



Student Name: Juan Pablo Zambrano Maldonado

Assignment: Robotics

Notes: Grip map

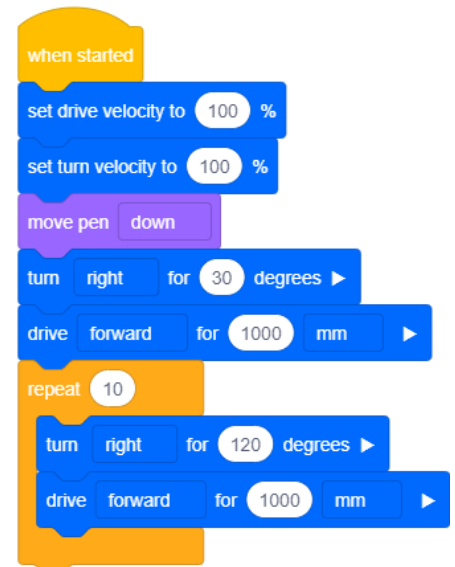
Playground: Grid Map

Project Name: PRACTICA 1 COMPLETA

Project Type: Blocks

Date: Thu Feb 09 2023

Playground Screenshot Not Found



when started

set drive velocity to 100 %

set turn velocity to 100 %

move pen down

drive forward for 200 mm ▶

turn right for 90 degrees ▶

drive forward for 200 mm ▶

turn right for 90 degrees ▶

drive forward for 200 mm ▶

turn right for 90 degrees ▶

drive forward for 200 mm ▶

turn right for 90 degrees ▶

when started

set drive velocity to 100 %

set turn velocity to 100 %

move pen down

turn right for 30 degrees ▶

drive forward for 1000 mm ▶

turn right for 120 degrees ▶

drive forward for 1000 mm ▶

turn right for 120 degrees ▶

drive forward for 1000 mm ▶

when started

set drive velocity to 100 %

set turn velocity to 100 %

move pen down

repeat 4

drive forward for 1000 mm ▶

turn right for 90 degrees ▶

when started

set drive velocity to 100 %

set turn velocity to 100 %

move pen down

turn right for 30 degrees ▶

drive forward for 1000 mm ▶

repeat 10

turn right for 120 degrees ▶

drive forward for 1000 mm ▶