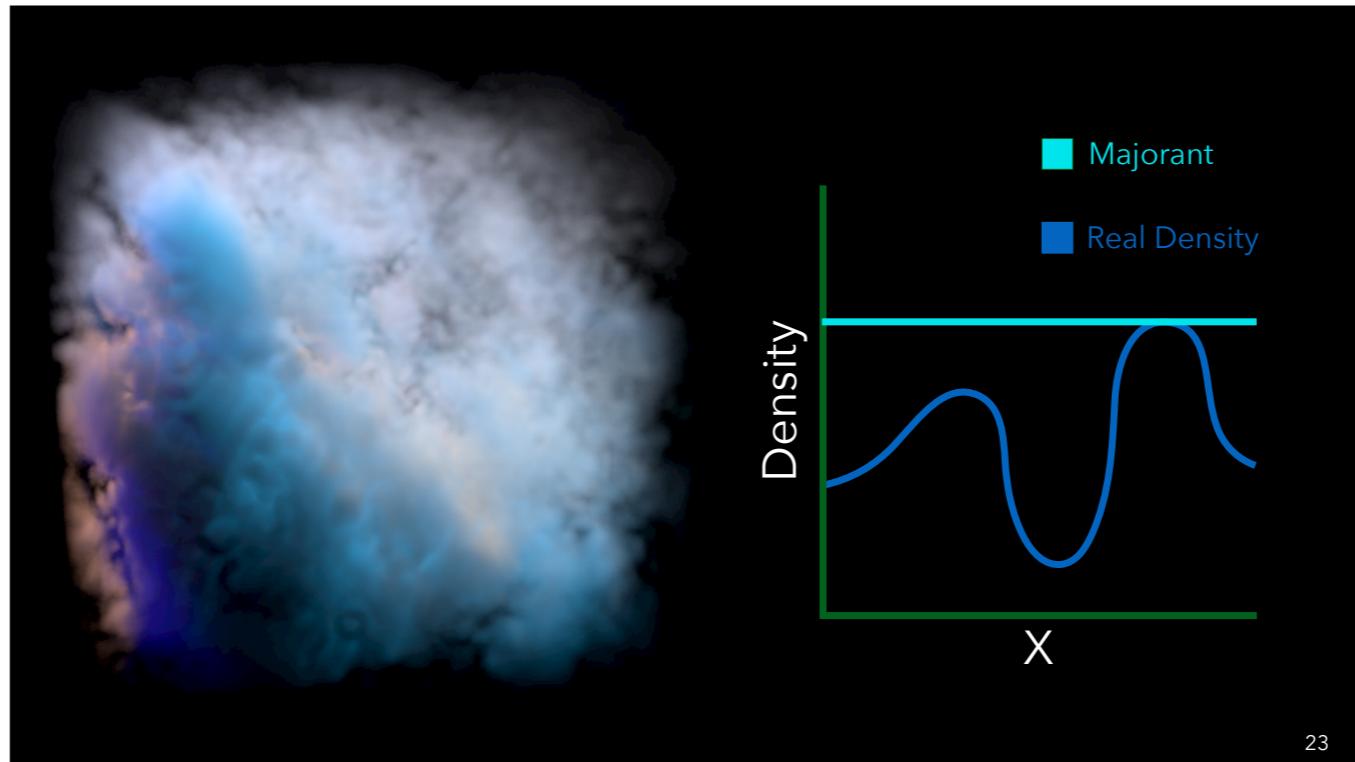
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But the variance of the renders will become so uncontrollable, that the renders will never converge in any reasonable amount of time. To have both low cost



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and guarantee low variance, we ideally want a majorant which (*click*) bounds the density as tightly as possible. However, getting these tight majorants



23

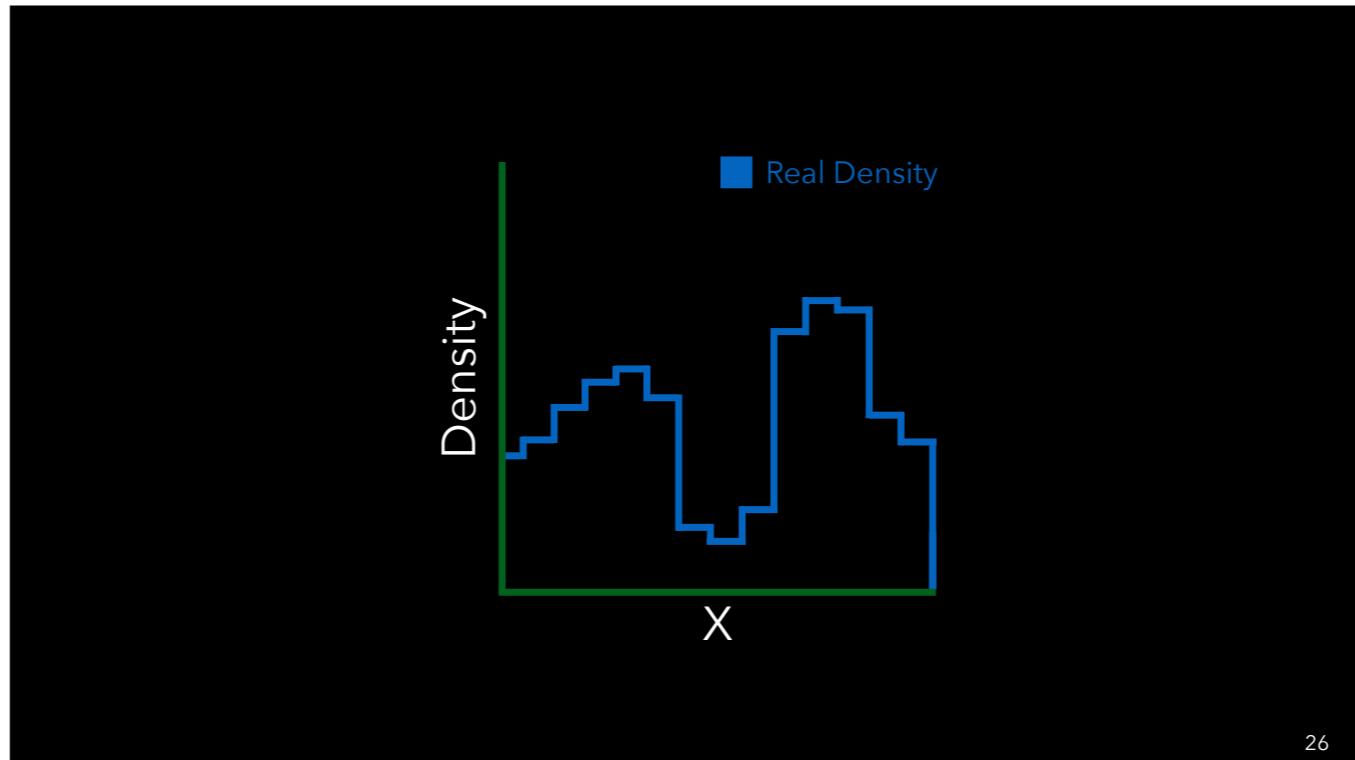


Depends on how we represent our volumes.



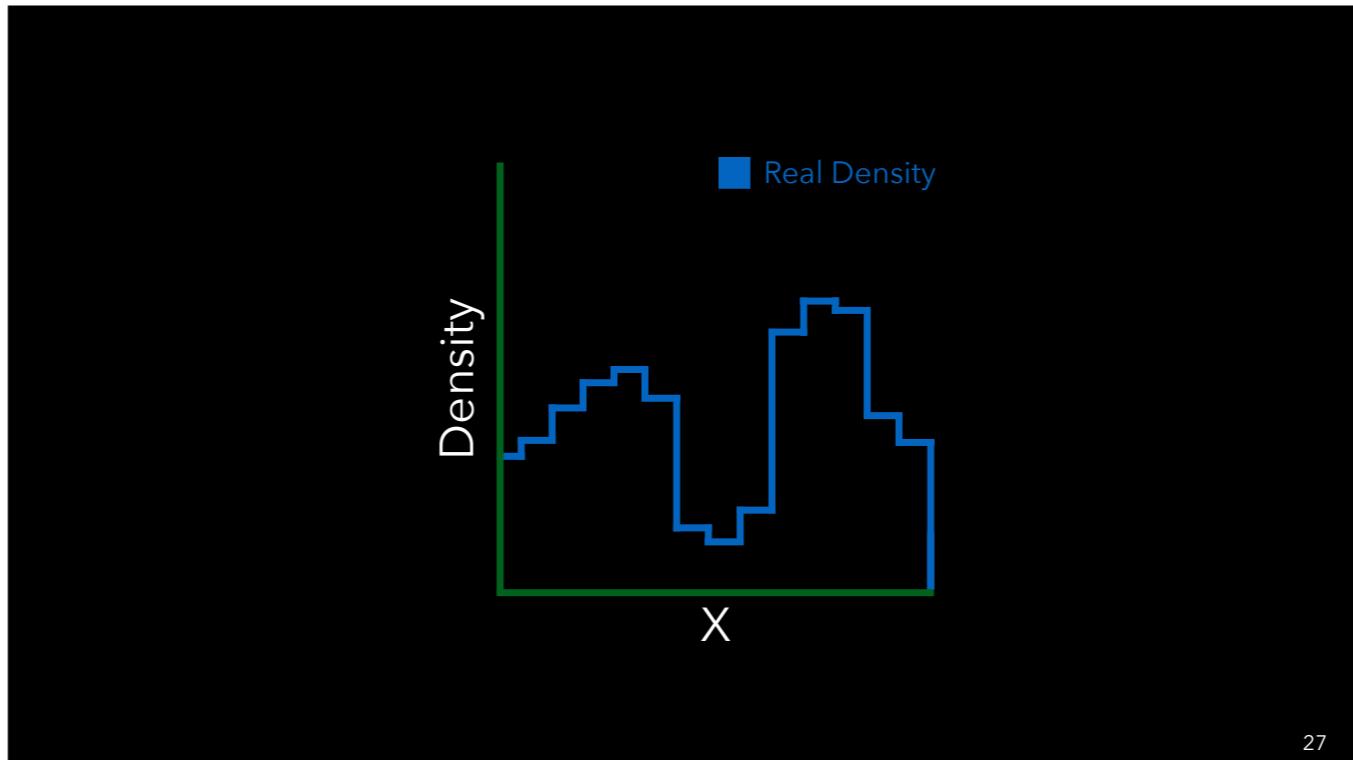
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if we only render volumes like the Disney cloud,



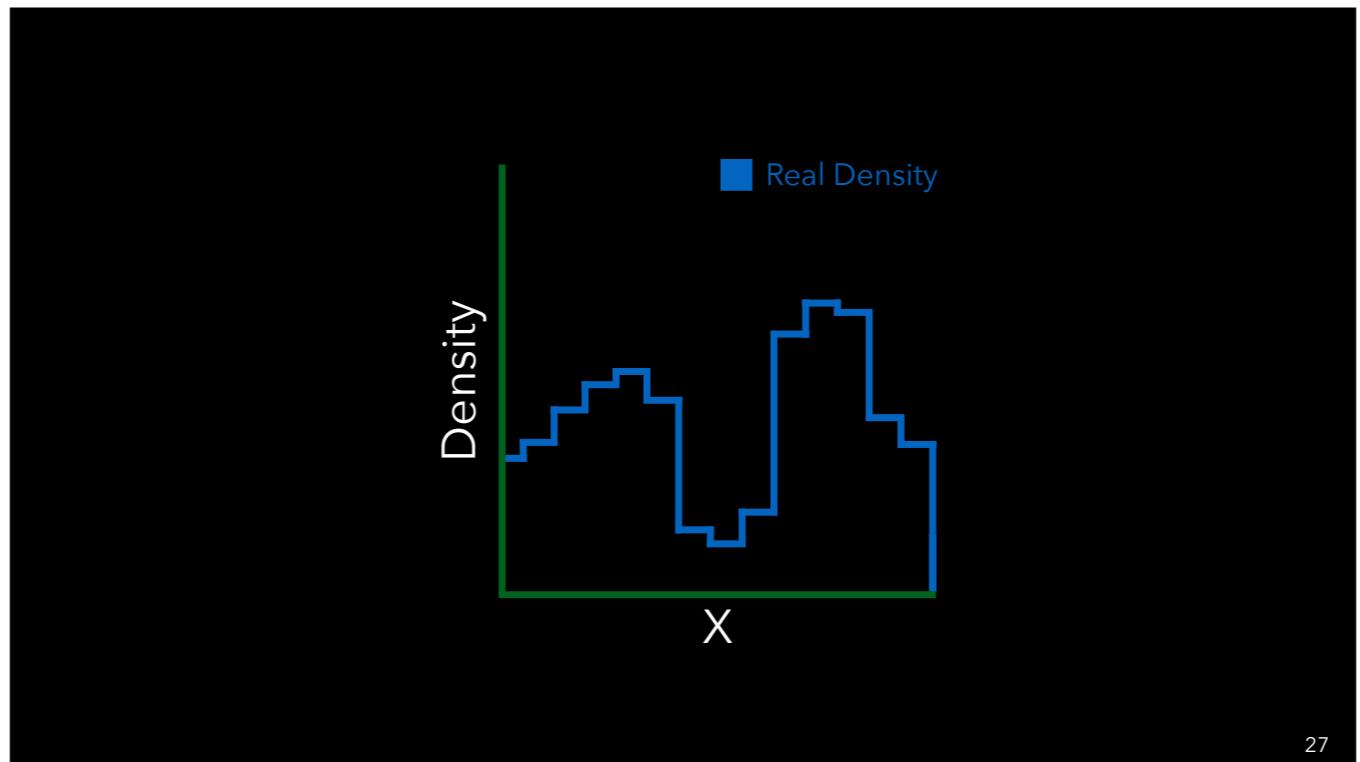
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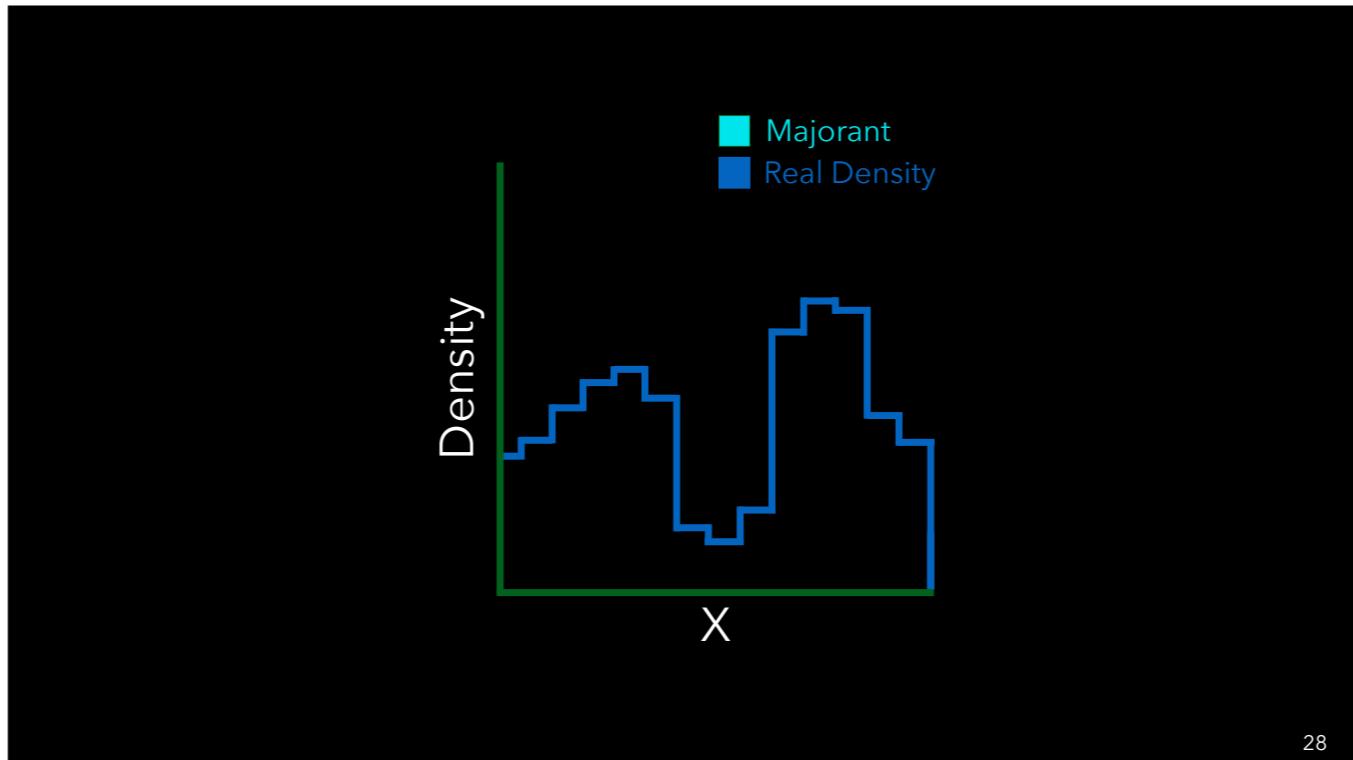
Which are explicitly stored as voxel density grids, then finding a tightly bounding majorant



27

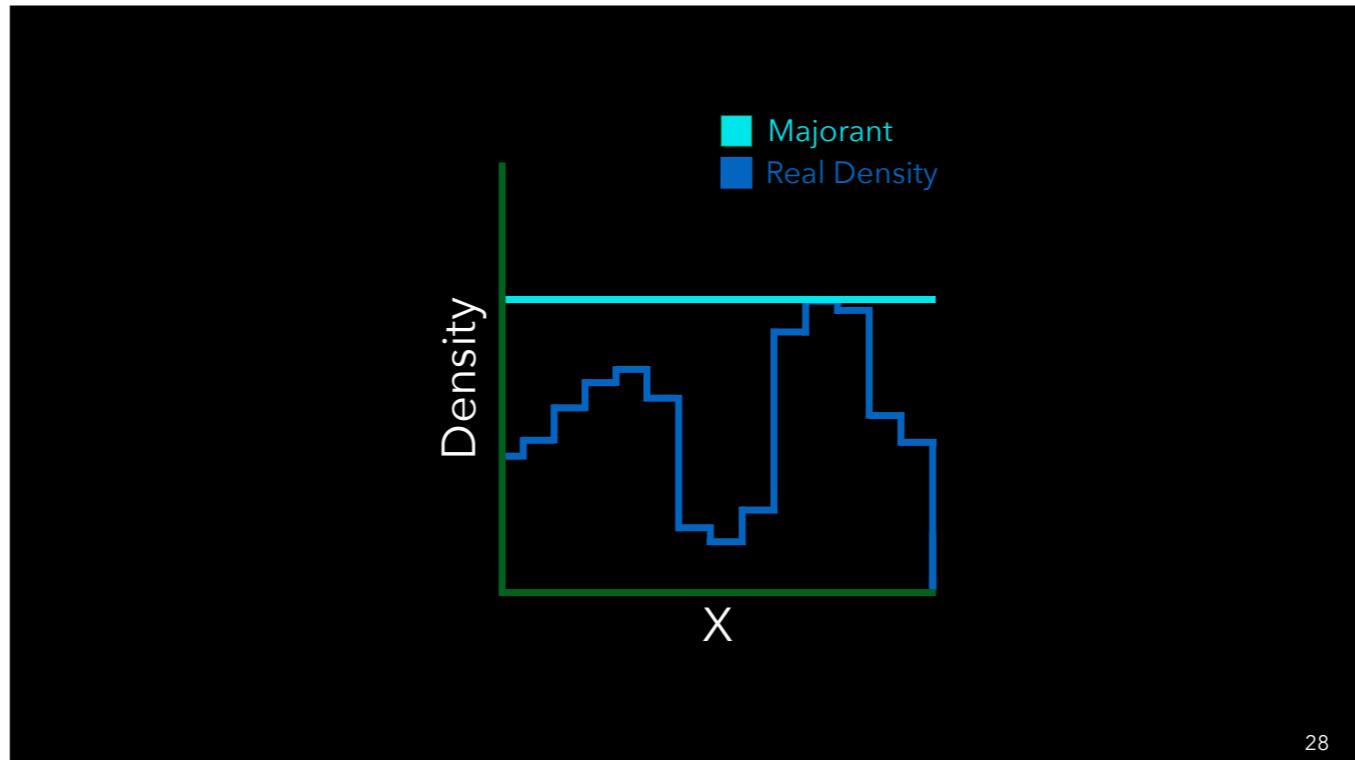
Is as easy (click) as iterating through all of the voxels,



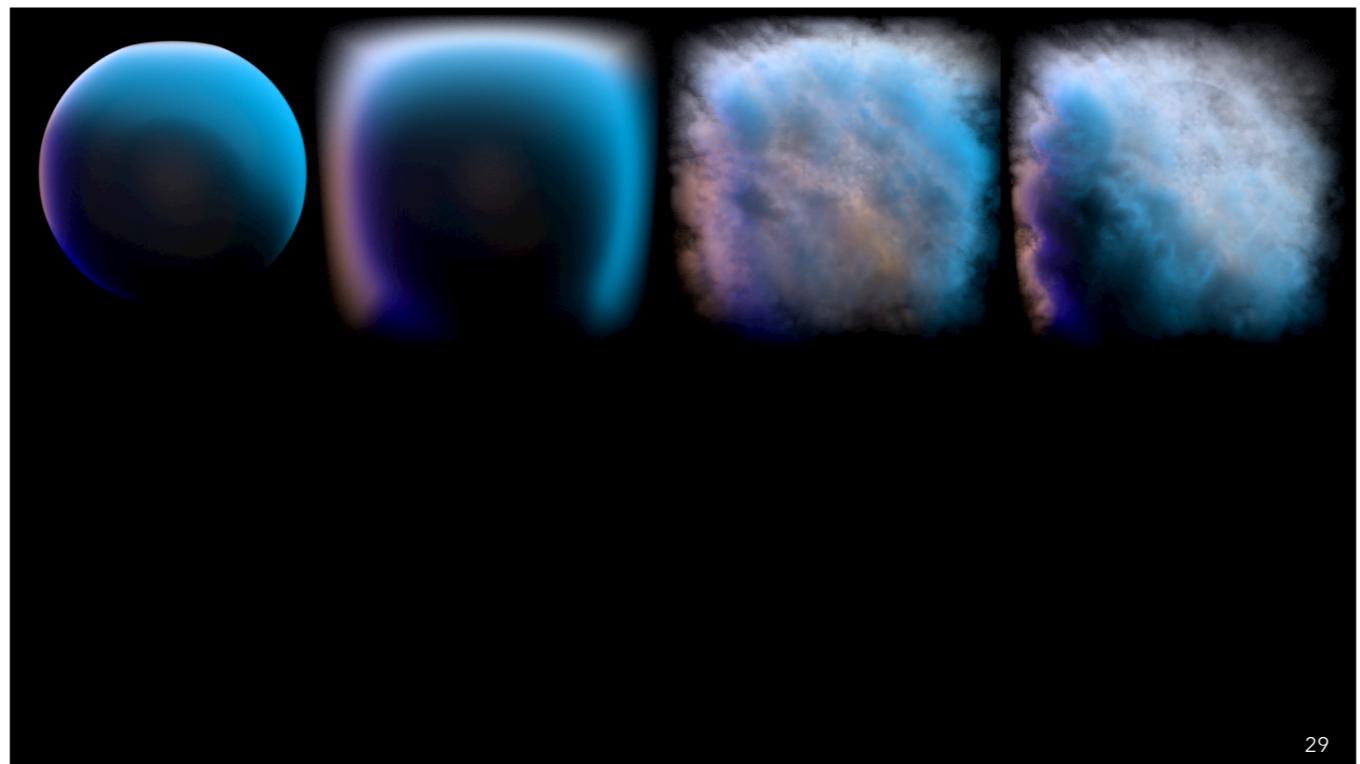


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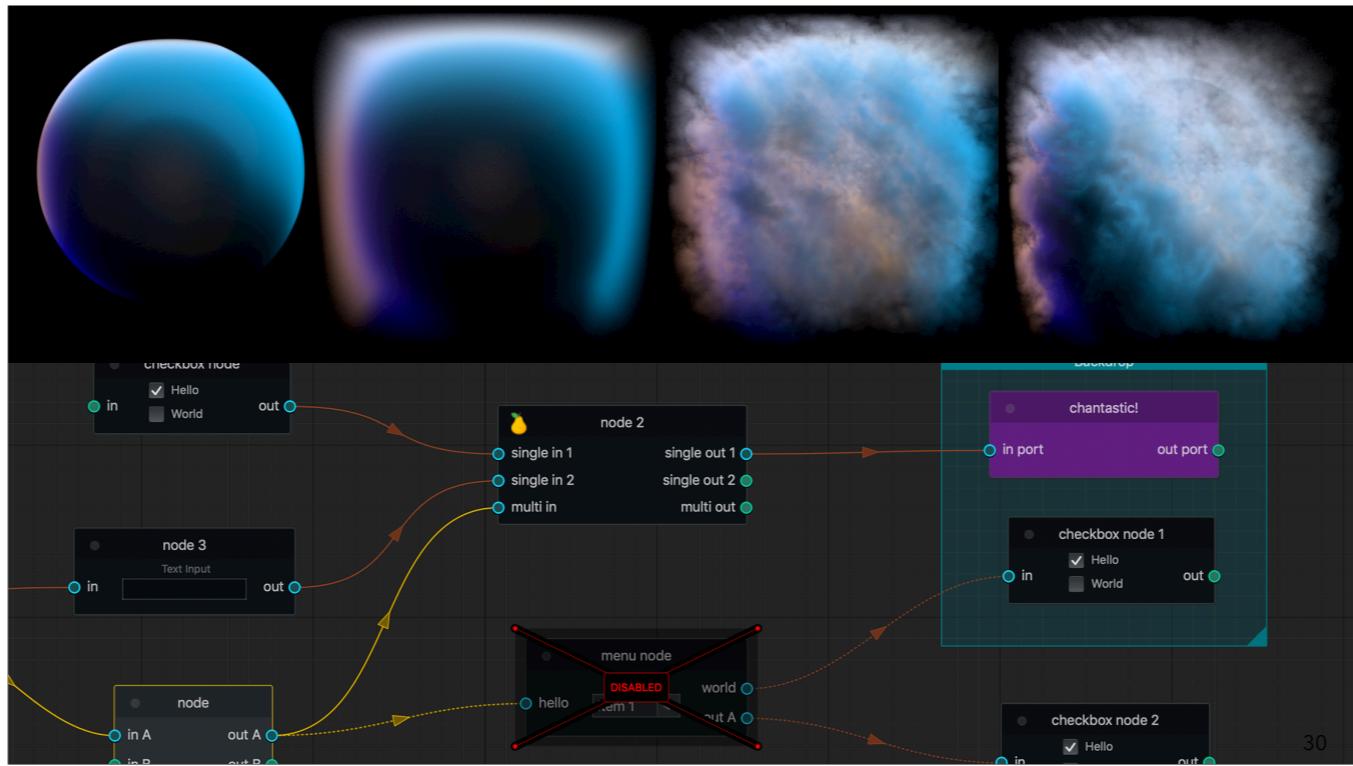
And setting the majorant to the largest found density. However,



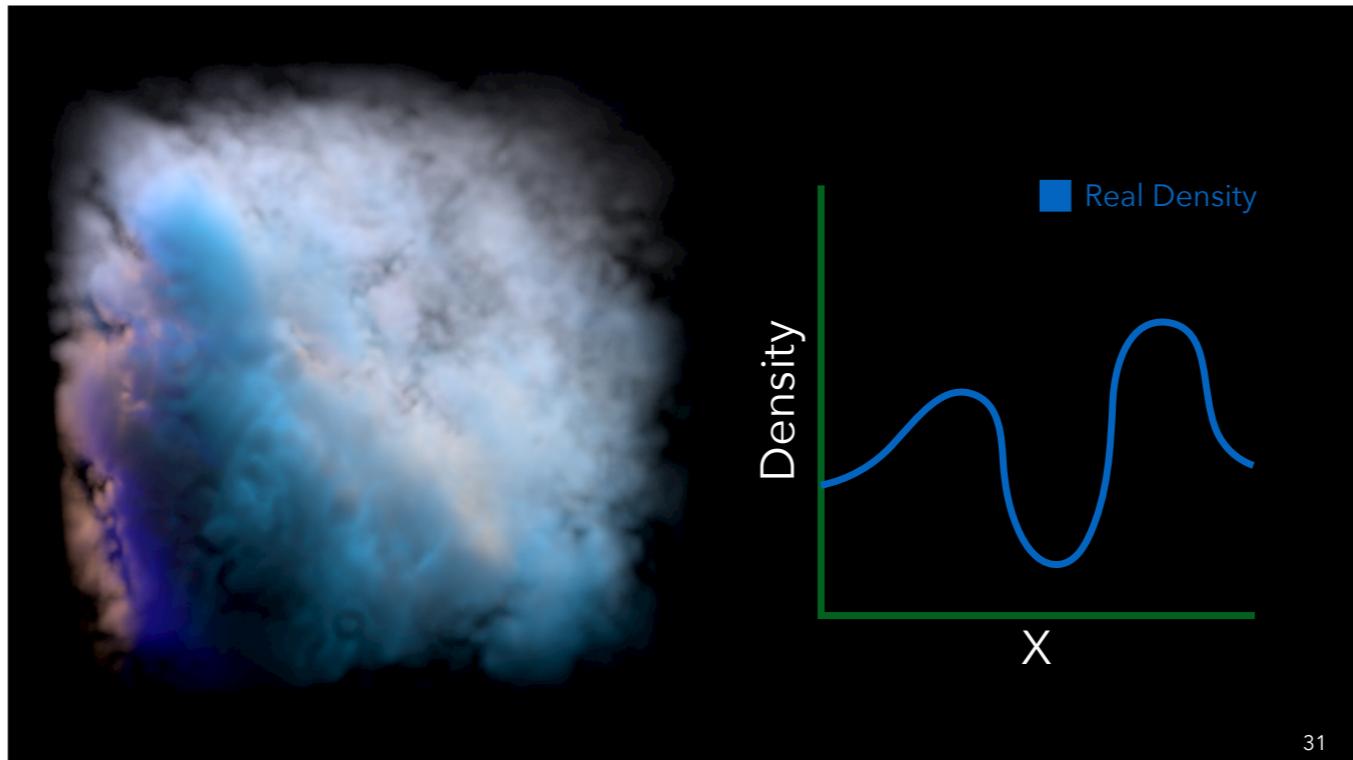
when dealing with purely procedural volumes,



29

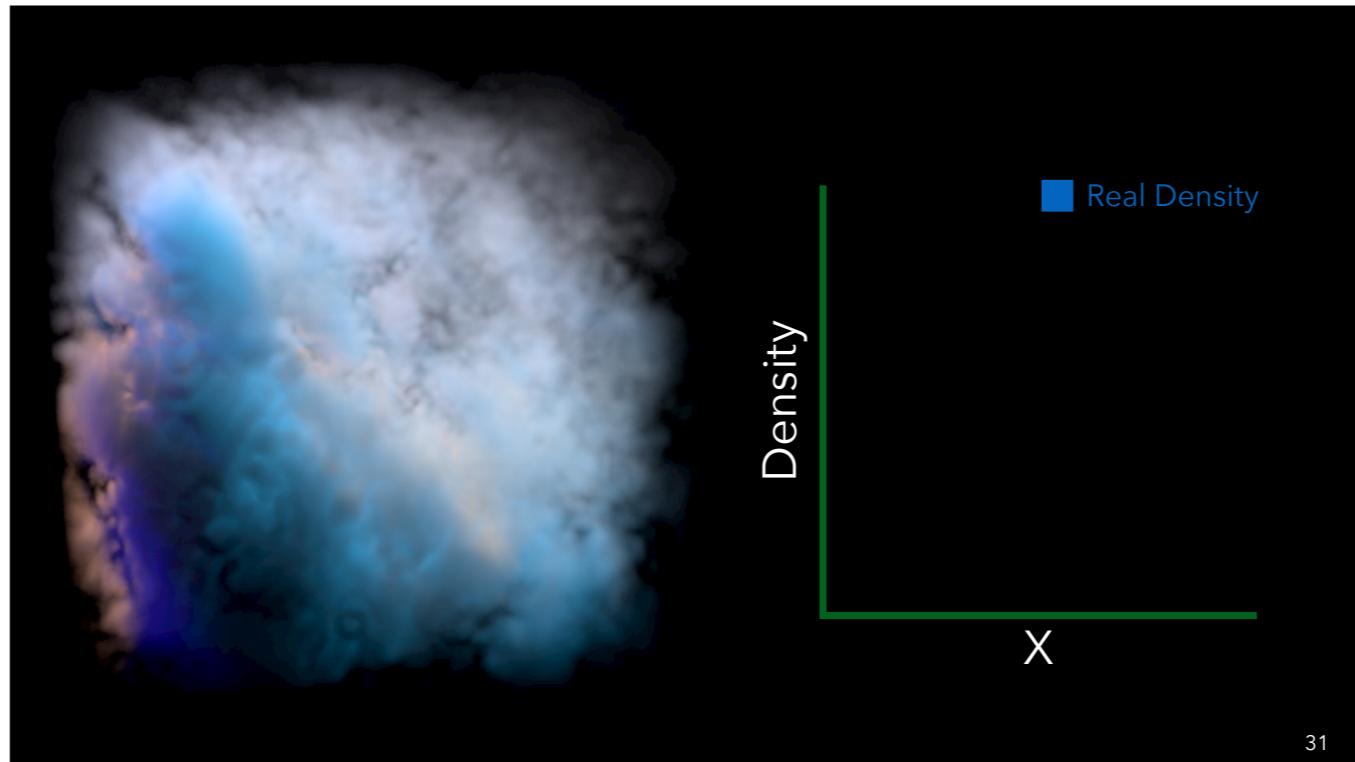


Or complicated production workflows,

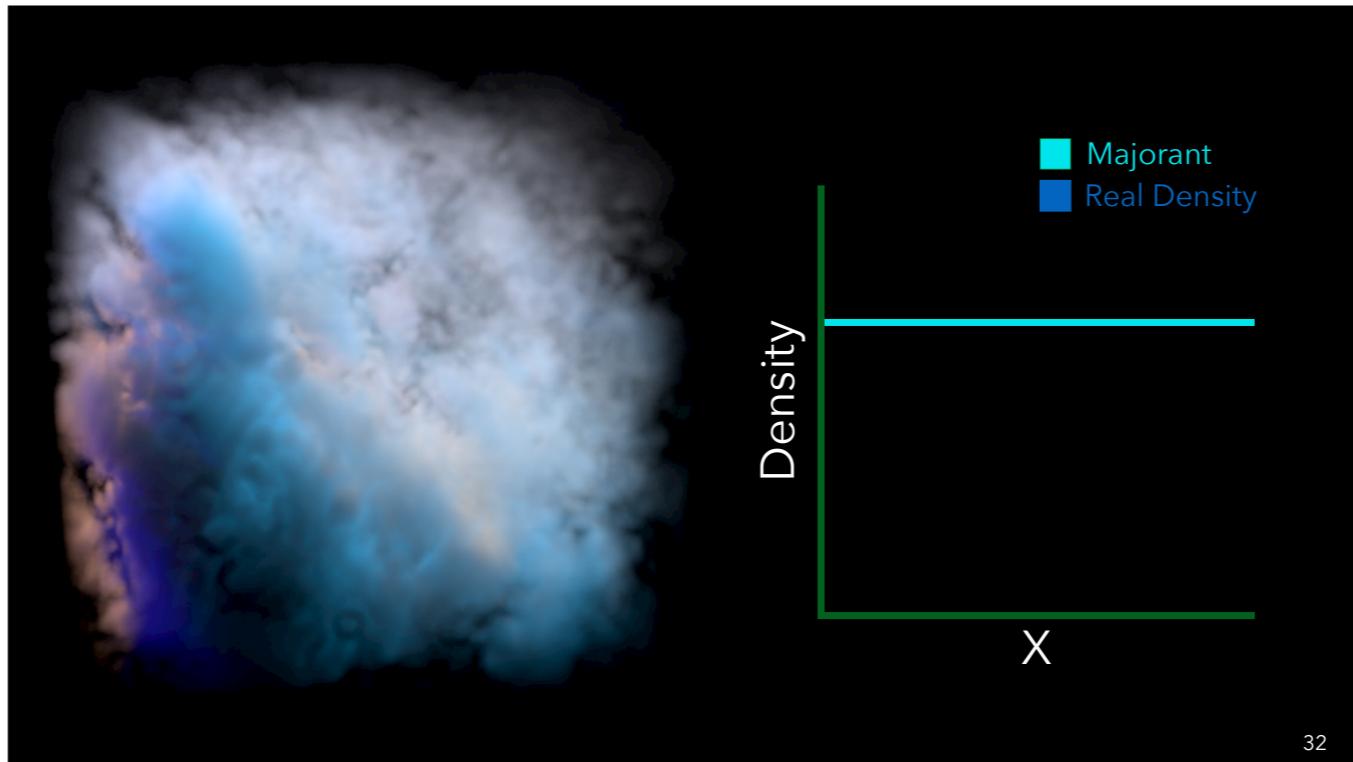


31

The underlying density (*click*) becomes a black box whose general shape is not known to the renderer.

