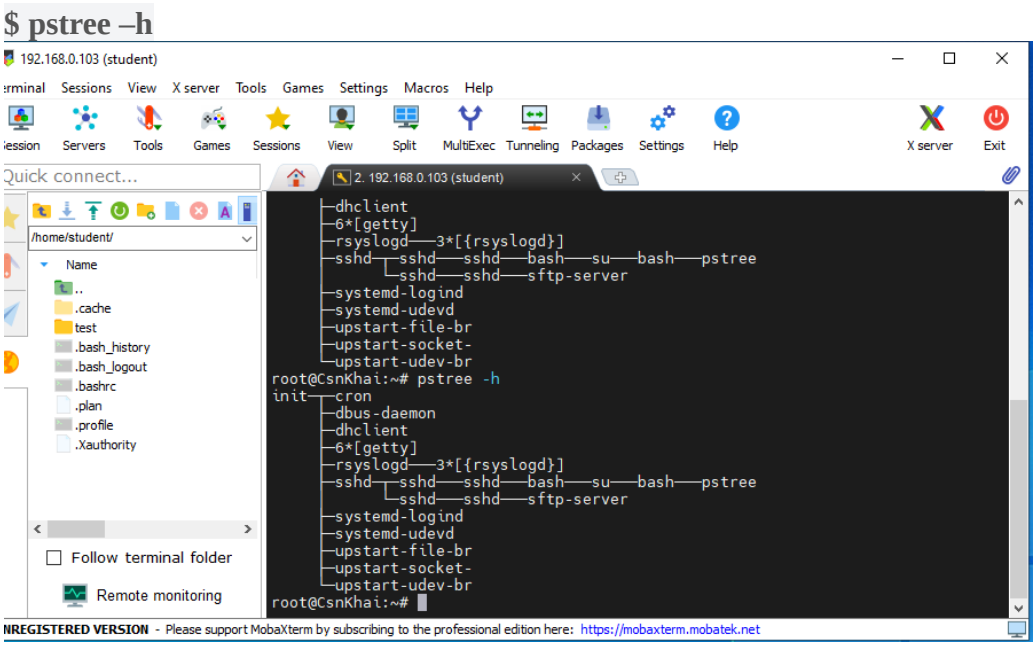
Part1

1. How many states could has a process in Linux?

There are five Linux process states: running & runnable, interruptable_sleep, uninterruptable_sleep, stopped, and zombie.

