Zackory Erickson

zackory@cmu.edu zackory.com Carnegie Mellon University Robotics Institute 5000 Forbes Avenue Pittsburgh, PA 15213

Current Positions

Assistant Professor, Carnegie Mellon University, Robotics Institute Courtesy appointment: Biomedical Engineering $Sept~2021{\rm-present}$

Education

Ph.D., Robotics 2016–2021

Georgia Institute of Technology Advisor: Charles C. Kemp

M.S., Computer Science 2020

Georgia Institute of Technology Advisor: Charles C. Kemp

B.S., Computer Science, Mathematics (double major)

2012-2016

University of Wisconsin-La Crosse

Honors and Awards

OSCAR Scholar, University of Pittsburgh, Alzheimer's Disease Research Center (ADRC) 2024

Best Paper Award, ACM/IEEE International Conference on Human-Robot Interaction (HRI) 2024 "Independence in the Home: A Wearable Interface for a Person with Quadriplegia to Teleoperate a Mobile Manipulator"

Best Poster Award, CMU Mechanical Engineering Research Symposium

"Extended Kalman Filter for Real-Time State Estimation of Cloth for Robot Manipulation"

NVIDIA Academic Hardware Grant
"Adapting to Distribution Shift in Deformable Manipulation with Assistive Robots"

NVIDIA Fellowship Finalist 2020

Best Student Paper Award, IEEE International Conference on Rehabilitation Robotics (ICORR) 2019 "Multidimensional Capacitive Sensing for Robot-Assisted Dressing and Bathing"

Best Paper Award in Service Robotics Finalist, IEEE ICRA

"Classification of Household Materials via Spectroscopy"

2019

President's Fellowship, Georgia Tech 2016–2020

4th Heidelberg Laureate Forum 2016

Honorable Mention, NSF GRFP 2016

Strzelczyk Award 2016

Awarded to the top graduating senior in the College of Science and Health for academic achievement and service to the campus and community.

MIT CONVERGE 2015

One of 18 prospective PhD students in the nation invited to tour MIT.

Berkeley Engineering Preview Days One of 14 prospective PhD students nationwide invited to tour UC Berkeley.	2015
Grace Olwell Memorial Endowment Fund Scholarship	2015
Xcel Energy Scholarship	2015
John and Lois Storlie Scholarship in Computer Science	2014
Undergraduate Research Grant, UW-La Crosse	2013
Scottish Rite Abbott Scholarship	2013
Dean's List, UW–La Crosse	8 semesters
Mentoring	
PhD Students	
Junxiang (Jim) Wang, CMU, RI	2024-
Zheyuan Hu , CMU, RI (co-advised with Aviral Kumar)	2024-
Hongyi Chen, CMU, RI (co-advised with Jeffrey Ichnowski)	2024-
Kavya Puthuveetil, CMU, RI	2022-
Zulekha Karachiwalla, CMU, RI (co-advised with Henny Admoni)	2022-
Je-Han Yang, CMU, BME (co-advised with Douglas Weber)	2022-
Yufei Wang, CMU, RI (co-advised with David Held)	2021-
Akhil Padmanabha, CMU, RI (co-advised with Carmel Majidi)	2021-
M.S. Students	
Alexis Hao, CMU, RI	2024-
Tiancheng (Tony) Wu, CMU, RI	2024-
Mino Nakura, CMU, RI	2024-
Pratik Bhowal, CMU, RI	2024-
Divyam Goel, CMU, RI	2024-
Xinwen Xu, CMU, MechE	2024-
Aditi Guruprasad, University of Pittsburgh, Bioengineering	2024-
Jing Gao, CMU, RI	2024-
Zoe LaLena, CMU, RI	2024-
Yatharth Ahuja, CMU, RI	2023-2024
Yiran Tao, CMU, RI	2023-
Michaela Tecson, CMU, RI	2023-
Tariq Hussain, CMU, MechE	2023-
Yexin Hu, CMU, CEE	2023-
Abhishek Tandon, CMU, RI Current: Adobe	2023-2024