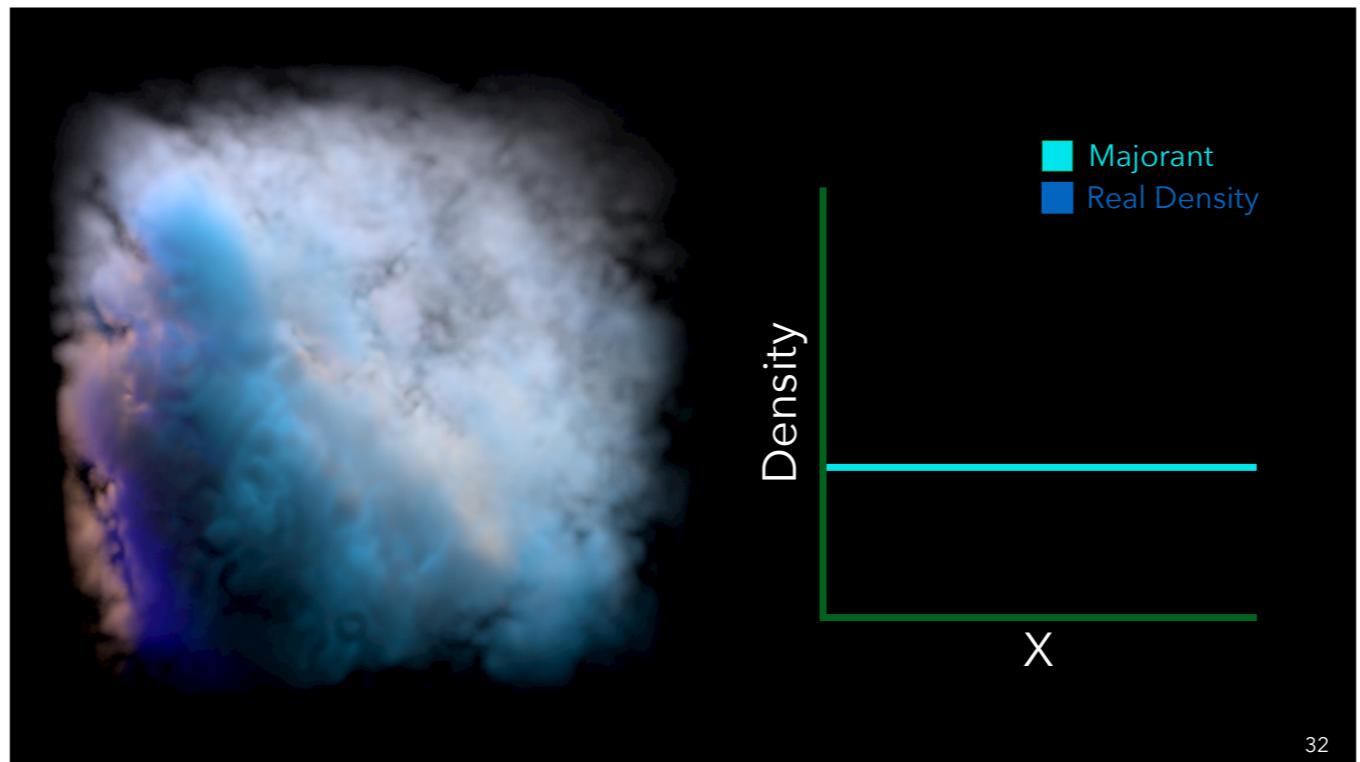


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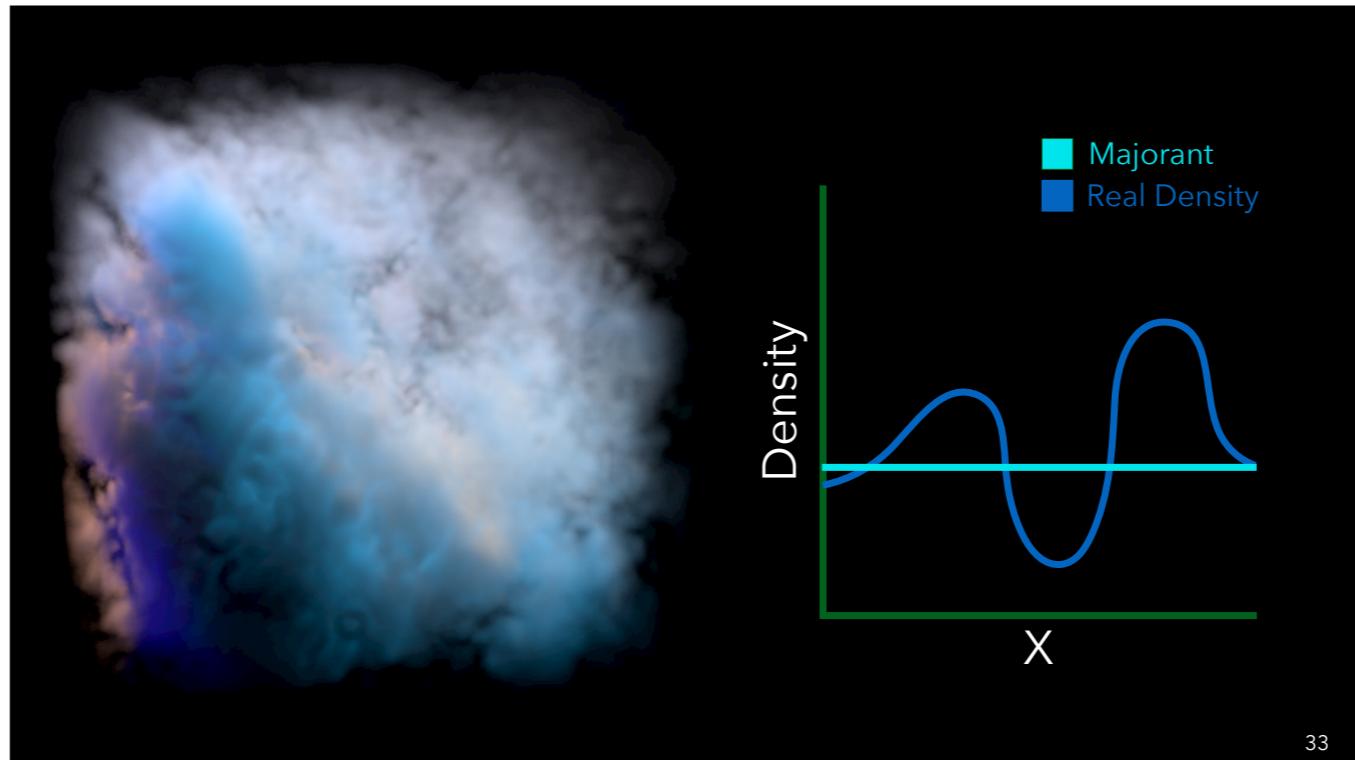


32

Any majorant which we specify, becomes an approximation for a bounding majorant,

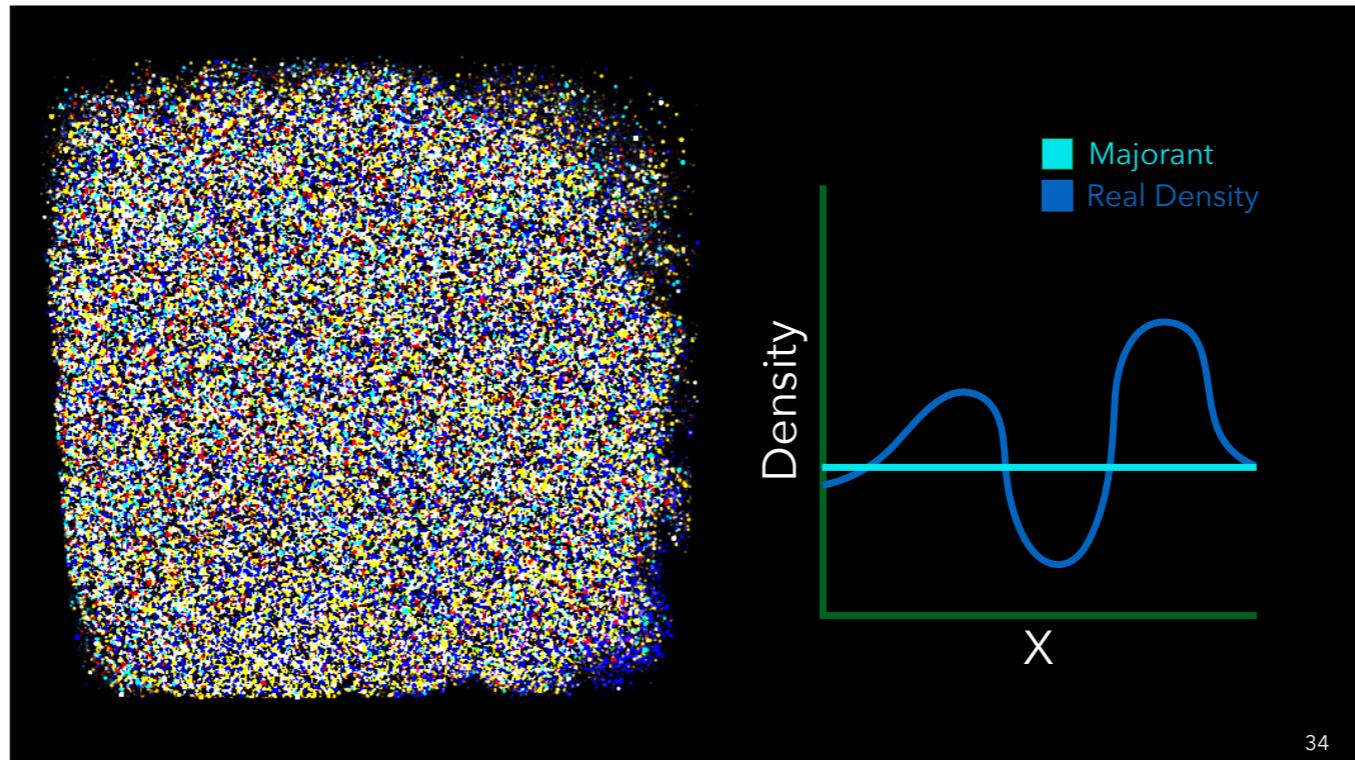


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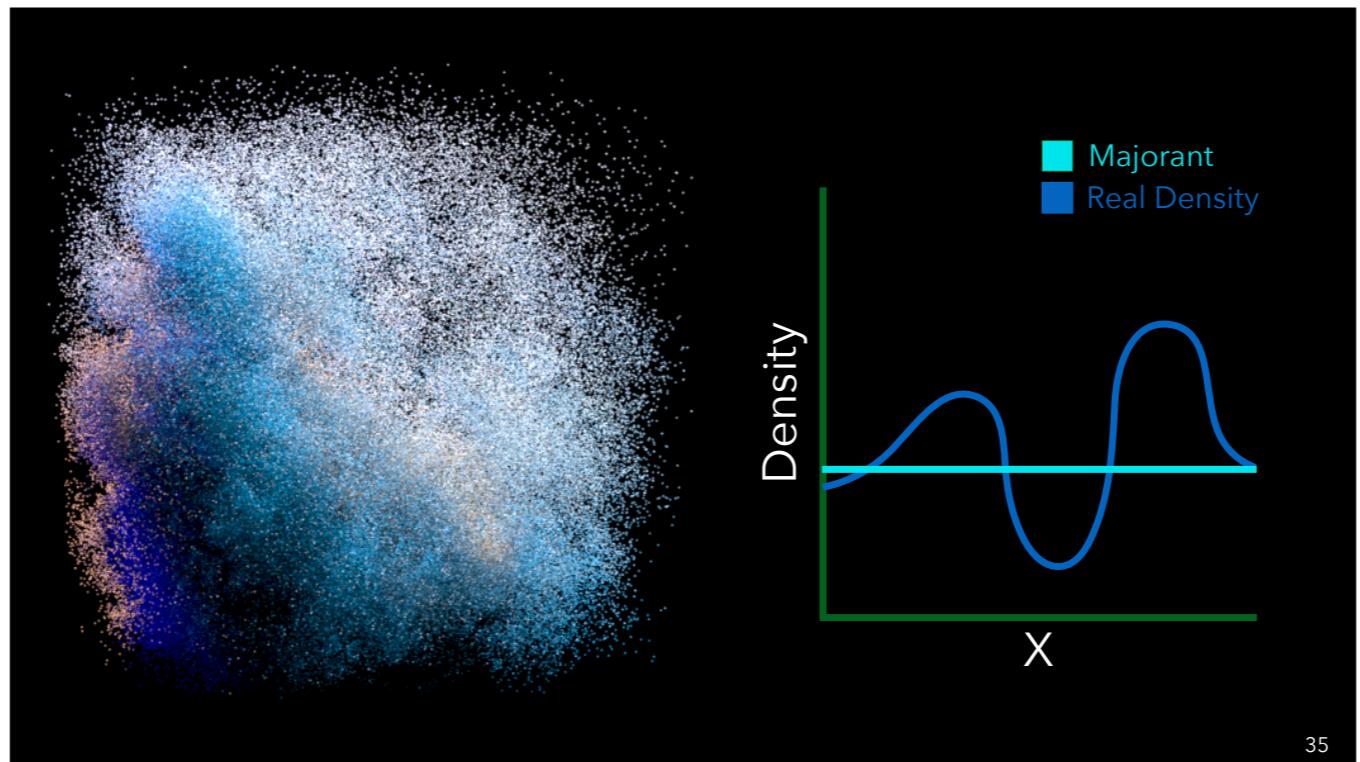
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Becoming very difficult to guarantee that we will ever have a tightly bounding one. And, without a tightly bounding majorant we can't be sure that we will avoid,



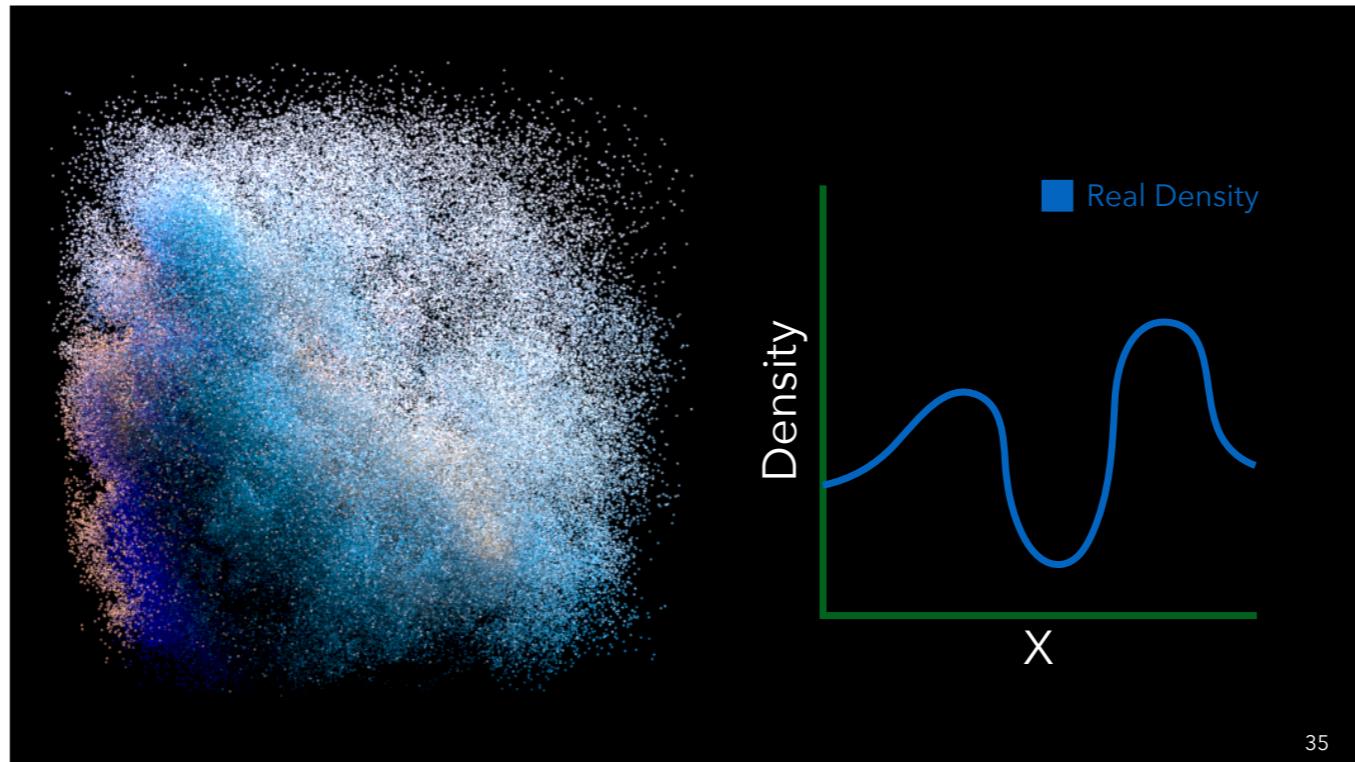
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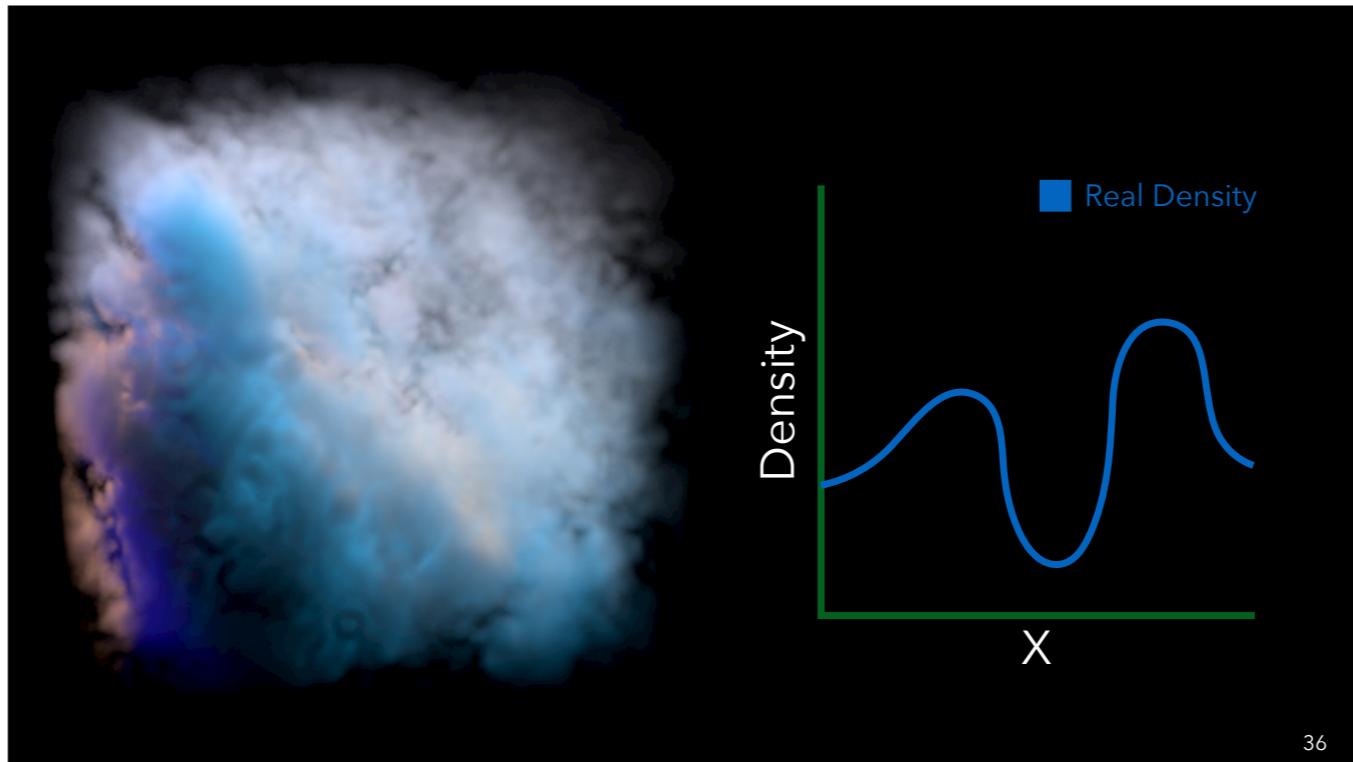
uncontrollable variance,



35

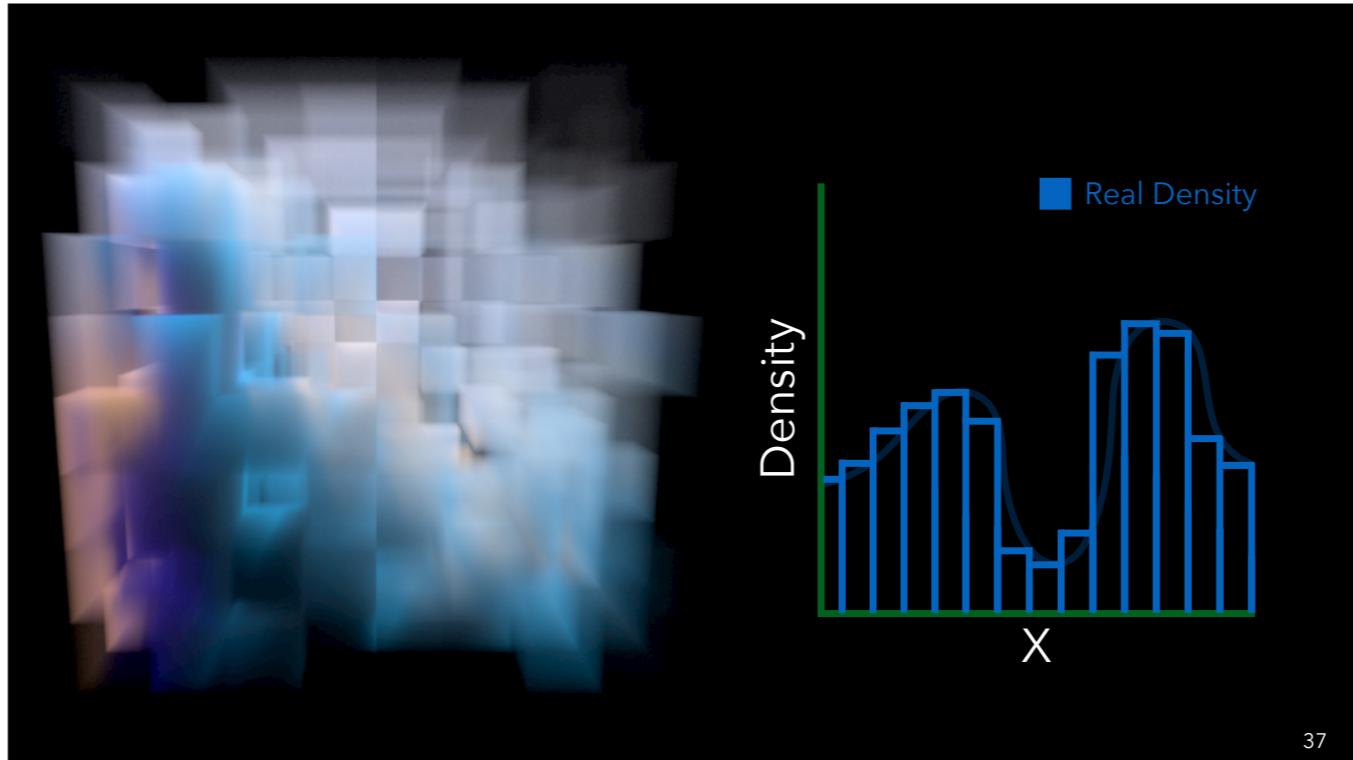
Or too inefficient of renders





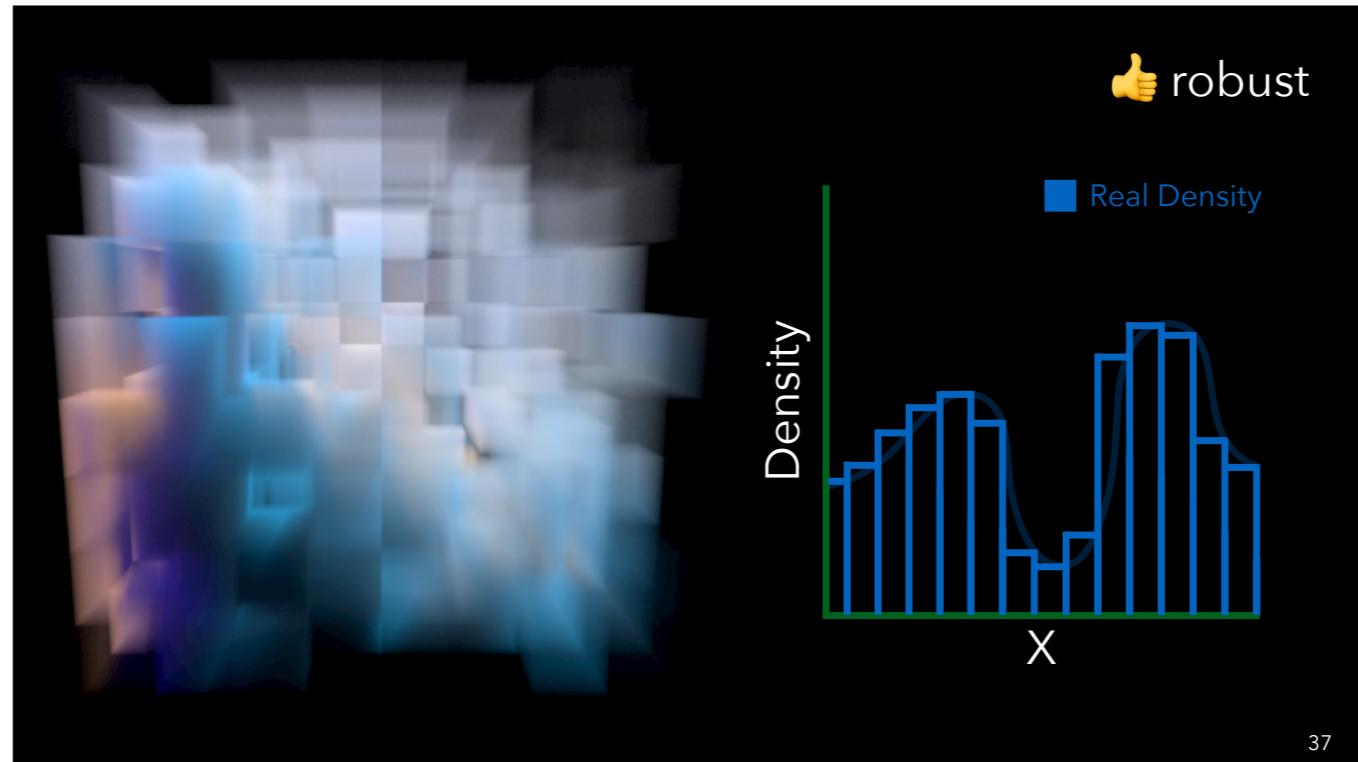
36

It is for this reason that Disney currently

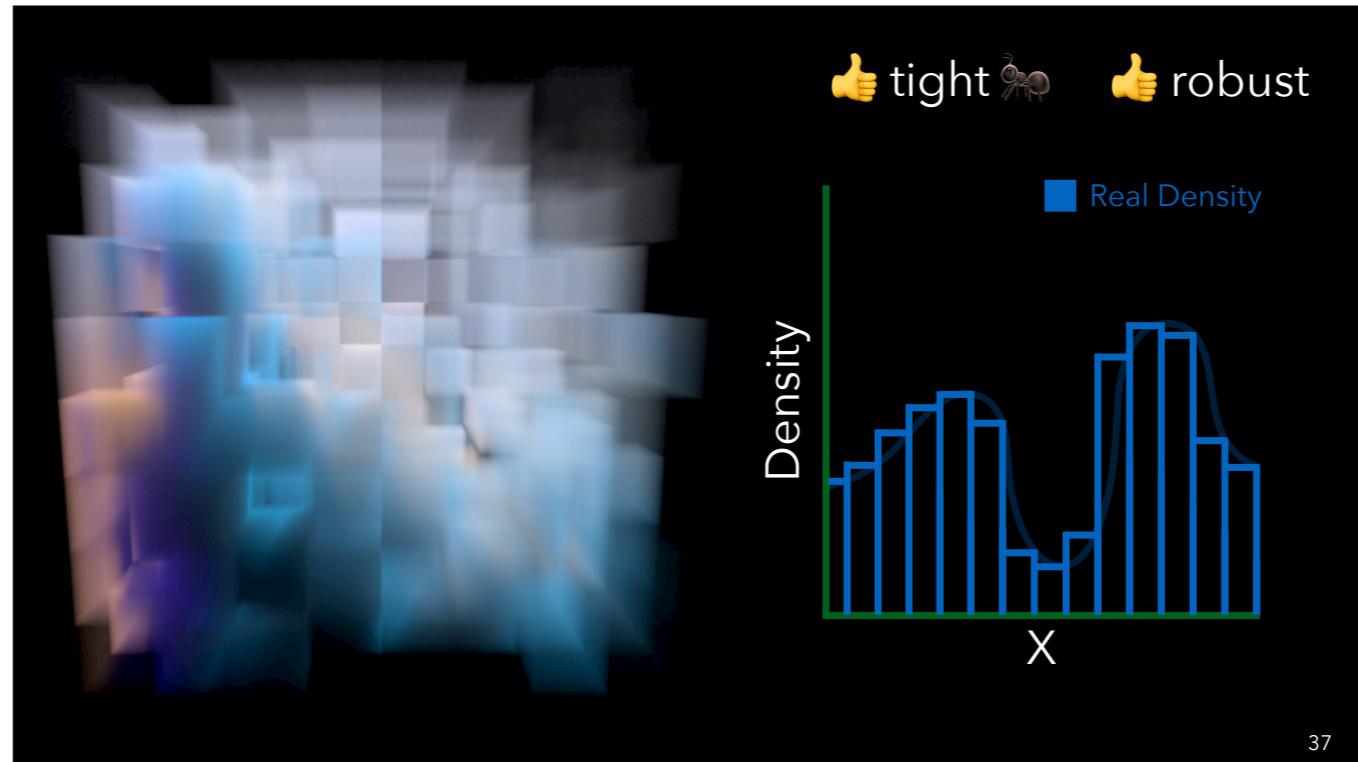


37

bakes all volumes into voxel density grids before rendering them. Representing all volumes as grids allows null-scattering techniques to be (*click*) robust, since, having a density grid (*click*) guarantees that tight majorants can always be found. However,