2. Examine the pstree command. Make output (highlight) the chain (ancestors) of the current process.

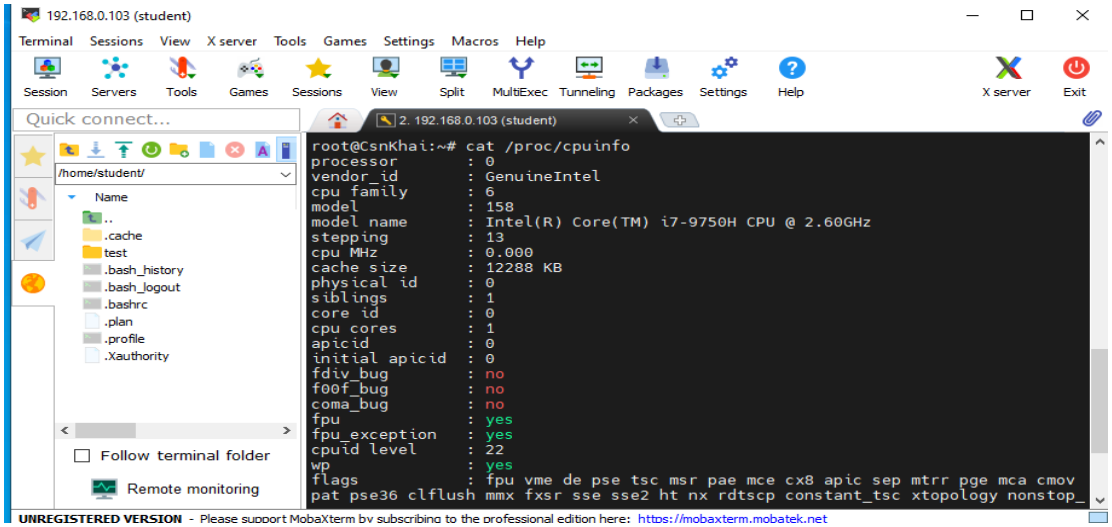


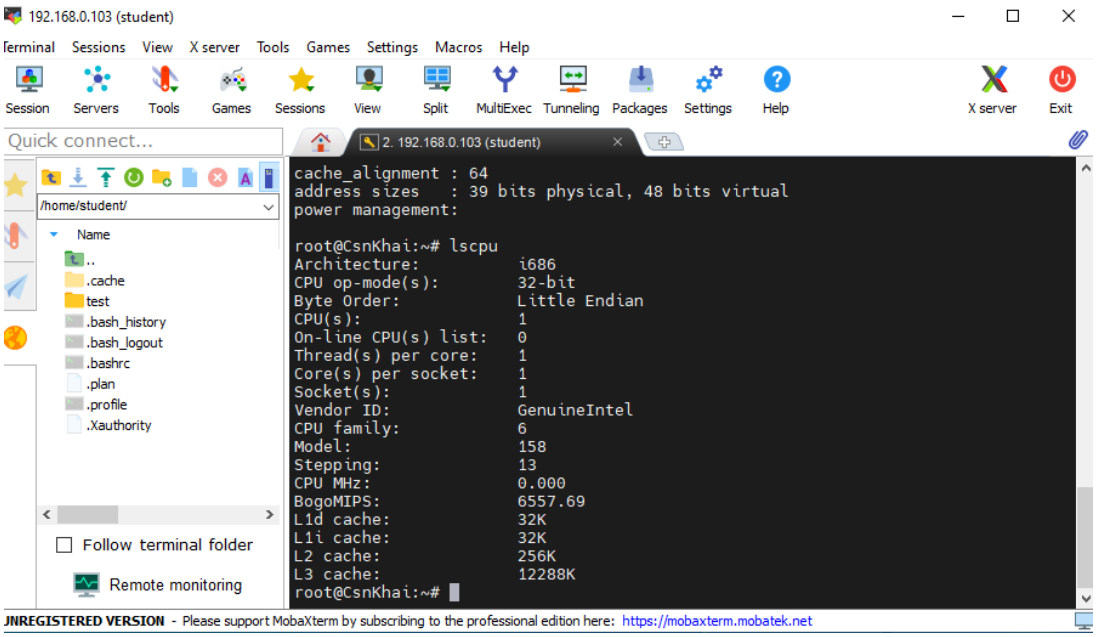
3. What is a proc file system?

Proc file system (procfs) is a virtual file system created on the fly when the system boots and is dissolved at the time of system shutdown. It contains useful information about the processes that are currently running, it is regarded as a control and information center for the kernel.

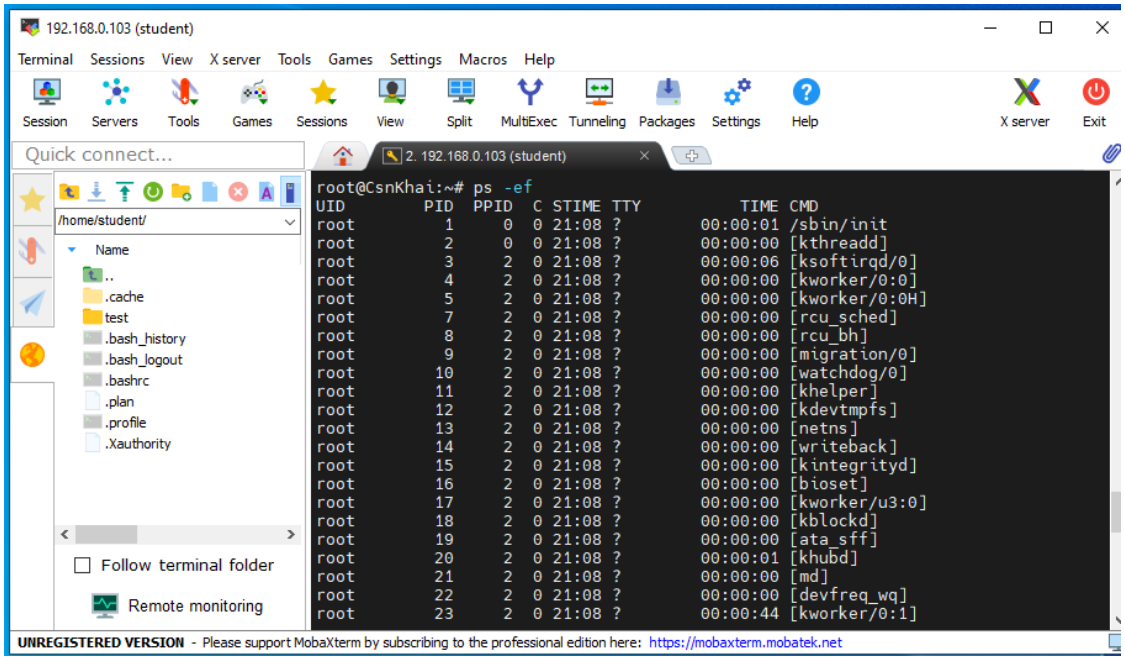
4. Print information about the processor (its type, supported technologies, etc.).

