

Unit symbols: a f p n μ m c d
 $10^{\wedge} : -18 -15 -12 -9 -6 -3 -2 -1$ K M G T P E
 $3 \quad 6 \quad 9 \quad 12 \quad 15 \quad 18$

Series RLC

Examination Aid Sheet

Faculty of Applied Science & Engineering

Both sides of the sheet may be used;

must be printed on 8.5" x 11" paper. $P = I^2 R = \frac{V^2}{R} = IV$

Ckt Pwr: (+) current enters

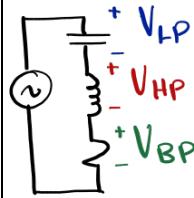
(+) terminal: pwr dissipated, > 0

(-) terminal: pwr supplied, < 0

Subject: ECE212 : Circuit Analysis

Candidate's name: _____

Candidate's signature: _____



BP: HP ↔ LP

BS: HP // LP

Voltage Divider: U_s $U_k = U_s \cdot \frac{R_k}{\sum_{j=1}^n R_j}$

Current Divider: I_s $I_k = I_s \cdot \frac{1}{\frac{R_k}{\sum_{j=1}^n \frac{1}{R_j}}}$

Nodal Analysis: Use KCL to find Voltage at Nodes, $N - 1 - N_V = \# \text{ equ.}$

Mesh Analysis: Use KVL to find Current through Loops, $B - N + 1 - N_I = \# \text{ equ.}$

Source Transformation: U_s $\leftrightarrow I_s$ $U_s = I_s R_p$ $R_p = R_s$

Thevenin and Norton Ckts: \leftrightarrow $V_{th} = I_N R_N$
 $R_{th} = \frac{V_{th}}{I_{sc}} = R_N$

Shortcut (only indep. srcs): deactivate all ssrcs,
 R_{th} = equivalent resistance from terminal of interest

Condition for Max Power ($R_L = R_{th}$): $P_{max} = \frac{V_{th}^2}{4R_{th}} = \frac{V_{th}^2}{4R_L}$

First Order Transient ODE: $\Sigma \frac{dx(t)}{dt} + x(t) = x(\infty)$ Solution: $x(\infty) \xrightarrow{x(0^+)} K_1 + K_2 e^{-t/\tau} x(0^+) - x(\infty)$

$x(t) = x(\infty) + [x(t_0^+) - x(\infty)] e^{-\frac{(t-t_0)}{\tau}}$ capacitors: $\tau = R_{th} C_0$ and $V_d(t_0^-) = V_d(t_0^+)$
 inductors: $\tau = \frac{L_0}{R_{th}}$ and $i_L(t_0^-) = i_L(t_0^+)$

Second Order Transient complete solution: $x(t) = x_{natural}(t) + x_{forced}(t) = x_n(t) + x(\infty)$

Series RLC: $i'' + \frac{R}{L} i' + \frac{1}{LC} i = 0$ $s^2 + 2\zeta\omega_0 s + \omega_0^2 = 0$
 Parallel RLC: $V'' + \frac{1}{RC} V' + \frac{1}{LC} V = 0$ $\zeta = \frac{R}{2\sqrt{LC}}$ $\omega_0 = \frac{1}{\sqrt{LC}}$ $\zeta < 1$: underdamped
 $\zeta = 1$: critically damped
 $\zeta > 1$: overdamped

AC Ckt Analysis $x(t) = A \cos(\omega t + \phi) \Rightarrow \bar{x} = A e^{j\phi} = A L \phi = A (\cos \phi + j \sin \phi)$

1. must have same frequency
 2. all cos or all sin
 3. peak amplitude same sign
 4. difference $< 180^\circ$ or π rad
 add 2π or 360°
- $\sin(\omega t + \phi) = \cos(\omega t + \phi - \frac{\pi}{2})$ $Z_R = R$, V and I in phase
 $\cos(\omega t + \phi) = \sin(\omega t + \phi + \frac{\pi}{2})$ $Z_L = j\omega L$, V leads I by 90°
 $-\sin(\omega t + \phi) = \sin(\omega t + \phi - \pi)$ $Z_C = \frac{1}{j\omega C}$, I leads V by 90°
 $-\cos(\omega t + \phi) = \cos(\omega t + \phi + \pi)$

Resistors $V_R = I_R R$

Series: $R_T = R_1 + R_2 + R_3$
 Parallel: $\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}$

Capacitor $i_C = C V_C'$

Series: $\frac{1}{C_T} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3}$
 Parallel: $C_T = C_1 + C_2 + C_3$