37



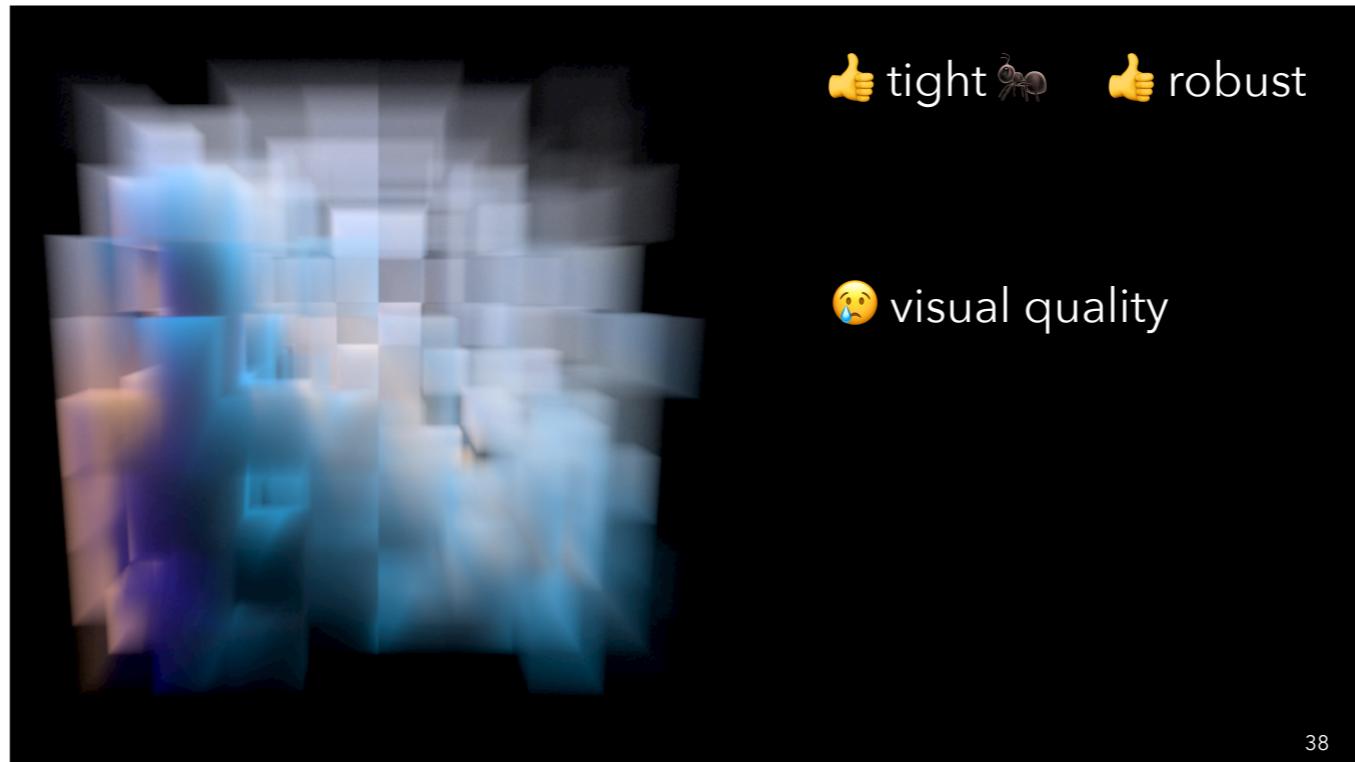
37



👍 tight 🎉 👍 robust

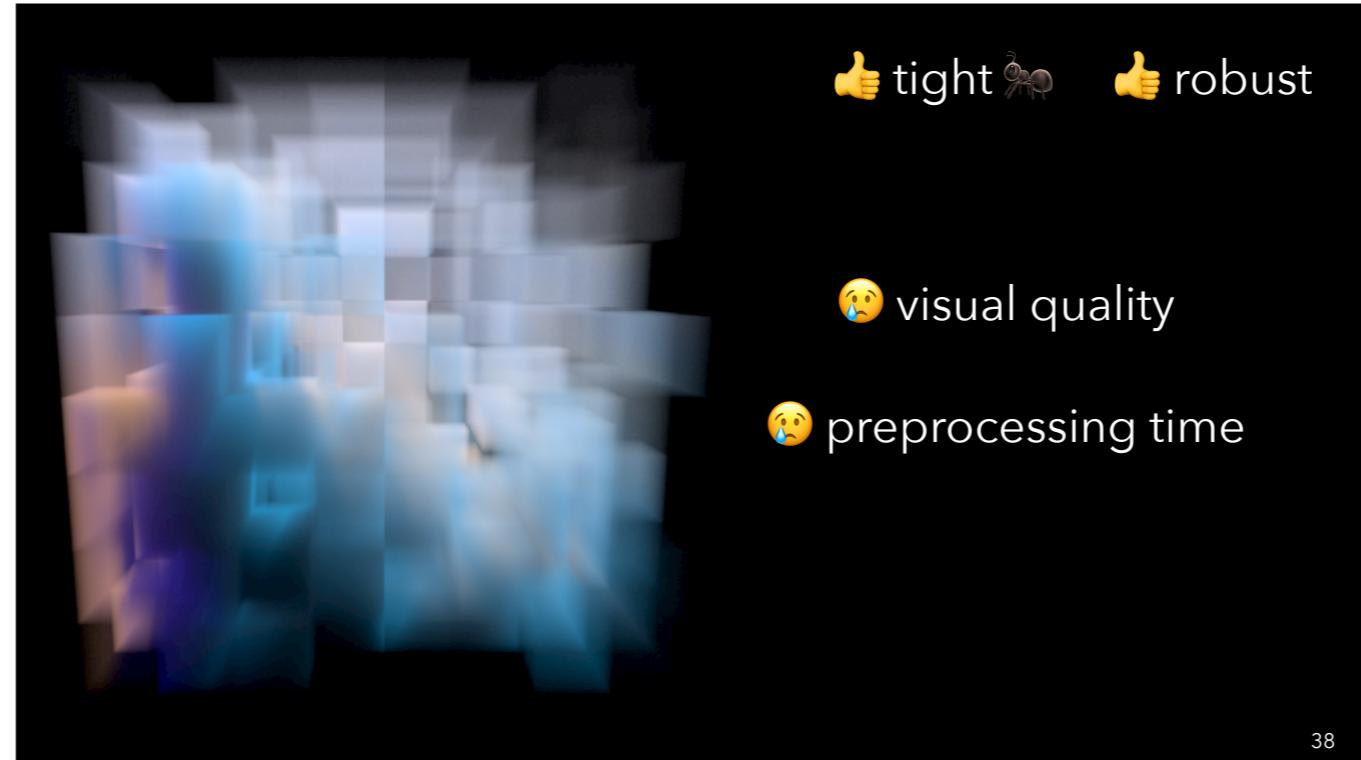
38

The process of baking reduces (*click*) the visual fidelity of all volumes, necessitates (*click*) preprocessing all volumes, and significantly increases (*click*) the storage requirements for all production scenes. We instead propose a solution which,



👍 tight 🤸‍♂️ 👍 robust

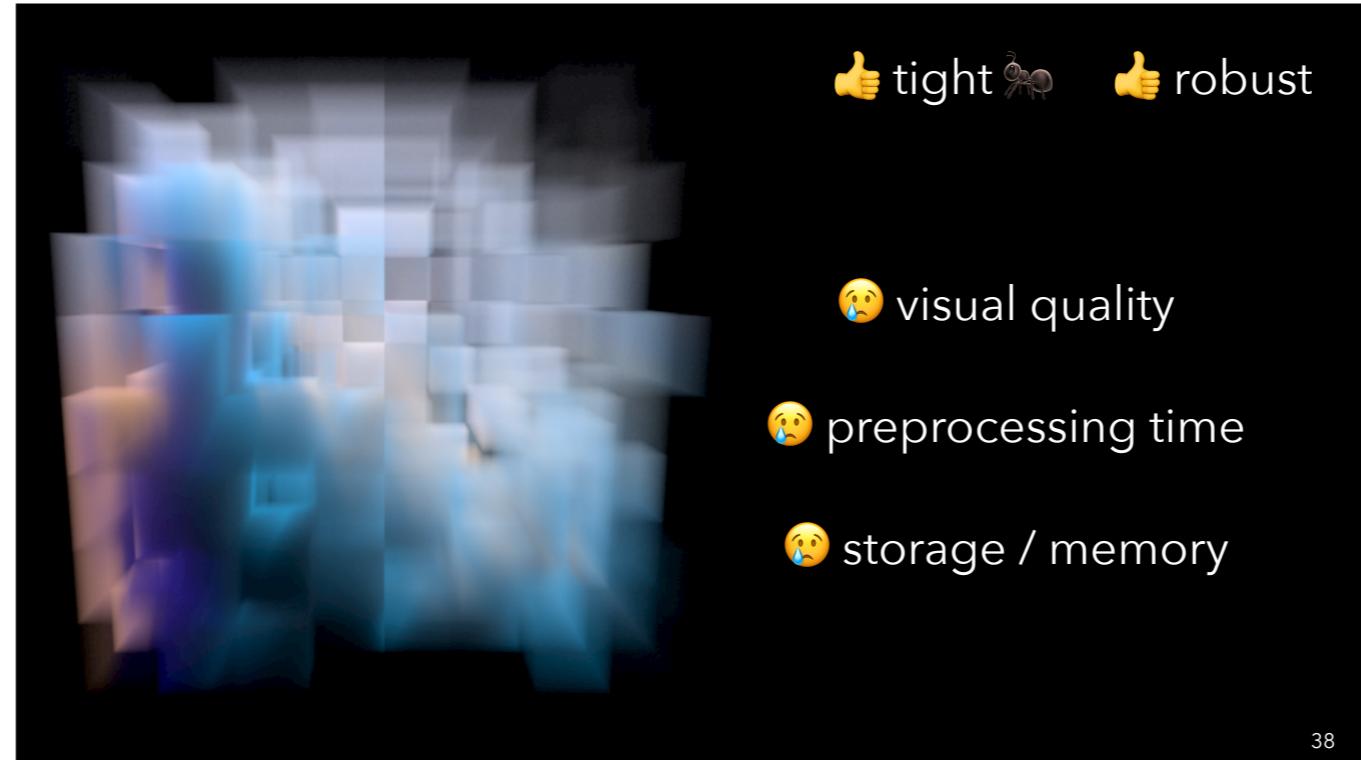
😢 visual quality



👍 tight 🎉 👍 robust

😢 visual quality

😢 preprocessing time

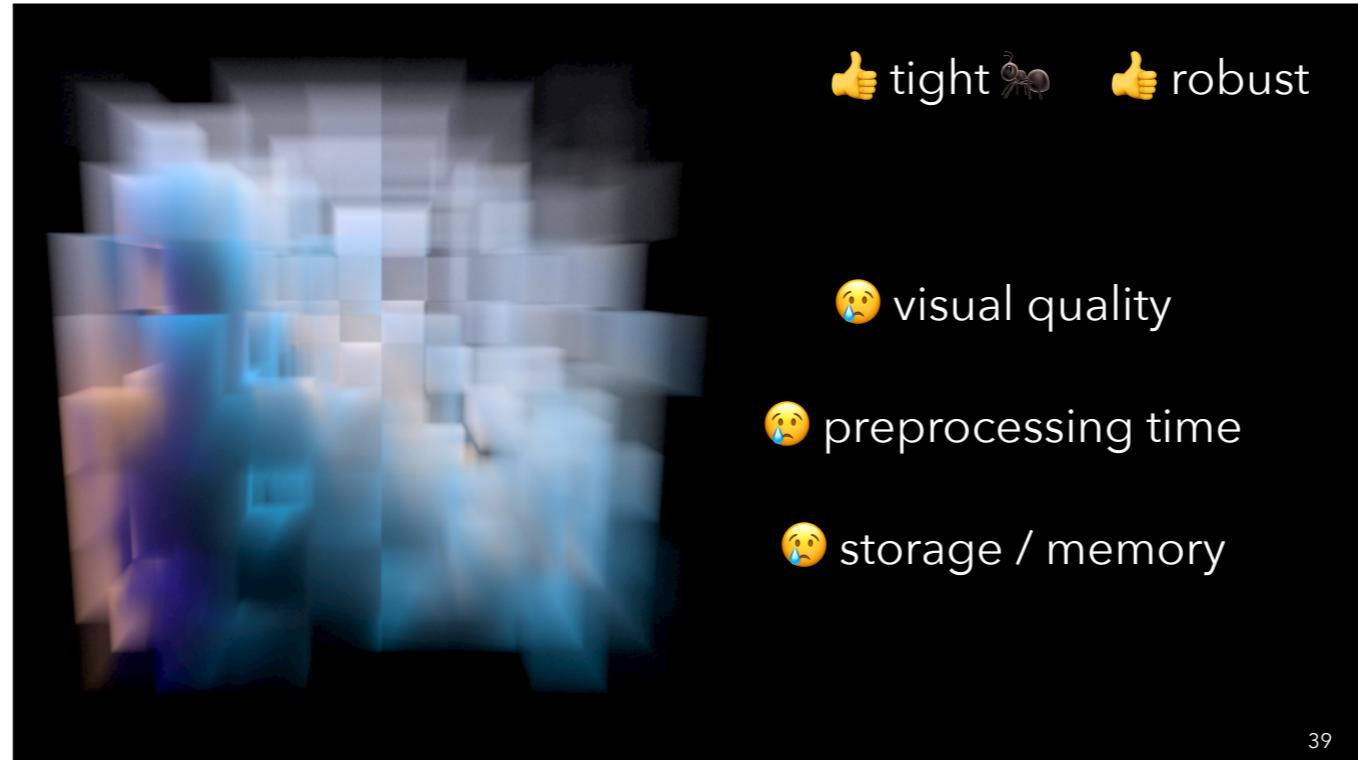


👍 tight 🤸‍♂️ 👍 robust

😢 visual quality

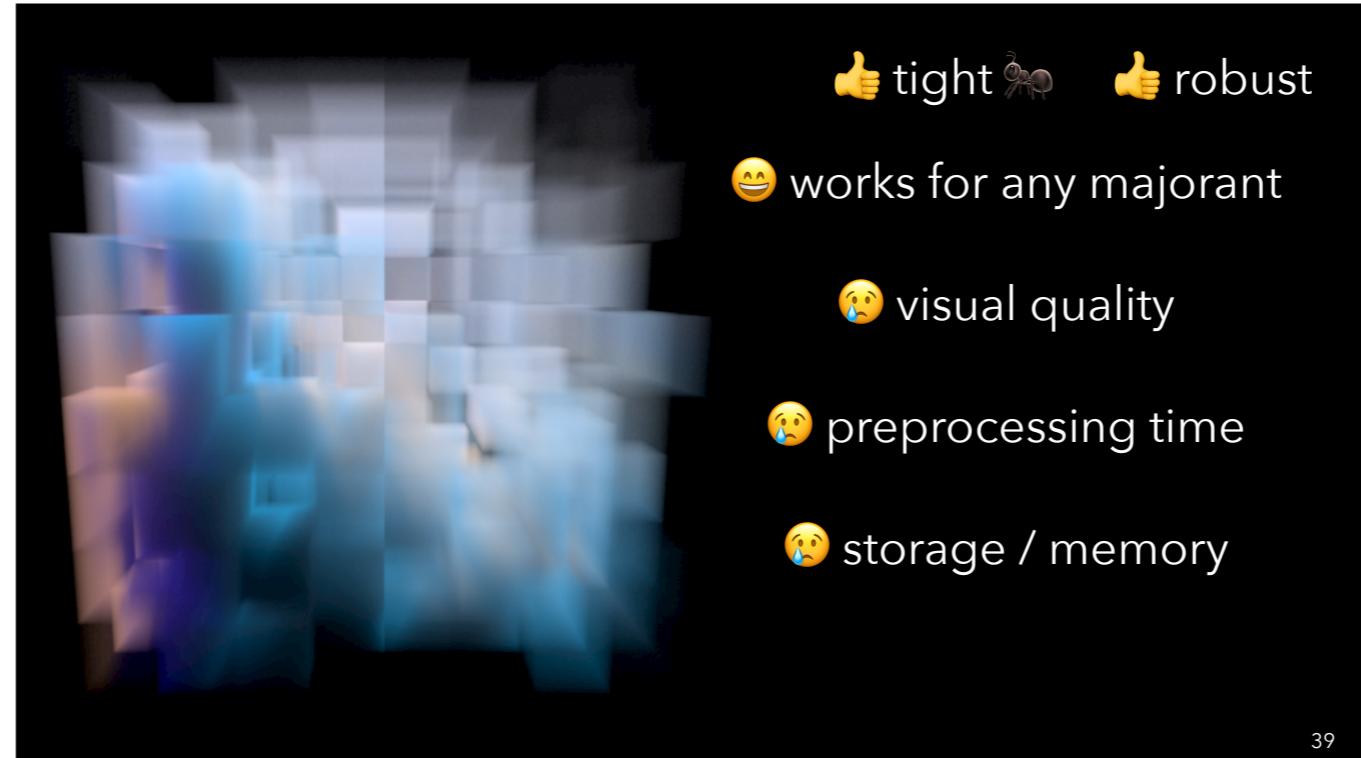
😢 preprocessing time

😢 storage / memory



39

Makes most null-scattering techniques resilient to non-bounding majorants. Our technique is (*click*) robust, discovers (*click*) tight majorants during render time,



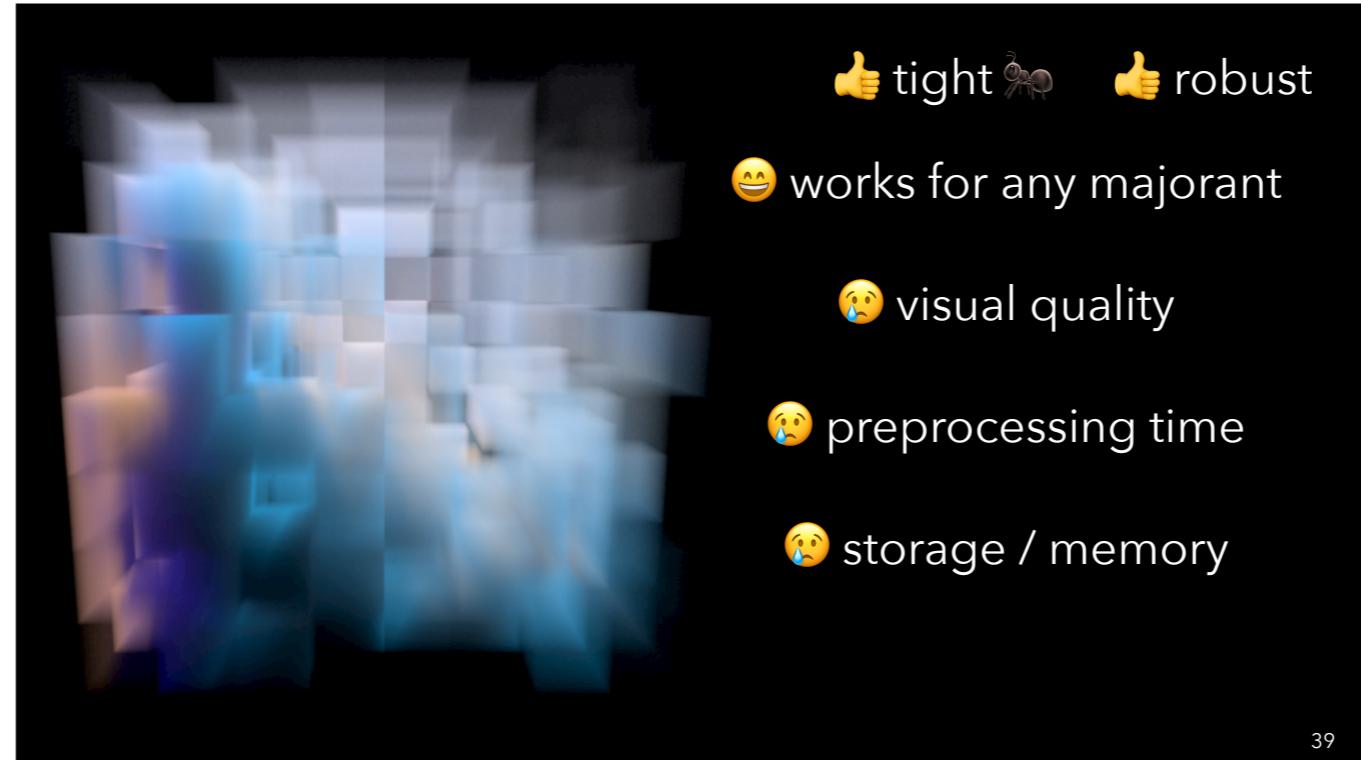
👍 tight 🧘‍♂️ 👍 robust

😅 works for any majorant

😢 visual quality

😢 preprocessing time

😢 storage / memory



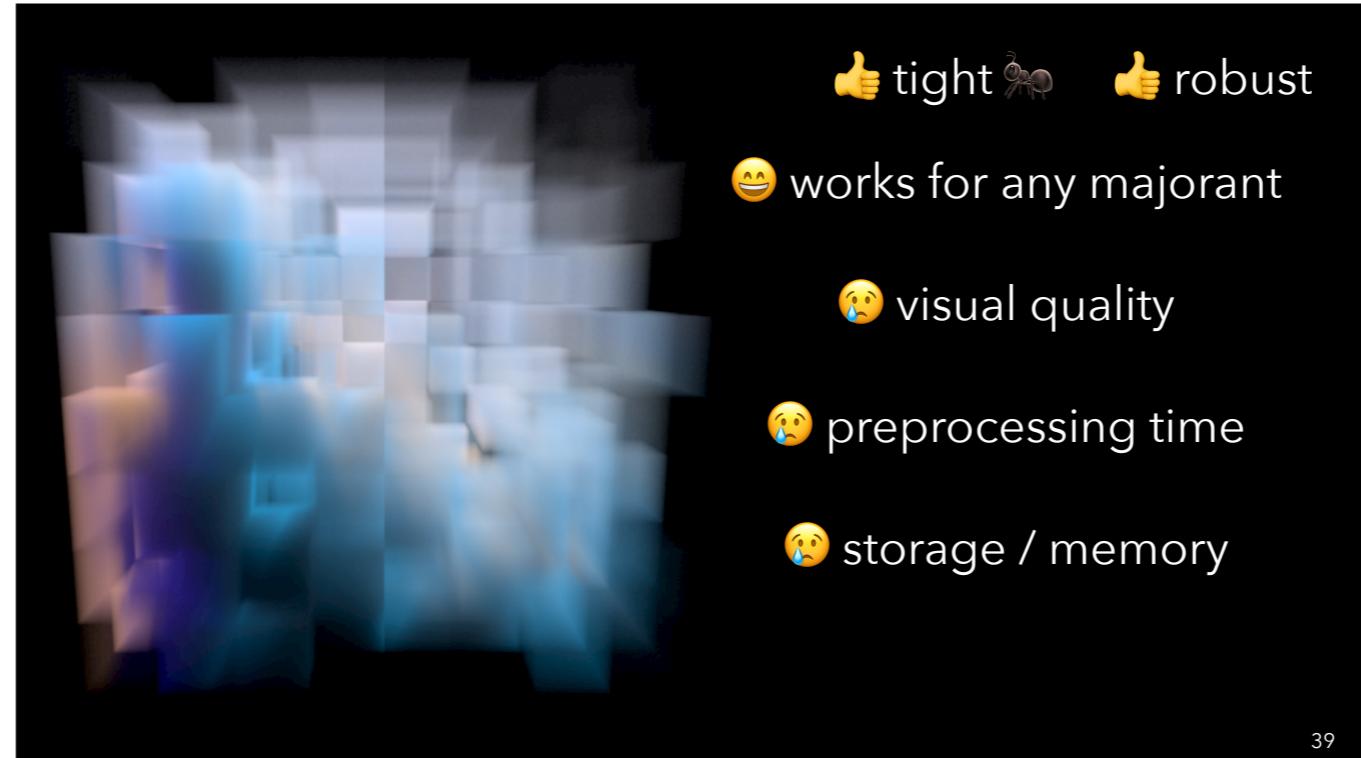
👍 tight 🧘‍♂️ 👍 robust

😅 works for any majorant

😢 visual quality

😢 preprocessing time

😢 storage / memory



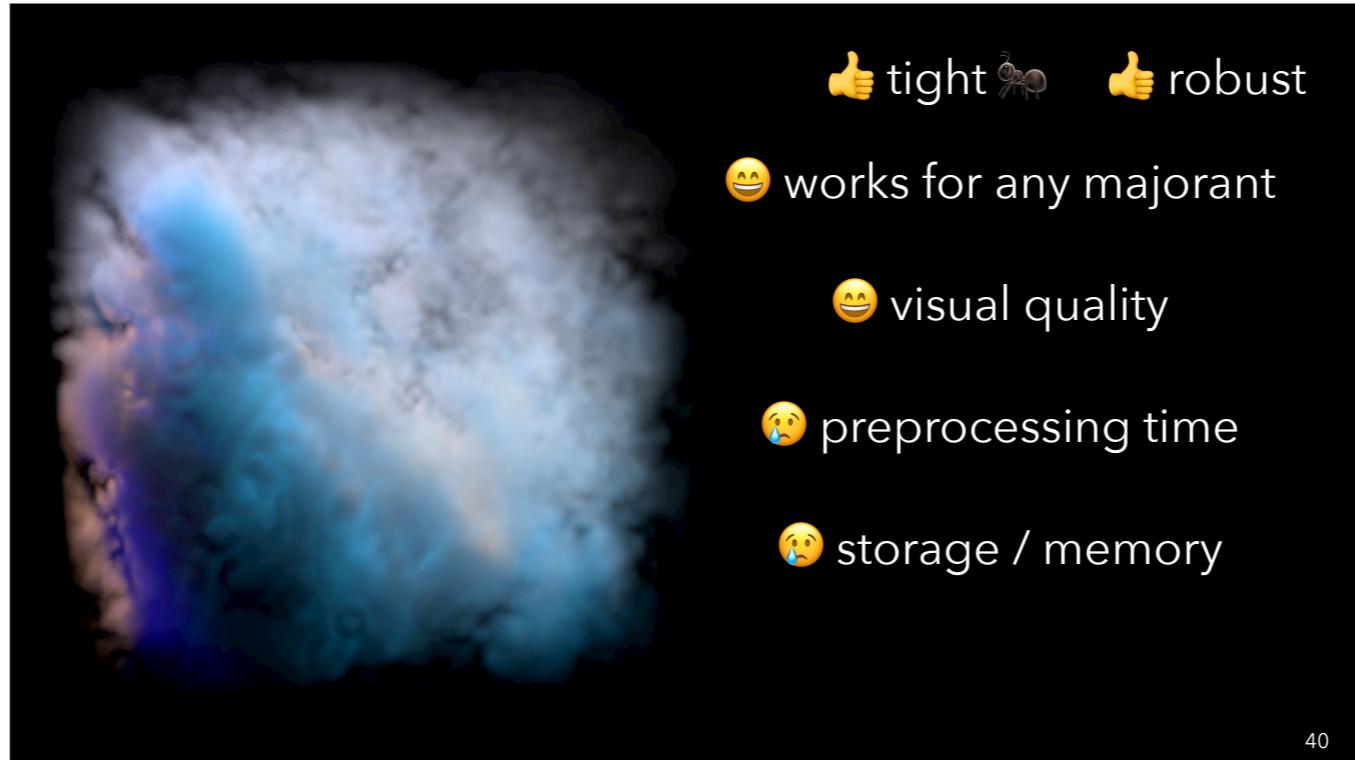
👍 tight 🧘‍♂️ 👍 robust

😅 works for any majorant

😢 visual quality

😢 preprocessing time

😢 storage / memory



👍 tight 🎈 👍 robust

😊 works for any majorant

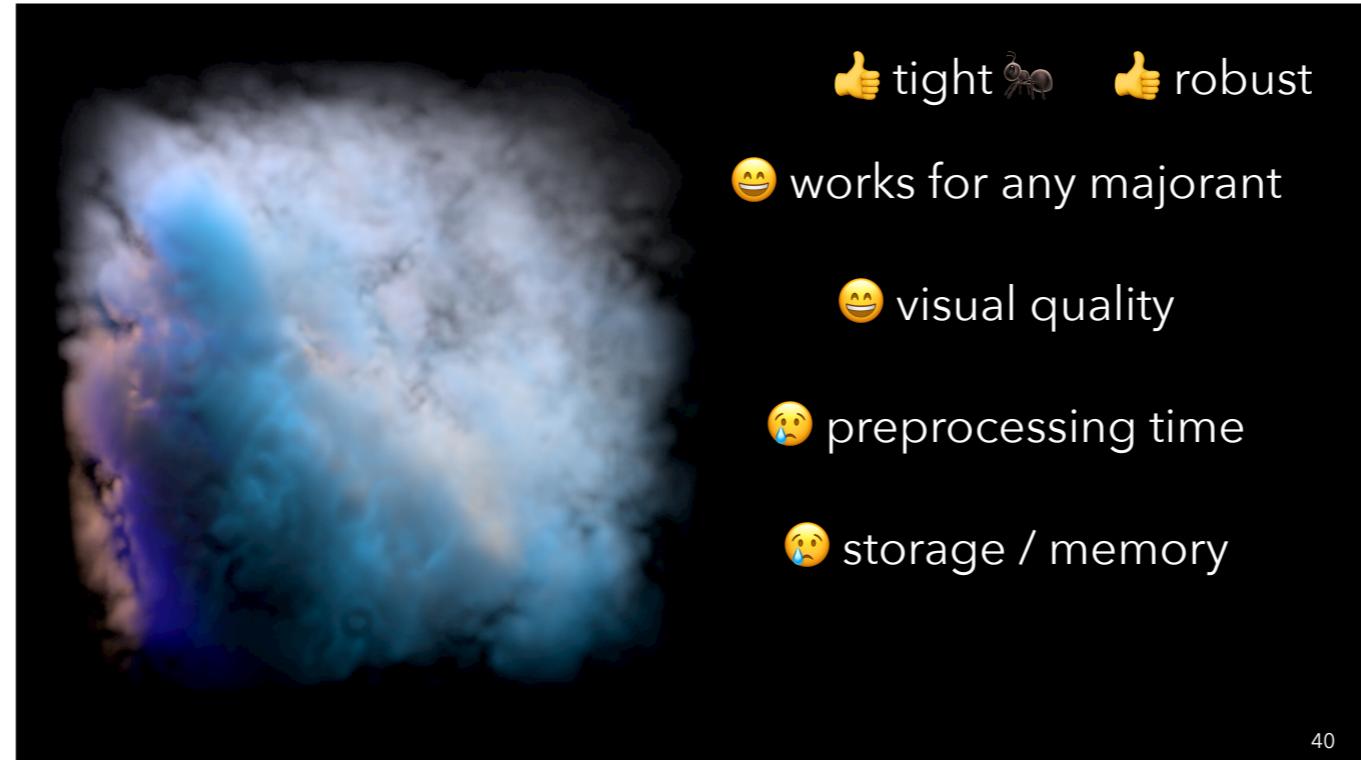
😊 visual quality

😢 preprocessing time

😢 storage / memory

40

maintains the same visual quality as using bounding majorants in the converged renders,