You can use the /proc/cpuinfo file or the lscpu command to find out all the information about the processor.





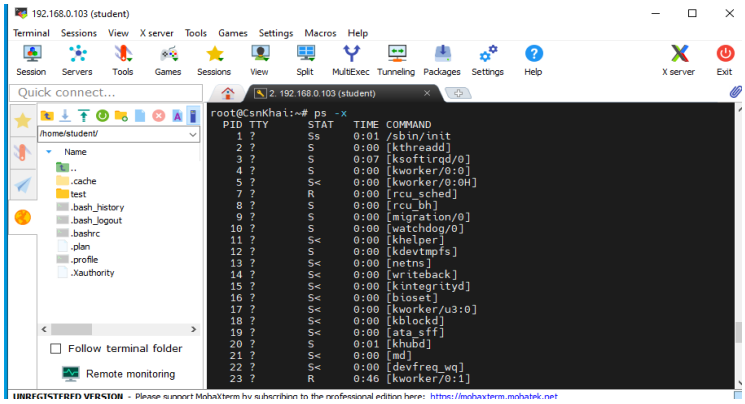
5. **Use the ps command to get information about the process. The information should be as follows: the owner of the process, the arguments with which the process was launched for execution, the group owner of this process, etc**.



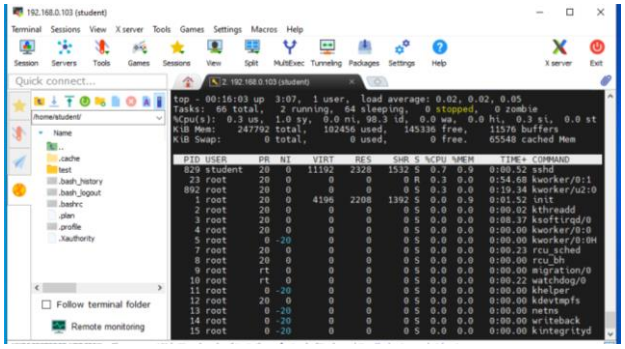
6. **How to define kernel processes and user processes?**

User-space processes have its own virtual address space. **Kernel processes** or threads do not have their own address space, they operate within kernel address space only. And they may be started before the kernel has started any user process.

If you want to find out exactly which tasks were opened on behalf of the current account, it will be enough to enter the line ps –x in the console



7. **Print the list of processes to the terminal. Briefly describe the statuses of the processes.**

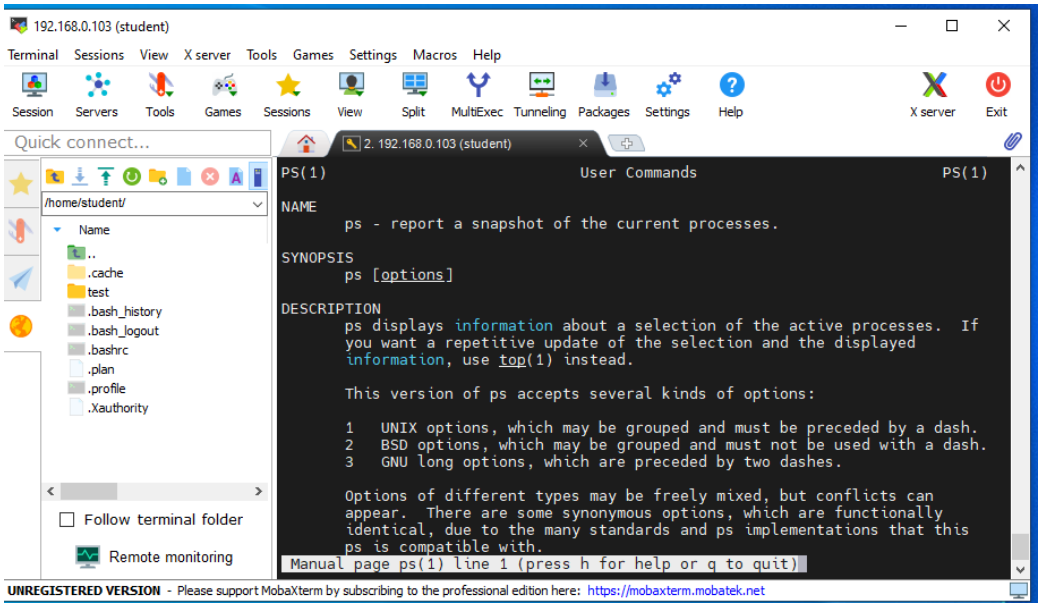


S is the current **status** of the process: **R** — running; S — sleeping, Z — zombie.

