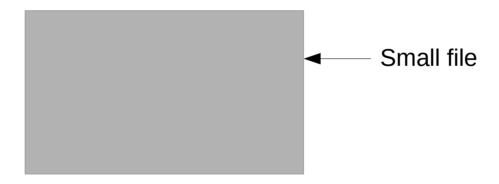
### Data Management

## Examining the Data

- Look at some random inputs
- Look at the largest and smallest inputs (by file size)
  - These are the most likely to be weird or corrupted



Manually solve the task

# **Splitting**

- Training set used by SGD to learn model parameters
- Validation set used by us to learn hyperparameters
- Test set used once to measure final model performance

## Overfitting

- Goal: Learn to classify unseen images
- Optimization objective: Learn to classify training set images

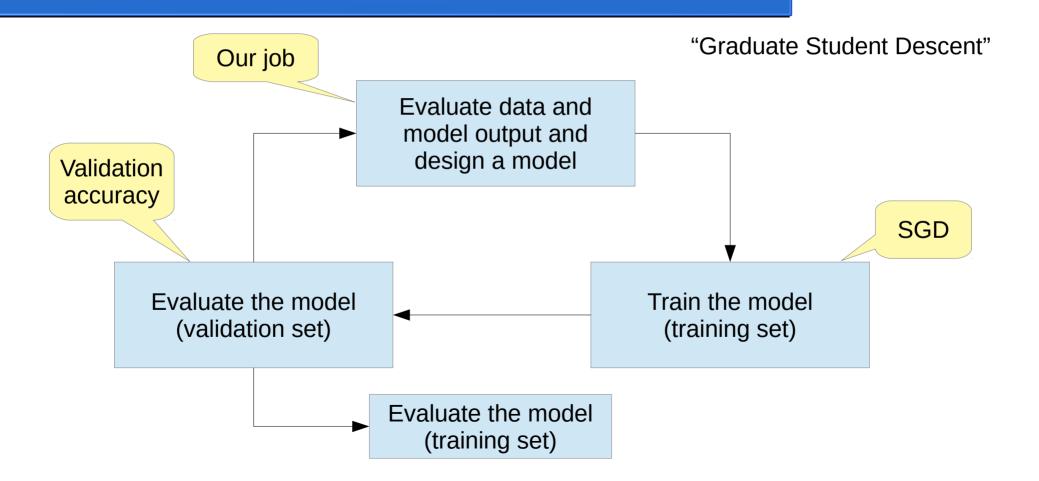
Training set (60-80% of data)
Model parameters overfit by SGD

Validation (10-20%)
Hyperparameters overfit by us

Test (10-20%)
Not used in training, not overfit

Be sure to split randomly

## Tuning

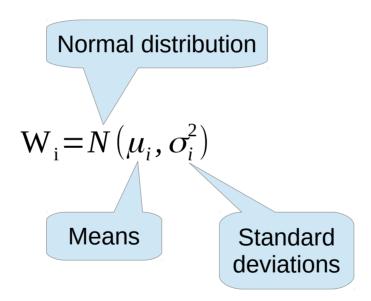


### Initialization

### Initialization – All Zero

	x = ???	$g_1 = 0$	
Linear 1	$\mathbf{v}_1 = \mathbf{W}_1 \mathbf{x}$	$g_1 = W_1^T g_2$	$\nabla_{\mathbf{W}_1} \mathcal{C}(\mathbf{v}_3) = \mathbf{g}_2 \mathbf{x}^{\mathrm{T}}$
	$\mathbf{v}_1 = 0$	$g_2 = 0$	0
ReLU	$\mathbf{v}_2 = \max(\mathbf{v}_{1,0})$	$g_2 = g_3[v_1 > 0]$	
	$v_2 = 0$	$g_3 = 0$	
Linear 2	$\mathbf{v}_3 = \mathbf{W}_2 \mathbf{v}_2$	$g_3 = W_2^T g_o$	$\nabla_{\mathbf{W}_2} \mathscr{C}(\mathbf{v}_3) = g_o \mathbf{v}_2^{\mathrm{T}}$
	$\mathbf{v}_3 = 0$	$g_{o} = ???$	0
$g_o = \nabla_{\mathbf{v}_3} \mathcal{L}(\mathbf{v}_3)$			

#### Initialization – Random



In practice, the mean is zero and we need to choose a standard deviation

### Initialization - Scaling

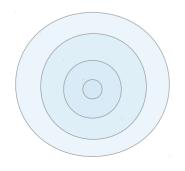
$$\mathbf{o} = \mathbf{W}_{2} \mathbf{W}_{1} \mathbf{x}$$

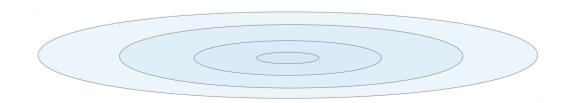
$$\nabla_{\mathbf{W}_{1}} \mathcal{E}(\mathbf{o}) = \left(\mathbf{W}_{2}^{T} \left(\nabla_{\mathbf{o}} \mathcal{E}(\mathbf{o})\right)\right) \mathbf{x}^{T}$$

$$\nabla_{\mathbf{W}_{2}} \mathcal{E}(\mathbf{o}) = \left(\nabla_{\mathbf{o}} \mathcal{E}(\mathbf{o})\right) (\mathbf{W}_{1} \mathbf{x})^{T}$$

$$\|\mathbf{W}_1\| \approx \|\mathbf{W}_2\|$$







### Choosing a Standard Deviation

## Math

(See the supplementary material for details)

## Kaiming Initialization

 Choose either activations or gradients and keep the magnitude roughly constant:

$$W \sim N\left(0, \frac{2}{n_{\rm in}}\right)$$

$$W \sim N\left(0, \frac{2}{n_{\text{out}}}\right)$$

#### **Xavier Initialization**

 Keep both activation and gradient magnitudes roughly constant throughout the network

$$W \sim N\left(0, \frac{4}{n_{\rm in} + n_{\rm out}}\right)$$

#### In Practice

 Xavier initialization (the PyTorch default) is usually good enough.

- The last layer can be initialized to zero.
  - If the previous layers are not zero, the last activation is not zero, so we still get gradients.