Anujraaj (Argo) Goyal, CMU, RI Current: Snapchat	2023-2024
Zhanyi Sun, CMU, RI Current: PhD Student at Stanford	2023-2024
MRSD Project: Operating room logistics, CMU, RI Students: Gaurav Sethia, Jinkai Qiu, Roman Kaufman, Tanmay Agarwal, Yungjun Kim Ghodasara	2023– ı, Siddharth
Sankalp Chopkar, CMU, RI	2022-2024
Atharva Kusalkar, CMU, RI	2022-2024
Saurav Kambil, CMU, MechE	2022-2024
Zilin Zhang, CMU, RI	2022-2024
MRSD Project: Auxilio, CMU, RI Students: Shaolin Kataria, Shivam Tripathy, Praveen Venkatesh, Abhinav Gupta, Atharva I	2022–2023 Pusalkar
Fukang Liu, CMU, MechE Current: PhD Student at Georgia Tech	2021-2023
Vaidehi Patil, CMU, RI	2021-2022
MRSD Project: TouRI , CMU, RI Students: Shivani Sivakumar, Jashkumar Diyora, Shruti Gangopadhyay, Prakhar Pradeep, Patel	2021–2022 Jigarkumar
Pratyusha Karnati, Georgia Tech, CS Current: Google X Robotics	2020-2021
Yijun (Esther) Gu, Georgia Tech, CS Current: PhD Student at Imperial College London	2019–2021
$Under graduate\ Students$	
Divya Gupta, CMU, CS	2024-
Vivianna Lieu, CMU, CS	2024-
Annika Srinivasan, UIUC, MechE	2024-
Cindy Sun, CMU, MechE	2024-
Victoria de Leon, Instituto Tecnológico y de Estudios Superiores de Monterrey (ITESM), Ro	botics2024-
Tanisha Mehta, CMU, ECE, CS	2024-
Catherine Li, CMU, CS	2024-
Navin Sriram, Indian Insitute of Technology Madras, CS	2024-
Sreyas Venkataraman, Indian Institute of Technology, Kharagpur, CS	2024-
Ziyu Wang, Tsinghua University, IIIS	2024-
Bharath Hegde, BITS Pilani University, CS	2024-
Zhenghao (Cary) Jin, CMU, ECE	2024-
Glenda Tan, CMU, CS	2024-
Jessica Han, CMU, CS	2024-
Ryan Ding, CMU, CS	2024-

Pranavi Kondapalli, CMU, CS	2024-
Maxwell Soh, CMU, CS	2023-
Ellen Lee, CMU, CS	2023-
Weikang Wan, Peking University, CS	2023-2024
Chen Chen, Tsinghua University, CS	2023-
Janavi Gupta, CMU, CS	2023-
Sumayya Syeda, CMU, CIT	2023-
Preethi Krishnamoorthy, CMU, CS	2023-
Jessie Yuan, CMU, CS	2023-
Madeliene Brutin, CMU, CS	2023-2024
Kendra Givens, Middle Tennessee State University (NSF REU, RISS), CS	2023-2024
Alexandra Gillespie, Colby College (NSF REU, RISS), CS	2023-2024
Yikang (Bruce) Cheng, CMU, CS	2022-2023
Jacob Delgado-López, University of Puerto Rico (NSF REU, RISS), CS	2022
Wesley Lewis, University of Virginia (NSF REU, RISS), CS	2022-2024
Allen Zheng, CMU, CS	2022-2024
Qin (Alicia) Wang, CMU, CS	2022-2023
Daphne Han, CMU, CB	2022
Alexandra (Sasha) Wald, CMU, CS	2021-2024
Kavya Puthuveetil, Virginia Commonwealth University (NSF REU), BME	2021 – 2022
Samantha Mutiti, Georgia Tech, BME	2021
Holden Schaffer, Georgia Tech, CS	2020-2021
Siyan (Sylvia) Li, Georgia Tech, CS	2018-2019
Jiaqi (Julia) Chen, Georgia Tech, CS Current: PhD Student at ETH Zurich	2018
Katelyn Sosnowski, University of Arizona (NSF REU), BME Current: BME PhD Student at University of Arizona	2018
Mallak Taleb, University of Michigan (NSF REU), BME	2018
Bharat Srirangam, Georgia Tech, CS Current: Woot, Inc.	2018–2020
Eliot Xing, Georgia Tech, CE	2017-2022
Vamsee Gangaram, Georgia Tech, CS Current: Microsoft	2017–2020
Jong Hwa (Austin) Jang, Georgia Tech, CS	2017–2018
Maggie Collier, University of Alabama at Birmingham (NSF REU), BME Current: Robotics PhD student at CMU, NDSEG fellow	2017
Nathan Luskey, Georgia Tech, BME Current: MSCS student at CMU	2017-2018