8. **Display only the processes of a specific user.**

$ ps –fU

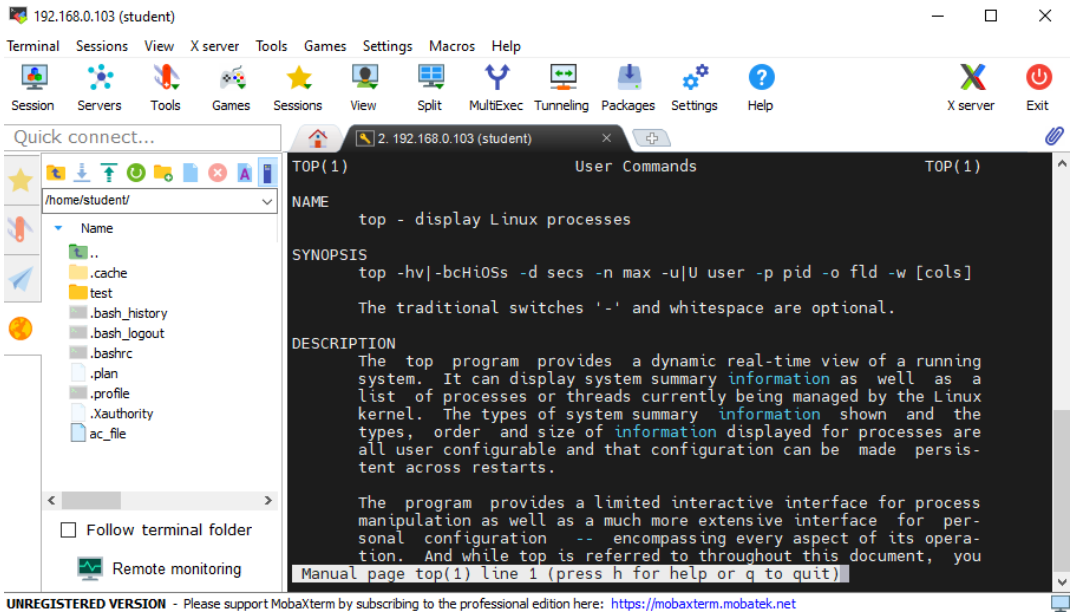
9. **What utilities can be used to analyze existing running tasks (by analyzing the help for the ps command)?**



Top is a command that allows users to monitor processes and system resource usage in Linux.

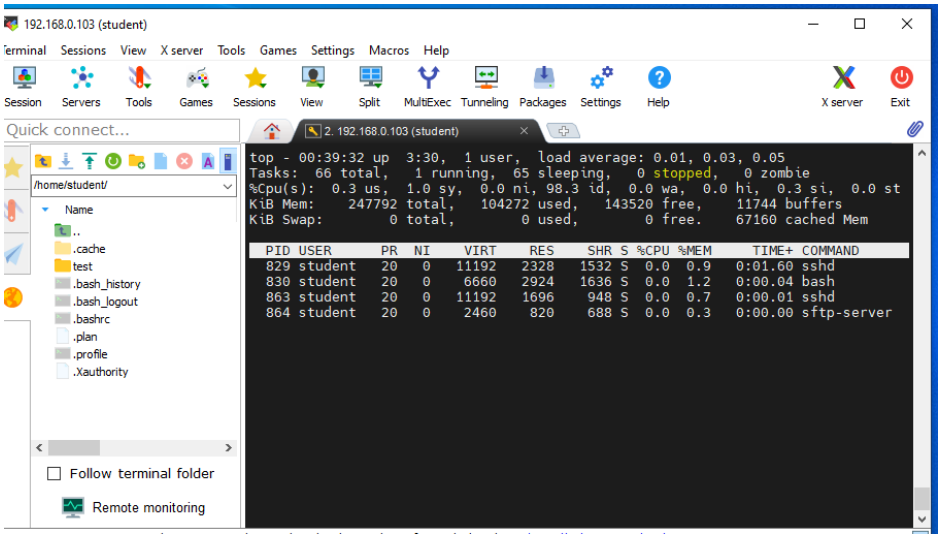
10. What information does top command display?

The top (table of processes) command shows a real-time view of running processes in Linux and displays kernel-managed tasks. The command also provides a system information summary that shows resource utilization, including CPU and memory usage.