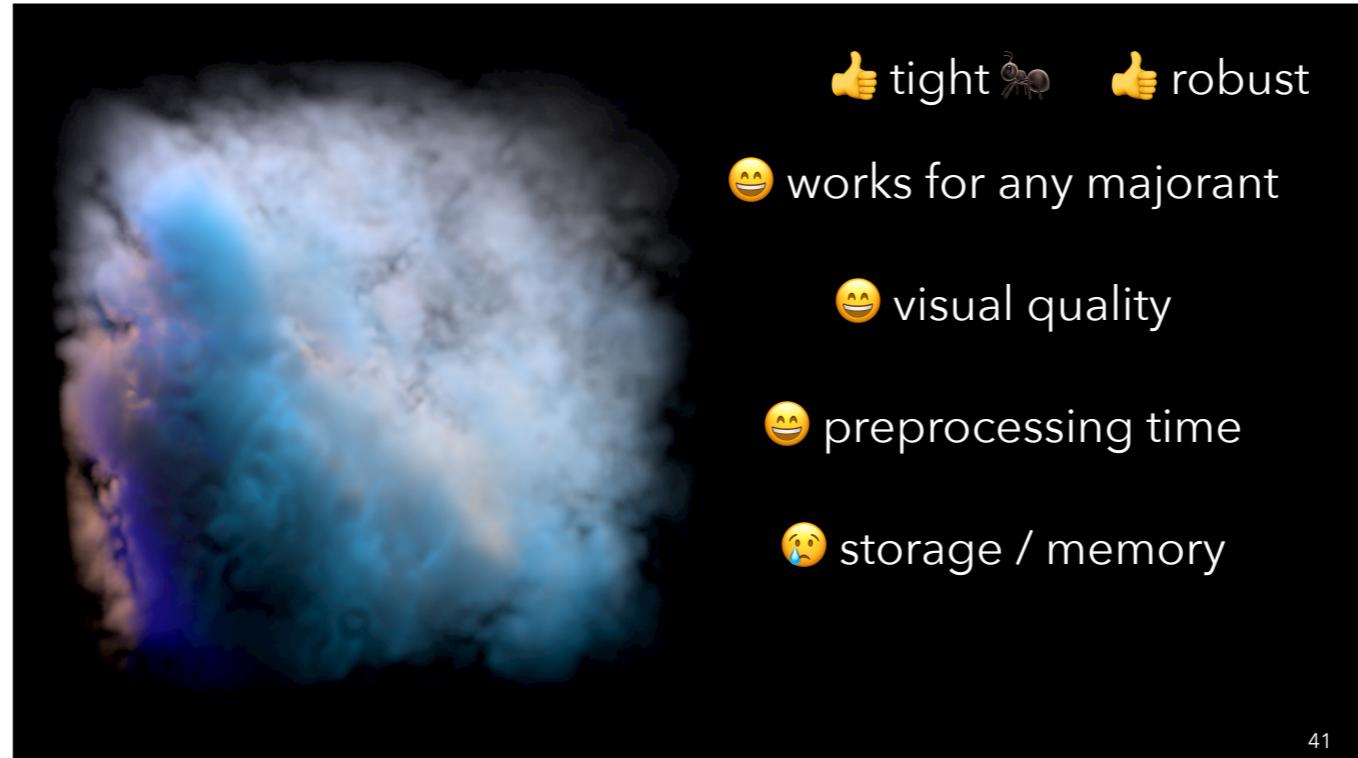
👍 tight 🎈 👍 robust

😊 works for any majorant

😊 visual quality

😢 preprocessing time

😢 storage / memory



👍 tight 🧘‍♂️ 👍 robust

🤩 works for any majorant

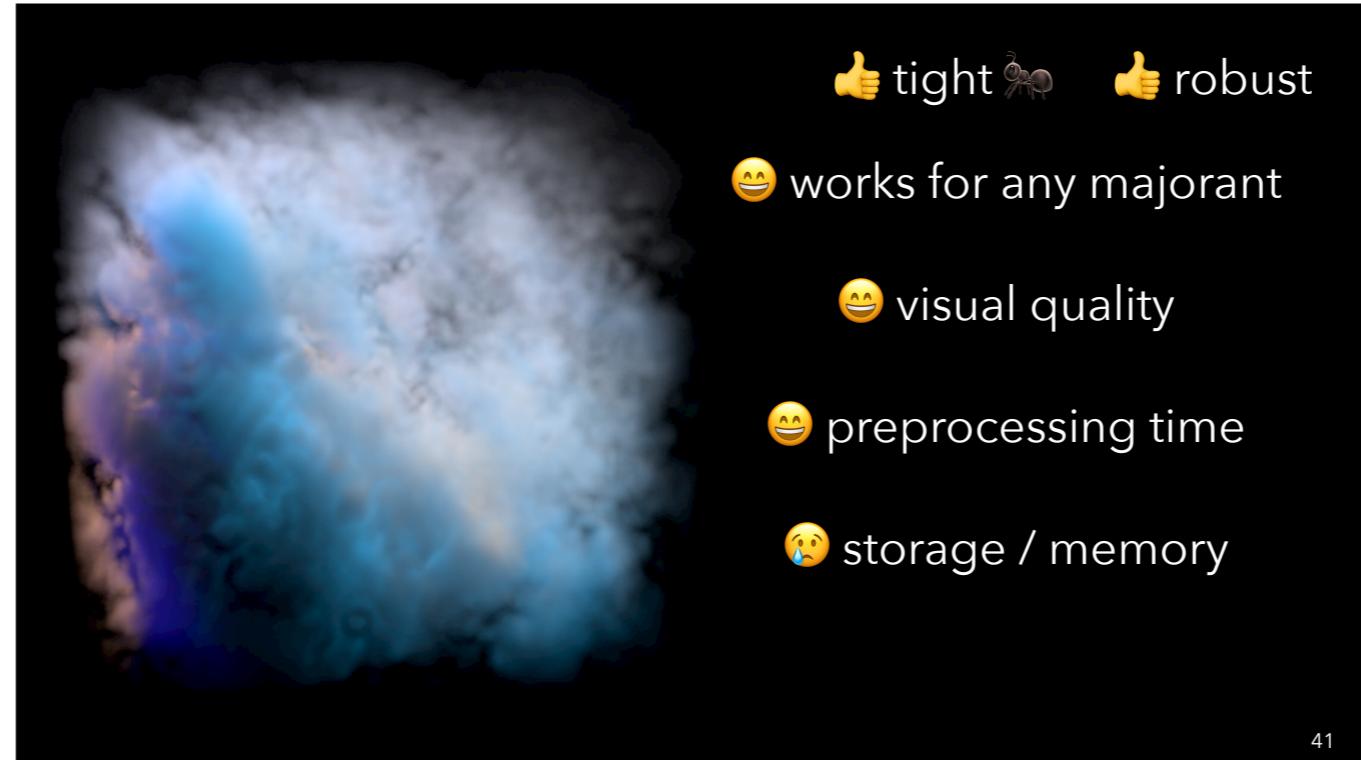
😊 visual quality

😂 preprocessing time

\泣 storage / memory

41

require little to no preprocessing time



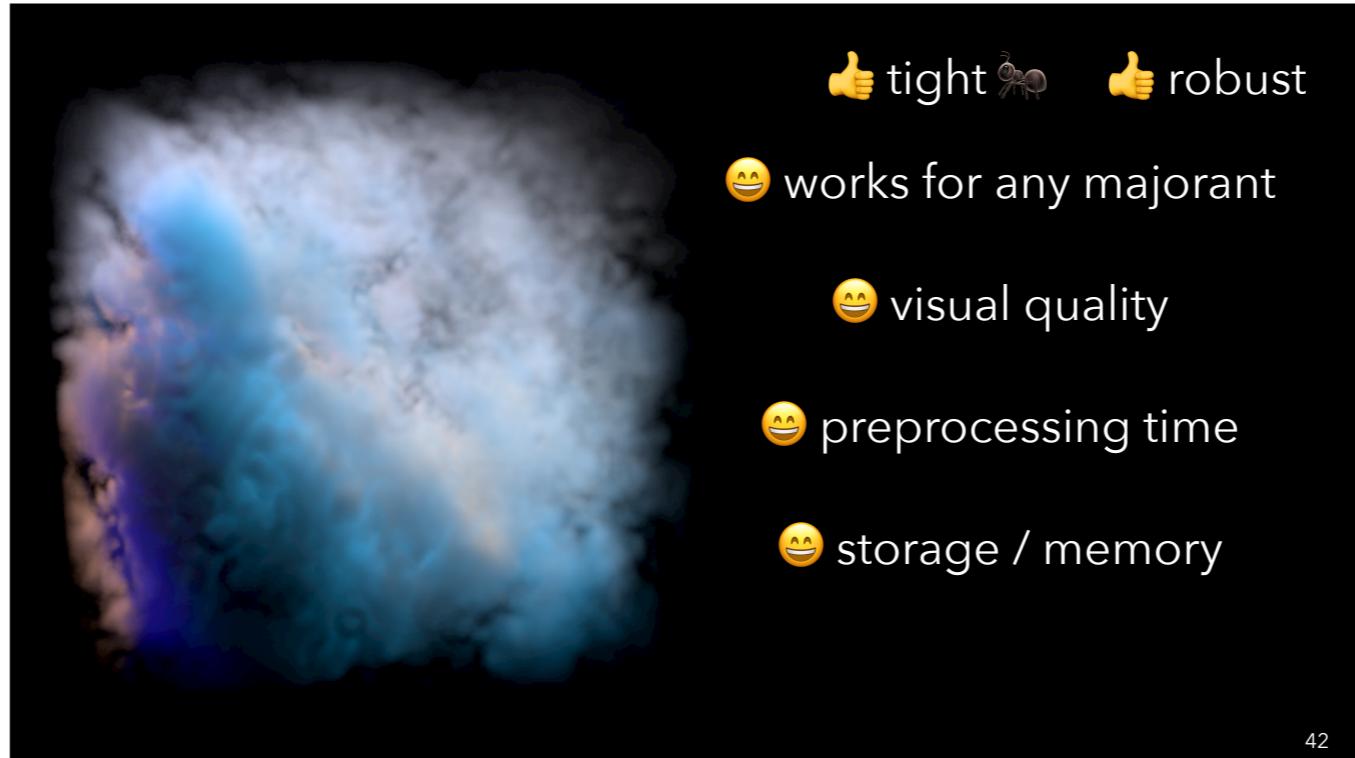
👍 tight 🧘‍♂️ 👍 robust

😊 works for any majorant

😊 visual quality

😊 preprocessing time

😢 storage / memory



👍 tight 🌱 👍 robust

😊 works for any majorant

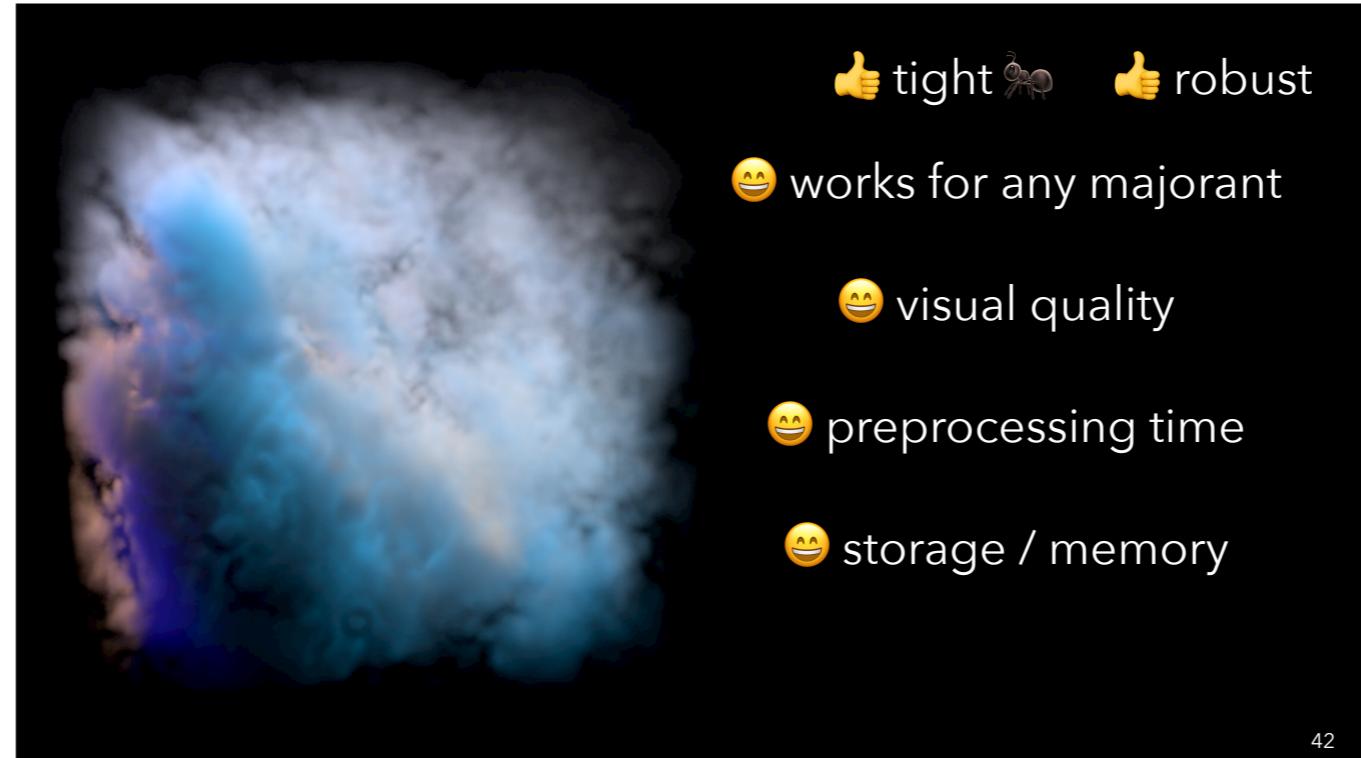
😊 visual quality

😊 preprocessing time

😊 storage / memory

42

And requires no extra storage on top of what is already needed in any practical implementation of null-scattering. However, in return for fixing all these prior issues,



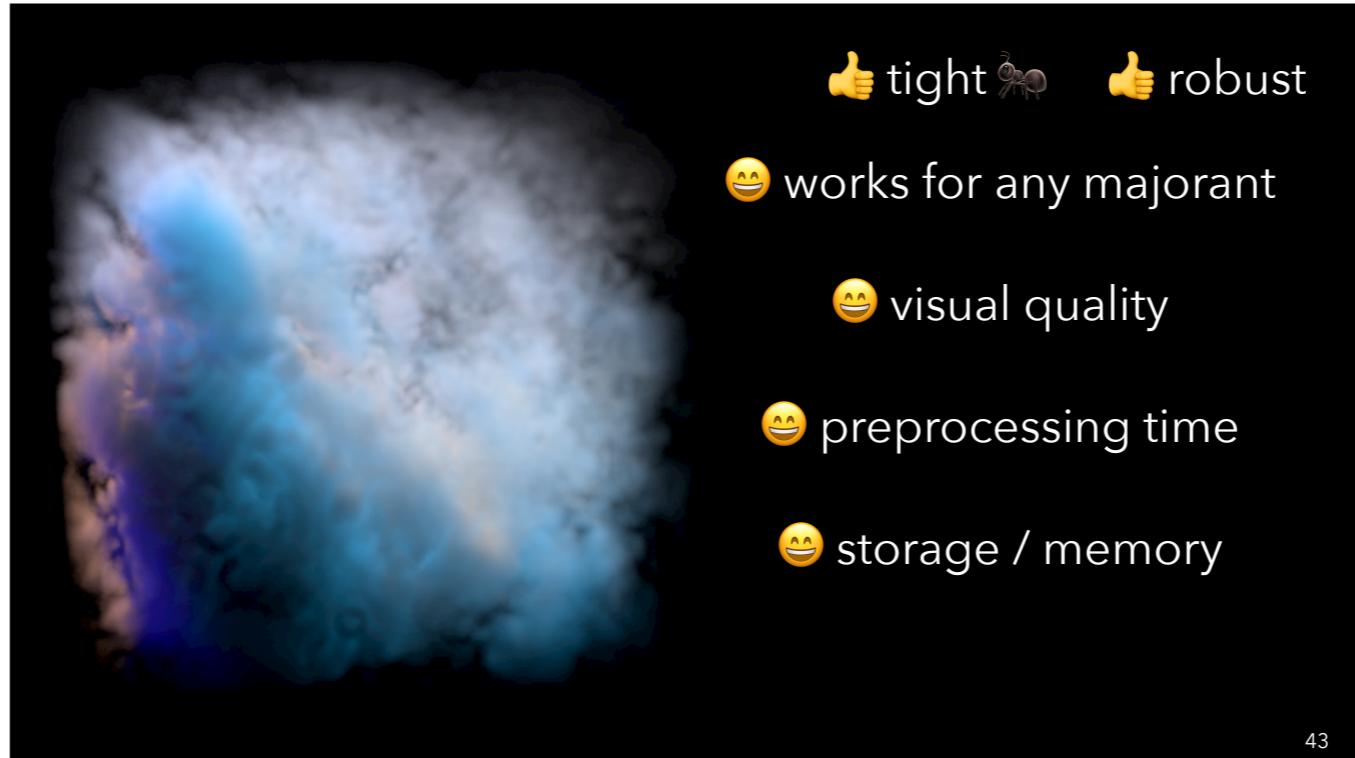
👍 tight 🧘‍♂️ 👍 robust

😊 works for any majorant

😊 visual quality

😊 preprocessing time

😊 storage / memory



👍 tight 🧠 👍 robust

😊 works for any majorant

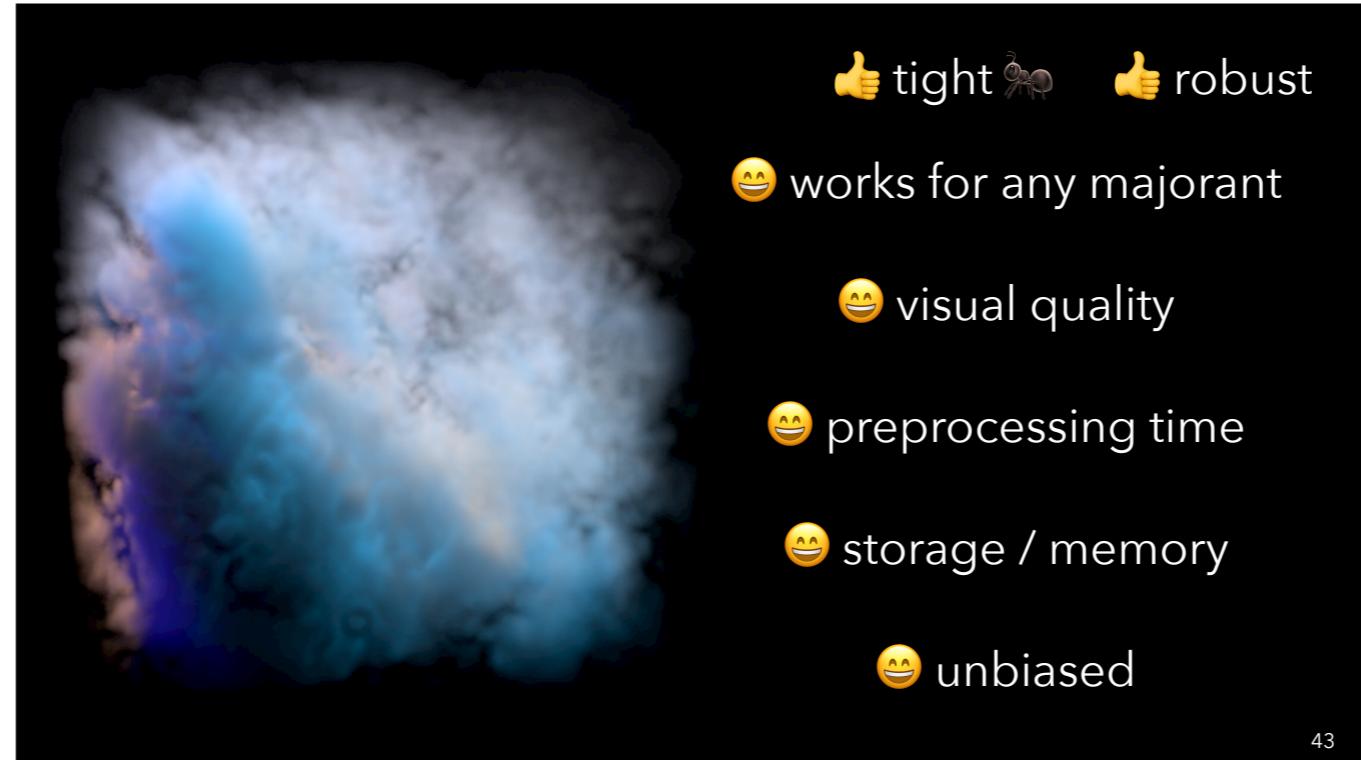
😊 visual quality

😊 preprocessing time

😊 storage / memory

43

Our technique requires that we relax the (*click*) unbiased property of most existing methods,



👍 tight 🧘‍♂️ 👍 robust

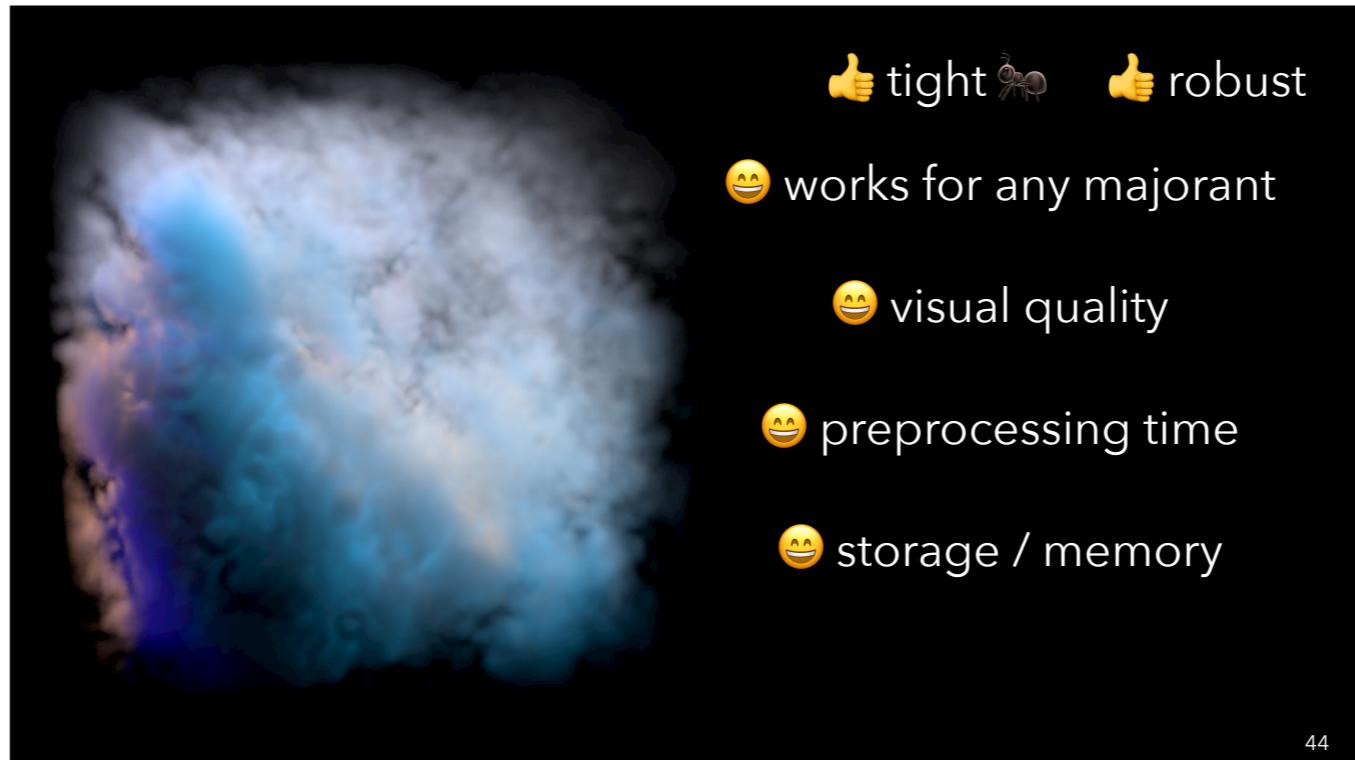
😊 works for any majorant

😊 visual quality

😊 preprocessing time

😊 storage / memory

😊 unbiased



👍 tight 🧘‍♂️ 👍 robust

🤩 works for any majorant

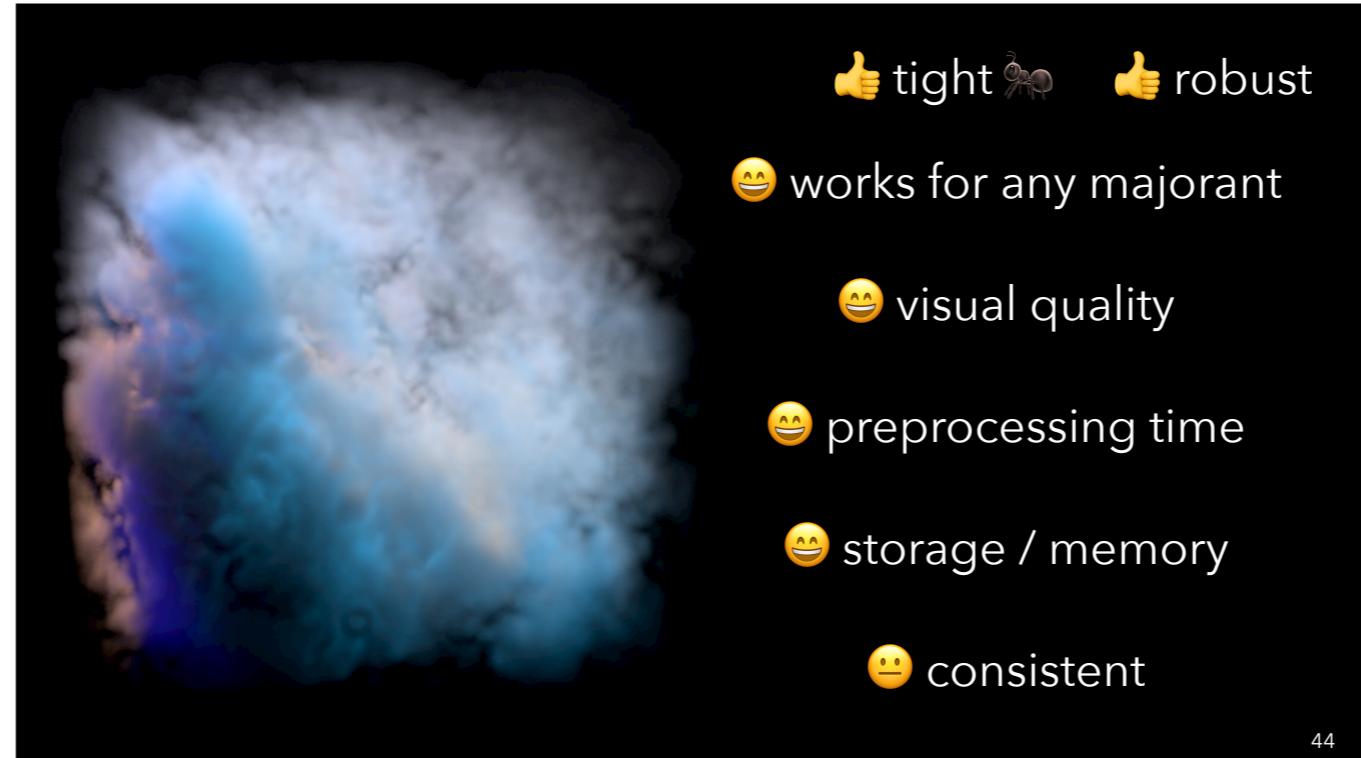
😊 visual quality

😊 preprocessing time

😊 storage / memory

44

To instead settle for only being consistent.



👍 tight 🎈 👍 robust

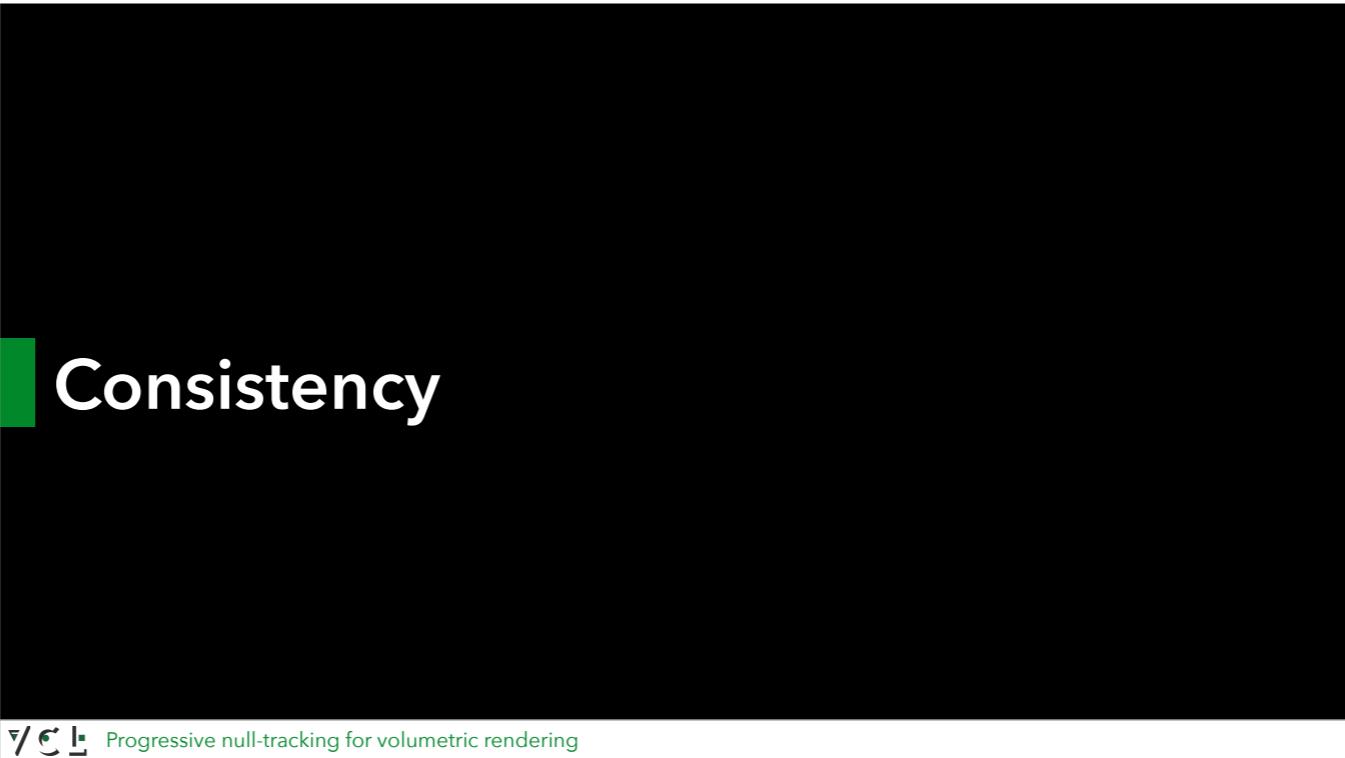
😊 works for any majorant

😊 visual quality

😊 preprocessing time

😊 storage / memory

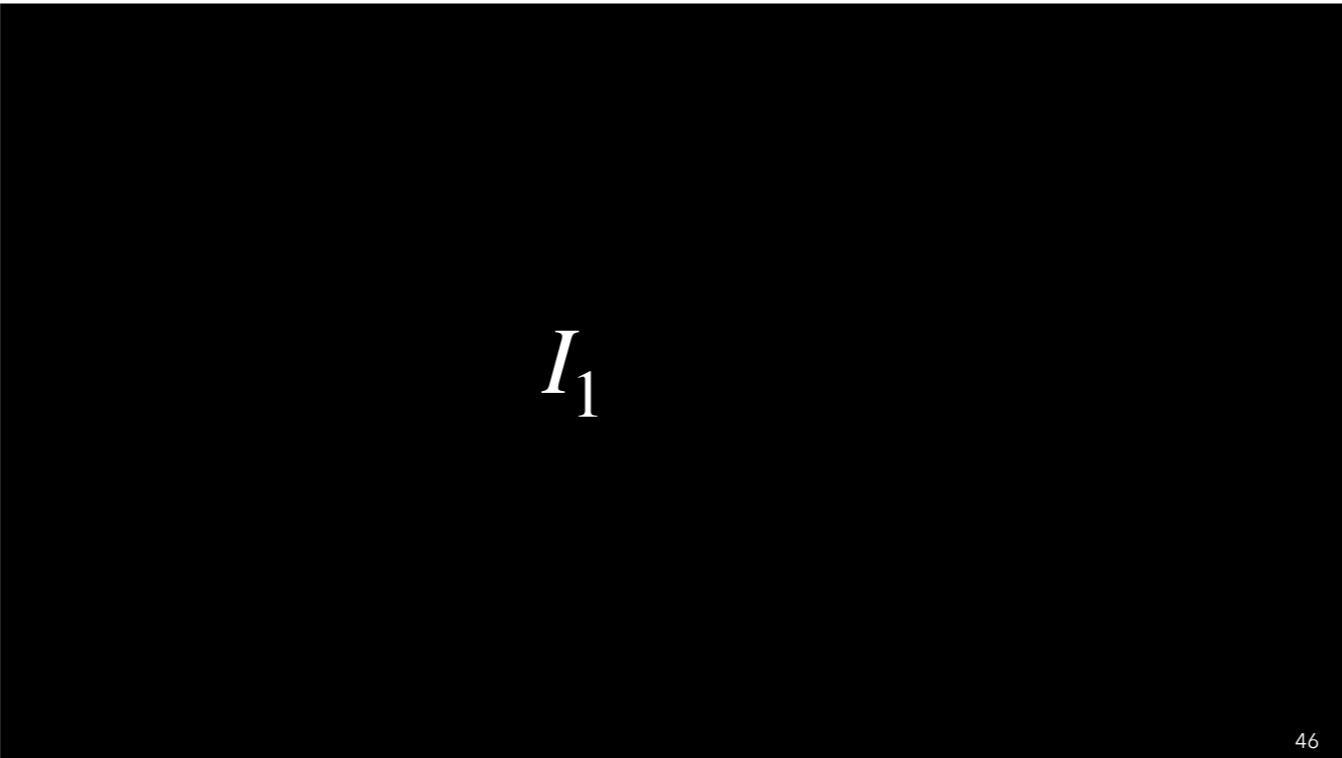
😐 consistent



Consistency

 Progressive null-tracking for volumetric rendering

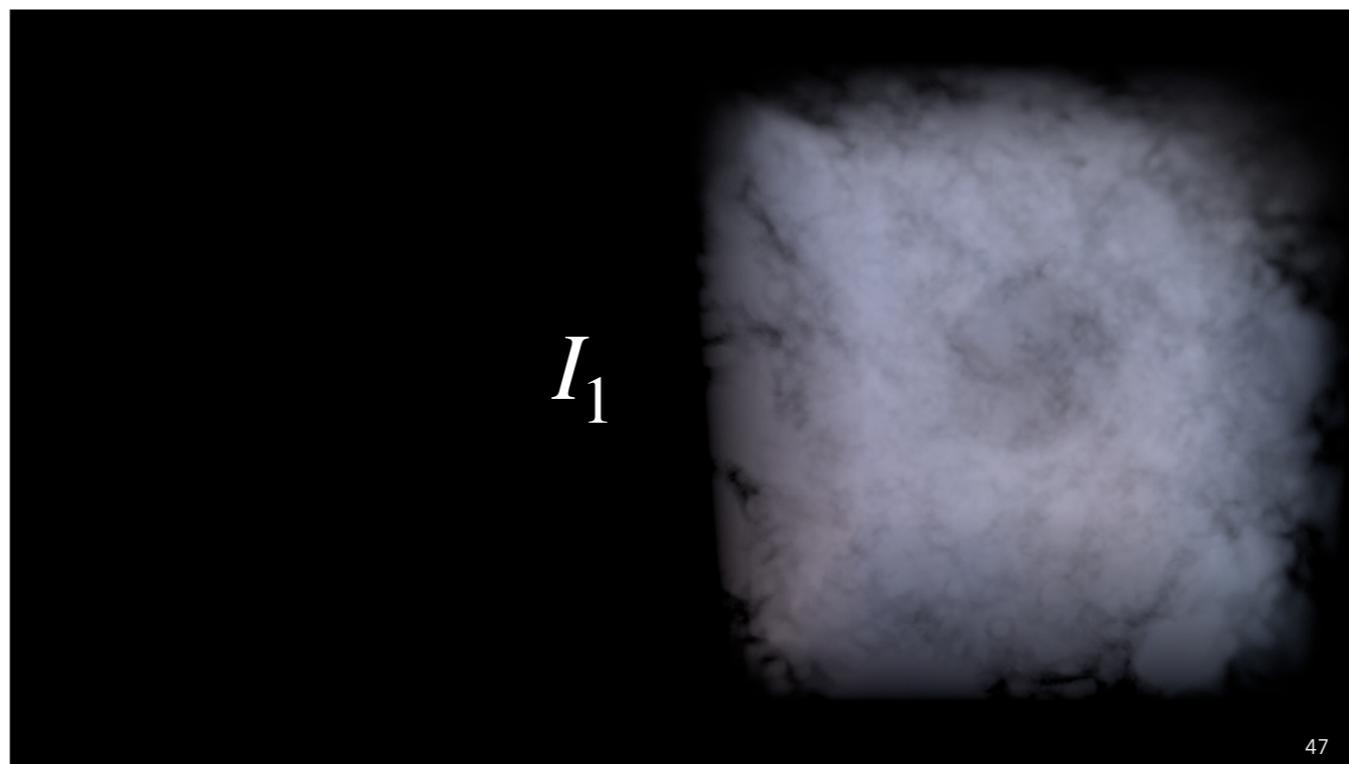
Now, let us define what we mean by consistency.