Teaching

16-467: Introduction to Human-Robot Interaction, CMU	Fall	2024
16-762: Mobile Manipulation, CMU	Spring	2024
16-741: Mechanics of Manipulation, CMU	Fall 2022-	2024
16-887: Robotic Caregivers and Intelligent Physical Collaboration, CMU	Spring 2022–	2023
Robotic Caregivers (BMED 4833/8813), Co-instructor, Georgia Tech	Spring	2021
Robotic Caregivers (BMED 4803/8813), Co-developer and instructor, Georgia Tech	Spring	2020
Invited Talks		
Robot Learning and Wearable Interfaces in Pursuit of Robotic Caregivers University of Texas at Austin		2024
Robot Learning, Wearable Sensing, and Teleoperation in Pursuit of Robotic C	-	
16-761: Mobile Robotics, CMU CMU RI Seminar		2024
RISS RoboLaunch		2023 2023
Northeastern University		2023
University of Utah		2023
University of Illinois Urbana-Champaign		2023
My Journey to Professor Robotics Institute Summer Scholars Seminar, CMU		2023
Robotics and Artificial Intelligence in Healthcare and Opportunities for Innov Clinical Impact Symposia, BrightSpring Health Services		2023
Capacitive Servoing and Spectroscopy for Physically Assistive Robotics 16-722: Sensing and Sensors, CMU		2022
Haptic Perspective-taking from Vision and Force CMU RI Seminar		2022
Capacitive Proximity Servoing for Physically Assistive Robotics Close Proximity Human-Robot Collaboration, RSS		2022
Robotic Caregiving and Human Interaction		
24-675: Humanoid Robotics and Cognition, CMU		2022
16-311: Introduction to Robotics, CMU		2022
05-899: Special Topics in HCI: Accessibility, CMU		2021
Capacitive Servoing for Physically Assistive Robotics 4th Workshop on Proximity Perception in Robotics, IROS		2021
$Robotic\ Caregivers-Sensing,\ Simulation,\ and\ Physical\ Human-Robot\ Interaction and\ Physical\ Human-Robot\ Physical\ Human-Robot\ Physical\ $	tion	
Carnegie Mellon University University of Pennsylvania		2021 2021
Physics-based Cloth Simulation and Learning Towards Robotic Caregiving Workshop on Representing and Manipulating Deformable Objects, ICRA		2021
Robotic Caregivers—Recent Advances in Physics-based Simulation Medical Robotics Club, Georgia Tech		2021
Robot-Assisted Dressing Workshop on Smart and Robotic Homes, RESNA		2018

Multimodal Anomaly Detection Mathematics Colloquium, UW–La Crosse	2015
Academic Service	
Area Chair — Robotics: Science and Systems (RSS)	2025
Workshop Organizer — HRI, Enhancing Independence with Physical Caregiving Robots	2025
Workshop Organizer — RSS, Learning for Assistive Robotics	2024
Faculty Senate — CMU, representing the Robotics Institute	2024-
Advisory board — University of Wisconsin–La Crosse, Computer Science Department	2024-
Panelist — HRI, Workshop on HRI for Aging in Place	2024
Workshop Organizer — ICRA, Exploring Role Allocation in Human-Robot Co-Manipulation	2024
Associate Editor — IEEE Robotics and Automation Letters (RA-L) Manipulation and Grasping	2023-
NSF AI-CARING Arena Lead — NSF AI Institute Arena on AI for Interactive Coaches and Services	2023-
Virtual Experience Chair — Conference on Robot Learning (CoRL)	2023
Seminar and Panel Organizer, Life as a Professor, CMU Semesterly seminar where a panel of CMU faculty discuss their perspectives on becoming and professor for graduate students interested in the academic career path	2023— d being a
${\bf Special~Session~Organizer-RO-MAN,~Special~Session~on~Human-Agent/Robot~Interaction~in~care~and~Medicine}$	n Health- 2023
Workshop Organizer — ICRA, Emerging paradigms for assistive robotic manipulation: from labs to the real world	research 2023
PhD Admissions Committee — CMU, Robotics Institute	2022 -
${f Chair}$ — IROS 2022 session on Art and Entertainment and Manipulation	2022
$ extbf{Co-Chair}$ — ICRA 2022 session on Physical HRI	2022
Area Chair — Conference on Robot Learning (CoRL)	022-2023
$ {\bf Workshop\ Organizer-} IROS, 5 th\ Workshop\ on\ Proximity\ Perception\ -\ Towards\ Next-Generation \ Modal\ Sensing\ in\ Soft\ Structures$	on Multi- 2022
Carnegie Mellon University PhD Admissions Committee Co-Chair PhD Admissions Committee Organized Seminar Series, Life as a Professor	2024– 2023– 2023–
Associate Editor IEEE Conference on Robot and Human Interactive Communication (RO-MAN)	021, 2022
Reviewer T-RO, ICRA, IROS, RA-L, CoRL, Humanoids, HRI, Sensors, RO-MAN, Science Robotics, RSS	Pioneers
Workshop Organizer — ICRA, Learning for Caregiving Robots	2021
Seminar Organizer, Georgia Tech Life as a Professor: Student Advising and Recruiting Life as a Professor: Funding 101	2020 2019