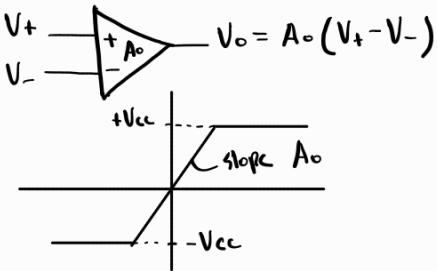
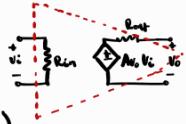
Inductors $V_L = L i_L'$

Series: $L_T = L_1 + L_2 + L_3$
 Parallel: $\frac{1}{L_T} = \frac{1}{L_1} + \frac{1}{L_2} + \frac{1}{L_3}$

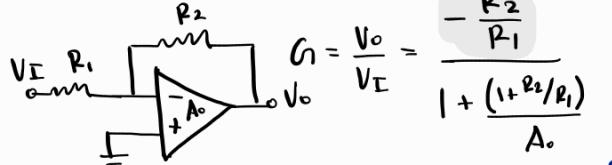
OpAmps

Ideal:

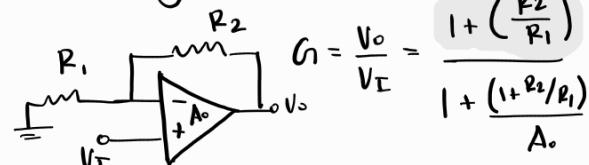
- $i_+ = i_- = 0$ (opamp)
- $V_- = V_+$ (negative feedback)



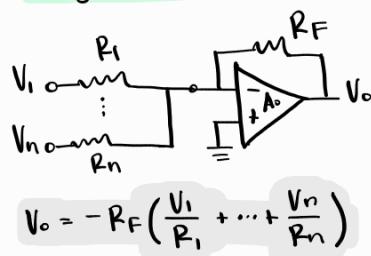
Inverting Config:



Non-inverting Config:

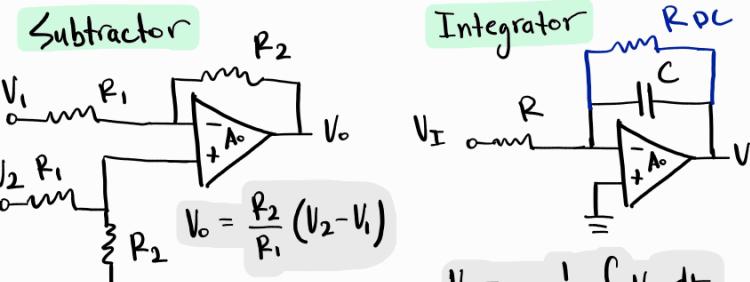
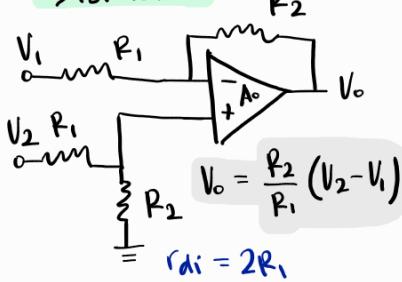


Weighted Sum Amplifier



$$V_o = -R_F \left(\frac{V_1}{R_1} + \dots + \frac{V_n}{R_n} \right)$$

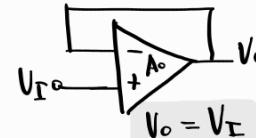
Subtractor



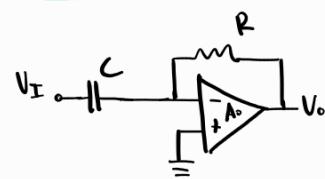
Integrator

$$V_o = -\frac{1}{RC} \int V_I dt$$

Unity Gain Buffer



Differentiator



$$V_o = -RC \frac{d}{dt} V_I$$

Inductors/Transformers

$$L = \frac{N \Phi}{i} = \frac{\mu_0 N^2 A}{l}$$

$$\Phi = B \cdot A = \mu_0 \frac{M}{l} i A$$

$$M \leq \sqrt{L_1 L_2} \quad k = \frac{M}{\sqrt{L_1 L_2}}$$

Turns Ratio: $n = \frac{N_2}{N_1}$

Voltage Ratio: $\frac{V_2(t)}{V_1(t)} = \pm \frac{N_2}{N_1} = \pm n$ additive

Current Ratio: $\frac{i_2(t)}{i_1(t)} = \mp \frac{1}{n}$ subtractive

Dot Convention: additive if both currents entering/leaving dots, subtractive otherwise