I_1

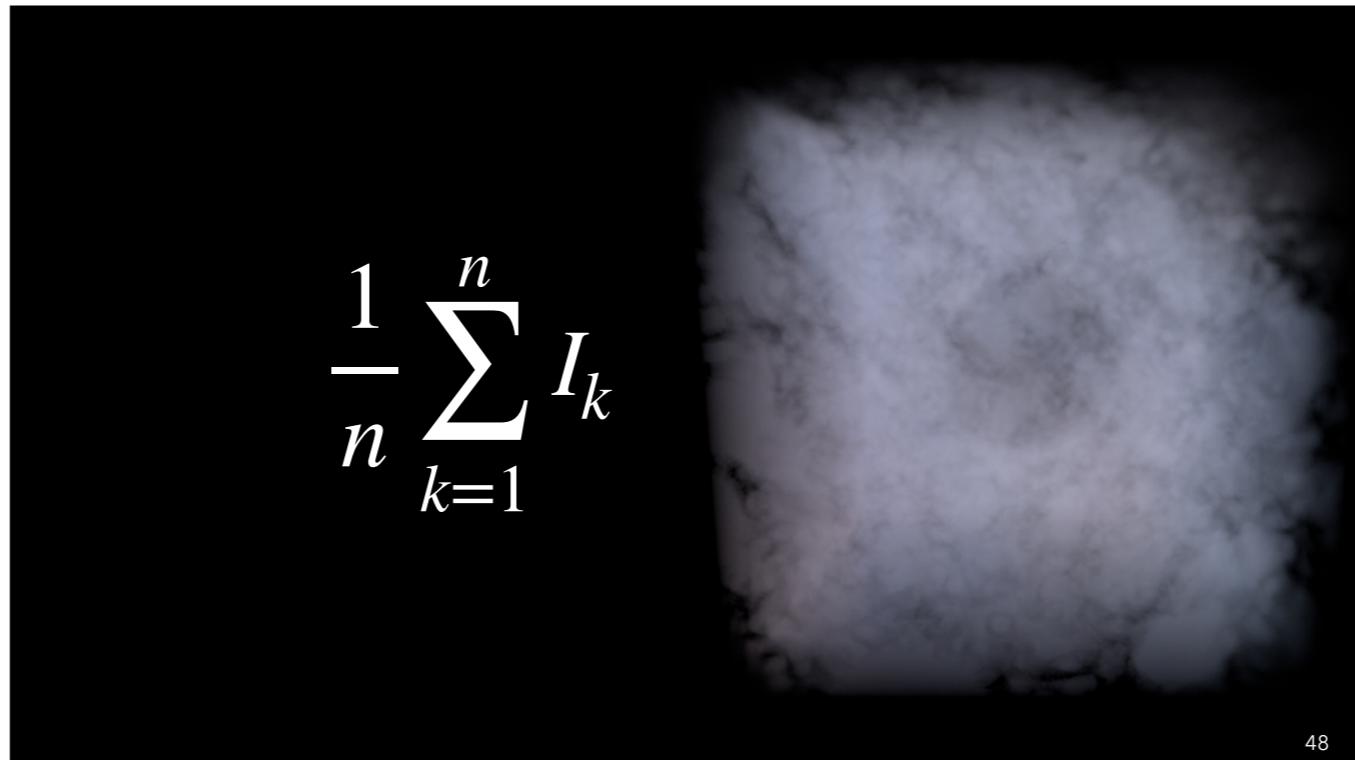
46

Let's represent the first pixel sample in a render as I of 1, and let's also assume that



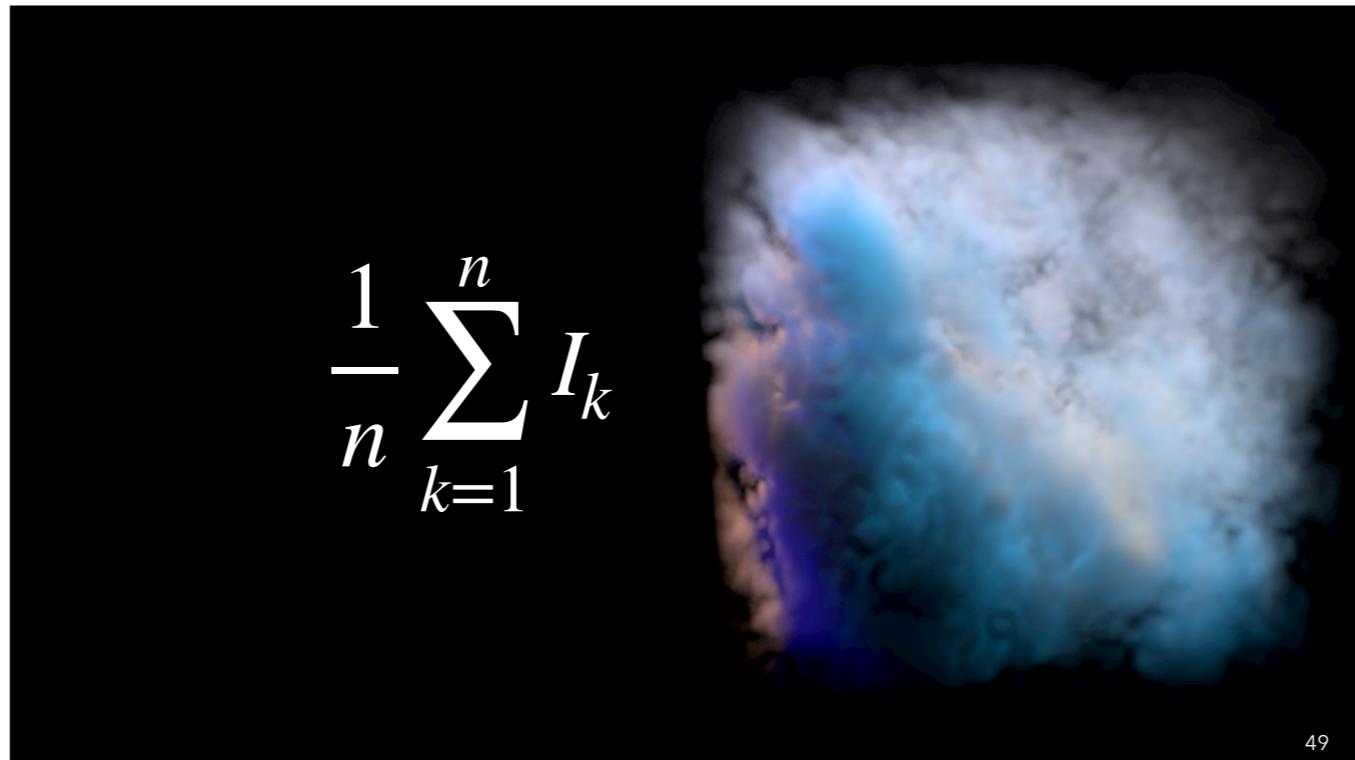
47

This first pixel sample is very biased.



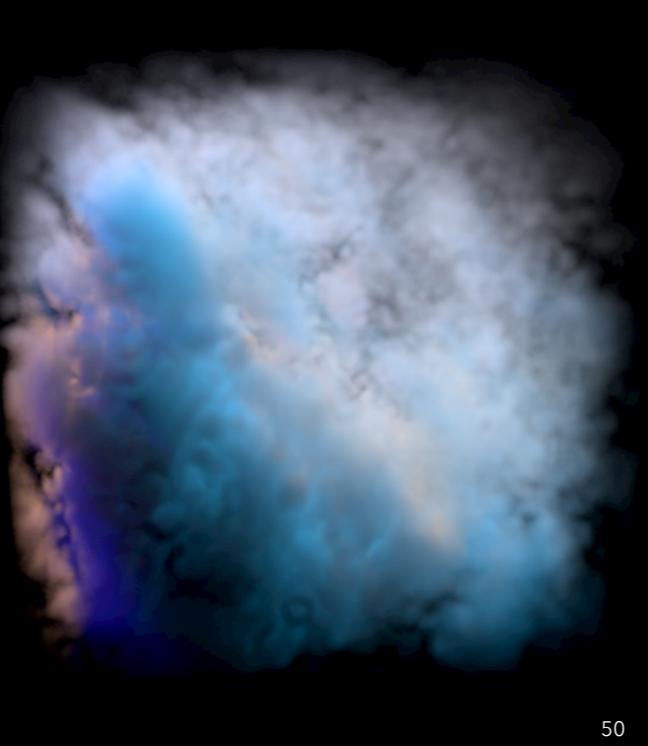
48

A full render effectively takes the average across many different pixel samples. A consistent algorithm

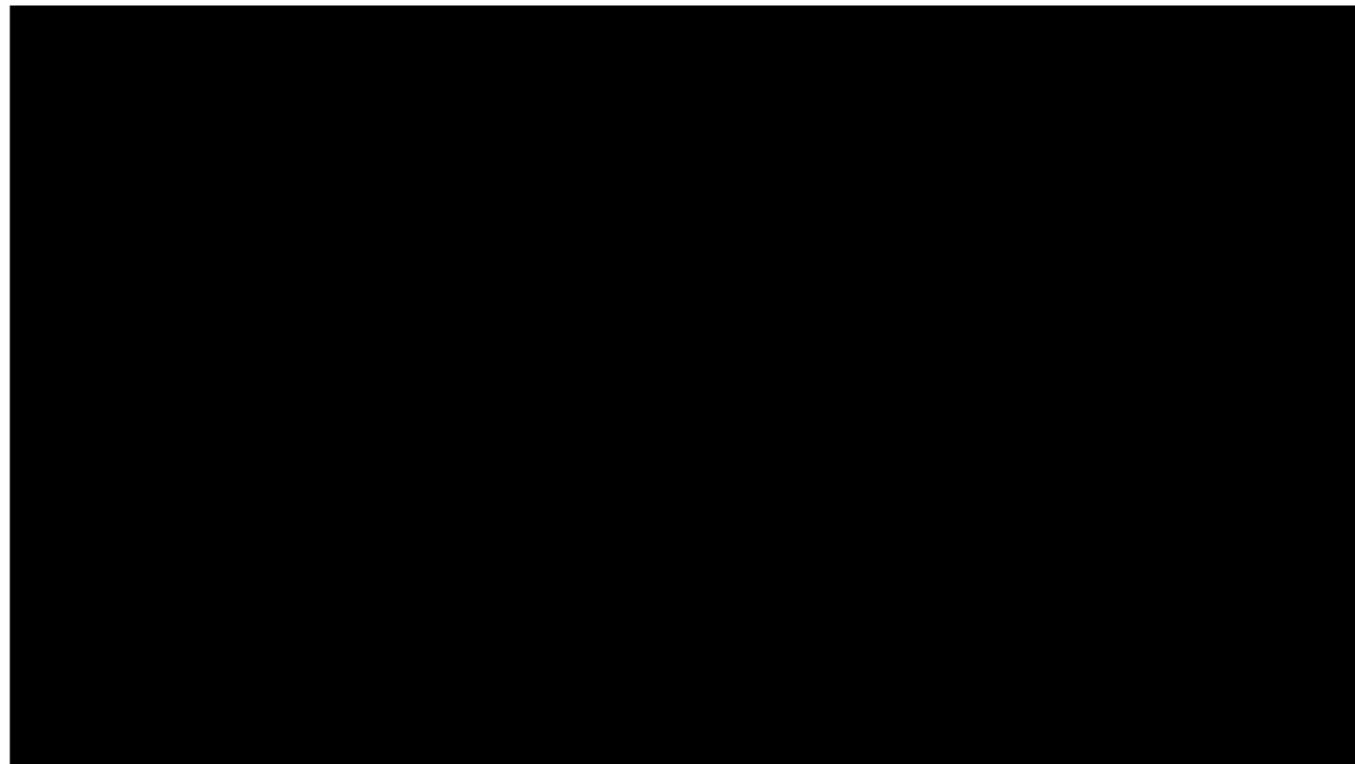


Is one which will guarantees that our render will eventually converge to the real solution,

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n I_k$$



in the limit. Regardless of how many individual pixel samples are biased.



Biased but consistent algorithms have appeared throughout graphics from photon mapping to many-light methods. And one idea, which has been used previously by virtual point lights,

Unbiased and consistent rendering using biased estimators

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ILYAN GEORGIEV, Autodesk, United Kingdom
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We introduce a general framework for transforming biased estimators into unbiased and consistent estimators for the same quantity. We show how several existing unbiased and consistent strategies in rendering are special cases of this framework, and we present a new unbiased example. We provide a recipe for constructing estimators using our generalized framework and demonstrate its applicability by developing novel unbiased forms of transmittance estimation, photon mapping, and finite differences.

CCS Concepts: • Computing methodologies → Rendering; Ray tracing

Additional Key Words and Phrases: Monte Carlo, infinite series, Taylor series

ACM Reference Format:

Zackary Misso, Benedikt Bitterli, Ilyan Georgiev, and Wojciech Jarosz. 2022. Unbiased and consistent rendering using biased estimators. *ACM Trans. Graph.* 41, 4, Article 48 (July 2022), 13 pages. <https://doi.org/10.1145/3528223.3530160>

1 INTRODUCTION

From estimating the amount of radiance reaching a camera sensor, to estimating how much light transmits through a participating medium, there are countless situations in graphics which require estimating intricate integrals. While we have developed a large arsenal of unbiased estimation techniques, situations still arise where we must fall back on biased formulations.

We consider problems where we need to compute some finite quantity I , but we only have a biased estimator $I(k)$ with a controllable amount of bias—dictated by some parameter k at our disposal. By adjusting the bias parameter towards some limit (e.g., $k \rightarrow \infty$) the estimator’s expected value $I(k)$ approaches the correct answer:

$$I = \lim_{k \rightarrow \infty} I(k). \quad (1)$$

The bias parameter k could be continuous or discrete; for example, a discrete k could represent the maximum path length in a path tracer, while a continuous k could correspond to the step size in ray tracing.

Progressive Photon Mapping

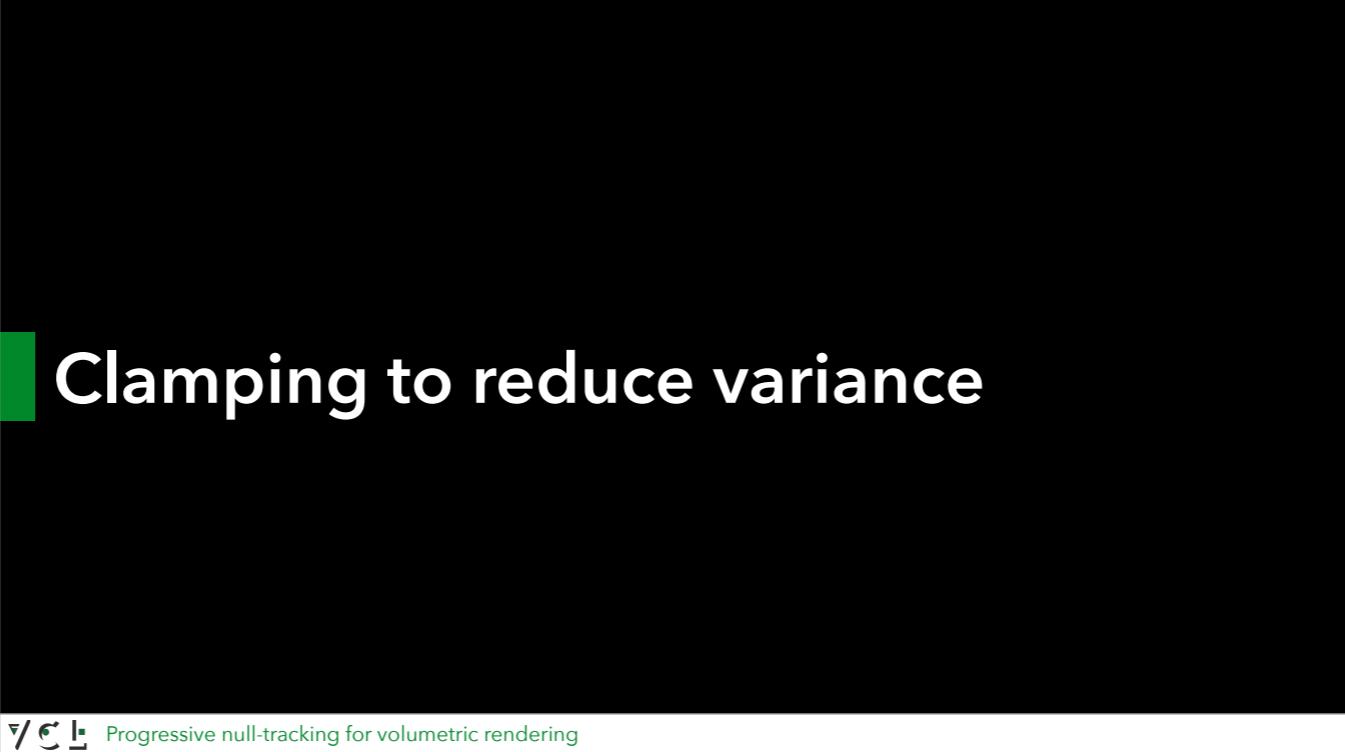
Toshiya Hachisuka
UC San Diego
Shinji Ogaki
The University of Nottingham
Henrik Wann Jensen
UC San Diego

EUROGRAPHICS 2013 / M. Sbert, L. Szirmay-Kalos
STAR – State of The Art Report

Scalable Realistic Rendering with Many-Light Methods

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Karlsruhe Institute of Technology
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Charles University, Prague
Miloš Hašan
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Adam Arshée
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Bruce Walter
Cornell University
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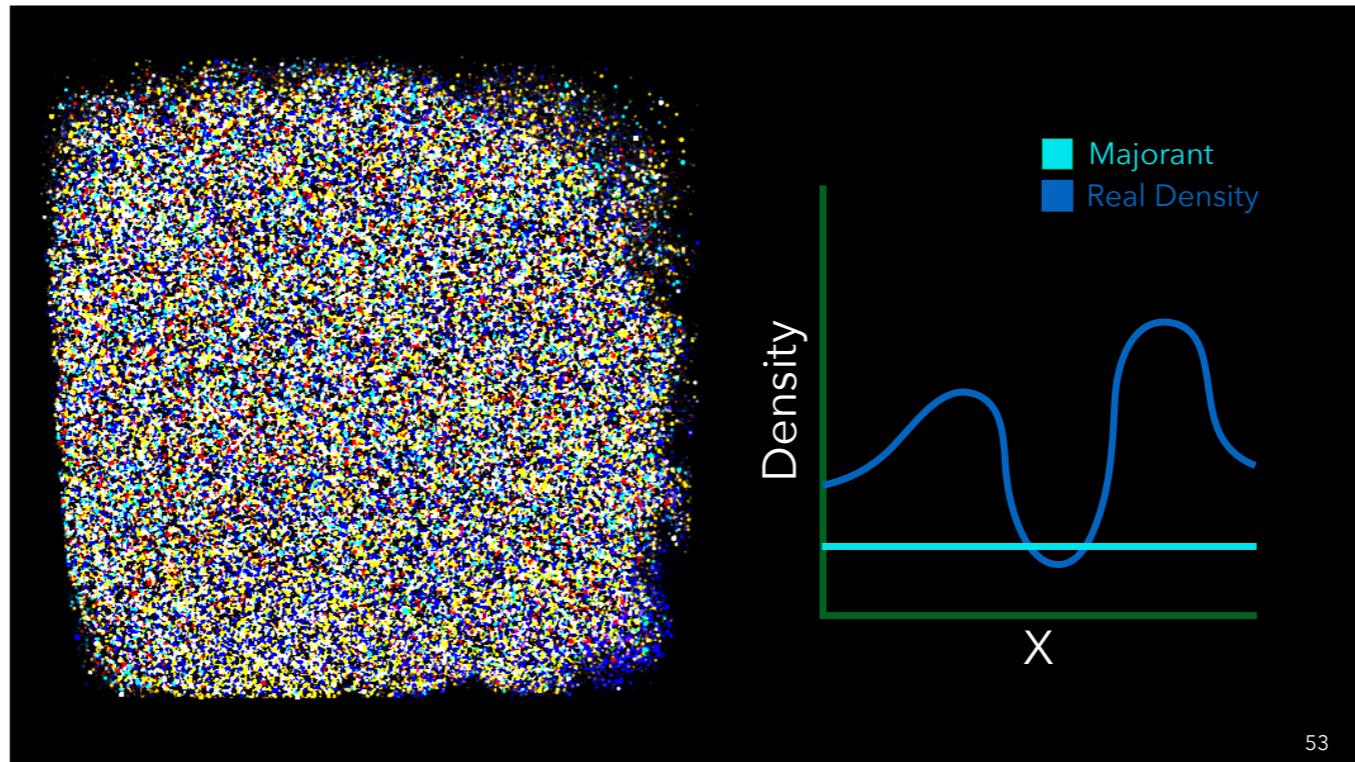
Figure 1: A glass lamp illuminates a wall and generates a complex caustics lighting pattern on the wall. The figure compares results from Monte-Carlo ray tracing methods such as path tracing, bidirectional path tracing, lighting seen through the lamp, and the final quality limited by the memory available for the photon map. Progressive photon mapping provides an image with substantially less noise in the same amount of time. The figure also includes a comparison of different photon mapping methods and a final image showing the combination of various rendering techniques.



Clamping to reduce variance

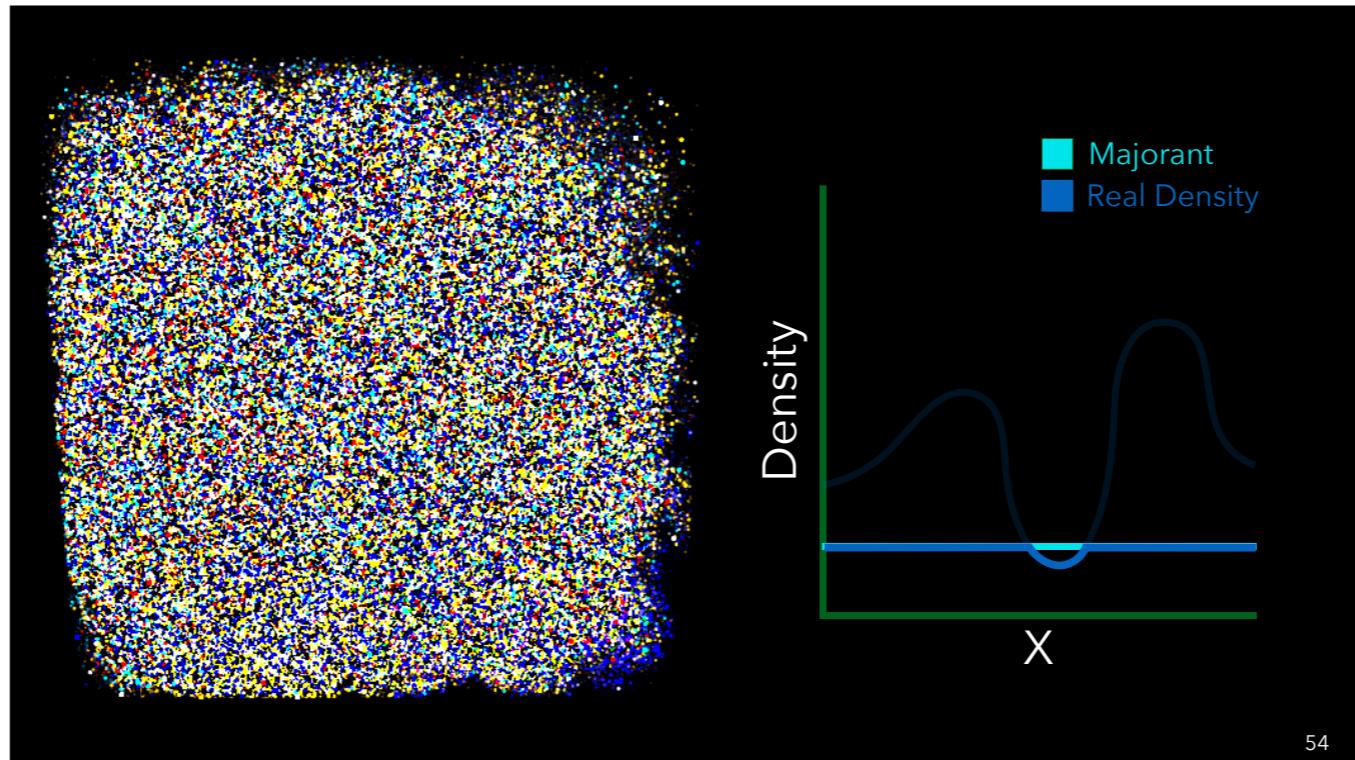
 Progressive null-tracking for volumetric rendering

Is the idea of clamping to reduce variance. This is the first step in our technique.



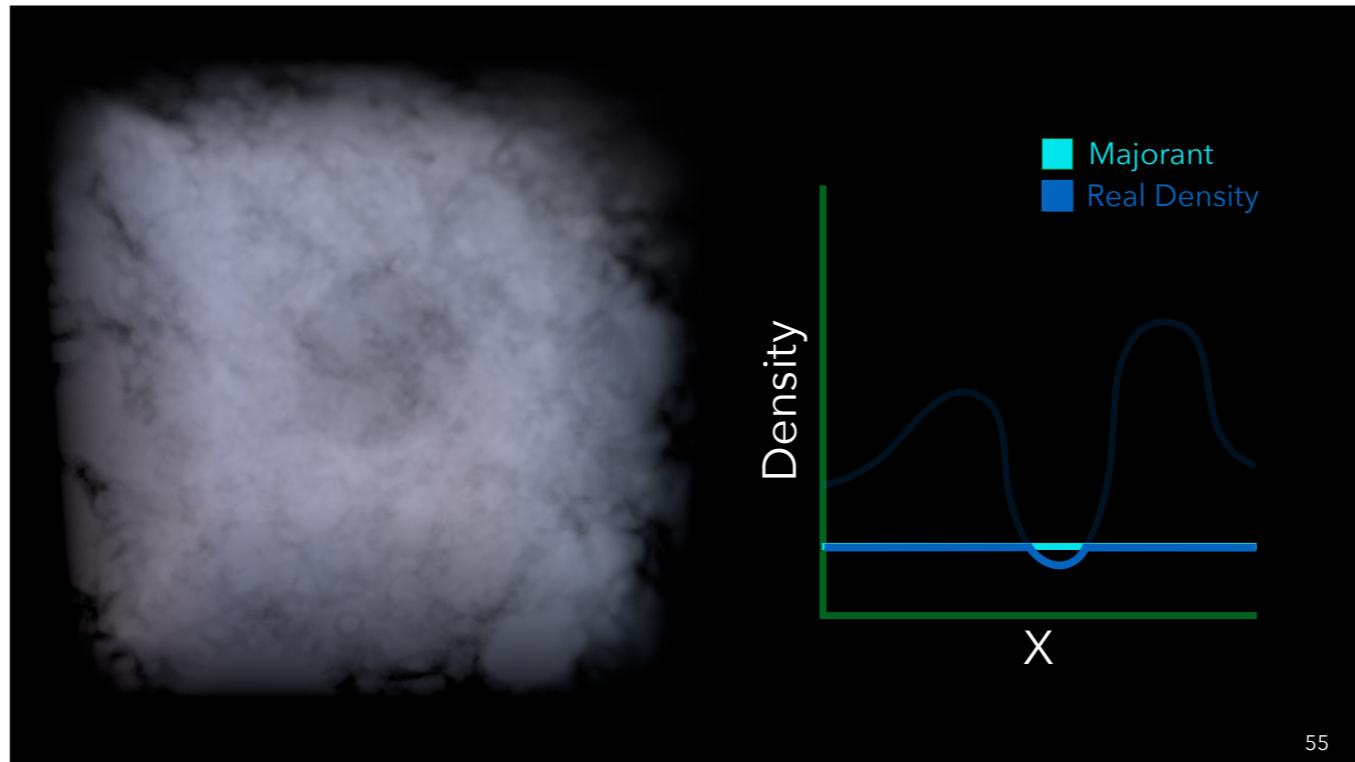
53

Significantly non-bounding majorants lead to uncontrollable variance, HOWEVER, we can enforce our majorants to be always bounding,

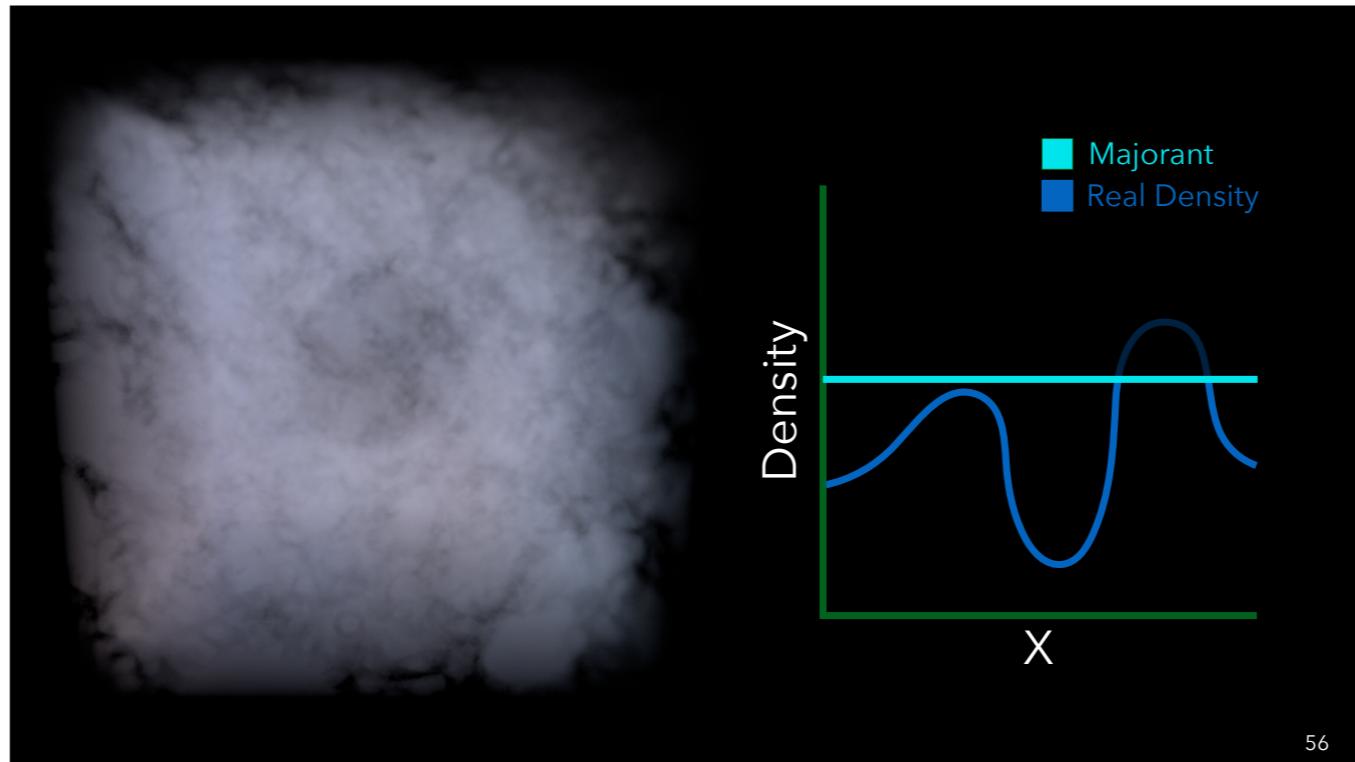


54

by clamping the medium density to the specified majorant. This process will obviously

