Zaid Duraid

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EDUCATION

Memorial University of Newfoundland

St. John's, NL, Canada

Bachelor of Engineering: Computer Engineering - CGPA: 4.00/4.00 (95.2%)

Sept. 2022 - April 2027

- Dean's List (2022-2025)
- Scholarships: Memorial University Alumni Entrance, Innovasea Computer Engineering, Verafin Inc. Computer Engineering, Charlie Sheppard Memorial Hatch, PEGNL Past-President, Bob Thorburn Memorial, Gander Lions Club Community Leaders, NLESD Education Foundation, Town of Gander

EXPERIENCE

Advanced Research Electrical Engineer Intern

May. 2025 - Aug. 2025

Solace Power

St. John's, NL, Canada

- Improved the design of a multi-MHz synchronous rectifier by adding a **PLL** for closed-loop control to maintain operation during ~100us loss of switch gate driver signal
- Designed and built single-layer PCBs to quickly verify **integration of subcircuits** (e.g., RC inverter delay line for phase shift on GaN FET driver signal) into multilayer PCBs
- Researched EMC solutions for a tens of MHz wireless power system, reducing noise on key harmonics
- Developed C firmware for a TI F28003x microcontroller to generate internal-clock or interrupt-driven PWM signals up to 9MHz, with adjustable frequency, duty cycle, and phase shift via CANBUS

FPGA Hardware Engineer Intern

Jan. 2024 - Apr. 2024 and Sept. 2024 - Dec. 2024

Avalon Holographics Inc.

St. John's, NL, Canada

- Developed and documented simulation testbenches for FPGA designs in SystemVerilog, leading to the discovery and resolution of critical display datapath bugs
- Built new **internal verification tools using Python** that integrated with existing testbenches to verify hardware image correction for the holographic display
- Contributed to **FPGA RTL code in SystemVerilog**, including adding runtime-accessible register maps (regmaps) for debug and hardware image correction parameter loading
- Followed internal test processes by assembling hardware, executing tests, and running TCL scripts for the bring-up of new/refurbished PCBs and validation of FPGA build releases

Software Team Co-Lead (Unpaid)

Aug. 2023 - Present

Eastern Edge Robotics

St. John's, NL, Canada

- Wrote backend applications utilizing ROS2 and Docker with Python and C++ to run on a Raspberry Pi and interface between the piloting frontend and the ROV's thrusters, tools, sensors, and control profiles database
- Contributed to two independent frontend applications, in ReactJS and C++, providing both convenient (browser-based) and low-latency options for piloting the ROV
- Led and mentored software team by preparing **onboarding resources**, **documentation**, **and task assignments**, resulting in significant contributions and experience-gain by 5+ members
- Competed and presented alongside the team at the International MATE ROV Competition Explorer Class in 2023, 2024, and 2025, placing in 11th, 9th, and 3rd place in the world out of around 20-30 teams, respectively

Projects

ROV Simulator - Gazebo, C++, ROS2, Python

Mar. 2024 - Present

• Implemented an ROV simulation environment in Gazebo Harmonic with custom C++ plugins, facilitating testing of the complete software stack, thruster configuration, and tooling for small ROV designs

Photosphere Board - KiCad

Dec. 2024 - Jan. 2025

• Designed a PCB in KiCad that interfaces with the Raspberry Pi Compute Module 4 and includes dual MIPI CSI camera ports and USB 2.0 for multi-view video streaming in a space-constrained environment

SKILLS

Programming Languages: Python, System Verilog, C/C++, React JS, HTML/CSS, Bash

Tools: Git, KiCad, Questa, Quartus, Vivado, Docker, ROS, Gazebo, LTSpice, Altium, Solidworks, Bluebeam Revu

Spoken Languages: English and Arabic (Native), French (Fluent, DELF B1 Certified)