Life as a Professor: Starting a Start-Up	2018
Panelist Graduate Intro to Robotics Research, Georgia Tech	2018
Summer Undergraduate Research Experience (SURE) Program, Georgia Tech	2017–2019
RoboGrads (robotics graduate student organization), Georgia Tech Vice President for Robotics PhD President	2019–2020 2018–2019
Student Thesis Committees	
Caleb Escobedo, CU Boulder, PhD	2024 -
Christian Berger, CMU, MSR	2024
Christopher Chang, CMU, MSR Zhiyang (Jerry) He, UC Berkeley, PhD	2024 $2023-$
Student Quelifying Every Committees	
Student Qualifying Exam Committees Maggie Collier, CMU, PhD	2024
Ruixuan Liu, CMU, PhD	2023
Outreach	
AI Scholars, Co-organizer, CMU Each summer, AIS provides 30+ rising high school seniors who have historically be STEM fields the opportunity to explore artificial intelligence through 4 weeks of cour projects with Carnegie Mellon faculty, staff, and researchers.	
AI4ALL, Co-organizer, CMU	2022
RoboGrads, Vice President of Outreach, Georgia Tech Organized K-12 outreach events for over 30 robotics labs at Georgia Tech	2017–2018
Biomedical Robotics Club, Mentor, Georgia Tech Mentoring over 50 undergraduate students in how to research and build assistive devices and robots for people with impairments.	2016–2019
Mentoring over 50 undergraduate students in how to research and build assistive	2016–2019 2015–2021
Mentoring over 50 undergraduate students in how to research and build assistive devices and robots for people with impairments.	

Peer-Reviewed Publications (Conferences and Journals)

[1] High-density Electromyography for Effective Gesture-based Control of Physically Assistive Mobile Manipulators

 $npj\ Robotics,\ 2025$

Jehan Yang, Kent Shibata, Douglas Weber, Zackory Erickson

[2] LAMS: LLM-Driven Automatic Mode Switching for Assistive Teleoperation

 $ACM/IEEE\ International\ Conference\ on\ Human-Robot\ Interaction\ (HRI),\ 2025$

Yiran Tao*, Jehan Yang*, Dan Ding, Zackory Erickson

[3] EMGBench: Benchmarking Out-of-Distribution Generalization and Adaptation for Electromyography

Advances in neural information processing systems (NeurIPS), 2024 Jehan Yang, Maxwell Soh, Vivianna Lieu, Douglas J Weber, Zackory Erickson

- [4] VoicePilot: Harnessing LLMs as Speech Interfaces for Physically Assistive Robots ACM Symposium on User Interface Software and Technology (UIST), 2024
 Akhil Padmanabha*, Jessie Yuan*, Janavi Gupta, Zulekha Karachiwalla, Carmel Majidi, Henny Admoni, Zackory Erickson
- [5] DiffTORI: Differentiable Trajectory Optimization for Deep Reinforcement and Imitation Learning

Advances in neural information processing systems (NeurIPS), 2024 (Spotlight Presentation) Weikang Wan*, Ziyu Wang*, Yufei Wang*, Zackory Erickson, David Held

[6] RoboGen: Towards Unleashing Infinite Data for Automated Robot Learning via Generative Simulation

International Conference on Mahince Learning (ICML), 2024 Yufei Wang*, Zhou Xian*, Feng Chen*, Tsun-Hsuan Wang, Yian Wang, Katerina Fragkiadaki, Zackory Erickson, David Held, Chuang Gan