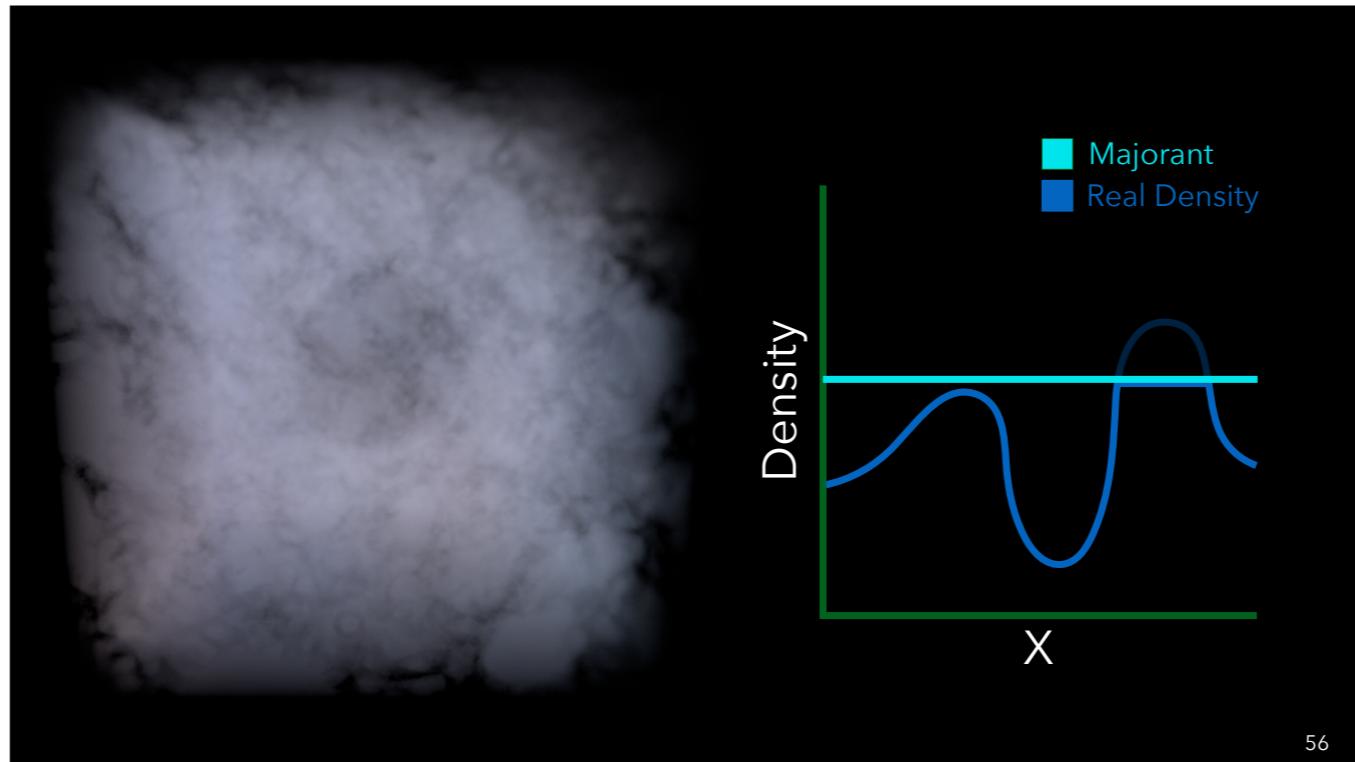


Make the medium itself biased. However, one thing to make note of is that if we

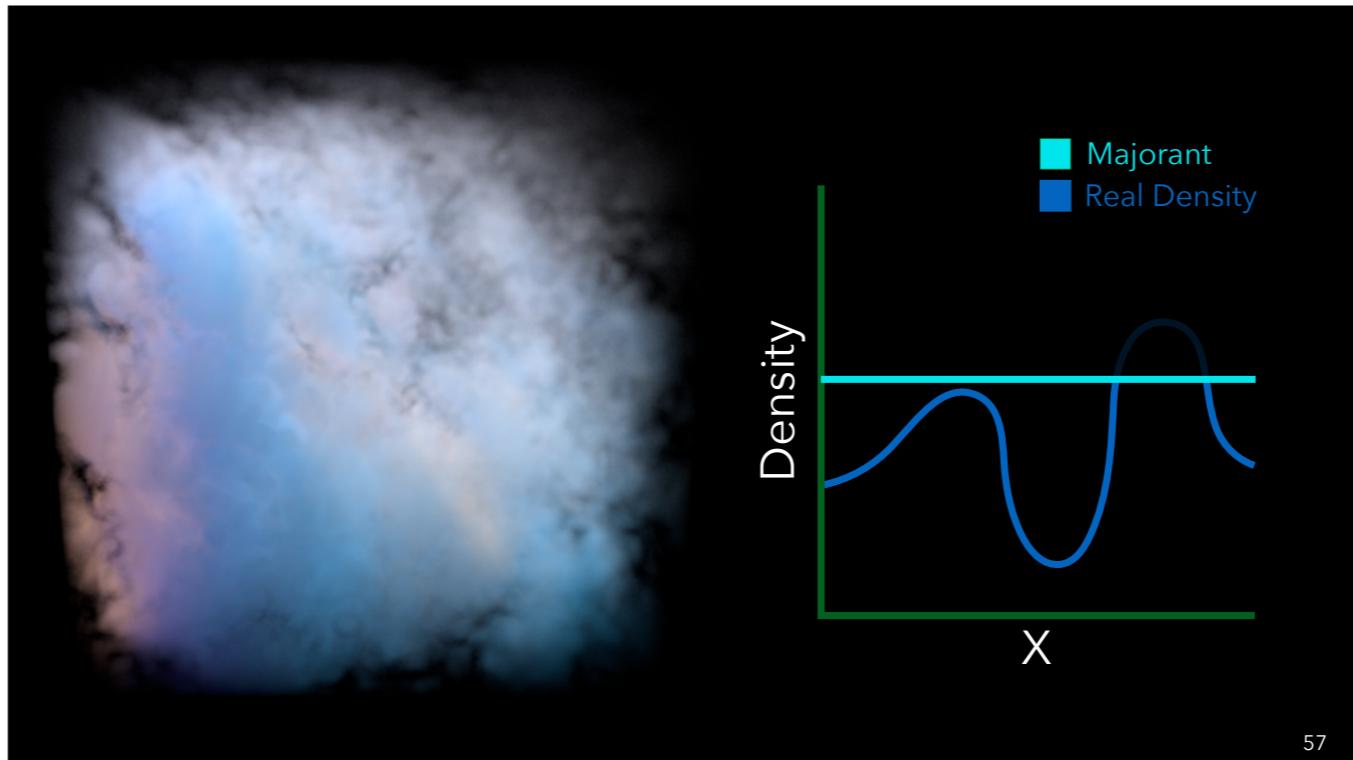


56

Increased the majorant, and thus clamped less of the density,

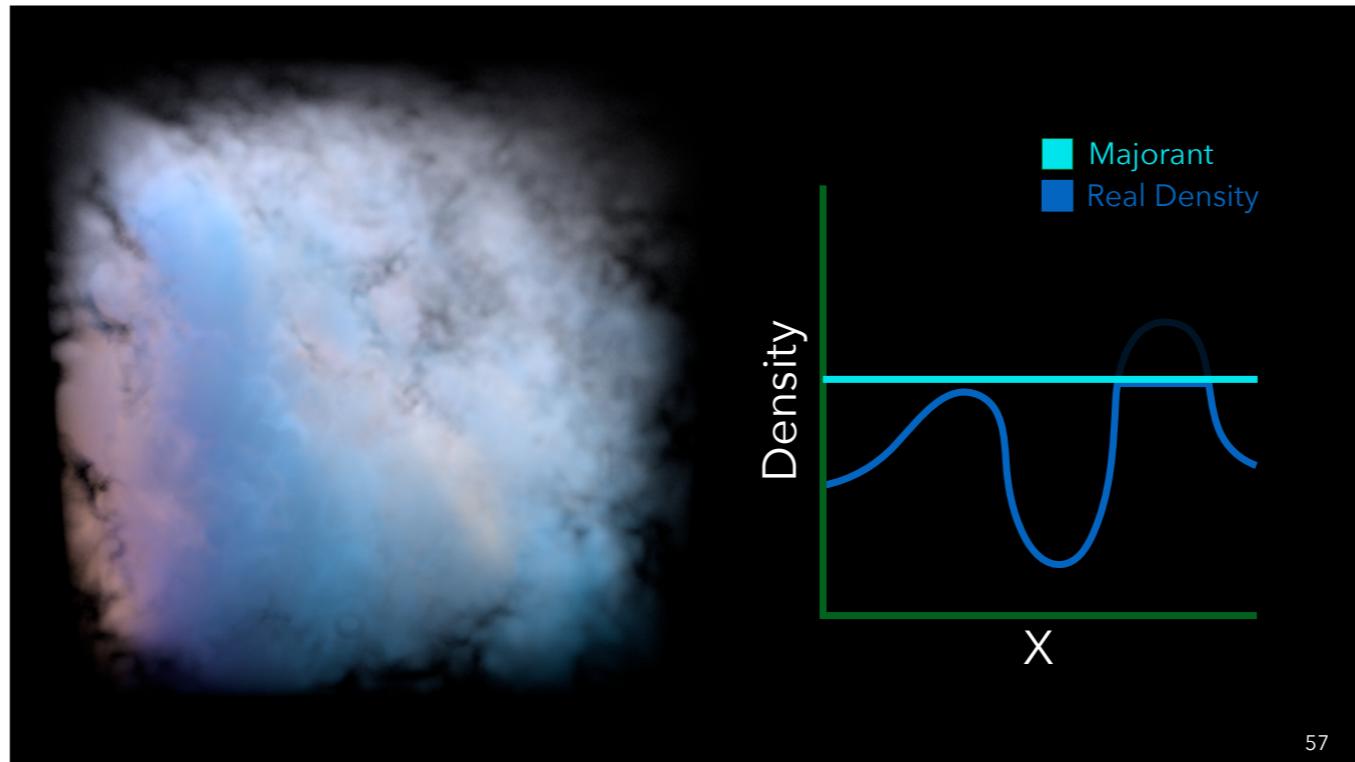


56

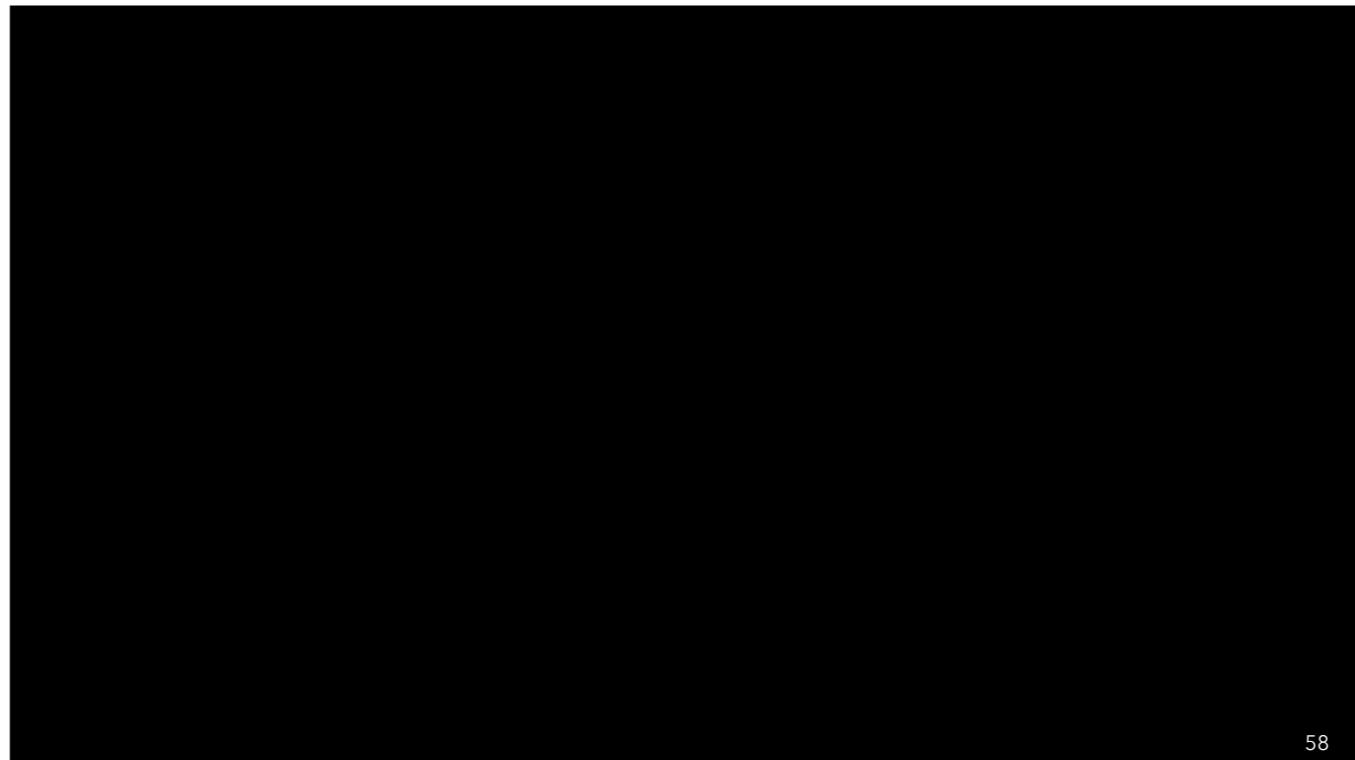


57

Our render would be less biased. And you can now start to see a thought experiment forming.

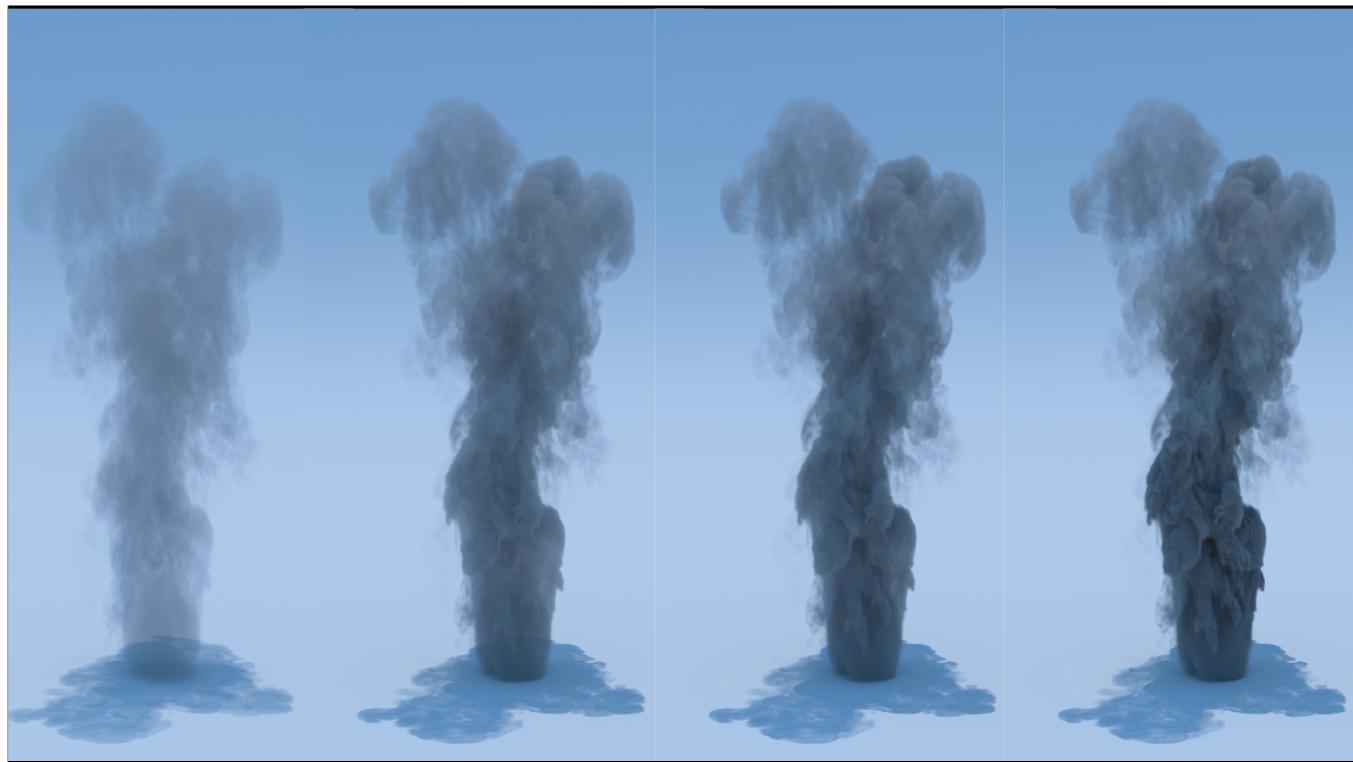


57

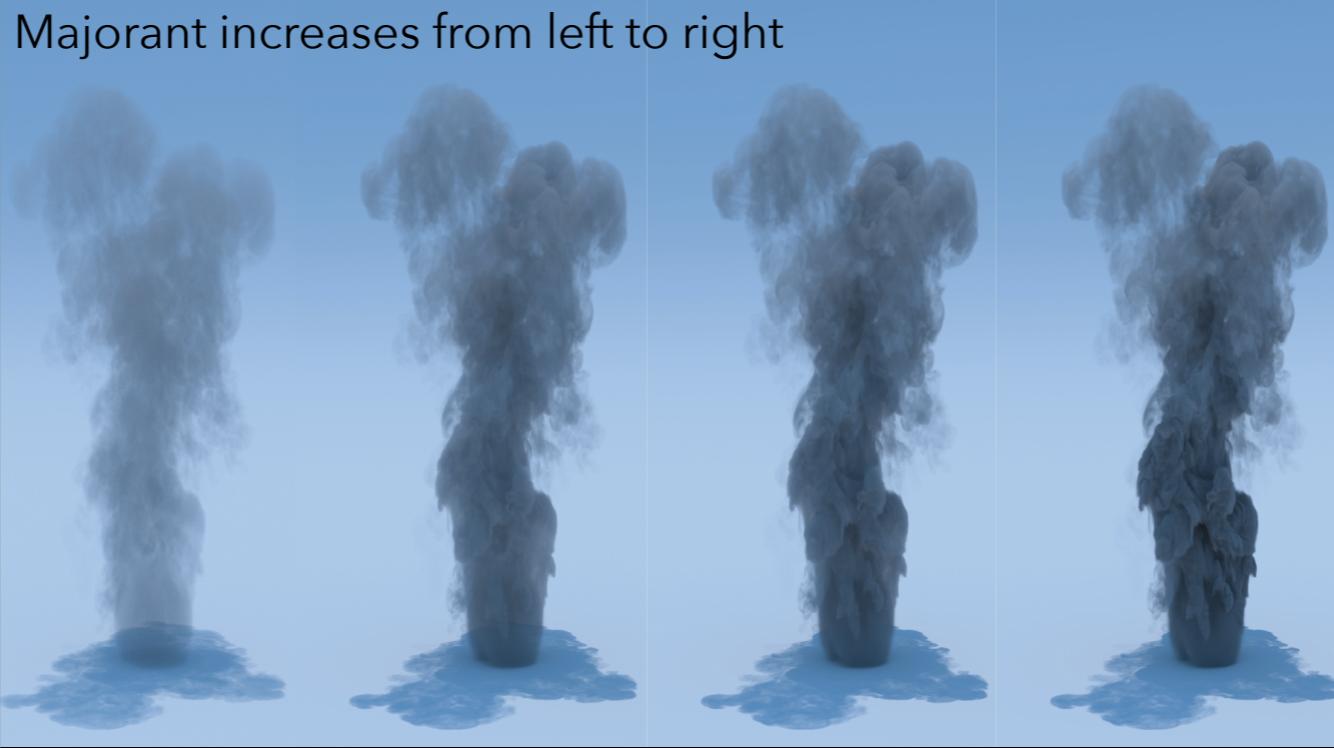


58

What if we had a sequence of pixel samples,



Majorant increases from left to right



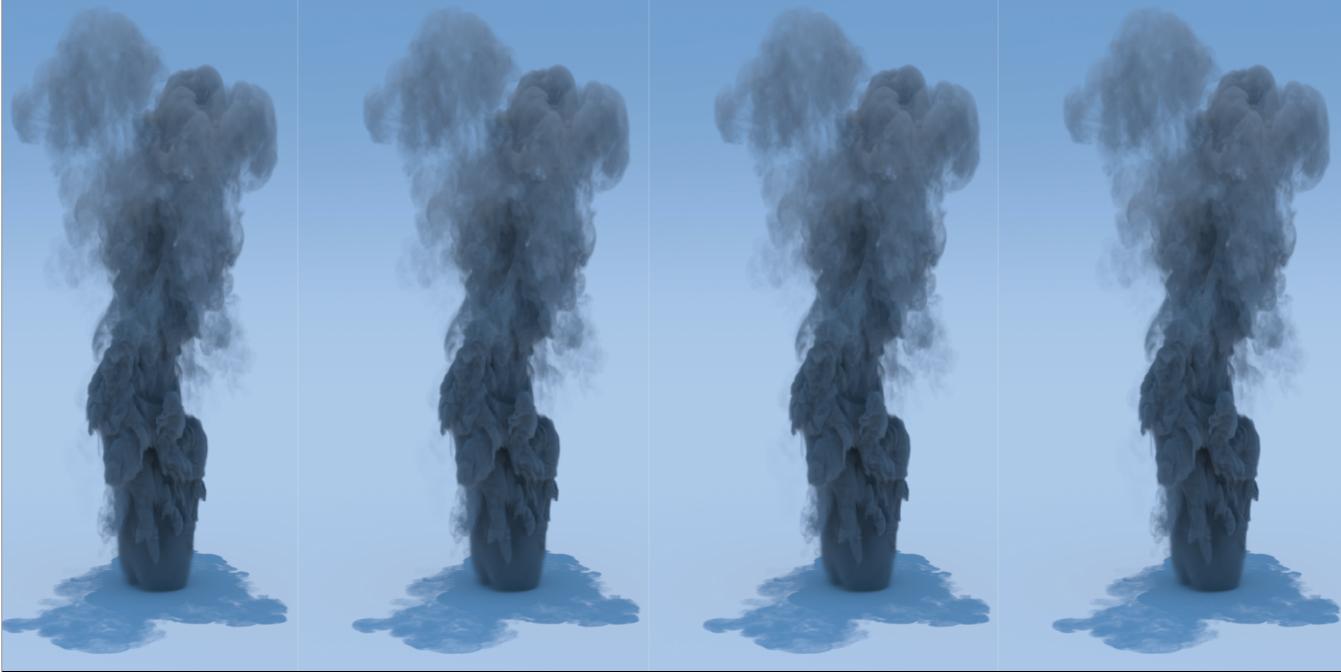
which all used monotonically increasing majorants. Meaning, the first few pixel samples will be biased,

Majorant increases from left to right



But after some finite point a bounding majorant will be found and every subsequent pixel sample will be unbiased.

Majorant increases from left to right



$$\sum_{k=1}^n \frac{I_k}{n}$$

61

The entire render would be the average of all these images.

$$\sum_{k=1}^j \frac{I_k}{n} + \sum_{k=j+1}^n \frac{I_k}{n}$$

62

Which we can decompose into a finite number of (*click*) biased terms, while the remainder are all (*click*) unbiased.

$$\sum_{k=1}^j \frac{I_k}{n} + \sum_{k=j+1}^n \frac{I_k}{n}$$

Biased

$$\sum_{k=1}^j \frac{I_k}{n} + \boxed{\sum_{k=j+1}^n \frac{I_k}{n}}$$

Biased

Unbiased

$$\lim_{n \rightarrow \infty} \left[\sum_{k=1}^j \frac{I_k}{n} + \sum_{k=j+1}^n \frac{I_k}{n} \right]$$

Biased

Unbiased

63

In the infinite limit, the biased contribution is going to converge to

$$\lim_{n \rightarrow \infty} \left[0 + \sum_{k=j+1}^n \frac{I_k}{n} \right]$$

Biased

Unbiased

64

Zero, while the contribution from the infinite remaining unbiased terms is going to converge to



65

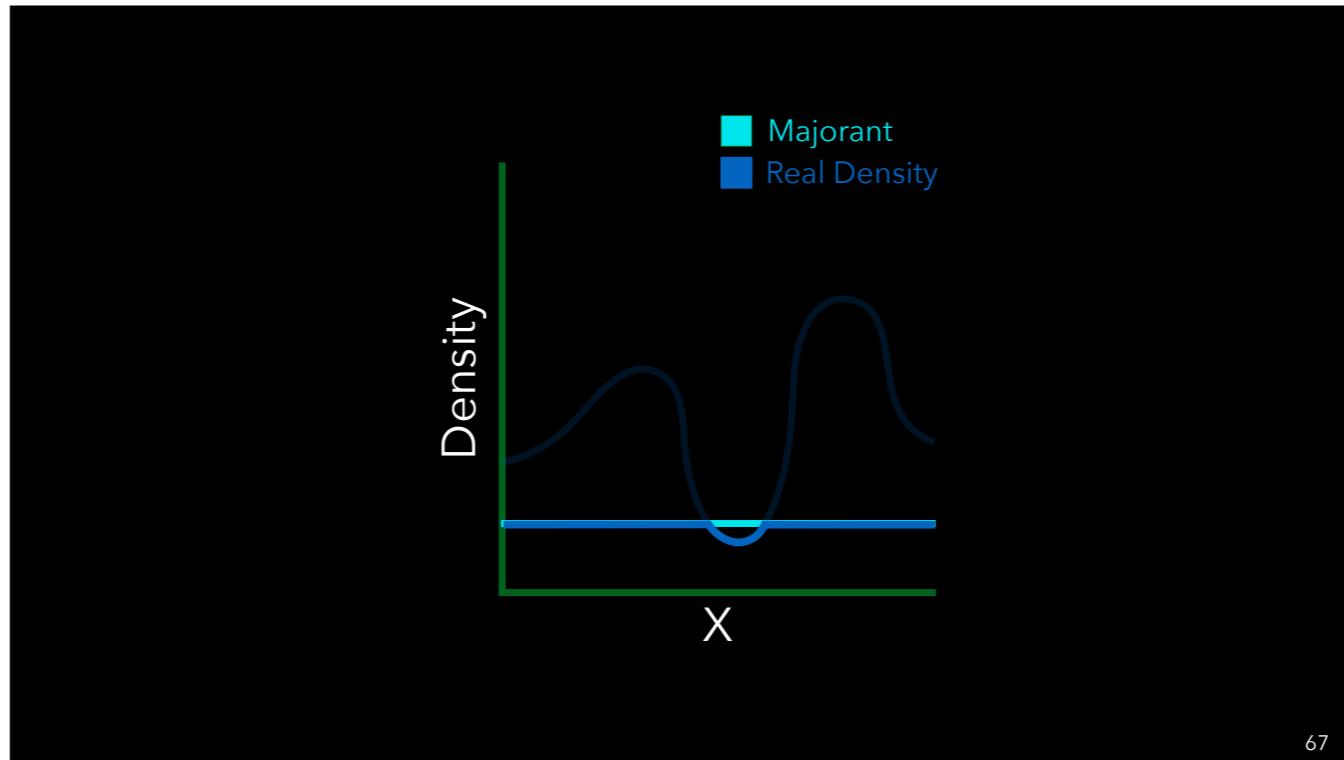
The true solution. So, if we discover a bounding majorant in finite time, we can make most null-scattering algorithms consistent while avoiding uncontrollable variance.



Progressively update majorants

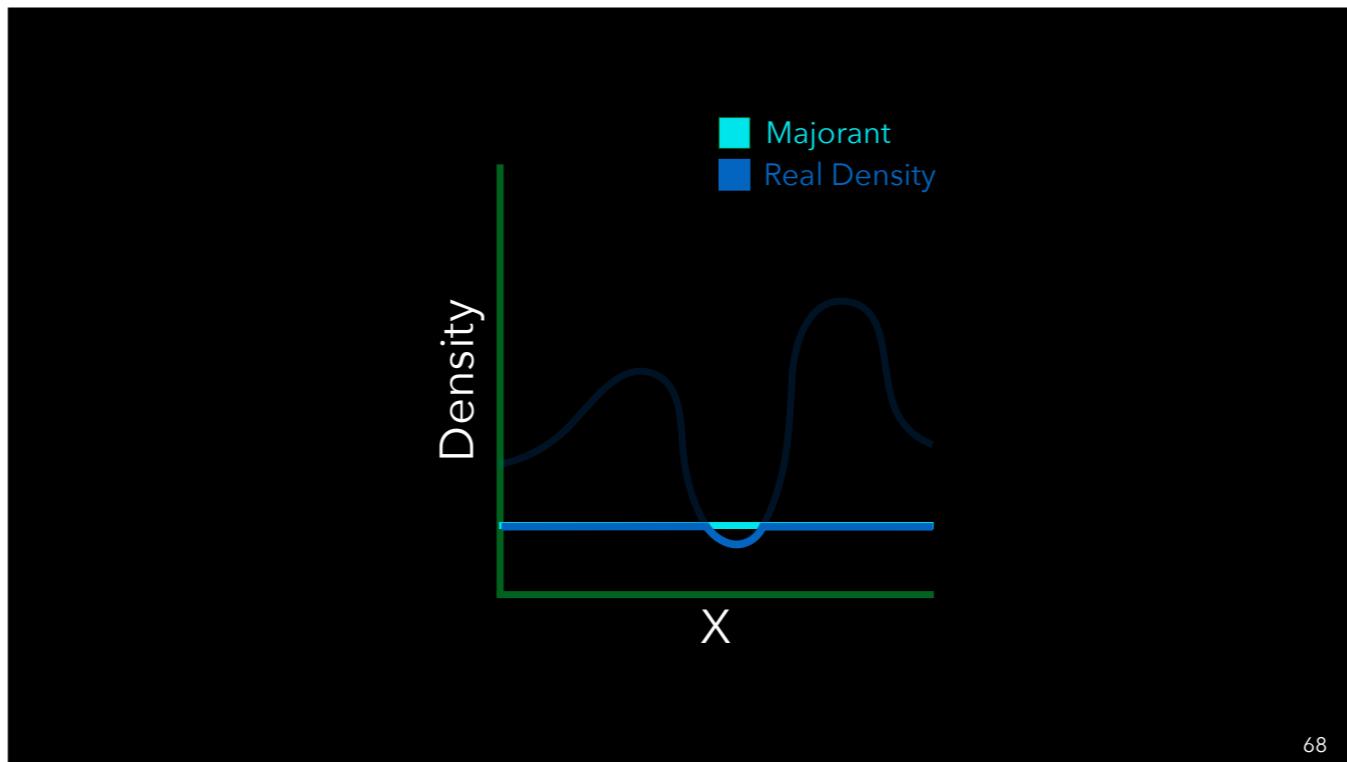
 Progressive null-tracking for volumetric rendering

Which brings us to the second step in our technique. Progressively updating the majorants.



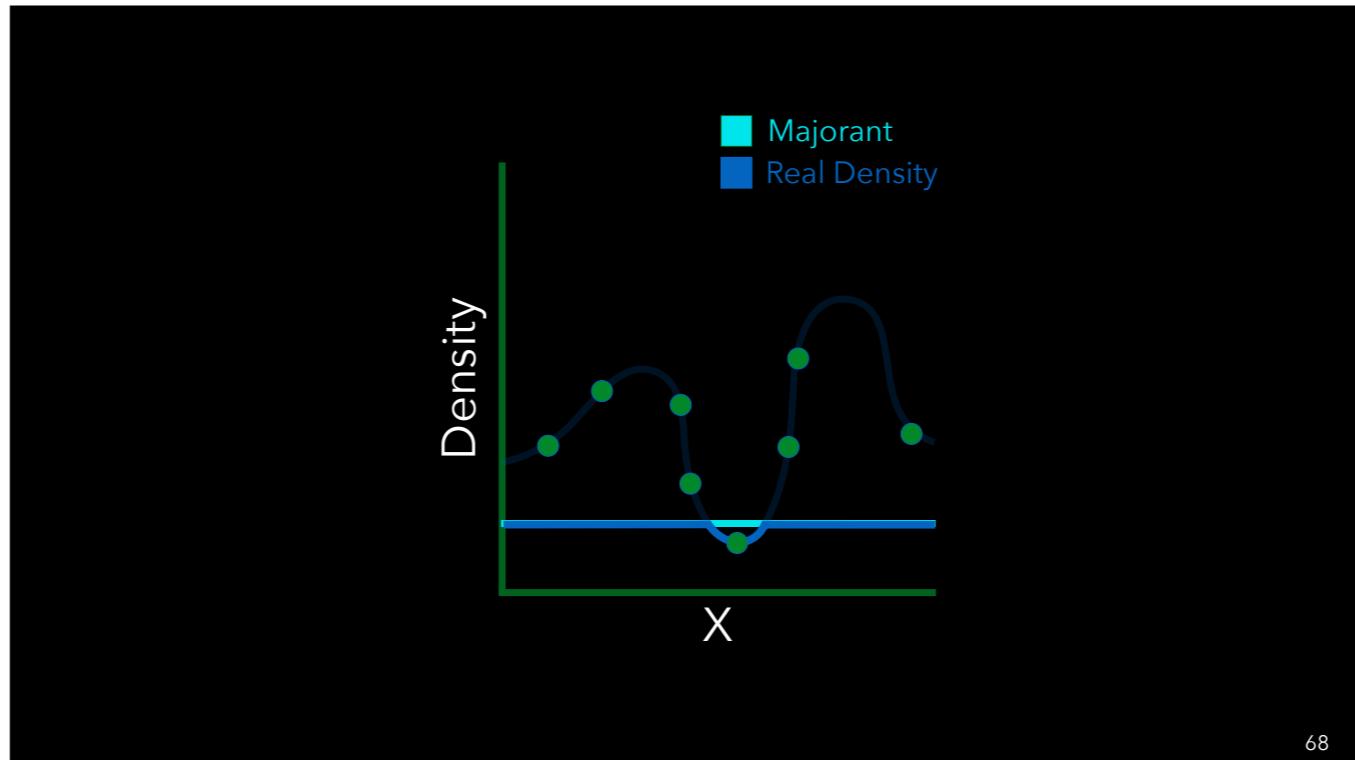
67

Over the course of rendering, we will naturally evaluate the density

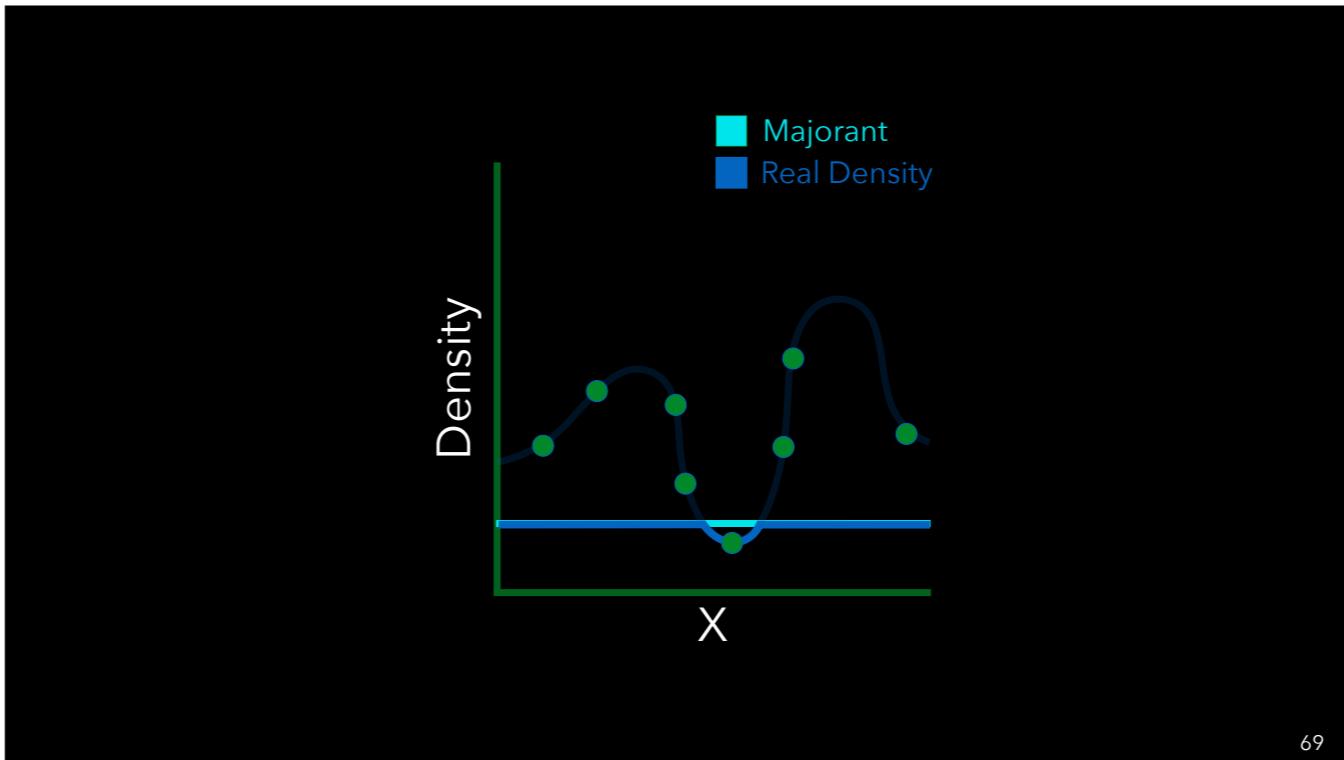


68

At many different points within the medium.