11. Display the processes of the specific user using the top command.

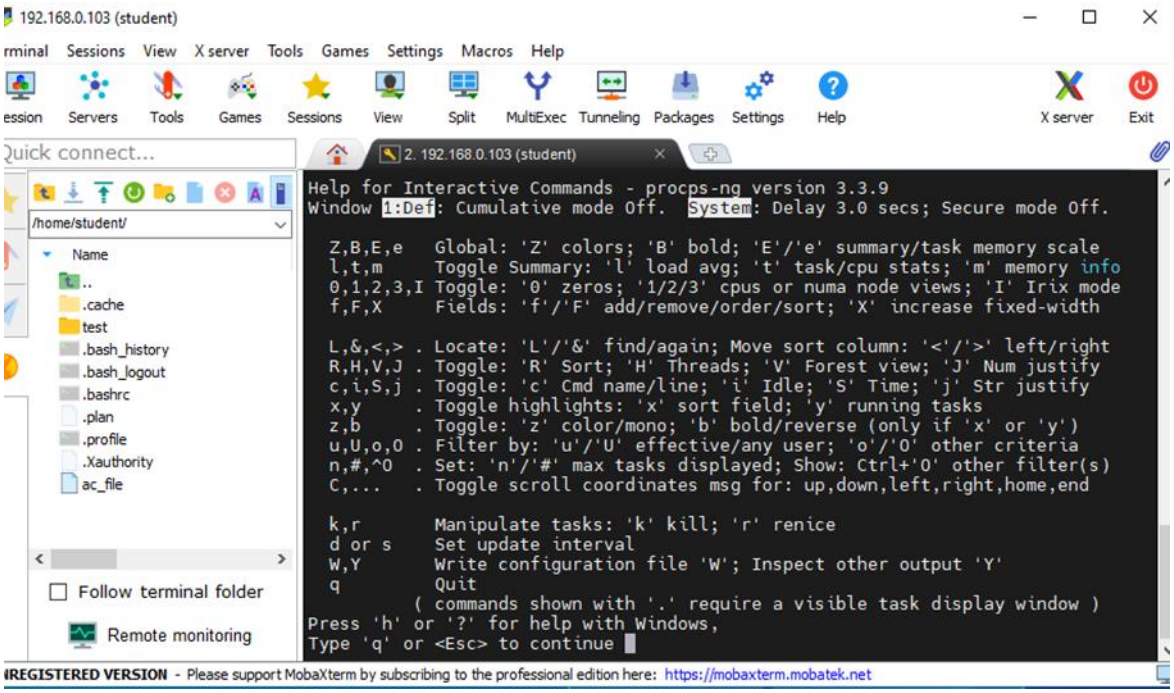
To filter processes running as a specific user, use the u command:



12. What interactive commands can be used to control the top command? Give a couple of examples.

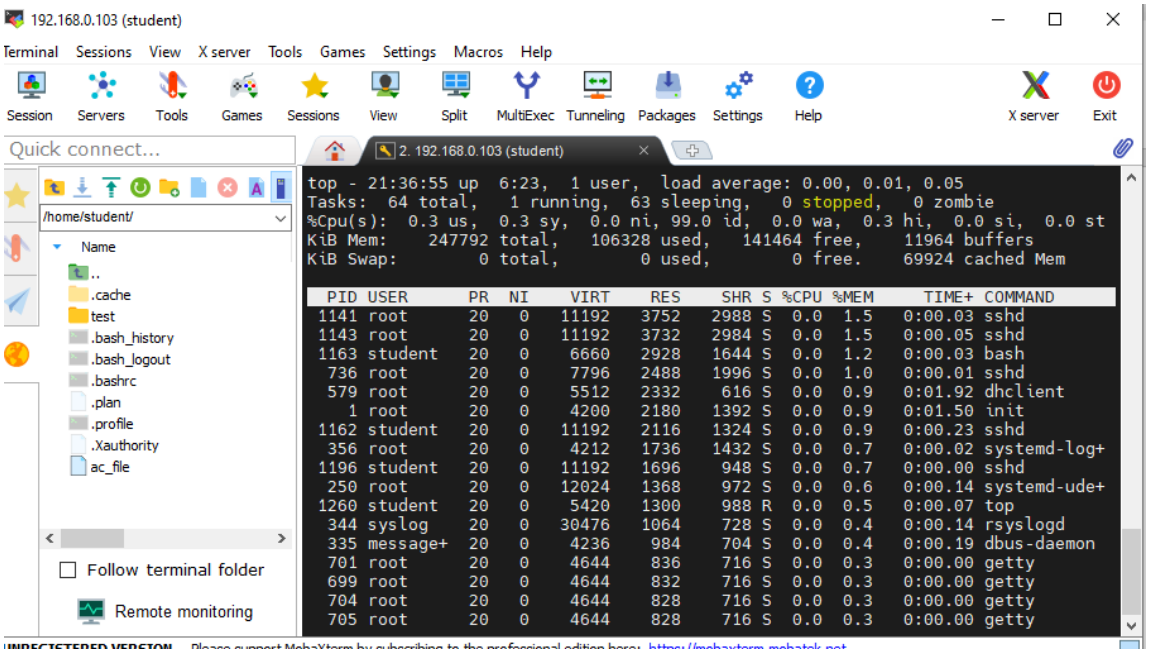
Command'k'- kill completion of the process
Command 'r' – renice, change the current task priority