- [7] RL-VLM-F: Reinforcement Learning from Vision Language Foundation Model Feedback International Conference on Mahince Learning (ICML), 2024 Yufei Wang*, Zhanyi Sun*, Jesse Zhang, Zhou Xian, Erdem Bıyık, David Held†, Zackory Erickson†
- [8] Do Mistakes Matter? Comparing Trust Responses of Different Age Groups to Errors Made by Physically Assistive Robots IEEE International Conference on Robot and Human Interactive Communication (ROMAN), 2024 Sasha Wald*, Kavya Puthuveetil*, Zackory Erickson
- [9] Unfolding the literature: A review of robotic cloth manipulation Annual Review of Control, Robotics, and Autonomous Systems, 2024 Alberta Longhini, Yufei Wang, Irene Garcia-Camacho, David Blanco-Mulero, Marco Moletta, Michael Welle, Guillem Alenyà, Hang Yin, Zackory Erickson, David Held, Júlia Borràs, Danica Kragic
- [10] AdaFold: Adapting Folding Trajectories of Cloths via Feedback-Loop Manipulation IEEE Robotics and Automation Letters (RA-L), 2024 Alberta Longhini, Michael C. Welle, Zackory Erickson, Danica Kragic
- [11] BodyMAP-Jointly Predicting Body Mesh and 3D Applied Pressure Map for People in Bed IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2024 Abhishek Tandon*, Anujraaj Goyal*, Henry M Clever, Zackory Erickson
- [12] Force Constrained Visual Policy: Safe Robot-Assisted Dressing via Multi-Modal Sensing IEEE Robotics and Automation Letter (RA-L), 2024 Zhanyi Sun*, Yufei Wang*, David Held†, Zackory Erickson†
- [13] Independence in the Home: A Wearable Interface for a Person with Quadriplegia to Teleoperate a Mobile Manipulator

ACM/IEEE International Conference on Human Robot Interaction (HRI), 2024 (Best Paper Award) Akhil Padmanabha, Janavi Gupta, Chen Chen, Jehan Yang, Vy Nguyen, Douglas J Weber, Carmel Majidi, Zackory Erickson

- [14] Quantifying Assistive Robustness Via the Natural-Adversarial Frontier Conference on Robot Learning (CoRL), 2023 Jerry Zhi-Yang He, Daniel S Brown, Zackory Erickson, Anca Dragan
- [15] A Multimodal Sensing Ring for Quantification of Scratch Intensity Nature Communications Medicine, 2023 Akhil Padmanabha, Sonal Choudhary, Carmel Majidi, Zackory Erickson

[16] Robust Body Exposure (RoBE): A Graph-based Dynamics Modeling Approach to Manipulating Blankets over People

IEEE Robotics and Automation Letters (RA-L), 2023

Kavya Puthuveetil, Sasha Wald, Atharva Pusalkar, Pratyusha Karnati, and Zackory Erickson

[17] One Policy to Dress Them All: Learning to Dress People with Diverse Poses and Garments Robotics Science and Systems (RSS), 2023

Yufei Wang, Zhanyi Sun, Zackory Erickson*, David Held*

[18] HAT: Head-Worn Assistive Teleoperation of Mobile Manipulators

IEEE International Conference on Robotics and Automation (ICRA), 2023

Akhil Padmanabha*, Qin Wang*, Daphne Han, Jashkumar Diyora, Kriti Kacker, Hamza Khalid, Liang-Jung Chen, Carmel Majidi, Zackory Erickson

[19] SLURP! Spectroscopy of Liquids Using Robot Pre-Touch Sensing

IEEE International Conference on Robotics and Automation (ICRA), 2023

Nathaniel Hanson*, Wesley Lewis*, Kavya Puthuveetil, Donelle Furline Jr, Akhil Padmanabha, Taskin Padir, Zackory Erickson

[20] EDO-Net: Learning Elastic Properties of Deformable Objects from Graph Dynamics

IEEE International Conference on Robotics and Automation (ICRA), 2023

Alberta Longhini*, Marco Moletta*, Alfredo Reichlin, Michael C. Welle, David Held, Zackory Erickson, Danica Kragic

