

Coding Assignment-3 (Outputs)

Computational Methods & Applications

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Q.1) Output:

1.1)

```
r= RowVectorFloat([1,2,3])  
print(r)
```

Result: 1 2 3

1.2)

```
r= RowVectorFloat([1,2,3])  
print(len(r))
```

Result: 3

1.3)

```
r= RowVectorFloat([])  
print(len(r))
```

Result: 0

1.4)

```
r= RowVectorFloat([1,2,4])  
print(r[1])
```

Result: 2

1.5)

```
r= RowVectorFloat([1,2,4])  
r[2]=5  
print(r)
```

Result: 1 2 5

```
r1 = RowVectorFloat([1, 2 , 4])  
r2 = RowVectorFloat([1, 1 , 1])  
r3 = 2*r1 + (-3)*r2  
print(r3)
```

Result: -1 1 5

.....

Q.2) Output:

2.1)

```
s = SquareMatrixFloat(3)
print(s)
```

Result:

```
The matrix is
0 0 0
0 0 0
0 0 0
```

2.2)

```
s = SquareMatrixFloat(4)
s.sampleSymmetric()
print(s)
```

Result:

```
5.12.0 (python 11.0.1)
The matrix is
0.1 0.75 0.05 0.21
0.75 1.55 0.32 0.59
0.05 0.32 1.88 0.93
0.21 0.59 0.93 3.66
```

2.3)

```
s = SquareMatrixFloat(4)
s.sampleSymmetric()
print(s)
s.toRowEchelonForm()
print(s)
```

Result:

```
5.12.0 (python 11.0.1)
The matrix is
0.1 0.75 0.05 0.21
0.75 1.55 0.32 0.59

The matrix is
1.0 0.23 0.07 0.16
0.0 1.0 0.4 0.29
0.0 0.0 1.0 0.08
0.0 0.0 0.0 1.0
```

2.4)

```
s = SquareMatrixFloat(4)
s.sampleSymmetric()
print(s.isDRDominant())
print(s)
```

Result:

```
False
The matrix is
4.44 0.05 0.39 0.54
0.05 1.22 0.78 0.67
0.39 0.78 1.28 0.94
0.54 0.67 0.94 2.33
```

```
True
The matrix is
2.22 0.22 0.12 0.08
0.22 3.76 0.95 0.36
0.12 0.95 3.57 0.87
0.08 0.36 0.87 1.79
```

2.5)

```
s = SquareMatrixFloat(4)
s.sampleSymmetric()
(e, x) = s.jSolve([1, 2, 3, 4], 10)
print(x)
print(e)
```

Result1:

```
<class 'Exception'>
Not solving because convergence not guranteed
```

Result2:

Solution:

[-0.07919356294984303, 0.24224970957088568, 1.2455888242505428, 0.9211083178601538]

Error:

**[4.032955855789316, 2.8984290702885693, 2.08294828660763, 1.5088422466841935,
1.087488435141784, 0.786195796335368, 0.5673826099926563, 0.4098906856203197,
0.2959379386178865, 0.2137397389115902]**

2.6)

```
s = SquareMatrixFloat(4)
s.sampleSymmetric()
(err, x) = s.gsSolve([1, 2, 3, 4], 10)
print(x)
print(err)
```

Result:

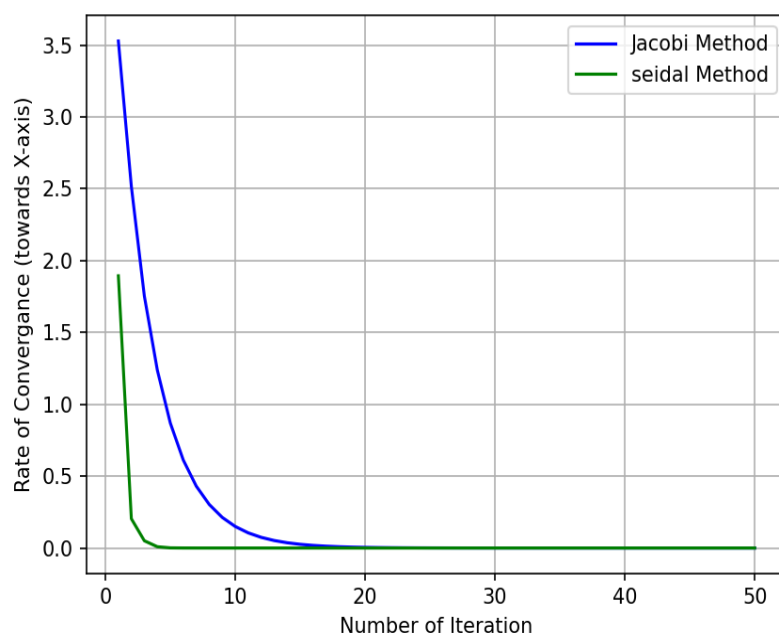
Solution:

[-1.1767958462323393, 0.8589684399402326, -0.0050721566890308155, 16.573308941502873]

Error:

**[4.747020872272483, 0.5079934393857451, 0.1895295148079645, 0.049007248043791536,
0.009203303795685801, 0.0012897998457234447, 0.00012069873433267575,
1.9508940875422325e-05, 6.920246185631002e-06, 1.6222793631222403e-06]**

Q.3) Output:



Observation: From this graph we can say that Gauss Seidal method converges faster than Jacobi method.

Q.4) Output:

4.1)

```
p = Polynomial([1, 2, 3])  
print(p)
```

Result:

```
Polynomial([1, 2, 3])  
Coefficients of the polynomial are:  
1 2 3
```

4.2)

```
p1 = Polynomial([1, 2, 3])  
p2 = Polynomial([3, 2, 1])  
p3 = p1 + p2  
print(p3)
```

Result:

```
Polynomial([4, 4, 4])  
Coefficients of the polynomial are:  
4 4 4
```

4.3)

```
p1 = Polynomial([1, 2, 3])  
p2 = Polynomial([3, 2, 1])  
p3 = p1 - p2  
print(p3)
```

Result:

```
Polynomial([-2, 0, 2])  
Coefficients of the polynomial are:  
-2 0 2
```

4.4)

```
p1 = Polynomial([1, 2, 3])  
p2 = (-0.5)*p1  
print(p2)
```

Result:

```
Polynomial([-0.5, -1.0, -1.5])  
Coefficients of the polynomial are:  
-0.5 -1.0 -1.5
```

4.5)

```
p1 = Polynomial([-1, 1])  
p2 = Polynomial([1, 1, 1])  
p3 = p1 * p2  
print(p3)
```

Result:

```
Polynomial([-1, 0, 0, 1])  
Coefficients of the polynomial are:  
-1 0 0 1
```

4.6)

```
p = Polynomial([1, 2, 3])  
print(p[2])
```

Result:

```
17
```

4.7)

```
p = Polynomial([1, -1, 1, -1])  
p.show(-1, 2)
```

Result:

