

Experiments and Events:

Def: An experiment is a process whose outcome is not known in advance with certainty.

Sample Space: Collection of *all* possible outcomes of an experiment. S or Ω . Each outcome is an element of the sample space $s \in S$.

Operations:

Union: $x \in S : A \cup B = \{x \in A \text{ or } x \in B\}$

$$A \cup B = B \cup A$$

$$A \cup A = A$$

$$A \cup \emptyset = A$$

$$A \cup S = S$$

$$A \subset B \Rightarrow A \cup B = B$$

$$A_1, A_2, \dots, A_n \Rightarrow A_1 \cup A_2 \cup \dots \cup A_n = \bigcup_{i=1}^n A_i$$

$$\bigcup_{i=1}^{\infty} A_i \rightarrow \bigcup_{i \in I} A_i$$

$$(A \cup B) \cup C = A \cup (B \cup C) = A \cup B \cup C$$

Intersections: $A \cap B = \{x \in A \text{ and } x \in B\} = AB$

$$A \cap B = B \cap A$$

$$A \cap A = A$$

$$A \cap \emptyset = \emptyset$$

$$A \cap S = A$$

$$A \subset B \Rightarrow A \cap B = A$$

$$\bigcap_{i \in I} A_i = \bigcap_{i=1}^{\infty} A_i$$

$$\bigcap_{i=1}^n A_i = A_1 \cap A_2 \cap \dots \cap A_n$$

$$(A \cap B) \cap C = A \cap (B \cap C) = A \cap B \cap C$$

Complements: $A^c = \{x \in S : x \notin A\}$

$$(A^c)^c = A$$

$$\emptyset^c = S$$

$$S^c = \emptyset$$

$$A \cup A^c = S$$

$$A \cap A^c = \emptyset$$

Disjoint Events:

A and B are *disjoint* or *mutually exclusive* if A and B have no outcomes in common. This happens only if $A \cap B = \emptyset$.

Def: A collection A_1, \dots, A_n is a collection of disjoint events if and only if $A_i \cap A_j = \emptyset, \forall i, j, i \neq j$

$$\left(\bigcup_{i \in I} A_i \right)^c = \bigcap_{i \in I} A_i^c$$

$$(A \cup B)^c = A^c \cap B^c$$

$$\begin{aligned} x \in (A \cap B)^c &\Rightarrow x \notin A \text{ and } x \notin B \\ &\Rightarrow x \in A^c \text{ and } x \in B^c \\ &\Rightarrow x \in A^c \cap B^c \end{aligned}$$

Probabilities:

Functions over S that measure the likelihood of events.

$$\forall A : Pr(A) \geq 0$$

$$Pr(S) = 1$$

For every *infinite sequence* of *disjoint* events $A_1, A_2, \dots (A_i \in S)$:

$$Pr\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} Pr(A_i)$$

$$Pr(A_1 \cup A_2 \cup \dots \cup A_n \cup \dots) = Pr(A_1) + Pr(A_2) + \dots + Pr(A_n) + \dots$$

$$Pr(\emptyset) = 0$$

$$Pr\left(\bigcup_{i=1}^n A_i\right) = Pr\left(\bigcup_{i=1}^n A_i + \bigcup_{i=n+1}^{\infty} \emptyset\right) = \sum_{i=1}^n Pr(A_i)$$

$$Pr(A^c) = 1 - Pr(A)$$

$$A \subset B \Rightarrow Pr(A) \leq Pr(B)$$

$$\forall A : 0 \leq Pr(A) \leq 1$$

$$Pr(A \cup B) = Pr(A) + Pr(B) - Pr(A \cap B)$$

Finite Sample Spaces:

$$S := \{s_1, s_2, \dots, s_n\}$$

To obtain a probability distribution over S we need to specify $Pr(s_i) = P_i, \forall i = 1, 2, \dots, n$, such that $\sum_{i=1}^n P_i = 1$

Def: A sample space S with n outcomes s_1, \dots, s_n is a *simple sample space* if the probability assigned to each outcome is $\frac{1}{n}$. If A contains m outcomes then $Pr(A) = \frac{m}{n}$.

Counting Methods:

Multiplication Rule: Suppose an experiment has k parts ($k \geq 2$) such that the i^{th} part of the experiment has n_i possible outcomes, $i = 1, \dots, k$, and that *all possible outcomes can occur regardless of which outcomes have occurred in other parts*. The sample space S will contain vectors of the form (u_1, u_2, \dots, u_k) . u_i is one of the n_i possible outcomes of part i . The total number of vectors is $n_1 \cdot n_2 \cdot \dots \cdot n_k$.

Permutations: Given an array of n elements the first position can be filled with n different elements, the second with $n - 1$, and so on. $n \cdot (n - 1) \cdot (n - 2) \cdot \dots \cdot 1 = n!$