[21] Elastic Context: Encoding Elasticity for Data-driven Models of Textiles

IEEE International Conference on Robotics and Automation (ICRA), 2023

Alberta Longhini, Marco Moletta, Alfredo Reichlin, Michael C. Welle, Alexander Kravberg, Yufei Wang, David Held, Zackory Erickson, Danica Kragic

[22] A Study of Causal Confusion in Preference-Based Reward Learning

International Conference on Learning Representations (ICLR), 2023

Jeremy Tien, Jerry Zhi-Yang He, Zackory Erickson, Anca D. Dragan, Daniel S. Brown

[23] ToolFlowNet: Robotic Manipulation with Tools via Predicting Tool Flow from Point Clouds Conference on Robot Learning (CoRL), 2022

Daniel Seita, Yufei Wang, Edward Yao Li, Sarthak J Shetty, Zackory Erickson, and David Held

[24] Learning Representations that Enable Generalization in Assistive Tasks

Conference on Robot Learning (CoRL), 2022

Jerry Zhi-Yang He, Zackory Erickson, Daniel S. Brown, Aditi Raghunathan, and Anca Dragan

[25] Characterization of a Meso-Scale Wearable Robot for Bathing Assistance

IEEE International Conference on Robotics and Biomimetics (ROBIO), 2022

Fukang Liu, Vaidehi Patil, Zackory Erickson, and Zeynep Temel

[26] Visual Haptic Reasoning: Estimating Contact Forces by Observing Deformable Object Interactions

IEEE Robotics and Automation Letters (RA-L), 2022

Yufei Wang, David Held, and Zackory Erickson

[27] CapSense: A Real-Time Capacitive Sensor Simulation Framework for Physical Human-Robot Interaction

IEEE Robotics and Automation Letters (RA-L), 2022

Christian Schöffmann, Zackory Erickson, and Hubert Zangl

[28] Bodies Uncovered: Learning to Manipulate Real Blankets Around People via Physics Simulations

IEEE Robotics and Automation Letters (RA-L), 2022

Kavya Puthuveetil, Charles C. Kemp, and Zackory Erickson

[29] Characterizing Multidimensional Capacitive Servoing for Physical Human-Robot Interaction

IEEE Transactions on Robotics (T-RO), 2022

Zackory Erickson, Henry M. Clever, Vamsee Gangaram, Eliot Xing, Greg Turk, C. Karen Liu, and Charles C. Kemp

- [30] Assistive VR Gym: Interactions with Real People to Improve Virtual Assistive Robots IEEE Conference on Robot and Human Interactive Communication (RO-MAN), 2020 Zackory Erickson*, Yijun Gu*, and Charles C. Kemp
- [31] Multimodal Material Classification for Robots using Spectroscopy and High Resolution Texture Imaging

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2020 Zackory Erickson, Eliot Xing, Bharat Srirangam, Sonia Chernova, and Charles C. Kemp

[32] Bodies at Rest: 3D Human Pose and Shape Estimation from a Pressure Image using Synthetic Data

IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2020 (Oral) Henry M. Clever, Zackory Erickson, Ariel Kapusta, Greg Turk, C. Karen Liu, and Charles C. Kemp

- [33] Assistive Gym: A Physics Simulation Framework for Assistive Robotics *IEEE International Conference on Robotics and Automation (ICRA)*, 2020 Zackory Erickson, Vamsee Gangaram, Ariel Kapusta, C. Karen Liu, and Charles C. Kemp
- [34] Learning to Collaborate from Simulation for Robot-Assisted Dressing IEEE Robotics and Automation Letters (RA-L), 2020 Alexander Clegg, Zackory Erickson, Patrick Grady, Greg Turk, Charles C. Kemp, and C. Karen Liu
- [35] Active Robot-Assisted Feeding with a General-Purpose Mobile Manipulator: Design, Evaluation, and Lessons Learned
 Robotics and Autonomous Systems, 2020

Daehyung Park, Yuuna Hoshi, Harshal P. Mahajan, Ho Keun Kim, Zackory Erickson, Wendy A. Rogers, Charles C. Kemp

- [36] Multidimensional Capacitive Sensing for Robot-Assisted Dressing and Bathing IEEE International Conference on Rehabilitation Robotics (ICORR), 2019 (Best Student Paper) Zackory Erickson, Henry M. Clever, Vamsee Gangaram, Greg Turk, C. Karen Liu, and Charles C. Kemp
- [37] Classification of Household Materials via Spectroscopy IEEE Robotics and Automation Letters (RA-L), 2019 (Best Paper Award in Service Robotics Finalist at ICRA 2019) Zackory Erickson, Nathan Luskey, Sonia Chernova, and Charles C. Kemp
- [38] Personalized Collaborative Plans for Robot-Assisted Dressing via Optimization and Simulation

