

High-speed image edge detector based on thin-film lithium niobate

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Abstract—We report a high-speed image edge detector based on an integrated lithium niobate photonic chip with processing sampling rates up to 92 GSa/s. We further use the devices to realize photonics-assisted segmentation of medical images.

Keywords—thin-film lithium niobate, microwave photonics, image edge detection, medical diagnosis

I. INTRODUCTION

With the rapid expansion of wireless networks and Internet of Things (IoTs), the electronic bandwidth and performance of underlying radio frequency (RF) systems are facing severe challenges [1]. Meanwhile, the ever-growing artificial intelligence (AI) technologies also demand ultrahigh-speed, low-power, and low-latency processing and computation of analog signals much beyond those offered by traditional electronic integrated circuits. Microwave photonics (MWP) can provide efficient solutions to address these challenges through the usage of optical devices to perform microwave signal generation, transmission and manipulation tasks [2]. Recently, the surge of photonics integration technologies has led to a dramatic reduction in size, weight, and power of the MWP system with enhanced robustness and functionalities [3]. The recently emerged thin-film lithium niobate (LN) platform is a promising candidate for integrated MWP signal processing owing to its unique electro-optic properties, low optical loss and excellent scalability [4-6].

Here, we demonstrate a high-speed image edge-feature detector based on LN platform, realizing high-speed analog computation of electronic signals up to 92 GSa/s. We further plug the photonics-assisted image-edge detector into a neural network-based image segmentation model, to showcase the effective identification of melanoma lesion outlines in medical diagnostic images.

II. HIGH-SPEED IMAGE EDGE DETECTOR

Figure 1 demonstrates the schematic diagram of high-speed image edge-feature detector, including a high-speed phase modulator (PM) and an MZI-based signal processor, together on thin-film LN platform. The RGB information of two-dimension (2D) images are grayed and serialized into a

time-domain data stream, and up-converted to optical domain by modulators. The MZI-based signal processing unit performs a real-time differentiation process of the data stream [7, 8]. Finally, we de-multiplex the captured time-series data back into matrix format to form the reconstructed image with clear edge information.

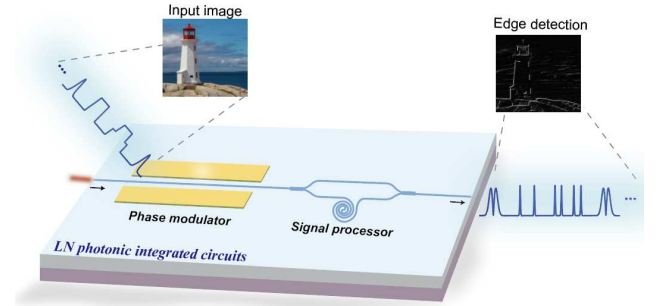


Fig. 1. Schematic diagram of high-speed image edge detector based on thin-film LN platform.

The basic working principle of on-chip signal processing section is shown in Fig. 2a: the input RF signal $x(t)$ is first loaded on a continuous-wave (CW) optical signal by the PM, leading to an instantaneous optical phase of $\omega_0 + \beta x(t)$, where ω_0 is the carrier frequency of the signal and β is the modulation index. This induces an instantaneous frequency chirp of $\omega_0 + \beta \frac{dx(t)}{dt}$ that exactly follows the differentiation of the input signal $\frac{dx(t)}{dt}$. The chirped frequency information is then mapped into optical field using a signal processing unit, i.e. an unbalanced MZI in this case. When biasing the MZI at the null point, where the output optical field is linearly proportional to the optical frequency, the output RF signals are exactly the differentiation form of input signals [7]. Fig. 2b shows the experimental setup, inset is the microscope image of the device. The measured transfer function of the unbalanced MZI is shown in Fig. 2c, consistent with the ideal linear response within a processing bandwidth of 40 GHz, limited by FSR.

Furthermore, we make a detailed performance comparison between traditional electronics-based algorithms (including convolution-based and simple differentiation-based algorithms) and our photonic-assisted segmentation model in Table 1. The performance metrics include raw lesion edge detection accuracy (before DCNN), final segmentation accuracy (after DCNN), and computation time. The accuracies of lesion edge detection and segmentation are measured by dice coefficient [12]. Our photonic edge detector shows a better raw edge detection accuracy (23.5%) than those of both convolution-based (18.1%) and differentiation-based (12.8%) algorithms, mainly because it picks up less false-positive details inside the lesion region. The final image segmentation accuracies are above 95% for all three methods but with drastically different processing time. For edge feature extraction of a 250×250-pixel image, our device is nearly three orders of magnitude faster than performing a traditional convolution algorithm on a generic personal computer. Therefore, our demonstrated high-speed photonics-assisted image segmentation model could pave the path for high-complexity, high-throughput and real-time medical diagnosis tasks.

TABLE I. PERFORMANCE COMPARISON WITH TRADITIONAL ELECTRONICS-BASED ALGORITHMS

	Differentiation algorithm	Convolution algorithm	This work
Raw lesion edge detection* [†]	12.831%	18.149%	23.509%
Segmentation accuracy*	95.602%	95.888%	95.437%
Computation time	0.12 ms	0.38 ms	679 ns

* Detection and segmentation accuracies are measured by dice coefficient.

[†] Raw detection accuracy right after edge detection algorithms, before entering DCNN.

IV. CONCLUSION

In summary, we have demonstrated a high-speed and high-fidelity image edge detector based on thin-film LN platform, with processing sampling rates up to 92 GSa/s. We further combined the edge detection system with DCNN algorithm to realize photonics-assisted image segmentation model for medical diagnosis, providing three orders of magnitude faster processing speed than traditional algorithm.

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