# **Practical Optimization**

## A Slight Change

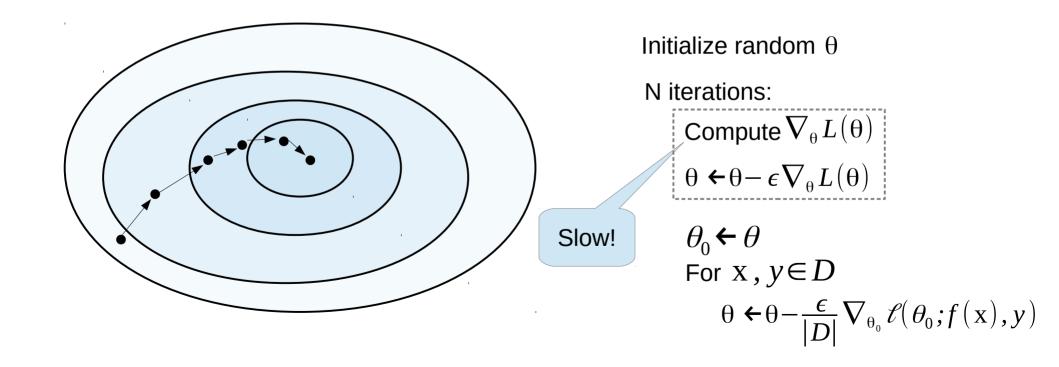
$$D = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$$

$$L(\theta) = \sum_{i} \mathcal{L}(\theta; \mathbf{x}_{i}, \mathbf{y}_{i})$$

$$L(\theta) = \frac{1}{|D|} \sum_{i} \mathcal{L}(\theta; \mathbf{x}_{i}, \mathbf{y}_{i})$$
$$= \mathbf{E}_{\mathbf{x}, \mathbf{y} \sim D} [\mathcal{L}(\theta; \mathbf{x}, \mathbf{y})]$$

### **Gradient Descent**

How do we find  $\operatorname{argmin}_{\theta}L(\theta)$ 



### Stochastic Gradient Descent

#### **Gradient Descent:**

Initialize random  $\theta$ 

N iterations:

$$\begin{aligned} & B_0 & \longleftarrow \\ & \text{For } \mathbf{x}, \mathbf{y} \in D \\ & \theta \leftarrow \theta - \frac{\epsilon}{|D|} \nabla_{\theta_\bullet} \mathcal{E}(\theta_\bullet; f(\mathbf{x}), \mathbf{y}) \end{aligned}$$

#### **Stochastic Gradient Descent:**

Initialize random  $\theta$ 

N iterations:

For 
$$x, y \in D$$
 Iteration 
$$\theta \leftarrow \theta - \frac{\epsilon}{|D|} \nabla_{\theta} \mathcal{E}(\theta; f(x), y)$$
 Epoch

Noisy but much faster than standard GD

### SGD – Variance

$$\mathbf{E}_{\mathbf{x},\mathbf{y}\sim D}[\nabla_{\theta} \mathcal{E}(\theta;\mathbf{x},\mathbf{y})] = \nabla_{\theta} L(\theta)$$

$$\nabla_{\theta} \mathcal{L}(\theta; \mathbf{x}_i, \mathbf{y}_i) \neq \nabla_{\theta} L(\theta)$$

$$\begin{aligned} \operatorname{Var} \left[ \nabla_{\theta} \ell(\theta; \mathbf{x}, y) \right] &= \operatorname{E}_{\mathbf{x}, y \sim D} \left[ \left\| \nabla_{\theta} \ell(\theta; \mathbf{x}, y) - \nabla_{\theta} L(\theta) \right\|^{2} \right] \\ &= \operatorname{E}_{\mathbf{x}, y \sim D} \left[ \left\| \nabla_{\theta} \ell(\theta; \mathbf{x}, y) \right\|^{2} \right] - \left\| \nabla_{\theta} L(\theta) \right\|^{2} \end{aligned}$$

### Mini-batches

#### **Stochastic Gradient Descent:**

Initialize random  $\theta$ 

N iterations:

For 
$$x, y \in D$$
 
$$\theta \leftarrow \theta - \frac{\epsilon}{|D|} \nabla_{\theta} \mathcal{E}(\theta; f(\mathbf{x}), y)$$

#### Minibatch Gradient Descent:

Initialize random  $\theta$ 

N iterations:

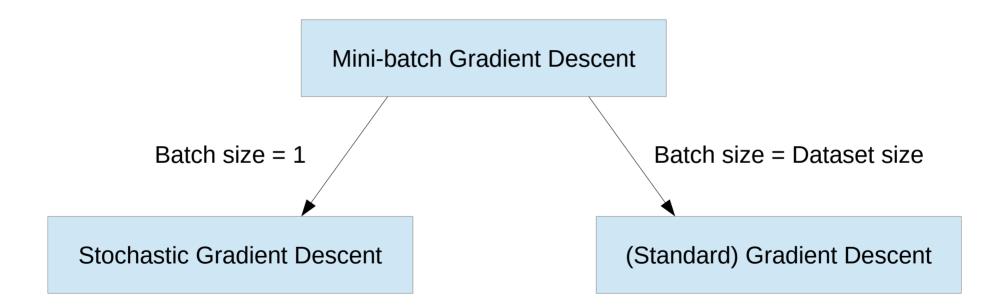
Partition D into  $D_1, \ldots, D_k$ 

For  $1 \le i \le k$ 

$$\theta \leftarrow \theta - \epsilon E_{x, y \sim D_i} [\nabla_{\theta} \mathcal{L}(\theta; f(x), y)]$$

Batch size = 
$$|D_1| = |D_2| = ... = |D_k|$$

## Gradient Descent Algorithms



### Mini-batch Variance

#### Stochastic Gradient Descent

$$\operatorname{Var}\left[\nabla_{\theta} \mathcal{E}(\theta; \mathbf{x}, y)\right] = \operatorname{E}_{\mathbf{x}, y \sim D}\left[\left\|\nabla_{\theta} \mathcal{E}(\theta; \mathbf{x}, y)\right\|^{2}\right] - \left\|\nabla_{\theta} L(\theta)\right\|^{2}$$

#### **Minibatch Gradient Descent**

$$\operatorname{Var}\left[\nabla_{\theta} \mathcal{L}(\theta; \mathbf{x}, \mathbf{y})\right] = \operatorname{E}_{D_{i}}\left[\operatorname{E}_{\mathbf{x}, \mathbf{y} \sim D_{i}}\left[\left\|\nabla_{\theta} \mathcal{L}(\theta; \mathbf{x}, \mathbf{y})\right\|\right]^{2}\right] - \left\|\nabla_{\theta} L(\theta)\right\|^{2}$$

**Smaller** 

### Momentum

Initialize random  $\theta$ 

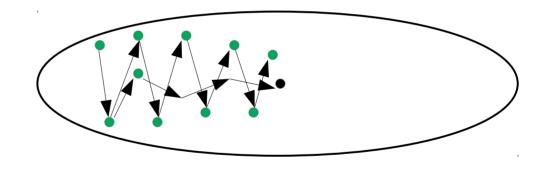
N iterations:

For 
$$x, y \in D$$

$$\mathbf{v} \leftarrow \nabla_{\theta} \mathcal{C}(\theta, f(\mathbf{x}), \mathbf{y})$$

$$\mathbf{v} \leftarrow \rho \mathbf{v} + \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}; f(\mathbf{x}), \mathbf{y})$$

$$\theta \leftarrow \theta - \epsilon v$$



$$\rho = 0.9$$