TEAM NAME:

Teem Sicks

TEAM MEMBERS AND ROLES:

JAMES BARRETT – Project Lead and Hardware Support
CAMERON HOPKINSON - Coding
TIM FOLEY - Coding
IAN BROADHURST - Hardware
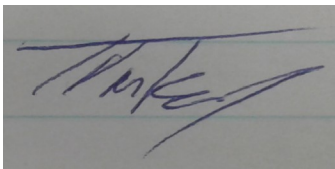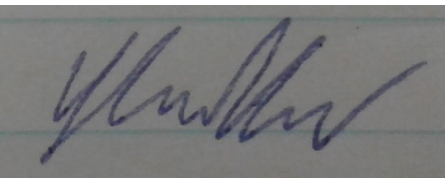ZALA HABIB – Testing and documentation

Team Agreement
By signing below, all team members are acknowledging that they have read and committed to their part in the AVC. They acknowledge that they will attempt to complete the tasks agreed on by the group each week and document this on the team github account. They acknowledge that failure to meet these goals can result in the team recommending any member receives a lesser grade for their AVC report. In the event that a team member is unable to complete their task due to circumstances beyond their control (i.e. sickness, bereavement etc) that they will inform the team at the earliest possible time. Finally, the team acknowledges that a member going a week without contact with other team members (except when discussed with the team in advance) will constitute the member in question being considered AWOL. In this instance the team agrees to inform the ENGR101 course co-ordinator immediately. The penalty this for this can range from a reduction in the final grade to immediate failure of the AVC (and thus the ENGR101 course). Should the team unanimously agree that a member (or members) have failed to contribute to the AVC sufficiently for other reasons, on the day of robot testing the team will be given the opportunity to anonymously vote for a team member to receive 0% for the robot part of the AVC. Should the team choose this option they MUST be able to show that the member in question had been assigned tasks that they failed to complete and that the team had afforded them an opportunity to make up for past mistakes.
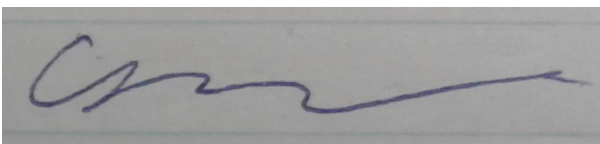
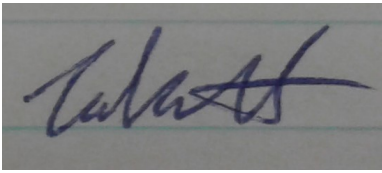Signed by all team members: (Printed Name)/ (Signature)
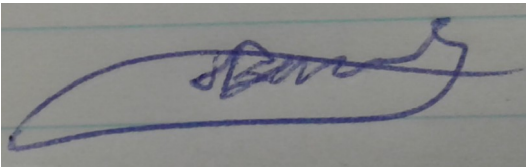
TIM FOLEY -

IAN BROADHURST -

CAMERON HOPKINSON -

ZALA HABIB –

JAMES BARRETT -

AVC TASK PLAN:

Table 1: Example AVC Timetable

WEEK	DATES	TEAM OBJECTIVE(S)	ITEMS DUE	CONFLICTING COMMITMENTS	TASKS
1	18th April	Plan for AVC, Robot moving in straight line	AVC Plan (Due 22nd April)	PHYS122 Test	Tim and Cam: Write code to make Robot move in straight line Ian: Assemble basic chassis and start sensor averaging Zala: Set up contacts and write project plan James: Arrange meetings and design chassis
2	25th April	Robot moving in straight line			Tim and Cam: Research PID and suggest order of methods and write code for opening the gate Ian: Finalise chassis and sensor Zala: Update github with

					progress and start progress report and plan week 3 goals James: Check team progress
3	2nd May	Quadrant 1 Complete	AVC Progress Report (Due 9th May)		Tim and Cam: Finish code for robot to clear first quadrant Ian: Have robot built to be able to clear first quadrant Zala: Start AVC progress report, test robot to finish first quadrant, update github with progress James: Plan meetings, create goals for next few weeks
4	9th May	Quadrant 2 Complete		COMP102 Test	
5	16th May	Quadrant 3 Complete	Progress Report due	ENGR121 Test	
6	23rd May	Quadrant 4 Complete			
7	30th May		Robot Due	ENGR101 Test 2	
8	6th June				
9	13th June		Final Report Due		