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/*
Name:-
roll _no:-
Div:-
AIM:- Write C++ program to implement Cohen -Sutherland line clipping algorithm.*/
#include<iostream>
/*#include<dos.h>*/
#include<stdlib.h>
#include<math.h>
#include<graphics.h>
using namespace std;
/* Defining structure for end point of line */
typedef struct coordinate
       int x;
       int y;
       char code[4];
}PT;
void drawwindow();
void drawline (PT p1,PT p2,int cl);
PT setcode(PT p);
int visibility (PT p1,PT p2);
PT resetendpt (PT p1,PT p2);
void check_line(PT p1,PT p2);
int main()
{
       int gd=DETECT, gm,n;
       PT p1,p2;
   cout<<"\n\t\tENTER n value ";</pre>
       cin>>n;
for(int i=0;i< n;i++)
{
       cout<<"\n\t\tENTER END-POINT 1 (x,y): ";</pre>
       cin>>p1.x>>p1.y;
       cout<<"\n\t\tENTER END-POINT 2 (x,y): ";</pre>
       cin>>p2.x>>p2.y;
}
       initgraph(&gd,&gm,NULL);
       drawwindow();
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drawline(p1,p2,15);
       check_line(p1,p2);
       return(0);
}
/* Function to draw window */
void drawwindow()
{
       setcolor(RED);
       line(150,100,450,100);
       line(450,100,450,350);
       line(450,350,150,350);
       line(150,350,150,100);
       delay(2000);
}
/* Function to draw line between two points
void drawline (PT p1,PT p2,int cl)
{
       setcolor(cl);
       line(p1.x,p1.y,p2.x,p2.y);
       delay(2000);
}
void check_line(PT p1,PT p2)
{
       int v;
       p1=setcode(p1);
       p2=setcode(p2);
       v=visibility(p1,p2);
       switch(v)
       {
               case 0: cleardevice(); /* Line conpletely visible */
               drawwindow();
               drawline(p1,p2,15);
               break;
               case 1: cleardevice(); /* Line completely invisible */
               drawwindow();
               break;
               case 2: cleardevice(); /* line partly visible */
               p1=resetendpt (p1,p2);
               p2=resetendpt(p2,p1);
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check_line(p1,p2);
              break;
delay(2000);
}
/* Function to set code of the coordinates
*/
PT setcode(PT p)
{
       PT ptemp;
       if(p.y<100)
       ptemp.code[0]='1'; /* TOP */
       else
       ptemp.code[0]='0';
       if(p.y>350)
       ptemp.code[1]='1'; /* BOTTOM */
       else
       ptemp.code[1]='0';
       if (p.x>450)
       ptemp.code[2]='1'; /* RIGHT */
       else
       ptemp.code[2]='0';
       if (p.x<150) /* LEFT */
       ptemp.code[3]='1';
       else
       ptemp.code[3]='0';
       ptemp.x=p.x;
       ptemp.y=p.y;
       return(ptemp);
}
/* Function to determine visibility of line
int visibility (PT p1,PT p2)
{
       int i,flag=0;
       for(i=0;i<4;i++)
              if((p1.code[i]!='0')||(p2.code[i]!='0'))
                     flag=2;
       }
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for(i=0;i<4;i++)
{
       if((p1.code[i]==p2.code[i]) &&(p1.code[i]=='1'))
       flag=1;
}
       if(flag==0)
               return(0);
       if(flag==1)
               return(1);
       if(flag==2)
               return(2);
}
/* Function to find new end points
PT resetendpt (PT p1,PT p2)
{
       PT temp;
       int x,y,i;
       float m,k;
       if( p1.code[3]=='1') /* Cutting LEFT Edge */
               x=150;
       if(p1.code[2]=='1') /* Cutting RIGHT Edge */
               x = 450;
       if((p1.code[3]=='1')||(p1.code[2]=='1'))
       {
               m=(float) (p2.y-p1.y)/(p2.x-p1.x);
               k=(p1.y+(m*(x-p1.x)));
               temp.y=k;
               temp.x=x;
               if(temp.y<=350&&temp.y>=100)
               return(temp);
       if(p1.code[0]=='1') /* Cutting TOP Edge */
               y=100;
       if(p1.code [1]=='1') /* Cutting BOTTOM Edge */
               y=350;
       if((p1.code[0]=='1')||(p1.code[1]=='1'))
               m=(float)(p2.y-p1.y)/(p2.x-p1.x);
               k=(float)p1.x+(float)(y-p1.y)/m;
               temp.x=k;
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temp.y=y;
if(temp.x<=450&&temp.x>=150)
return(temp);
}
else
return(p1);
}
/*******OUPUT*********
user@user:~$ g++ EXP3.cpp -lgraph
user@user:~$ ./a.out

ENTER n value 1
ENTER END-POINT 1 (x,y): 50 200
ENTER END-POINT 2 (x,y): 300 400 */
```