Pressing the **h** key displays command help:

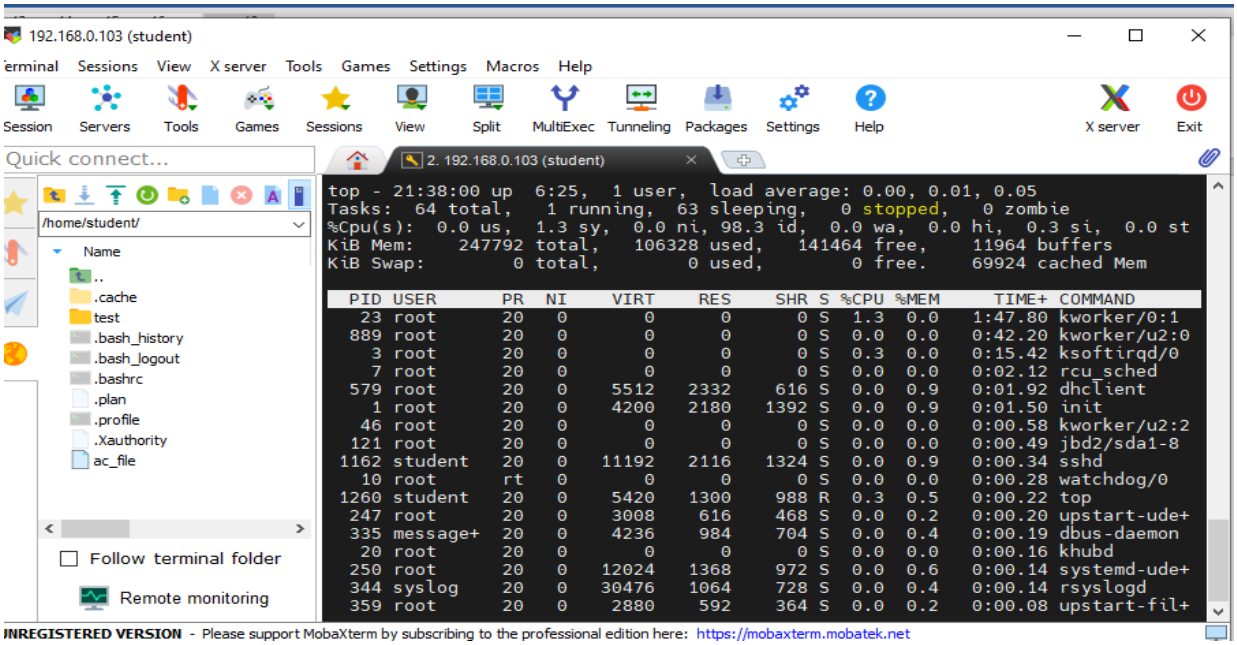


13. Sort the contents of the processes window using various parameters (for example, the amount of processor time taken up, etc.)