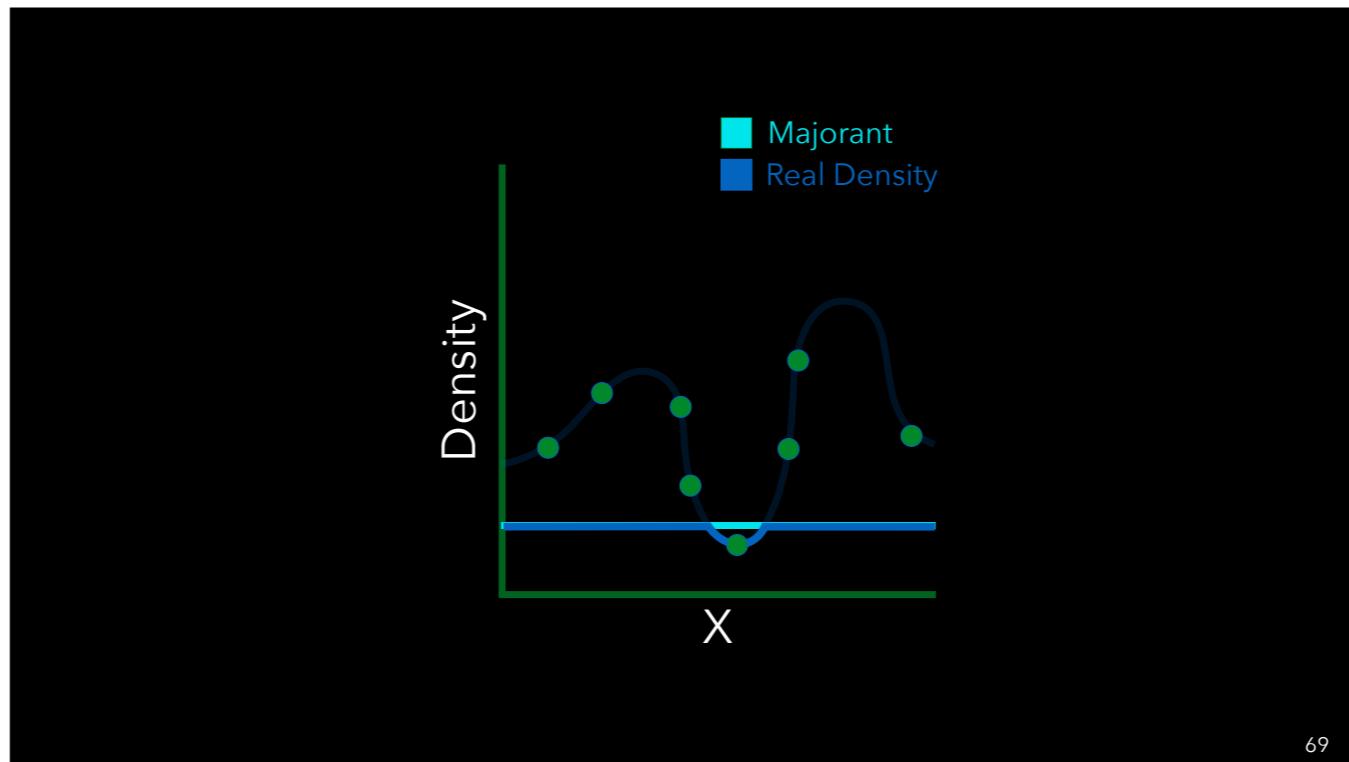


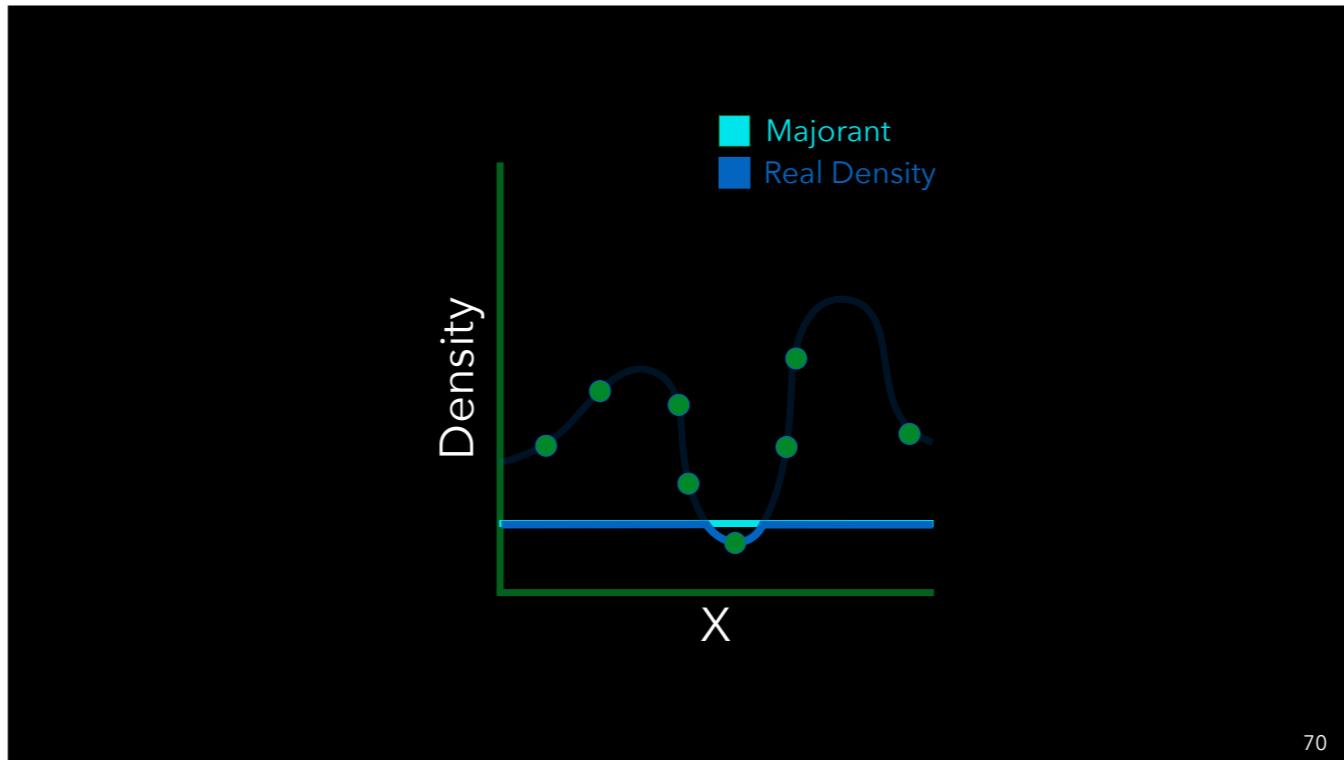
68



69

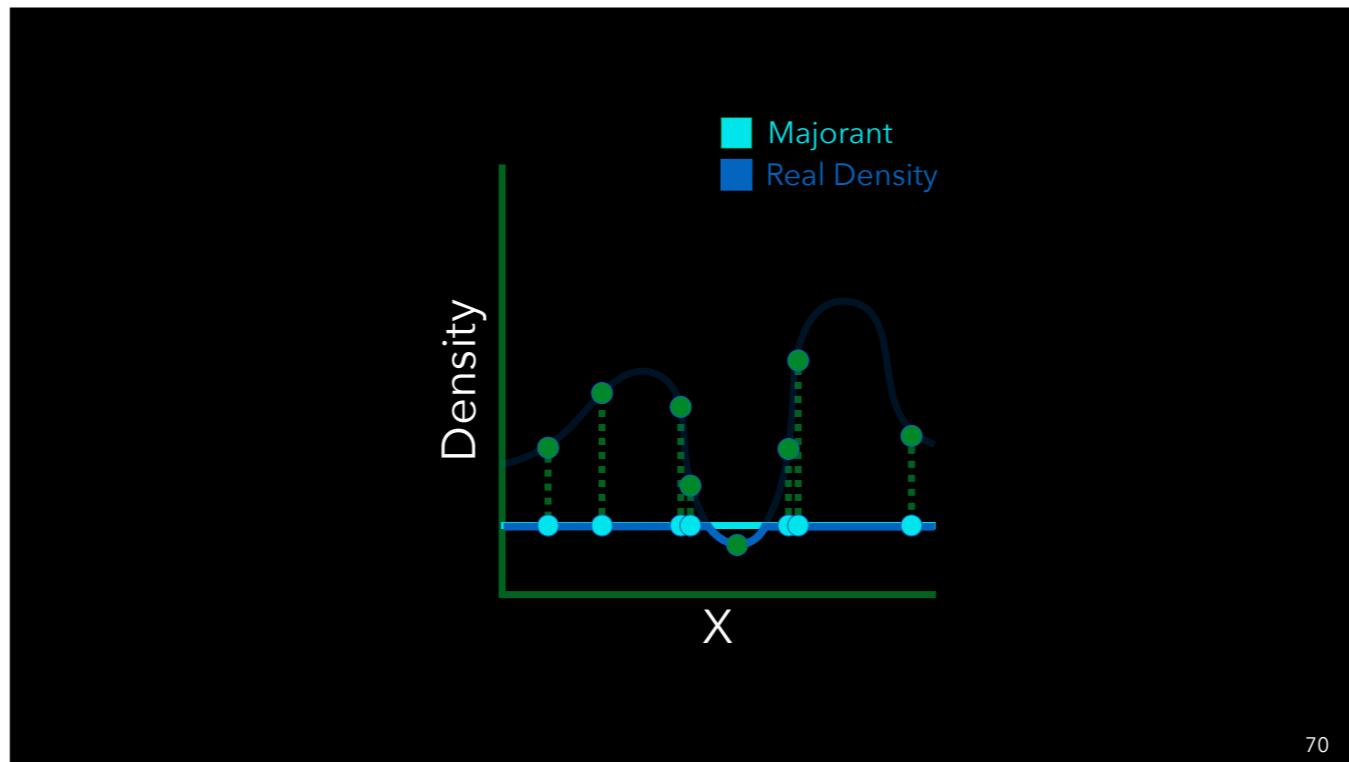
Every single one of these density evaluations may or may not



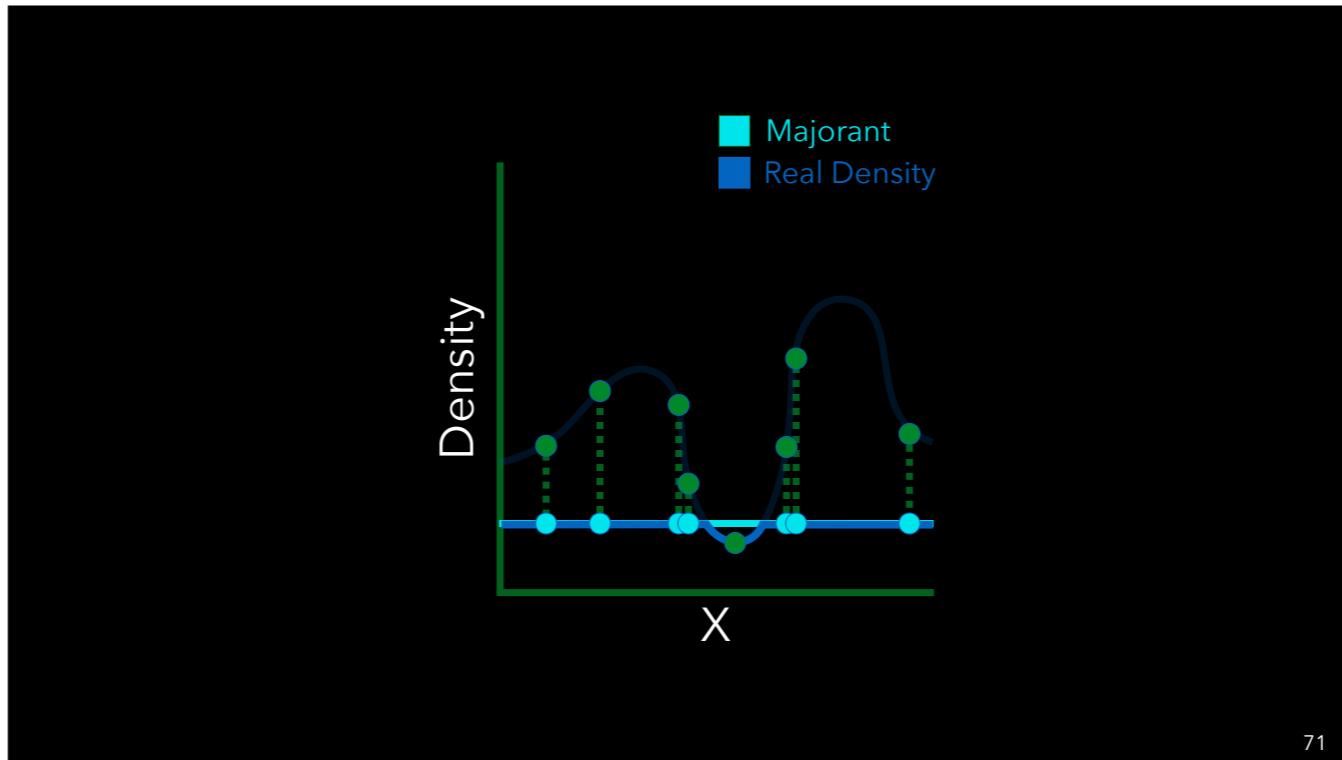


70

get clamped. However, All of these evaluations give us direct,

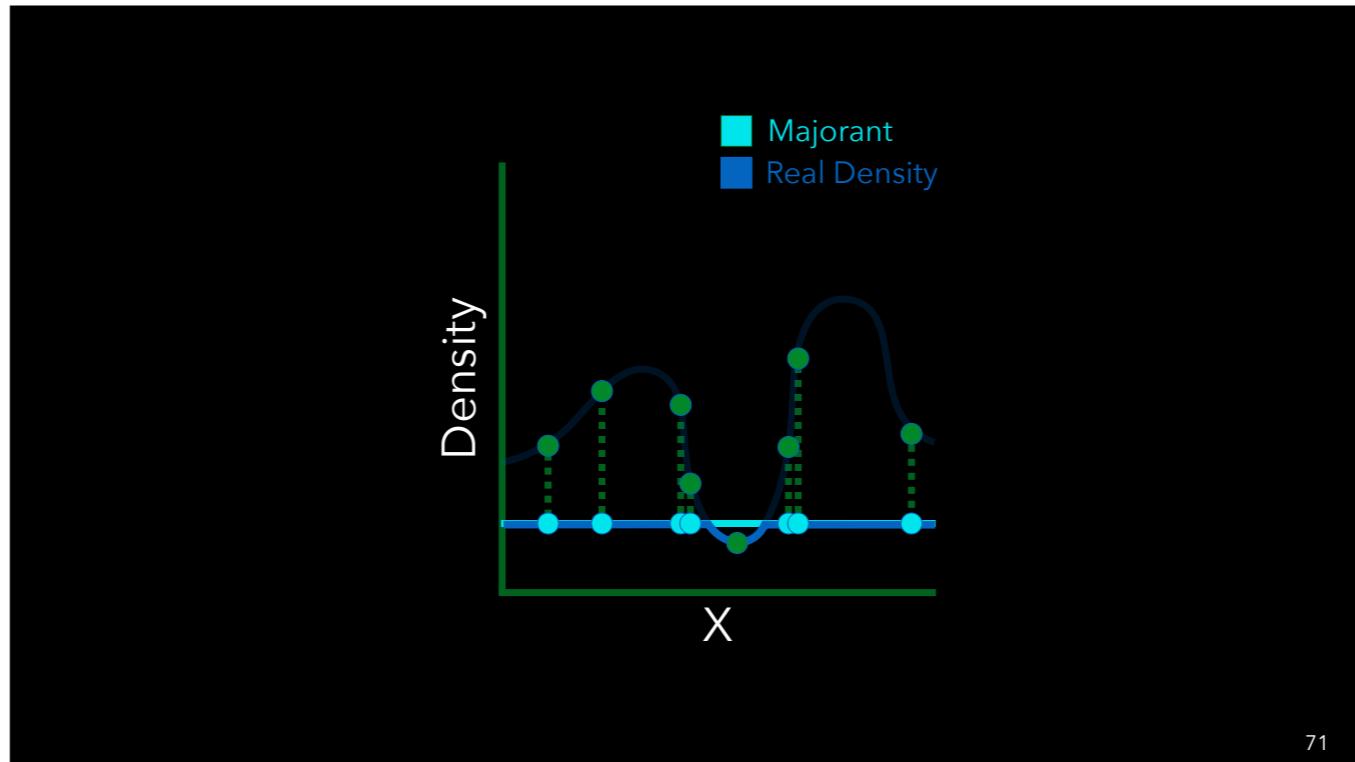


70

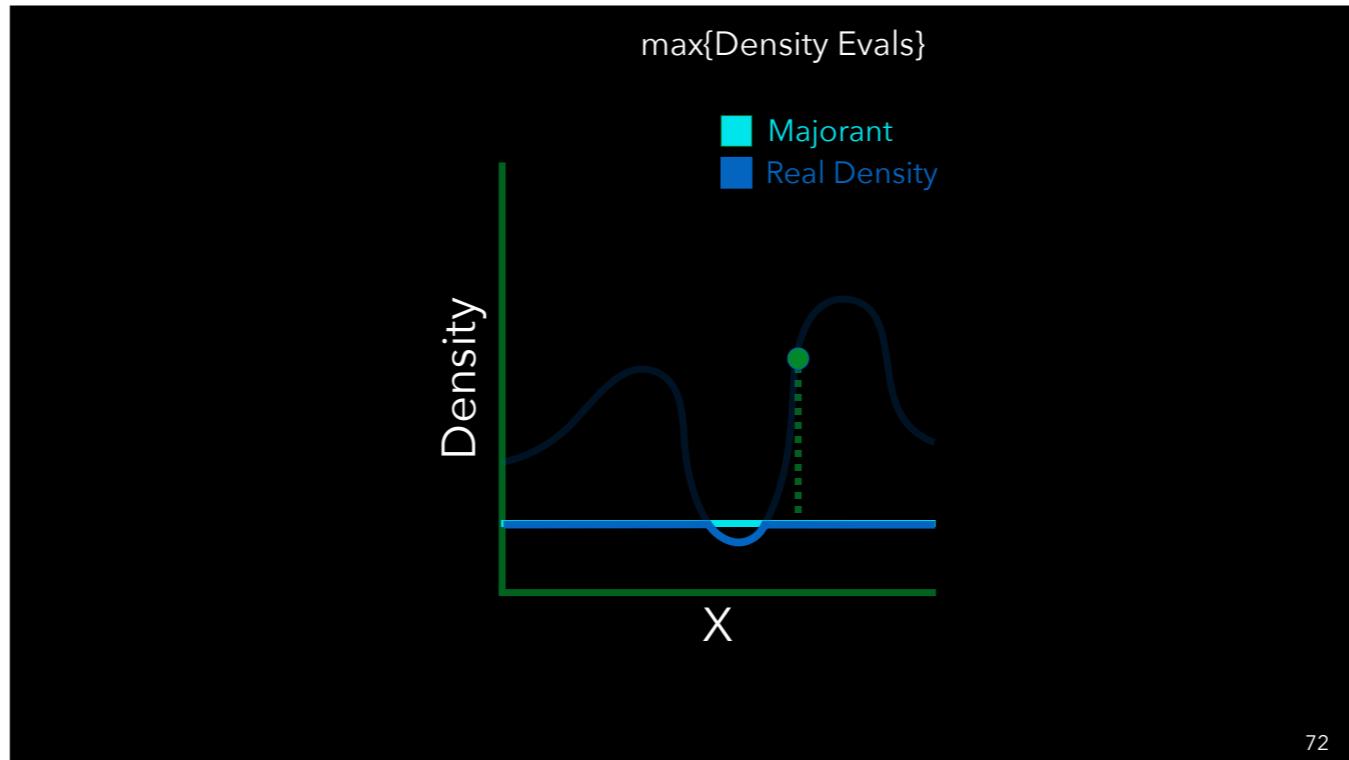


71

Estimates for how non-bounding our majorant actually is. We can then choose



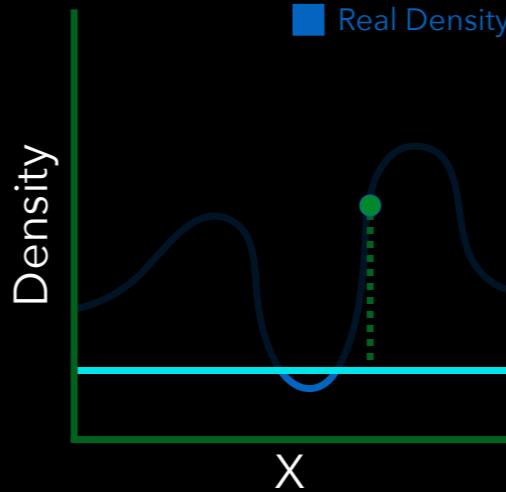
71



the largest difference between any of the density evaluations and our current majorant,

Next Majorant = $\max\{\text{Density Evals}\}$

Majorant
Real Density

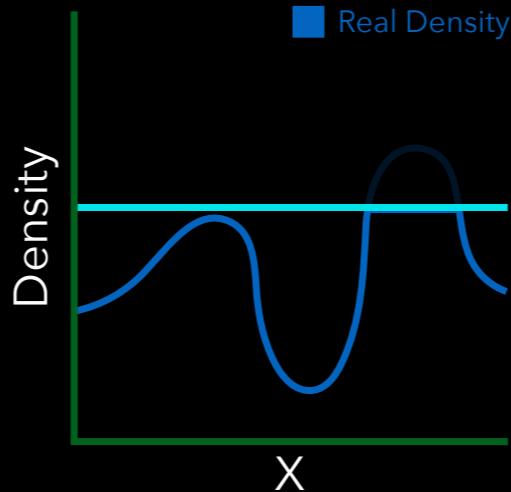


73

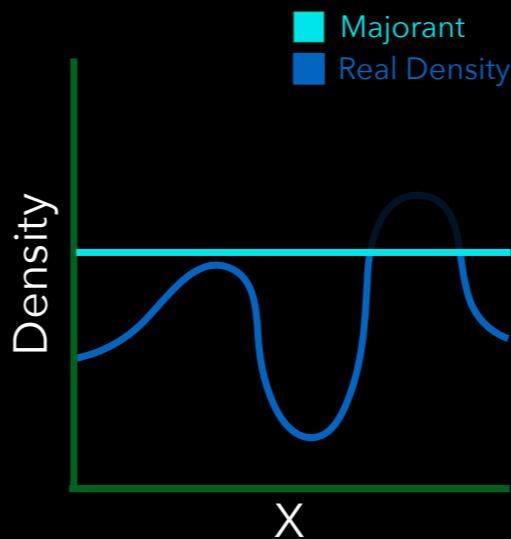
To directly set the majorant to use for the next render pass. We also add a small non-zero

Next Majorant = $\max\{\text{Density Evals}\}$

Majorant
Real Density



Next Majorant = $\max\{\text{Density Evals}\} + C$

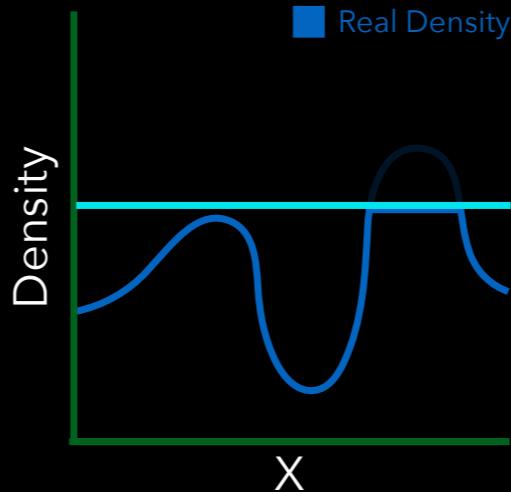


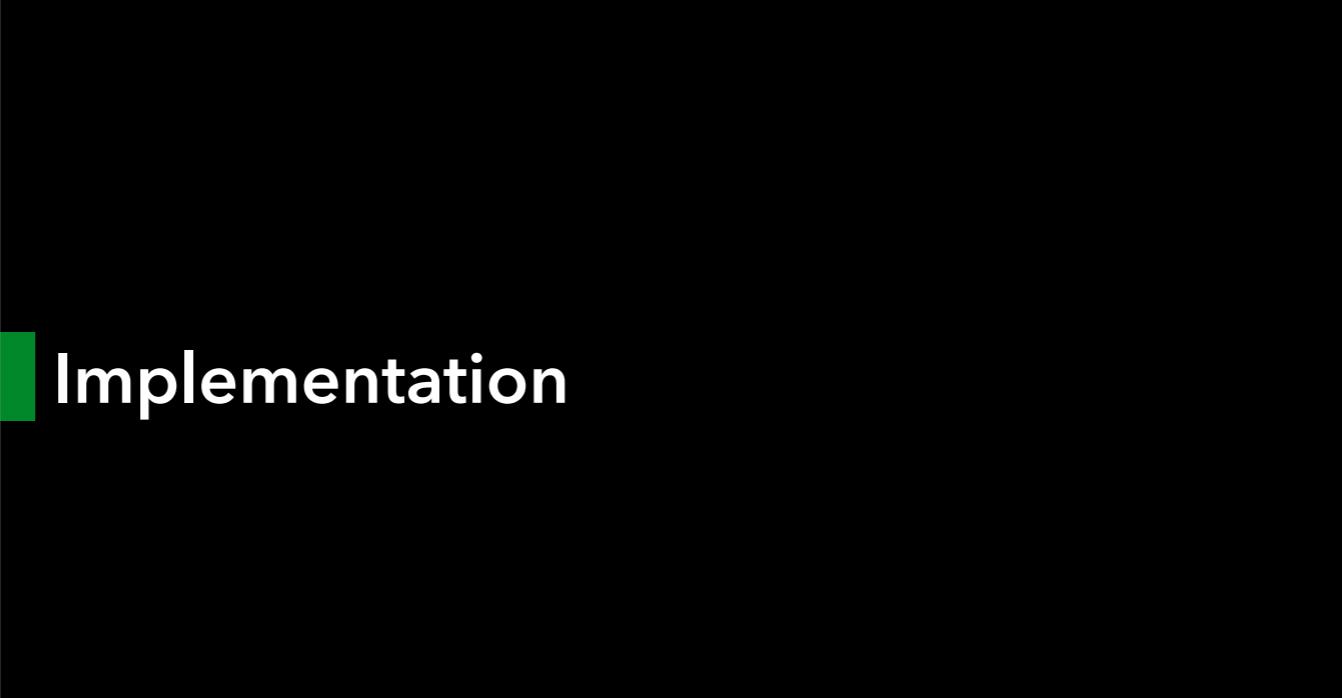
74

constant to the updated majorant to guarantee that we will discover a bounding majorant in finite time. For brevity, we refer you to the paper for our explanation regarding this. The combination of clamping then progressively updating majorants fully summarizes our progressive null-tracking technique.