Autonomous Robots, 2019

Ariel Kapusta, Zackory Erickson, Henry M. Clever, Wenhao Yu, C. Karen Liu, Greg Turk, and Charles C. Kemp

- [39] Autonomous Tool Construction Using Part Shape and Attachment Prediction Robotics: Science and Systems (RSS), 2019 Lakshmi Nair, Nithin Srikanth, Zackory Erickson, Sonia Chernova
- [40] Deep Haptic Model Predictive Control for Robot-Assisted Dressing IEEE International Conference on Robotics and Automation (ICRA), 2018 Zackory Erickson, Henry M. Clever, Greg Turk, C. Karen Liu, and Charles C. Kemp
- [41] Tracking Human Pose During Robot-Assisted Dressing using Single-Axis Capacitive Proximity Sensing

IEEE Robotics and Automation Letters (RA-L), 2018 Zackory Erickson, Maggie Collier, Ariel Kapusta, and Charles C. Kemp

[42] 3D Human Pose Estimation on a Configurable Bed from a Pressure Image IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2018 Henry M. Clever, Ariel Kapusta, Daehyung Park, Zackory Erickson, Yash Chitalia, Charles C. Kemp

[43] Semi-Supervised Haptic Material Recognition for Robots using Generative Adversarial Networks

Conference on Robot Learning (CoRL), 2017 Zackory Erickson, Sonia Chernova, and Charles C. Kemp

[44] What Does the Person Feel? Learning to Infer Applied Forces During Robot-Assisted Dressing

IEEE International Conference on Robotics and Automation (ICRA), 2017 Zackory Erickson, Alexander Clegg, Wenhao Yu, Greg Turk, C. Karen Liu, and Charles C. Kemp

[45] Learning to Navigate Cloth using Haptics IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2017 Alexander Clegg, Wenhao Yu, Zackory Erickson, C. Karen Liu, and Greg Turk

- [46] A Multimodal Execution Monitor with Anomaly Classification for Robot-Assisted Feeding IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2017 Daehyung Park, Hokeun Kim, Yuuna Hoshi, Zackory Erickson, Ariel Kapusta, and Charles C. Kemp
- [47] Multimodal Execution Monitoring for Anomaly Detection During Robot Manipulation IEEE International Conference on Robotics and Automation (ICRA), 2016

 Daehyung Park, Zackory Erickson, Tapomayukh Bhattacharjee, and Charles C. Kemp

Workshop Papers

[1] Towards an LLM-Based Speech Interface for Robot-Assisted Feeding UIST 2024 demo track: Symposium on User Interface Software and Technology, 2024 Jessie Yuan, Janavi Gupta, Akhil Padmanabha, Zulekha Karachiwalla, Carmel Majidi, Henny Admoni, Zackory Erickson

[2] Towards the Development of Wound Care Robots: An Observational Study Outlining Robotic Design Needs for Wound Care

HRI 2024: Workshop on HRI for Aging in Place, 2024 Zulekha Karachiwalla, Ellen Lee, Andrew Dierkes, Zackory Erickson, Henny Admoni

[3] Elastic Context: Encoding Elasticity for Data-driven Models of Textiles ICRA 2023: Embracing contacts. Making robots physically interact with our world, 2023 Alberta Longhini, Marco Moletta, Alfredo Reichlin, Michael C. Welle, Alexander Kravberg, Yufei Wang, David Held, Zackory Erickson, Danica Kragic

[4] HAT: Head-Worn Assistive Teleoperation of Mobile Manipulators

ICRA 2023: Emerging paradigms for assistive robotic manipulation: from research labs to the real world, 2023

Akhil Padmanabha*, Qin Wang*, Daphne Han, Jashkumar Diyora, Kriti Kacker, Hamza Khalid, Liang-Jung Chen, Carmel Majidi, Zackory Erickson

[5] A Study of Causal Confusion in Preference-Based Reward Learning ICML 2022: Workshop on Spurious Correlations, Invariance and Stability, 2022

Jeremy Tien, Jerry Zhi-Yang He, Zackory Erickson, Anca Dragan, Daniel S. Brown