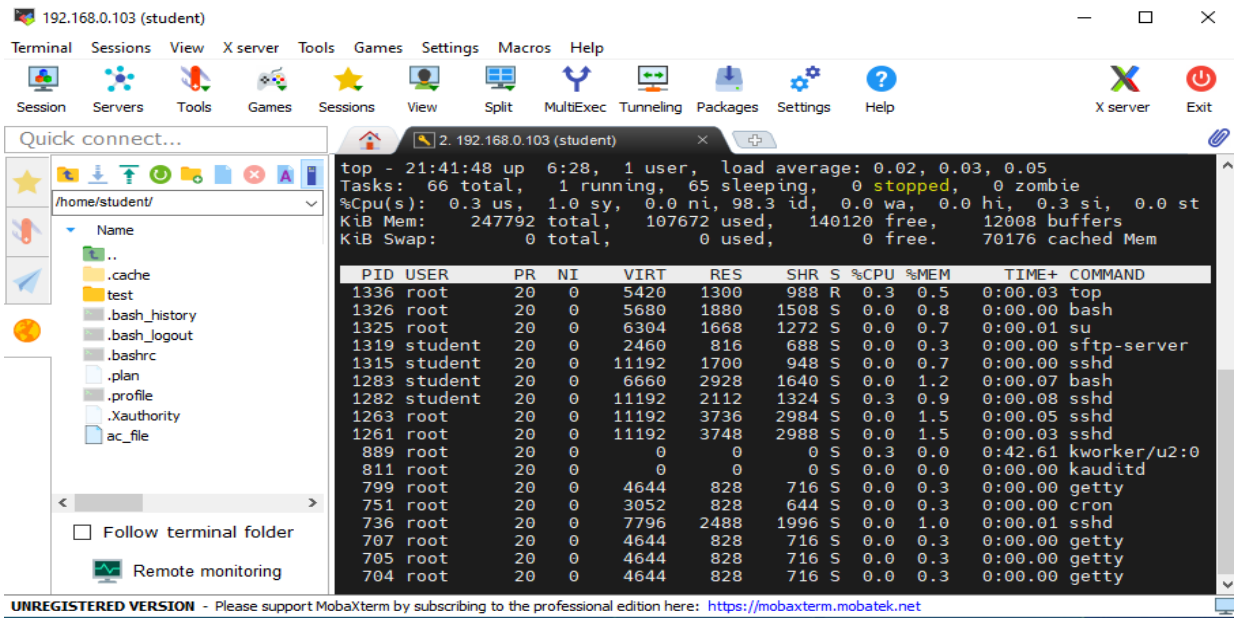
Shift+M Sort by memory (%MEM):



Shift+T Sort by time:



Shift+N Sort by PID:



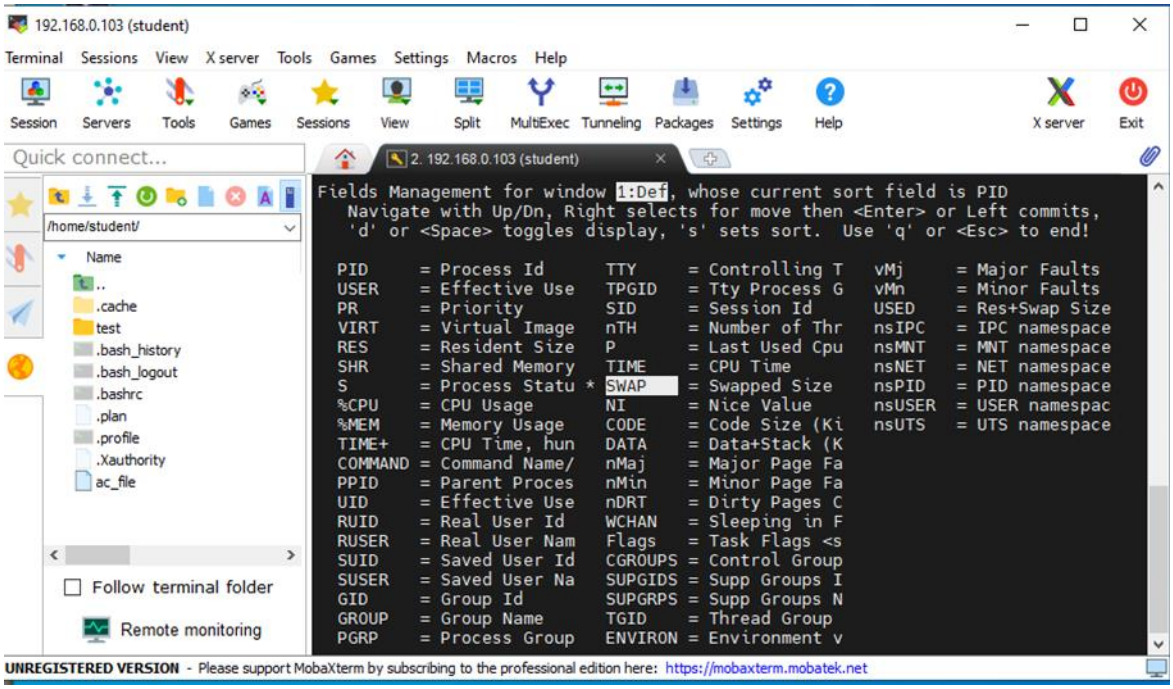
Sort by SWAP:

Shift+F

Choose SWAP

+d

+s



14. Concept of priority, what commands are used to set priority?

To change the priority of processes, the **nice and renice** commands are used. When a process starts, its priority is set by the value of the parent process, for example, an xterm terminal or a shell command.

The nice command allows you to start a process with a priority equal to the sum of the parent (for example, 8) and the number specified as an option of the nice command:

nice -< number > command

Example:

$ nice -4 mc - will start mc with priority = 8+4=12.