Next Majorant = $\max\{\text{Density Evals}\} + C$

Majorant
Real Density



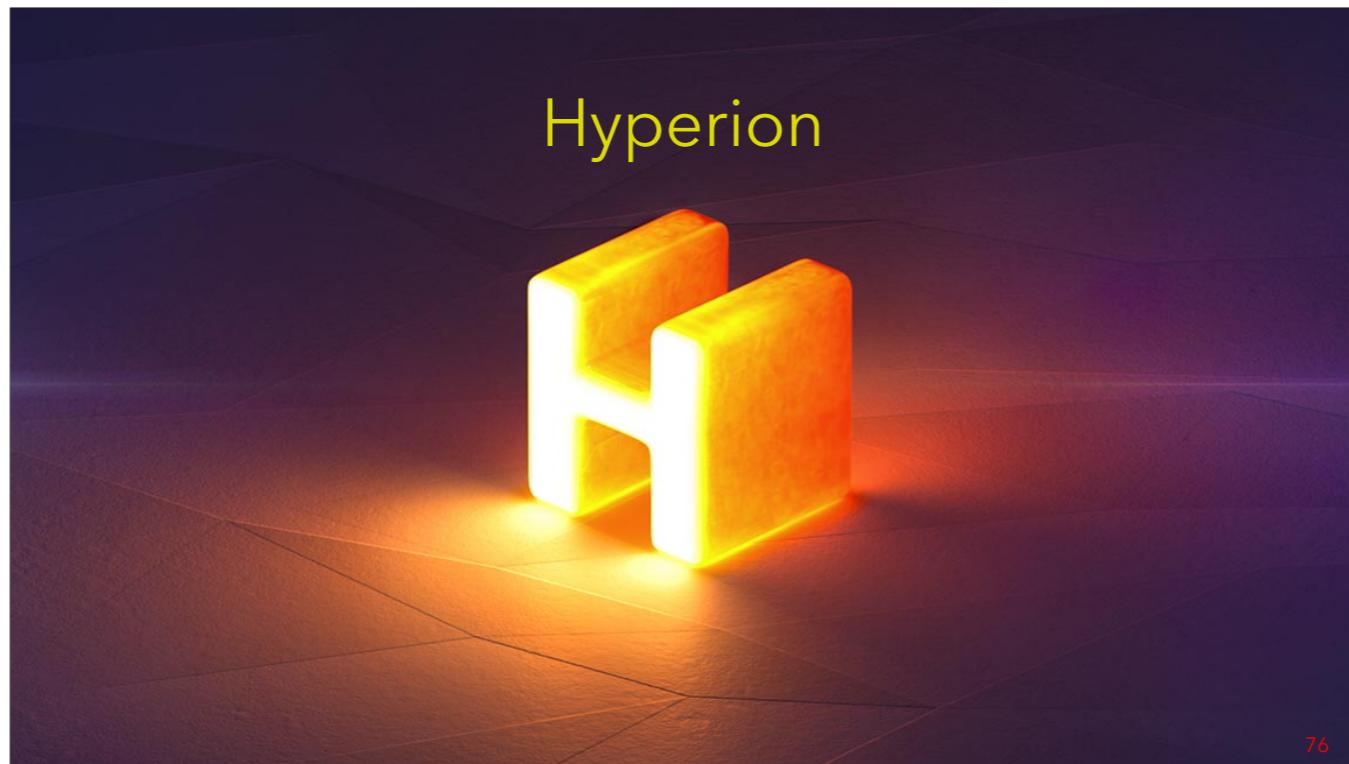


Implementation

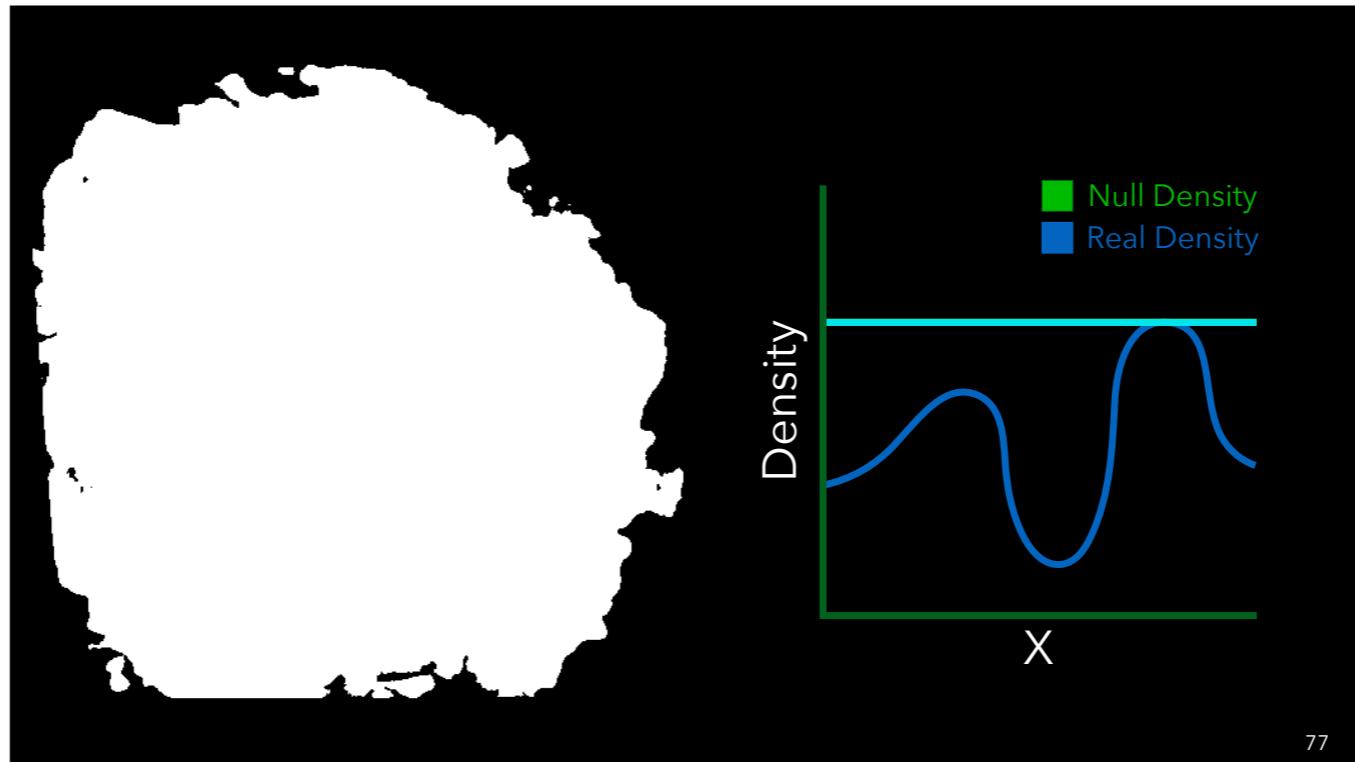


VCL Progressive null-tracking for volumetric rendering

Before we move onto results. We need to mention that while it is our intention to eventually incorporate this technique

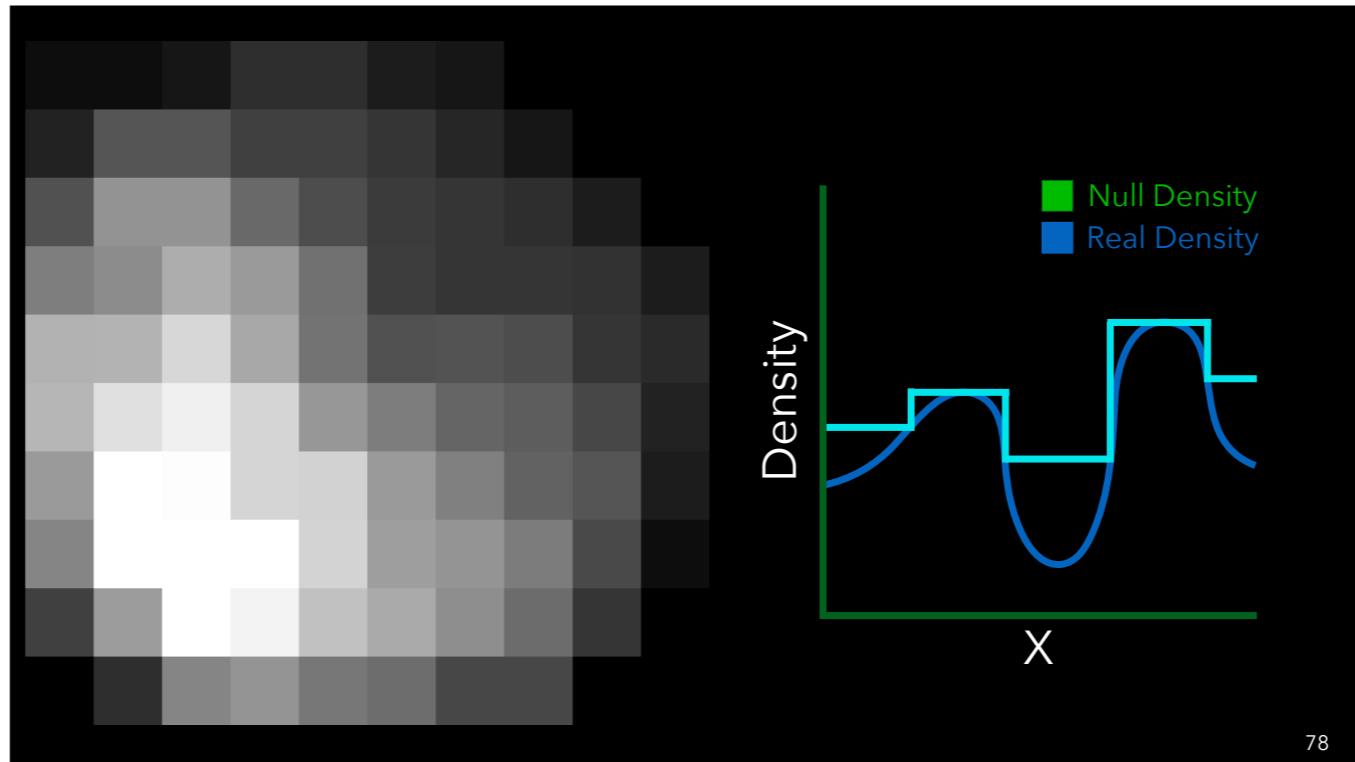


Into Hyperion, most of our implementations and results are from PBRT.



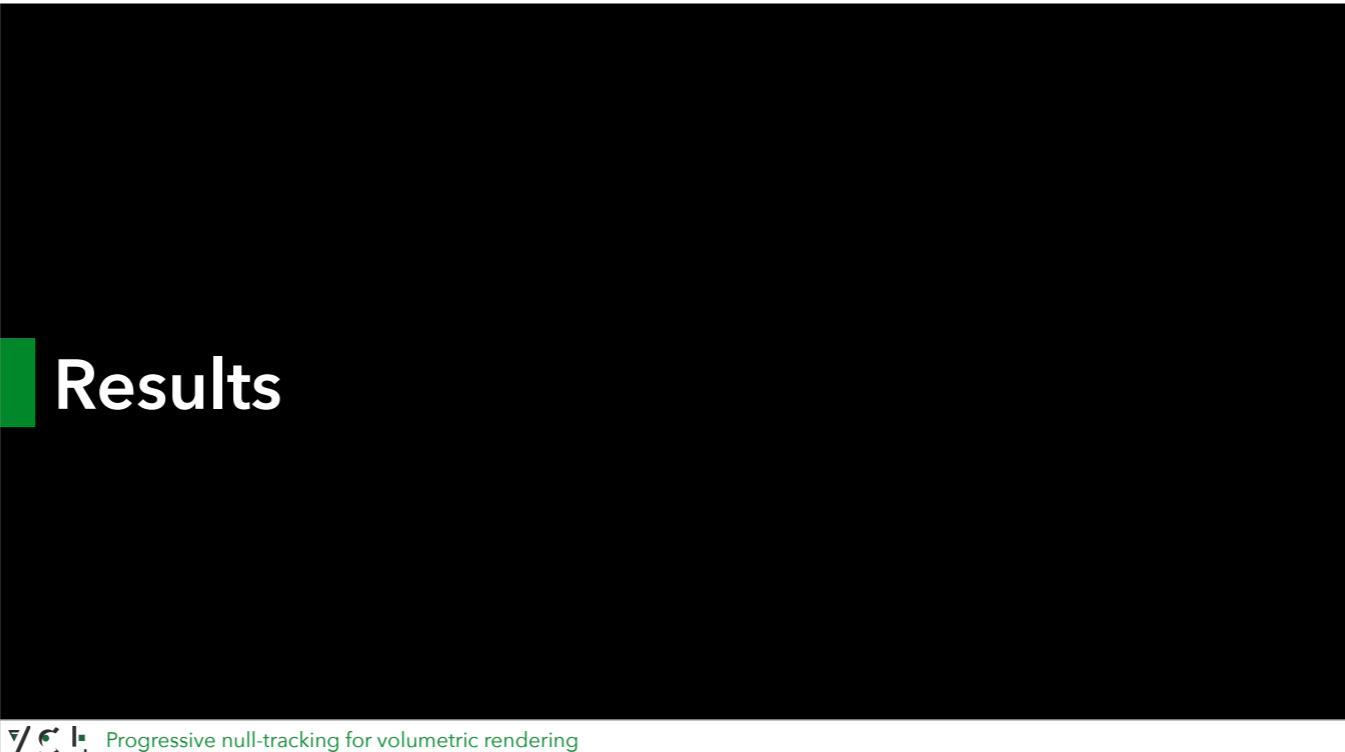
77

Additionally, while we introduced the idea of a majorant as if it were a singular global constant. In practice, we store it



78

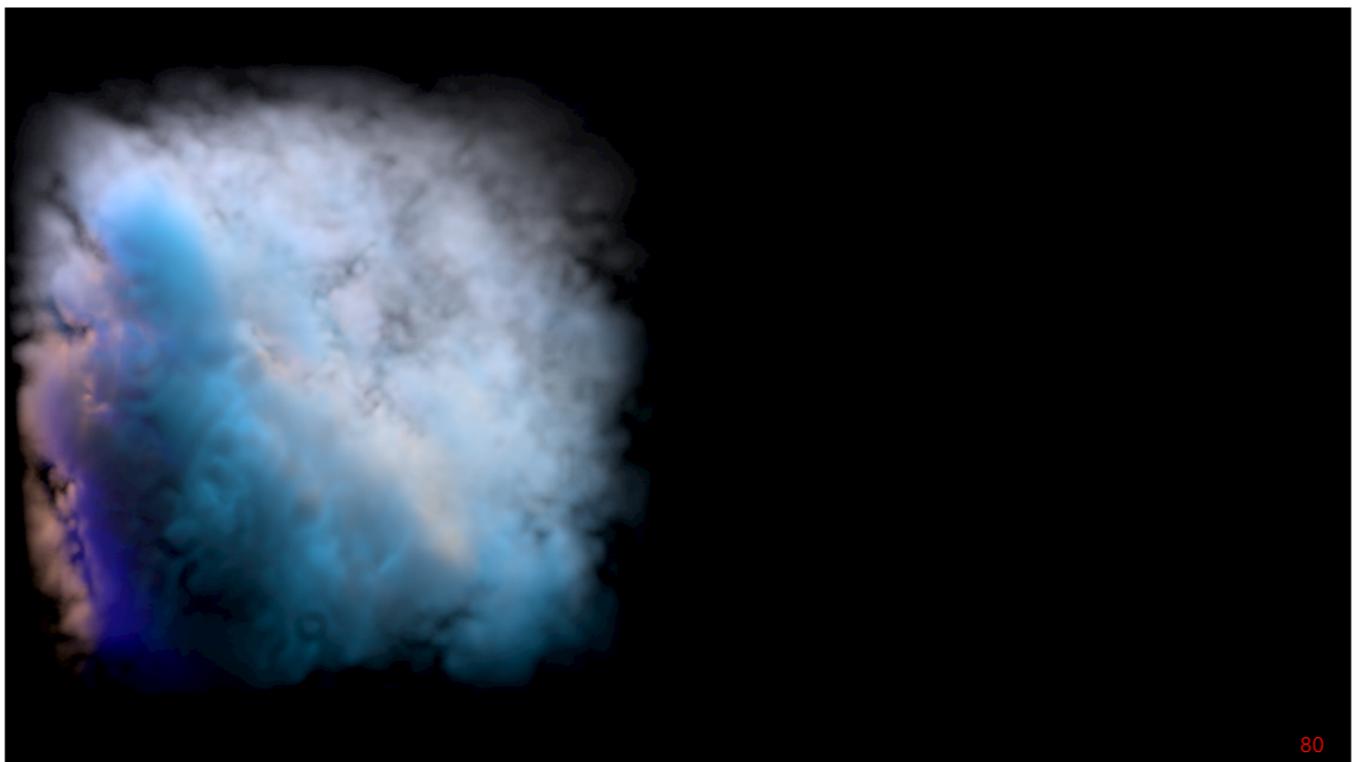
As a piecewise constant function to better locally fit the medium. Thus, we progressively update each majorant individually.



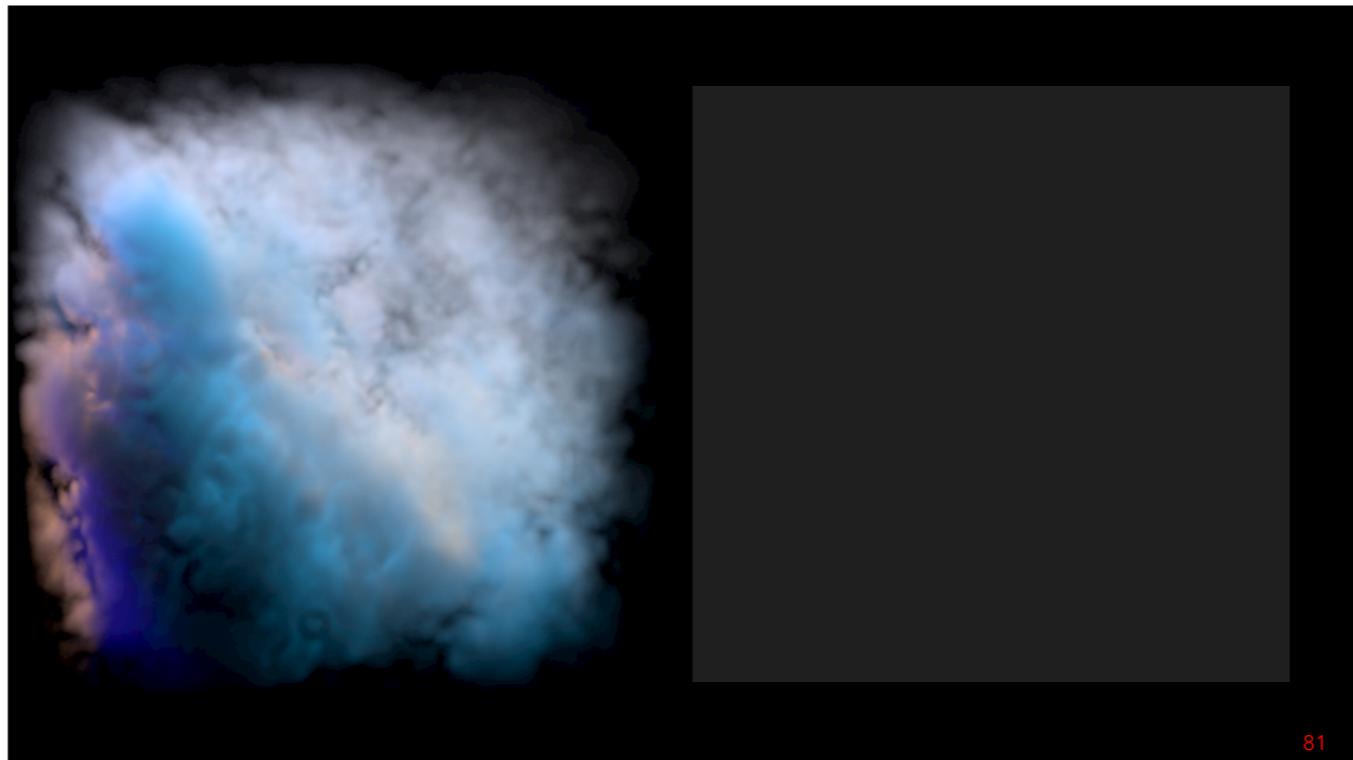
Results

 Progressive null-tracking for volumetric rendering

Now, on to some results.

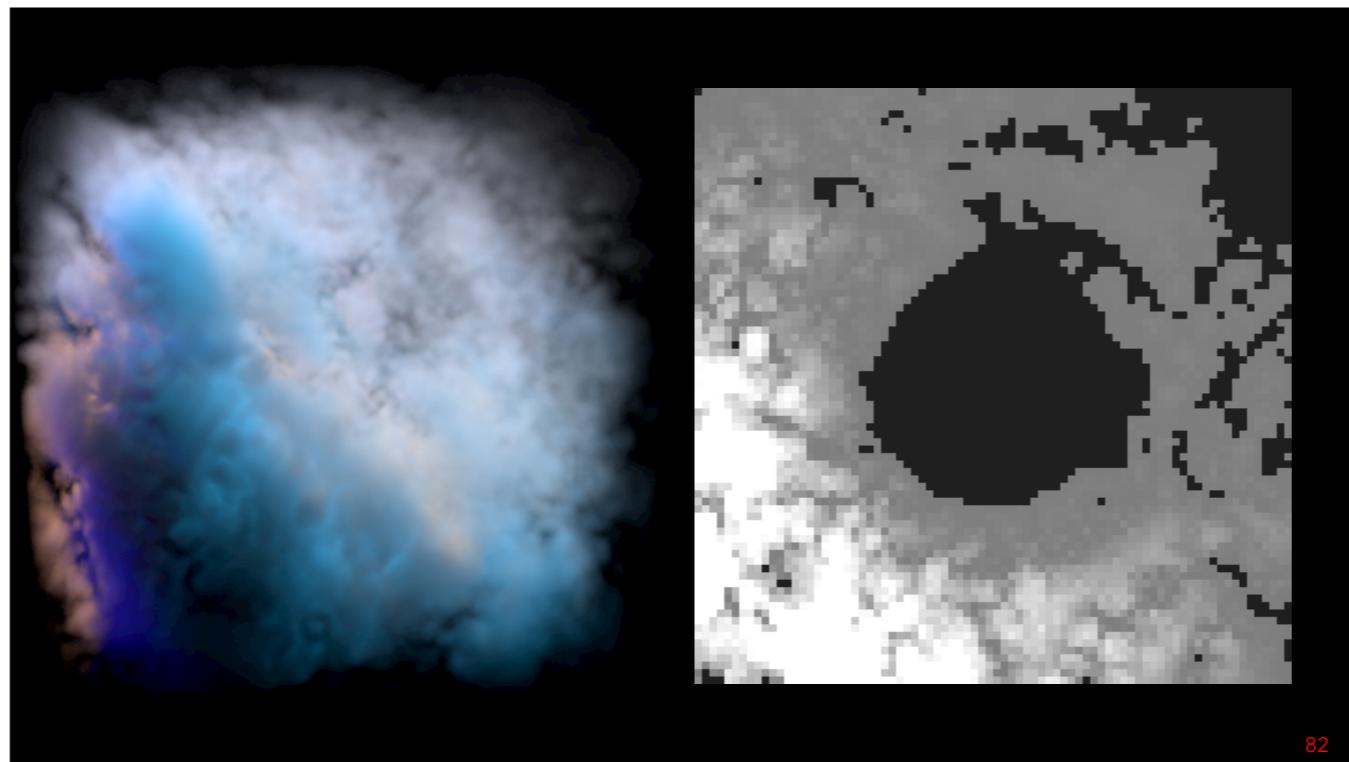


For all results rendered using our technique,



81

We initialize our majorants to be near-zero to convey the robustness of our technique in the worst case scenario. Our progressive method then updates

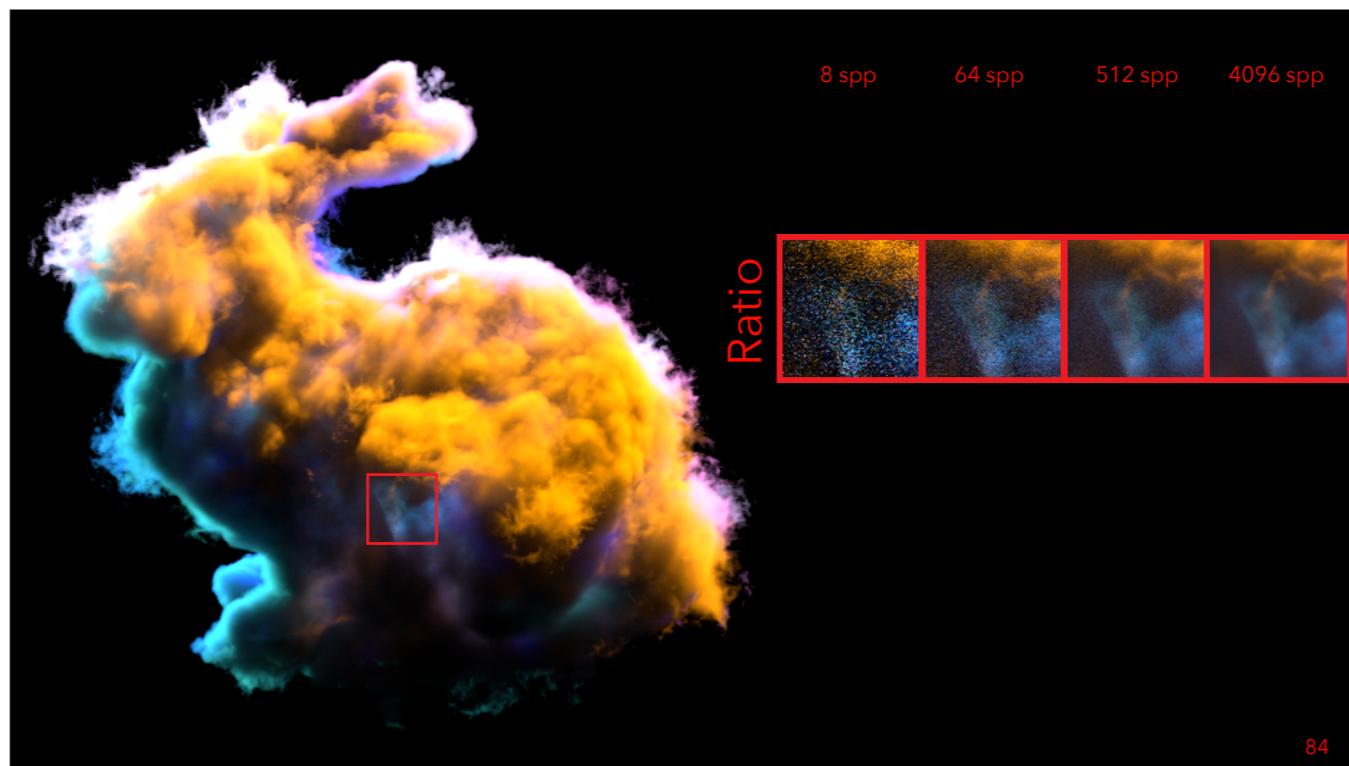


82

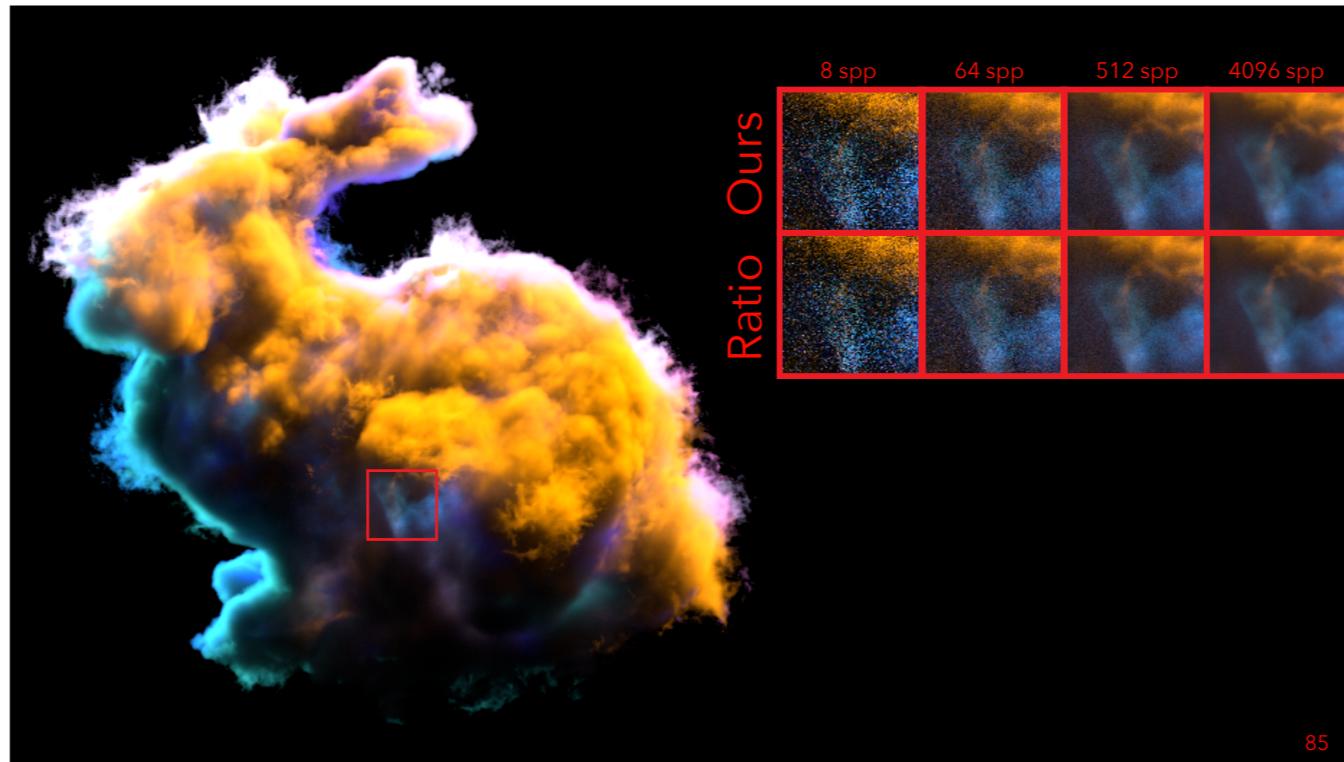
Those majorants over the course of a render.



For this bunny scene, we compare

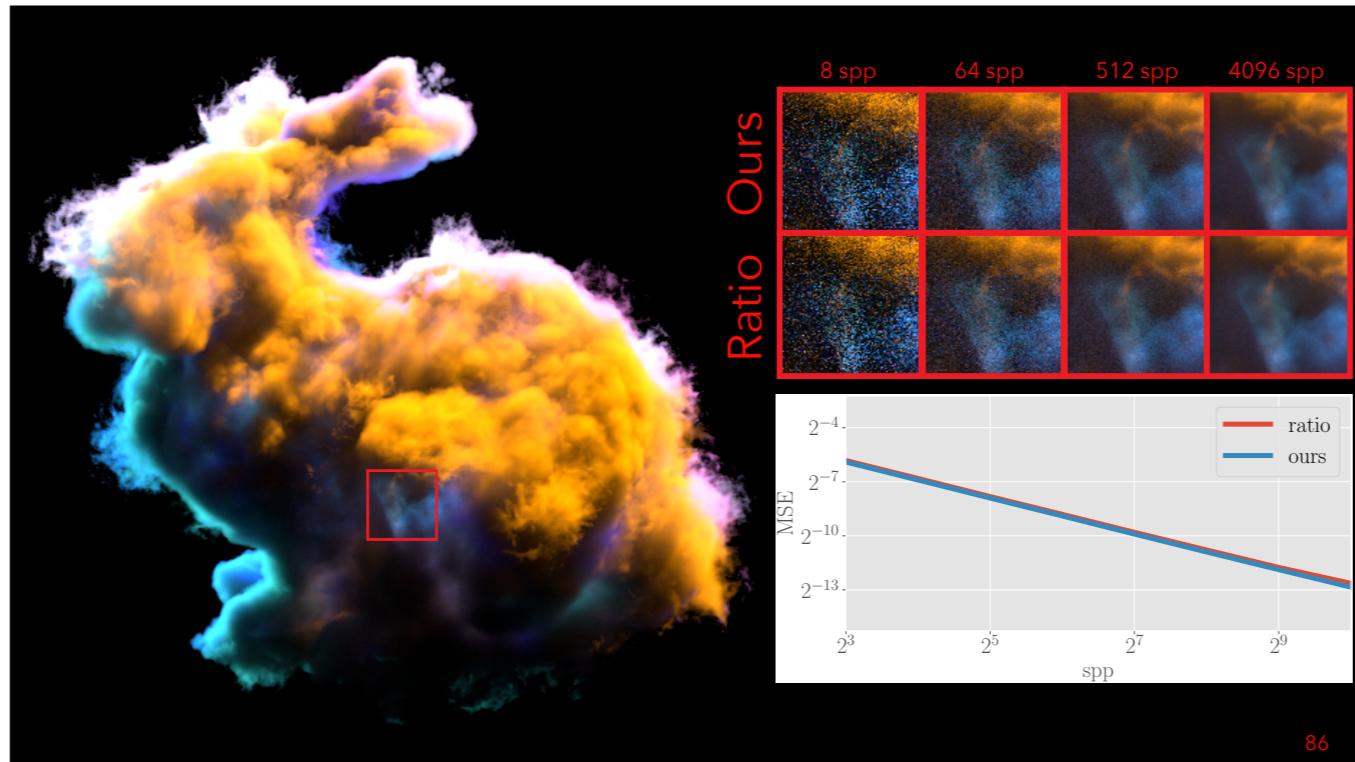


ratio plus weighted delta tracking which are given tightly bounding majorants ahead of time



85

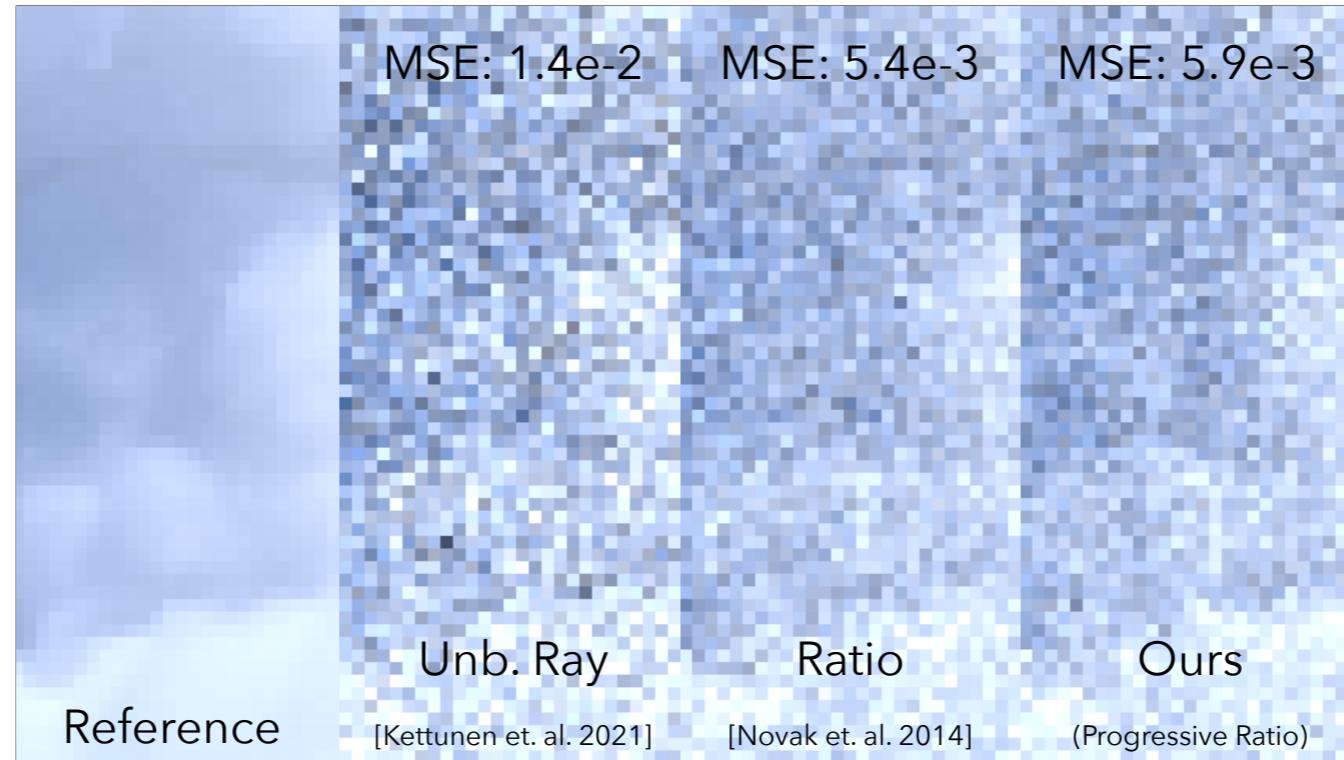
To our technique, which also uses ratio and weighted delta tracking, except with our progressive clamping and updating. For this scene, our discovered majorants converge to become bounding very quickly so the bias seems visually imperceptible.



In terms of error, our technique converges fairly similarly to ratio tracking.



For the Disney cloud scene, which is a lot more dense, we performed



Equal extinction call comparisons between our method and a few state of the art transmittance estimators. In scenes like this where most of the variance comes from sources outside of transmittance estimation, low cost but higher variance estimators like ratio tracking are still preferable which is why we apply our progressive technique to ratio tracking. The point of this comparison is to show that even in these difficult scenes our progressive technique makes current methods resilient to non-bounding extinctions without taking a significant performance hit.

Conclusion

 Progressive null-tracking for volumetric rendering

In conclusion, we have introduced a progressive method for making most null-scattering techniques resilient to non-bounding majorants. Our method imposes no significant performance loss, requires no major modification to any existing null-scattering algorithm, and can be implemented as a simple abstraction layer on top of a renderers medium interface.

In the paper

 Progressive null-tracking for volumetric rendering

90

In the paper

- Full analysis of explosive variance

In the paper

- Full analysis of explosive variance
- Adaptive ratio tracking

In the paper

- Full analysis of explosive variance
- Adaptive ratio tracking
- Proofs and convergence rates

Future work

Future work

- Residual

Future work

- Residual
- Better majorant updating

Future work

- Residual
- Better majorant updating
- Full incorporation into Hyperion



Thank you!