Reflected Impedance:

$$Z_{in} = \frac{Z_L}{n^2}$$

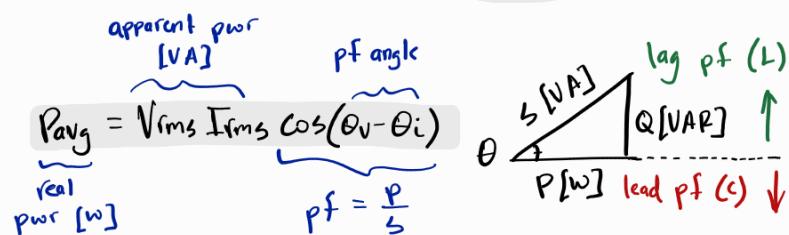
$$Z_L = n^2 Z_S$$

Power $P_{avg} = RI_{rms}^2 = V_{rms}^2 / R$, Thvenin Max Pwr if $Z_L = Z_{TH}$, $P_m = [V_{TH rms}]^2 / 4R_{TH}$ $V_{PK} = \sqrt{2} V_{rms}$

$$\mathcal{S} \triangleq \bar{V}_{rms} \bar{I}_{rms} = V_{rms} I_{rms} \angle \theta_V - \theta_i$$

$$= V_{rms} I_{rms} \cos(\theta_V - \theta_i) + j V_{rms} I_{rms} \sin(\theta_V - \theta_i)$$

$$= P + jQ = I_{rms}^2 Z = V_{rms}^2 / Z^* = V_{rms}^2 \Psi^*$$



$f(t)$	$F(s)$	$f(t)$	$F(s)$
$u(t)$	$\frac{1}{s}$	$\cos kt$	$\frac{s}{s^2 + k^2}$
t	$\frac{1}{s^2}$	$\sin kt$	$\frac{k}{s^2 + k^2}$
t^2	$\frac{2!}{s^3}$	$\cosh kt$	$\frac{s}{s^2 - k^2}$
t^n	$\frac{n!}{s^{n+1}}$	$\sinh kt$	$\frac{k}{s^2 - k^2}$
e^{at}	$\frac{1}{s-a}$	$e^{at} \cos kt$	$\frac{s-a}{(s-a)^2 + k^2}$
$\delta(t-a)$	e^{-as}	$e^{at} \sin kt$	$\frac{k}{(s-a)^2 + k^2}$

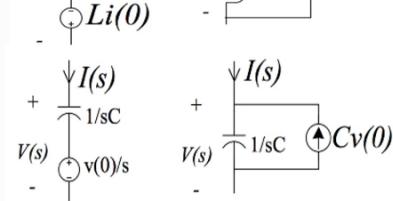
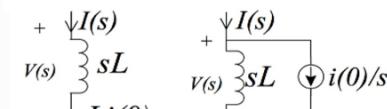
Time Domain	s-Domain
$\alpha f(t) + \beta g(t)$	$\alpha F(s) + \beta G(s)$
$f^{(n)}(t)$	$s^n F(s) - s^{n-1} f(0) - \dots - f^{(n-1)}(0)$
$\int_0^t f(\tau) d\tau$	$\frac{F(s)}{s}$
$\int_0^t f(\tau) g(t-\tau) d\tau$	$F(s) G(s)$
$t^n f(t)$	$(-1)^n \frac{d^n}{ds^n} F(s)$
$e^{at} f(t)$	$F(s-a)$
$f(t-a) u(t-a)$	$e^{-as} F(s)$
$g(t) u(t-a)$	$e^{-as} \mathcal{L}\{g(t+a)\}$
$f(t) = f(t+T)$	$\frac{1}{1-e^{-sT}} \int_0^T e^{-st} f(t) dt$

For complex roots, $F(s) = \dots + \frac{k^*}{s+\alpha+j\beta} + \frac{k^*}{s+\alpha-j\beta}$

where $k = |k| \angle \theta$ and $k^* = |k| \angle -\theta$

the inverse Laplace:

$$f(t) = (\dots + 2|k| e^{-\alpha t} \cos(\omega_n t + \theta) + \dots) u(t)$$



$$P_{avg} = V_{rms} I_{rms} \cos(\theta_V - \theta_i)$$

$$\text{real pwr } [W]$$

$$\text{apparent pwr } [VA]$$

$$\text{pf angle } \theta$$

$$\text{pf } \frac{P}{S}$$

$$\text{lag pf (L)}$$

$$\text{lead pf (C)}$$