The **renice** command is used to change the priority of an already running process:

$ renice < number > -p PID

Example**:**

$ renice 4 -p 11597 – will set the priority value for process mc (PID=11597) to 4.

After execution, renice will issue the following result: 11597: old priority 12, new priority 4 - old priority 12, new priority 4.

Negative values and 0 can be set only by the root user.

15. Can I change the priority of a process using the top command? If so, how?

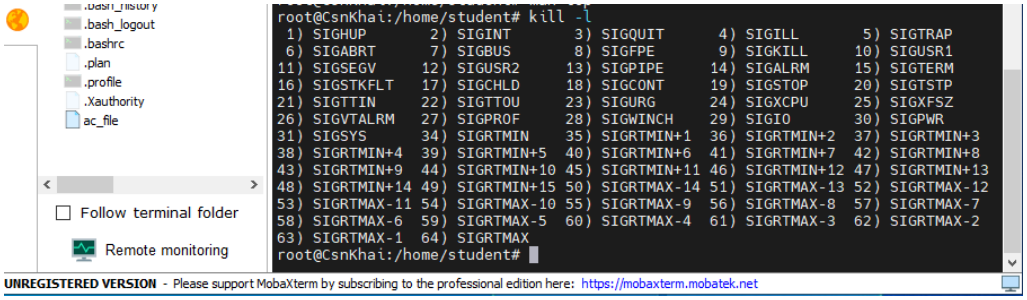
In order to change the current task priority, you need to use **the -r (renice) command** with top. The PID will be queried, and then the new priority value (displayed in the NI column). The range

of priority values is from minus 20 (the highest) to plus 19. Only the root user can set negative values and 0.

16. Examine the kill command. How to send with the kill command process control signal? Give an example of commonly used signals.

list of signal numbers and names:

$ kill -l



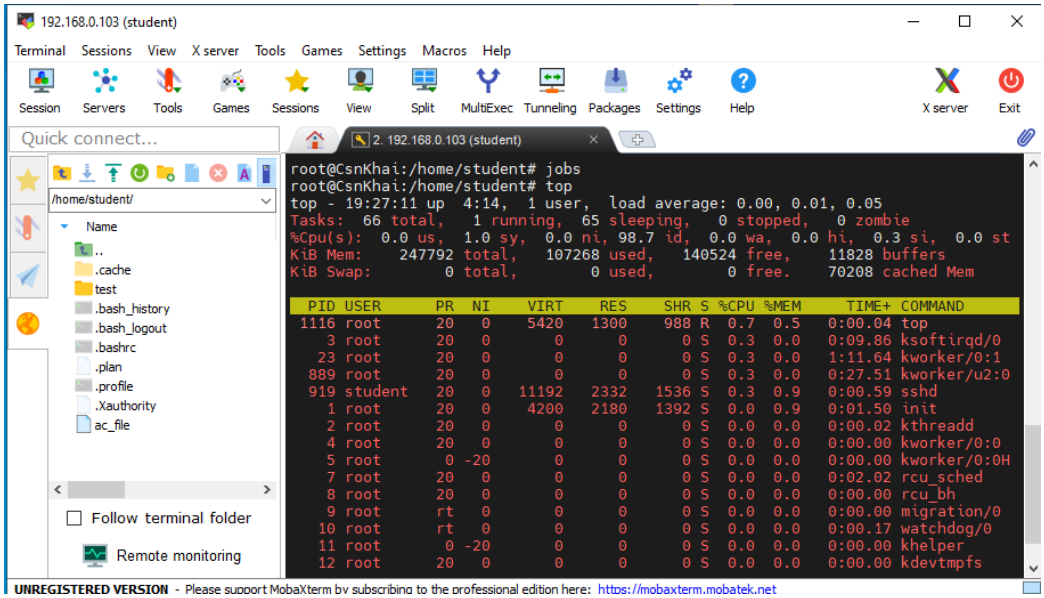
To send a specific signal to a given process:

$ kill <signal number> the PID number of the selected process

17. Commands jobs, fg, bg, nohup. What are they for? Use the sleep, yes command to demonstrate the process control mechanism with fg, bg.

CTRL+Z - Stops and sends commands to the back**.**

Jobs shows all stopped commands.



In order to output the command from the background process, is used the **fg** (**foreground)** command. Which can either be passed the task number as an argument, or run without arguments. In the latter case, the task marked with a + sign in the jobs list will be displayed – the last task sent to the background.

The **bg (background)** command is used to keep processes running in the background.

Nohup keeps processes running on Linux systems even after exiting a shell or terminal. It prevents processes or jobs from receiving a SIGHUP (Signal Hang UP) signal.